



LMS-240

Fish-finding Sonar & Mapping GPS

Operation Instructions

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WARNING!

A CAREFUL NAVIGATOR NEVER RELIES ON ONLY ONE METHOD TO OBTAIN POSITION INFORMATION.

CAUTION

When showing navigation data to a position (waypoint), a GPS unit will show the shortest, most direct path to the waypoint. It provides navigation data to the waypoint regardless of obstructions. Therefore, the prudent navigator will not only take advantage of all available navigation tools when traveling to a waypoint, but will also visually check to make sure a clear, safe path to the waypoint is always available.

WARNING!

When a GPS unit is used in a vehicle, the vehicle operator is solely responsible for operating the vehicle in a safe manner. Vehicle operators must maintain full surveillance of all pertinent driving, boating or flying conditions at all times. An accident or collision resulting in damage to property, personal injury or death could occur if the operator of a GPS-equipped vehicle fails to pay full attention to travel conditions and vehicle operation while the vehicle is in motion.

Section 1: Read Me First!

How this manual can get you out on the road, fast!

Welcome to the exciting world of digital sonar and GPS! We know you're anxious to begin navigating and finding fish, but we have a favor to ask. Before you grab the unit and begin installing it, please give us a moment or two to explain how our manual can help you get the best performance from this compact, wide-screen, combination fish finder and mapping GPS receiver.

First, we want to thank you for buying a Lowrance LMS-240. Whether you're a first time user or a professional fisherman, you'll discover that the LMS-240 is easy to use, yet capable of handling demanding navigation and sonar tasks. When you team a LMS-240 with our custom mapping software MapCreate™ 6, you have an incredible combination. You won't find another combination GPS and sonar unit with this much power and this many features for this price!

Our goal for this book is to get you on the water fast, with a minimum of fuss. Like you, we'd rather spend more time boating or fishing and less time reading the manual!

So, we designed our book so that you *don't* have to read the *whole thing* from front to back for the information you want. At the start (or end) of each segment, we'll tell you what content is coming up next. If it's a concept you're already familiar with, we'll show you how and where to skip ahead for the next important topic. We've also made it easy to look up any tips you may need from time to time. Here's how:

The manual is organized into 10 sections. This first section is an introduction to the LMS-240, sonar and GPS. It tells you the basics you need to know before you can make the unit look around and tell you where you are, or look below the surface to find some fish.

Section 2 will help you install your LMS-240, the transducer and the GPS antenna module. We'll show you how to get the MultiMedia Card (MMC) correctly installed inside the unit. We'll also tell you about some of the available accessories.

Section 3 is covers *Basic Sonar Operation*. It will show you how easy it is run your LMS-240 sonar, right out of the box. This section features a one-page Sonar Quick Reference. (**If you've already jumped ahead and figured out how to install the unit yourself, and you just can't wait any longer, turn to the Quick Reference on page 43 and head for the water with your LMS-240!**)

After you've gained some experience with your sonar, you'll want to check out Section 4, which discusses more advanced *Sonar Options and Other Features*.

When you come to a sonar menu command on the LMS-240 screen, you can look it up in the manual by skimming over the table of contents, just flipping through Section 3 or scanning through the sonar options in Section 4.

If you're having difficulty with your sonar, you can find an answer to the most common problems in Section 5, *Sonar Troubleshooting*.

The manual switches from sonar to navigation in Section 6, which introduces you to *Basic GPS Operations*. **This section features a one-page GPS Quick Reference on page 96.**

Section 6 contains short, easy-to-scan GPS lessons that follow one another in chronological order. They're all you'll need to know to find your way on the water quickly.

After you've learned the basics (or if you already have some GPS experience), you may want to try out some of LMS-240's many advanced navigation features. That brings us to Section 7, *Advanced GPS Operations*. This section contains the rest of LMS-240's GPS command functions, organized in alphabetical order.

When you come to a GPS menu command on the LMS-240 screen, you can look it up in the manual by skimming over the table of contents, just flipping through Section 6 or scanning through the command portion of Section 7.

LMS-240 is ready to use right out of the box, but you can fine tune and customize it's operation with dozens of options. Since sonar is the unit's key feature, we put the main sonar options in Section 4. Some options, such as screen brightness settings, affect both sonar and GPS operations. We describe how to use those common options along with GPS options in Section 8, *System Setup and GPS Setup Options*. Sec. 8 is organized in alphabetical order.

In Section 9, we go into more detail on one of LMS-240's most remarkable GPS capabilities — Searching. We'll introduce a search example in the Basic GPS Operation section, but there are so many map items you can search for, we had to give this function it's own section in the manual! For example, did you know LMS-240 can look up business phone numbers, functioning as a virtual Yellow Pages? We'll show you how in Section 9.

Finally, in Section 10, we offer *Supplemental Material*, including a list of the GPS datums used, warranties and customer service information.

Now, if you're into the fine details, glance over the next segment on specifications to see just how much sonar and GPS power your unit contains. It's important to *us* (and our power users), but, if *you* don't care how many watts of power the unit has, or how many waypoints LMS-240 can store, skip ahead to important information on how LMS-240 sonar works, on page 5. (Background on GPS also begins on page 5.)

Capabilities and Specifications

General

Display:..... 5.0" (12.7 cm) diagonal high contrast Film SuperTwist; programmable to viewing preference.

Resolution:..... 240 pixel x 240 pixel resolution; 57,600 total pixels

Backlighting:..... Advanced cold cathode screen with multiple lighting levels; backlit keypad.

Input power:..... 10 to 15 volts DC

Case size:..... 5.4" H x 6.9" W x 3.4" D (13.8 x 17.6 x 8.6 cm); sealed and waterproof; suitable for saltwater use.

MMC slots:One with waterproof door (SD card compatible)

Back-up memory: ... built-in memory stores sonar records and GPS data for decades

Languages:..... 10; menu languages selectable by user

Sonar

Frequency:..... 200 kHz

Transducer: Skimmer® with temperature sensor; up to 60° coverage with high sensitivity settings.

Watts: 3,000 peak-to-peak power/375 RMS power

Sonar sounding

depth capability: 1,000 feet/305 meters. (actual capability depends on transducer configuration and installation, bottom composition and water conditions. All sonar units typically read deeper in fresh water than in salt water.)

Depth display:..... Continuous display

Graph recording:..... Up to 128 MB on one MMC (or SD) card

Audible alarms: Deep/shallow/fish/zone

Automatic ranging:.... Yes, with instant screen updates

Zoom bottom track: ... Yes

Split-screen zoom:..... Yes

Surface water temp:.. Yes

Speed/distance log:.... Optional (requires optional speed sensor)

GPS

Receiver/antenna:... External; LGC-12w 12 parallel channel
GPS/WAAS; DGPS beacon receiver optional.

Recording:MMC memory cards for recording GPS trip
details and displaying charts or custom maps

Background map:....Built-in custom, detailed Lowrance map

Custom mapping:MapCreateTM 6 software optional;
Navionics[®] charts optional.

Mapping memory: ...Up to 128 MB on one MMC (or SD) card

Position updates:Every second

Position points:1,000 waypoints; 1,000 event marker icons

Audible alarms:Arrival/off-course/anchor

**Graphic symbols for
waypoints or event
marker icons:**42

Routes:.....100

Plot Trails:10 savable; up to 9,999 points per trail

Zoom range:.....37 ranges; 0.05 to 4,000 miles

Key features: full-screen or split-screen viewing with split-screen map
zoom; searchable databases of highway exits and Points of Interest; trail
backtracking; Man Overboard (MOB) capability; full one-year warranty.

NOTE:

The above memory capacities refer only to LMS-240's on-board
memory. The amount of GPS or sonar data you can record and save
for recall later is only limited by the number of MMC cards you have.

NOTICE!

The storage temperature range for your unit is from -4 degrees to +167
degrees Fahrenheit (-20 degrees to +75 degrees Celsius). *Extended stor-
age in temperatures higher or lower than specified will damage the liq-
uid crystal display in your unit. This type of damage is not covered by
the warranty.* For more information, contact the factory's Customer
Service Department; phone numbers are listed on the last page.

How LMS-240 Sonar Works

Sonar has been around since the 1940s, so if you already know how it works, skip down to read about the relatively new technology of GPS. But, if you've never owned a sonar fish finder, this segment will tell you the under water basics.

Sonar is an abbreviation for SOund NAvigation and Ranging, a technology developed during World War II for tracking enemy submarines. (Lowrance developed the world's *first* transistorized *sportfishing* sonar in 1957.) A sonar consists of a transmitter, transducer, receiver and display. In simple terms, here's how it finds the bottom, or the fish:

The transmitter emits an electrical impulse, which the transducer converts into a sound wave and sends into the water. (The sound frequency can't be heard by humans or fish.) The sound wave strikes an object (fish, structure, bottom) and bounces back to the transducer, which converts the sound back into an electrical signal.

The receiver amplifies this return signal, or echo, and sends it to the display, where an image of the object appears on the scrolling sonar chart. The sonar's microprocessor calculates the time lapse between the transmitted signal and echo return to determine the distance to the object. The whole process repeats itself several times each second.

Your LMS-240 can record a log of the sonar signals that scroll across the screen and save them to the MMC memory card. (These recordings are also called sonar charts or sonar graphs.) You can replay this sonar log in the unit using the Sonar Simulator function, or play it back on a personal computer using our free Sonar Viewer. The viewer is available for download from the Lowrance web site, www.lowrance.com.

You can save several different sonar log files, erase 'em and record new ones, over and over again. The size of your sonar recordings is only limited by the free space available on your MMC.

How LMS-240 GPS Works

You'll navigate faster and easier if you understand how the LMS-240 scans the sky to tell you where you are on the earth — and, where you're going. (But if you already have a working understanding of GPS receivers and the GPS navigation system, skip on ahead to Section 2, *Installation & Accessories* on page 11. If you're new to GPS, read on, and you can later impress your friends with your new-found knowledge.)

First, think of your LMS-240 as a small but powerful computer. (But don't worry — we made LMS-240 easy to use, so you don't need to be a computer expert to find your way!) The unit includes a keypad and a

screen with menus so you can tell LMS-240 what to do. The screen also lets LMS-240 show your location on a moving map, as well as point the way to your destination.

This gimbal-mounted unit uses an external antenna/receiver module, which makes the whole system work something like your car radio. But instead of your favorite dance tunes, this receiver tunes in to a couple of dozen GPS satellites circling the earth. (It will also listen in to the WAAS satellites in orbit, but more about that in the upcoming segment introducing you to GPS and WAAS.)

Your LMS-240 listens to signals from as many satellites as it can "see" above the horizon, eliminates the weakest signals, then computes its location in relation to those satellites. Once LMS-240 figures its latitude and longitude, it plots that position on the moving map shown on the screen. The whole process takes place several times a second!

The performance doesn't stop there. Stored in the permanent memory of each LMS-240 is a basic background map of the *entire* world. We lock it in here at the factory — you can't change or erase this map.

This background map includes: low-detail maps of the whole world (containing cities, major lakes, major rivers, political boundaries); and medium-detail maps of the United States (containing all incorporated cities; Interstate, U.S. and state highways; Interstate highway exits and exit services information; large- and medium-sized lakes and streams.)

Another portion of LMS-240's onboard memory is devoted to *recording* GPS navigation information, which includes waypoints, event marker icons, trails and routes. This lets you look back the way you came. Think of this data storage like the hard drive memory in a computer or a tape in a cassette tape recorder. You can save several different GPS data files, erase 'em and record new ones, over and over again. Like any computer file, these **GPS Data Files** (file format *.usr) can be shared between LMS-240s, other Lowrance GPS or sonar/GPS units, even personal computers.

LMS-240 has one more thing in common with a personal computer. Just as computers have a floppy disk drive for storing and exchanging files, the LMS-240 has a slot for an MMC (MultiMedia Card) or SDC (Secure Digital card) flash memory card. These solid-state memory devices are about the size of a postage stamp, but can hold data ranging from 8 MB to 128 MB in size. (Compare that to a floppy disk's 1.44 MB

capacity!) LMS-240 uses all that MMC space for two key GPS purposes. (The MMC is also used to record sonar logs...see page 5.)

First, you can backup your onboard GPS Data Files by copying them to the MMC. Since the MMC is removable (like a floppy disk or a cassette tape), you can store these GPS Data Files on a personal computer equipped with an MMC card reader. (Or store them on a pocketful of MMCs, if you don't have a computer.) Our MapCreate mapping software can save, edit or create its own GPS Data Files, which can be copied to the MMC and then loaded from the MMC into LMS-240's memory. (**NOTE:** No matter where they come from, GPS Data Files *must* be loaded from the MMC into memory before LMS-240 can use them.)

The other key GPS use for MMCs is storage of special high-detail, custom maps, which you can produce on your computer with our MapCreate software. These MapCreate custom maps contain much greater detail than the basic background map. These ***Custom Map Files*** (file format *.lcm) can also be shared between LMS-240s, other Lowrance GPS or sonar/GPS units and personal computers. (For example, the exact same MMC, custom map files and GPS data files can be used interchangeably between your gimbal-mounted LMS-240 and the hand-held iFINDER™ GPS receiver.)

LMS-240 automatically reads Custom Map Files directly from the MMC or SDC. To use a custom map, all you need to do is slide an MMC containing a map into the unit.

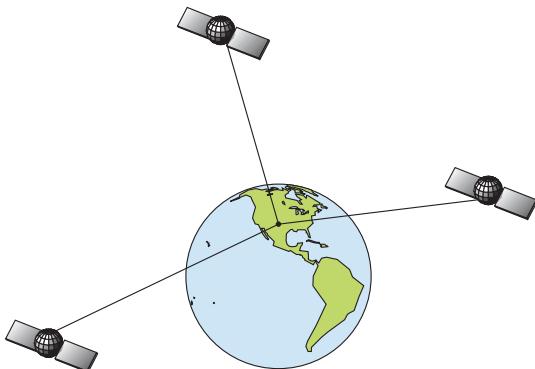
Introduction to GPS and WAAS

Well, now you know the basics of how LMS-240 does its work. You might be ready to jump ahead to Section 2, *Installation & Accessories*, on page 11, so you can mount your unit and plug in the power. Or you might want to see how our text formatting makes the manual tutorials easy to skim. If that's the case, move on to "How to Use This Manual" on page 9. But, if you want to understand the current state of satellite navigation, look over this segment describing how GPS and its new companion WAAS work together to get you where you're going.

The Global Positioning System (GPS) was launched July 17, 1995 by the United States Department of Defense. It was designed as a 24-hour-a-day, 365-days-a-year, all weather global navigation system for the armed forces of the U.S. and its allies. Civilian use was also available at first, but it was less accurate because the military scrambled the signal somewhat, using a process called Selective Availability (SA.)

GPS proved so useful for civilian navigation that the federal government discontinued SA on May 2, 2000, after the military developed other methods to deny GPS service to enemy forces. Reliable accuracy for civilian users jumped from 100 meters (330 feet) under SA to the present level of 10 to 20 meters (about 30 to 60 feet.)

Twenty-four satellites orbit 10,900 nautical miles above the Earth, passing overhead twice daily. A series of ground stations (with precisely surveyed locations) controls the satellites and monitors their exact locations in the sky. Each satellite broadcasts a low-power signal that identifies the satellite and its position above the earth. Three of these satellites are spares, unused until needed. The rest virtually guarantee that at least four satellites are in view nearly anywhere on Earth at all times.



A minimum of three satellites are required to determine a 2D fix.

The system requires signal reception from three satellites in order to determine a position. This is called a 2D fix. It takes four satellites to determine both position and elevation (your height above sea level — also called altitude.) This is called a 3D fix.

Remember, the unit must have a clear view of the satellites in order to receive their signals. Unlike radio or television signals, GPS works at very high frequencies. These signals can be easily blocked by trees, buildings, an automobile roof, even your body.

Like most GPS receivers, LMS-240 doesn't have a compass or any other navigation aid built inside. It relies solely on the signals from the satellites to calculate a position. Speed, direction of travel, and distance are all calculated from position information. Therefore, in order for LMS-240 to determine direction of travel, you must be moving and the faster, the better. This is not to say that it won't work at walking or trolling speeds — it will. There will simply be more "wandering" of the data shown on the display.

GPS is plenty accurate for route navigation, but the U.S. Federal Aviation Administration has special needs for aircraft traffic control that go beyond basic GPS. The FAA has a plan under way to boost GPS performance even further with its Wide Area Augmentation System, or WAAS. This GPS add-on will include a time control element that will help airliners fly closer together while avoiding collisions. In addition to carefully spacing airplanes along travel corridors, WAAS will eventually make instrument landings and takeoffs more accurate as it replaces existing aviation navigation systems.

Non aviators can use WAAS signals to make their GPS navigation even more accurate. Your LMS-240 receives both GPS and WAAS signals. However, WAAS has some limits you should know about.

First, the U.S. government has not completed construction of the WAAS system, so it is not yet fully operational. The ground stations are in place, but only a few of the needed WAAS satellites have been launched.

WAAS *can* boost the accuracy of land GPS navigation, but the system is designed for aircraft. The satellites are in a fixed orbit around the Equator, so they appear very low in the sky to someone on the ground in North America. Aircraft and vessels on open water can get consistently good WAAS reception, but terrain, foliage or even large man-made structures frequently block the WAAS signal from ground receivers.

You'll find that using your GPS receiver is both easy and amazingly accurate. It's easily the most accurate method of electronic navigation available to the general public today. Remember, however, that this receiver is only a tool. Always have another method of navigation available, such as a map or chart and a compass.

Also remember that this unit will always show navigation information in the shortest line from your present position to a waypoint, regardless of terrain! It only calculates position, it can't know what's between you and your destination, for example. It's up to you to safely navigate around obstacles, no matter how you're using this product.

How to use this manual: typographical conventions

Many instructions are listed as numbered steps. The keypad and arrow "keystrokes" appear as boldface type. So, if you're in a real hurry (or just need a reminder), you can skim the instructions and pick out what menu command to use by finding the boldface command text. The following paragraphs explain how to interpret the text formatting for those commands and other instructions:

Arrow Keys

The arrow keys control the movement of dotted cross-hair lines on your mapping screen called the cursor. The arrow keys also control a horizontal line depth cursor on the sonar screen. The arrow keys help you move around the menus so you can execute different commands. They are represented by symbols like these, which denote the down arrow key, the up arrow, the left arrow and the right arrow: ↓ ↑ ← → .

Keyboard

The other keys perform a variety of functions. When the text refers to a key to press, the key is shown in bold, sans serif type. For example, the "Enter/Icons" key is shown as **ENT** and the "Menu" key is shown as **MENU**.

Menu Commands

A menu command or a menu option will appear in small capital letters, in a bold sans serif type like this: **ROUTE PLANNING**. These indicate that you are to select this command or option from a menu or take an action of some kind with the menu item. Text that you may need to enter or file names you need to select are shown in italic type, such as *trail name*.

Instructions = Menu Sequences

Most functions you perform with LMS-240 are described as a sequence of key strokes and selecting menu commands. We've written them in a condensed manner for quick and easy reading.

For example, instructions for navigating a trail would look like this:

1. From the Map Page, press **MENU** | **MENU** | ↓ to **MY TRAILS** | **ENT**.
2. Press ↓ to *Trail 1* | **ENT** | → | ↓ to **NAVIGATE** | **ENT**.
3. You are asked to wait while it converts the trail into a route.
4. The wait message disappears and the unit begins showing navigation information along the trail. Now, begin moving and follow your LMS-240.

Translated into complete English, step 1 above would mean: "Start on the Map Page. Press the Menu key twice. Next, repeatedly press (or press and hold) the down arrow key to scroll down the menu and select (highlight) the My Trails menu command. Finally, press the Enter key."

Step 2 would mean: "Press the down arrow key repeatedly to scroll to the trail named Trail 1, and press Enter. Next, press the right arrow key and then the down arrow key to highlight the Navigate command, then press Enter."

Section 2: Installation & Accessories

Preparations

You can install the sonar and GPS systems in some other order if you prefer, but we recommend this installation sequence:

Caution:

You should read over this entire installation section before drilling any holes in your vehicle!

1. Determine the approximate location for the sonar/GPS unit, so you can plan how and where to route the cables for the antenna, transducer and power. This will help you make sure you have enough cable length for the desired configuration.
2. Determine the approximate location for the transducer and its cable route.
3. Determine the approximate location for the GPS antenna module and its cable route.
4. Determine the location of your battery or other power connection, along with the power cable route.
5. Install the transducer and route the transducer cable to the sonar/GPS unit.
6. Install the GPS antenna and route the antenna cable to the sonar/GPS unit.
7. Install the power cable and route it to the sonar/GPS unit.
8. Mount the sonar/GPS unit.

Transducer Installation

Some of the models covered by this manual have a transom-mount transducer included. There are two different transducers that could be packed with your unit. One is a 20° cone angle Skimmer® transducer that can be mounted on the transom or epoxied inside certain boats to "shoot-thru" the hull.

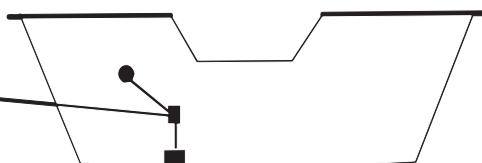
Read this manual carefully before attempting the installation. Determine which of the mounting positions is right for your boat. Use extreme care if mounting the transducer inside the hull, since once it is epoxied into position, the transducer usually cannot be removed. *Re-*

member, the transducer location is the most critical part of a sonar installation.

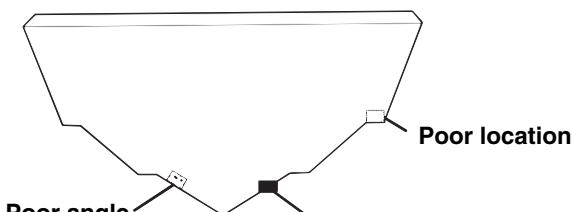
Location – General – All Transducers

1. The transducer must be placed in a location that has a smooth flow of water at all times. If the transducer is to be mounted inside the hull, then the chosen location must be in the water at all times. If the transducer is not placed in a smooth flow of water, interference will show on the sonar's display in the form of random lines or dots whenever the boat is moving.
2. The transducer should be installed with its face pointing straight down, if possible.
3. If the transducer is mounted on the transom, make certain it doesn't interfere with the trailer or hauling of the boat. Also, don't mount it closer than approximately one foot from the engine's lower unit. This will prevent cavitation interference with the propeller. Typically, the transducer should be mounted as deep in the water as possible. This helps insure that it will be in the water while running at high speed. This also reduces the possibility of air bubble interference.
4. If possible, route the transducer cable away from other wiring on the boat. Electrical noise from engine wiring, bilge pumps and aerators can be displayed on the sonar's screen. Use caution when routing the transducer cable around these wires.

CAUTION: Clamp the transducer cable to transom near the transducer. This will help prevent the transducer from entering the boat if it is knocked off at high speed.



Good location



Poor location

Good location

Good and poor transducer locations.

Shoot-thru-hull vs. Transom Mounting (20° Transducer Only)

Typically, shoot-thru-hull installations give excellent high speed operation and good to excellent depth capability. There is no possibility of damage from floating objects. It can't be knocked off when docking or loading on the trailer.

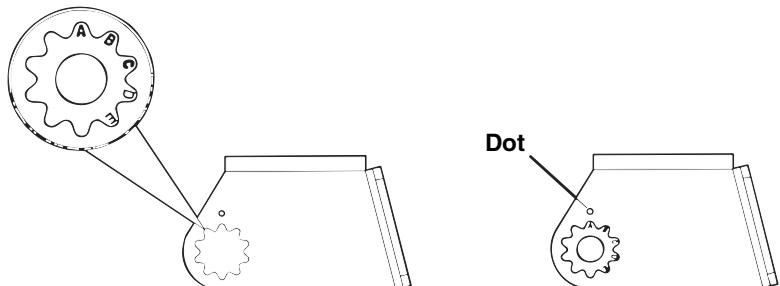
However, the shoot-thru-hull installation does have its drawbacks. One, some loss of sensitivity does occur, even on the best hulls. This varies from hull to hull, even from different installations on the same hull. This is caused by differences in hull lay-up and construction.

Two, the angle of the transducer cannot be adjusted for the best fish arches. This can be a problem on some hulls that sit with the bow high when at rest or at slow trolling speeds. Follow the test procedure listed in the shoot-thru-hull installation section in this manual to determine if you can satisfactorily shoot through the hull.

Transducer Assembly and Transom Mounting (20° Transducer Only)

The best way to install this transducer is to loosely assemble all of the parts first, place the transducer's bracket against the transom and see if you can move the transducer so that it's parallel with the ground.

1. Press the two small plastic ratchets into the sides of the metal bracket as shown below. Notice there are letters molded into each ratchet. Place each ratchet into the bracket with the letter "A" aligned with the dot stamped into the metal bracket. This position sets the transducer's coarse angle adjustment for a fourteen (14°) degree transom. Most outboard and stern-drive transoms have a fourteen degree angle.

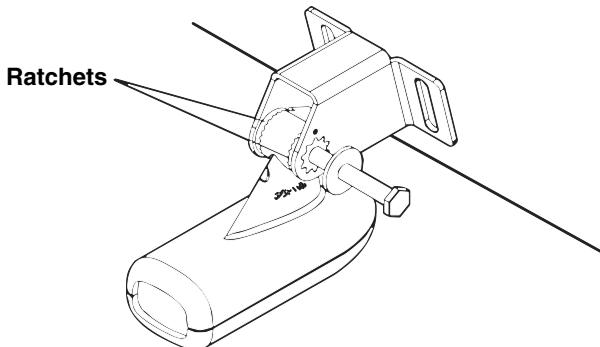


Align plastic ratchets in bracket.

2. Slide the transducer between the two ratchets. Temporally slide the bolt though the transducer assembly and hold it against the transom.

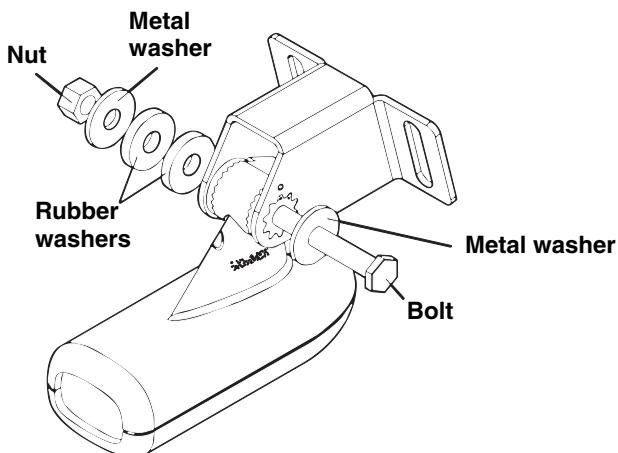
Looking at the transducer from the side, check to see if it will adjust so that its face is parallel to the ground. If it does, then the "A" position is correct for your hull.

If the transducer's face isn't parallel with the ground, remove the transducer and ratchets from the bracket. Place the ratchets into the holes in the bracket with the letter "B" aligned with the dot stamped in the bracket. Reassemble the transducer and bracket and place them against the transom. Again, check to see if you can move the transducer so it's parallel with the ground. If you can, then go to step 3. If it doesn't, repeat step 2, but use a different letter until you can place the transducer on the transom correctly.



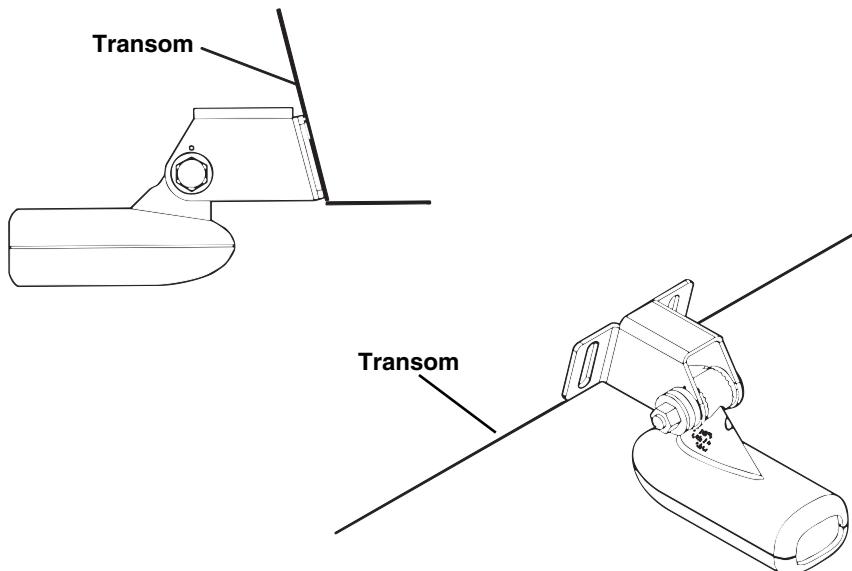
Insert bolt and check transducer position on transom.

3. Once you determine the correct position for the ratchets, assemble the transducer as shown below. Don't tighten the lock nut at this time.

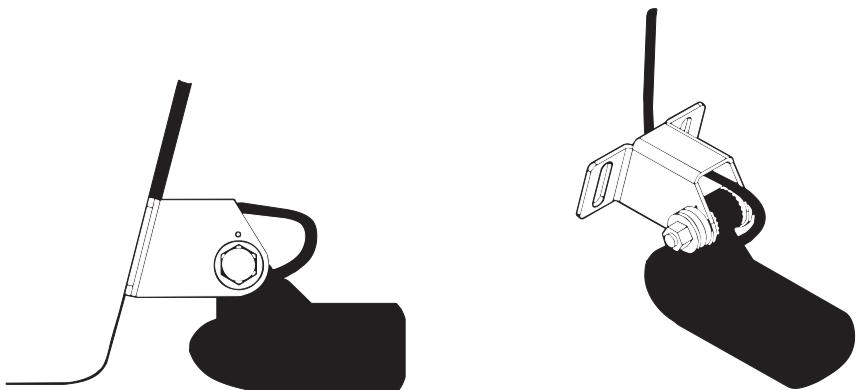


Assemble transducer.

4. Hold the transducer and bracket assembly against the transom. The transducer should be roughly parallel to the ground. The bottom of the transducer bracket should be in line with the bottom of the hull. Don't let the bracket extend below the hull! Mark the center of the slots for the mounting holes. Drill two 5/32" holes in the marked locations for the #10 screws supplied with the transducer.



**Position transducer mount on transom,
side view (left) and seen from above (right).**



**Route cable through bracket and mount transducer, side view (left)
and seen from above (right).**

5. Remove the transducer from the bracket and re-assemble it with the cable passing through the bracket over the bolt as shown above. Attach the transducer to the transom. Slide the transducer up or down until it's aligned properly on the transom as shown above. Tighten the bracket's mounting screws. Adjust the transducer so that it's parallel to the ground and tighten the lock nut until it touches the flat washer, then add 1/4 turn. Don't over tighten the lock nut! If you do, the transducer won't "kick-up" if it strikes an object in the water.

6. Route the transducer cable to the sonar unit. Plug it in the left socket on the back. Make sure to leave some slack in the cable at the transducer as shown on the previous page. If possible, route the transducer cable away from other wiring on the boat. Electrical noise from the engine's wiring, bilge pumps, VHF radio wires and cables, and aerators can be picked up by the sonar. Use caution when routing the transducer cable around these wires.

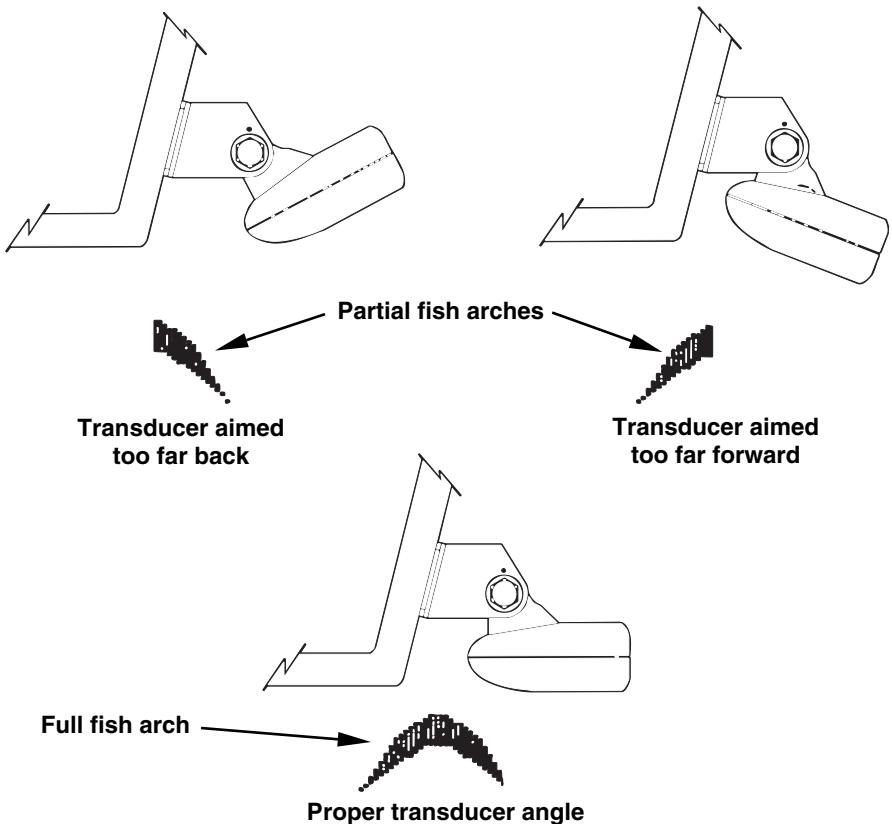
WARNING:

Clamp the transducer cable to the transom close to the transducer. This can prevent the transducer from entering the boat if it is knocked off at high speed.

7. Make a test run to determine the results. If the bottom is lost at high speed, or if noise appears on the display, try sliding the transducer bracket down. This puts the transducer deeper into the water, hopefully below the turbulence causing the noise. But remember, don't allow the transducer *bracket* to go below the bottom of the hull!

Transducer Orientation and Fish Arches

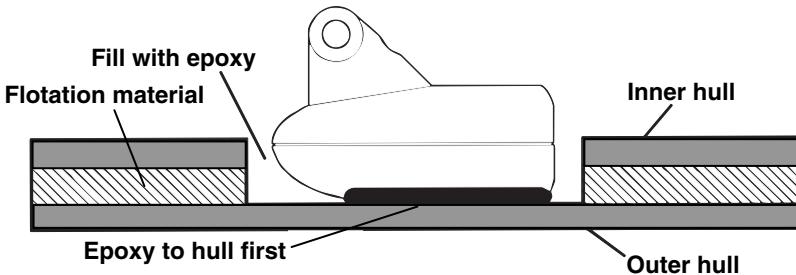
If you do not get good fish arches on your display, it could be because the transducer is not parallel with the ground when the boat is at rest in the water or at slow trolling speeds. If the arch slopes up – but not back down – then the front of the transducer is too high and needs to be lowered. If only the back half of the arch is printed, then the nose of the transducer is angled too far down and needs to be raised. See the illustrations at the top of the next page.



Transducer angles and their effects on fish arches.

Shoot-thru-Hull Preparation (20° Transducer Only)

The transducer installation inside a fiberglass hull must be in an area that does not have air bubbles in the resin or separated fiberglass layers. The sonar signal must pass through solid fiberglass. A successful transducer installation can be made on hulls with flotation materials (such as plywood, balsa wood or foam) between layers of fiberglass if the material is removed from the chosen area. The figure on the following page shows how a shoot-thru-hull installation looks in cross section view.



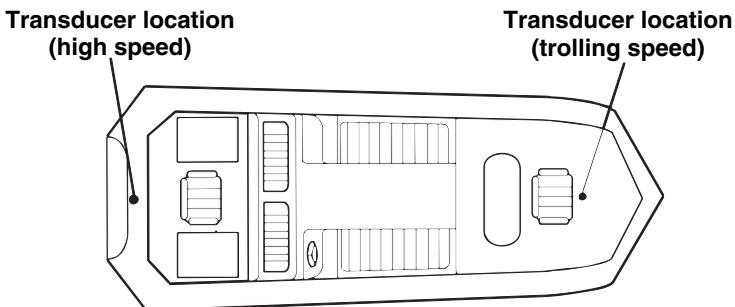
Epoxy the transducer to a solid portion of the hull.

For example, some manufacturers use a layer of fiberglass, then a core of balsa wood, finishing with an outer layer of fiberglass. Removing the inner layer of fiberglass and the balsa wood core exposes the outer layer of fiberglass. The transducer can then be epoxied directly to the outer layer of fiberglass. After the epoxy cures, the hull is watertight and structurally sound. Remember, the sonar signal must pass through solid fiberglass. Any air bubbles in the fiberglass or the epoxy will reduce or eliminate the sonar signals.

To choose the proper location for thru-hull mounting, anchor the boat in 60 feet of water. Add a little water to the sump of the boat. Plug the transducer into the sonar unit, turn it on, then hold the transducer over the side of the boat. Adjust the sensitivity and range controls until a second bottom echo is seen on the display. (You will need to turn off both automatic and ASP™. The **AUTO SENSITIVITY** and **SENSITIVITY** commands and the **AUTO DEPTH RANGE** and **DEPTH RANGE** commands are found on the Sonar Page Menu. To access them, from the Sonar Page press the **MENU** key. The Noise Rejection command, used to control ASP, is found by selecting **SONAR FEATURES** from the Sonar Page Menu.) Don't touch the controls once they've been set.

Next, take the transducer out of the water and place it in the water in the sump of the boat. Observe the sonar signal to see if there is a noticeable decrease in sensitivity. The second bottom signal may disappear and the bottom signal may decrease in intensity.

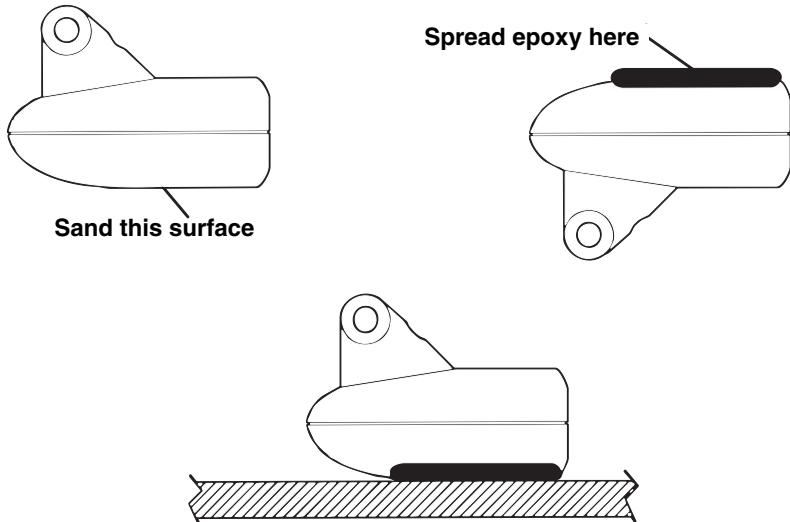
Move the transducer around to find the best location. If the sensitivity control must be increased greatly to compensate, then the transducer should be mounted on the outside of the hull. If not, then mark the location that shot through the hull the best and follow the instructions on the following pages for a shoot-thru-hull mounting.



Shoot-thru-hull transducer locations for high speed or trolling speed operation.

Shoot-thru-hull Installation (20° Transducer Only)

1. Make certain the area is clean, dry and free of oil or grease, then sand both the inside surface of the hull and the face of the transducer with 100 grit sandpaper. The surface of the hull must be flat so the entire transducer face is in contact with the hull prior to bonding.



Epoxy transducer to hull.

2. Follow the instructions on the epoxy package and mix it thoroughly. Do not mix it too fast, as it will cause bubbles to form in the epoxy. Apply a small amount on the face of the transducer as shown above, then spread a small amount onto the sanded area on the hull.

Place the transducer into the epoxy, twisting and turning it to force any air bubbles out from under the transducer face. The face of the

transducer should be parallel with the hull, with a minimum amount of epoxy between the hull and transducer. After the epoxy dries, route the cable to the sonar unit.

SPEED/TEMPERATURE SENSORS

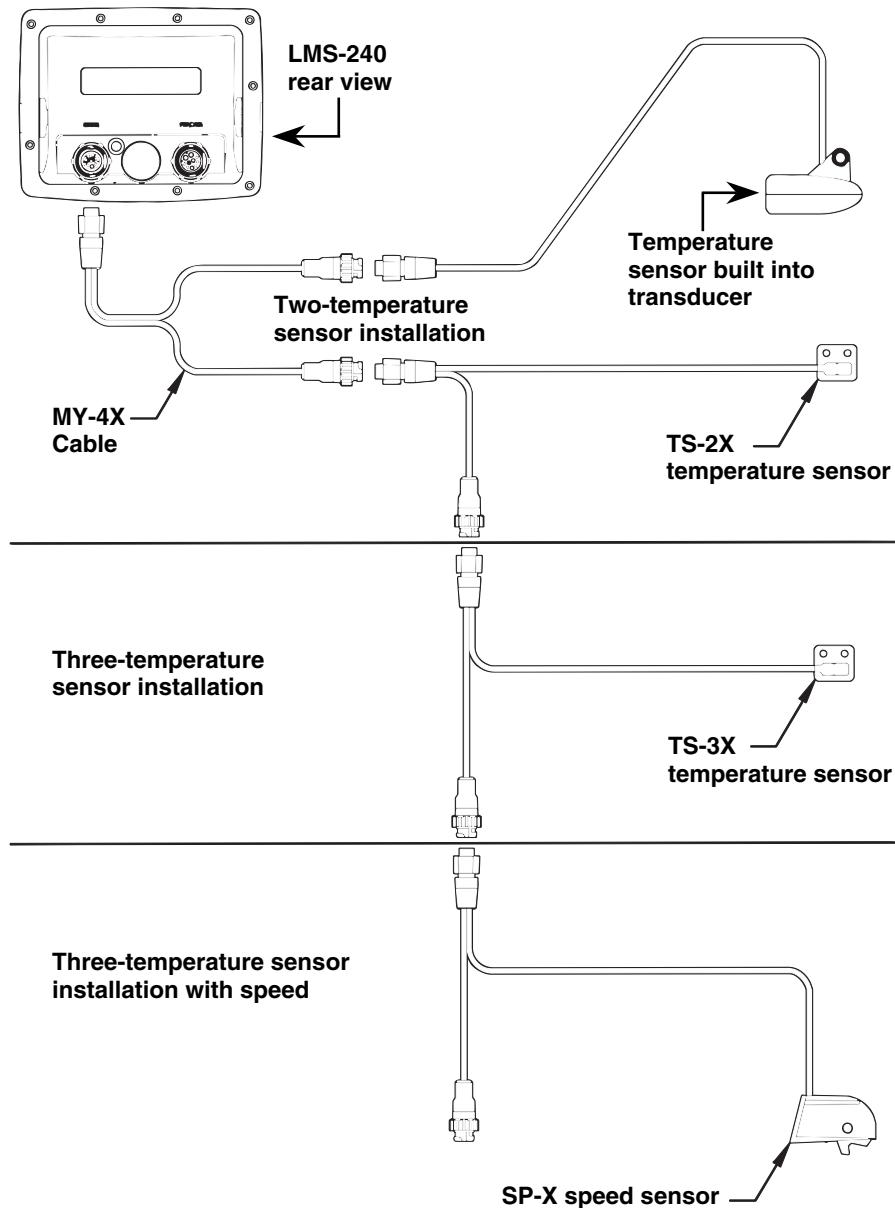
This unit accepts up to three temperature sensors which can monitor surface water, live well, air and virtually any other temperature. If you want to use more than one temperature sensor or a speed sensor, you must purchase the optional MY-4X adapter cable. You also need to be careful when purchasing the temperature sensors, because each temperature sensor has its own fixed electronic "address." The sensors are labeled "Water," "T-2" (or Temp-2) and "T-3" (or Temp-3).

The first "Water" temperature sensor is built into the transducer. This is the sensor that measures surface water temperature. If you want two (or more) temperature readings from other locations, you'll need to use the proper sensors. For example, you can't use two additional T-3 sensors. The sensors that fit this unit are:

- TS-1X This sensor will over-ride the temperature sensor built into the transducer and over-ride the temperature sensor in a ST-TGY combination sensor. (This sensor is not recommended.)
 - TS-2X One sensor for "T-2" temperature display.
 - TS-3X One sensor for "T-3" temperature display.
 - SP-X One speed sensor for "Speed" display.
 - ST-TGY This combination sensor will provide speed and temperature readings, but the temperature reading will be displayed as the "Water" temperature because it will over-ride the temperature sensor in the transducer. (This sensor is not recommended.)

See the wiring diagram on the following page for temperature and speed sensor combinations.

Sensor Chart



Optional Speed Sensor Installation

If you wish to purchase an optional speed sensor for your LMS-240, refer to the accessory ordering information inside the back cover of this manual. The following instructions describe how to install the speed sensor accessory.

Mount the speed sensor on the boat's transom in a location where the flow of water is the smoothest. There should be a minimum of turbulence and air bubbles in the chosen location. The port (left) side of the transom is preferred, however, the starboard (right) side can be used if necessary. Do not mount the speed sensor behind strakes, ribs, or thru-hull fittings. These will disturb the flow of water to the speed sensor.

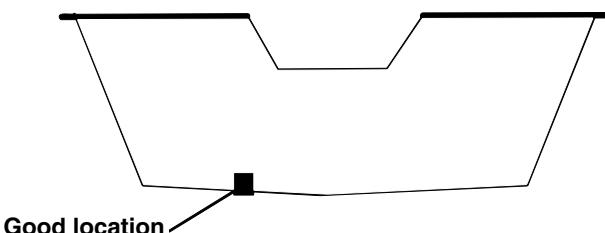
In a typical installation, the speed sensor is mounted six to twelve inches from the centerline of the hull. The sensor must always be in the water to function properly. Make certain the chosen location is in the water even at high speed or when the boat is on plane.

Once you determine the proper location, place the sensor on the transom. Make sure the sensor's bottom is flush with the bottom of the hull. Mark the transom in four places, two in each slot. Drill a mounting hole at each location using a size 27 drill bit.

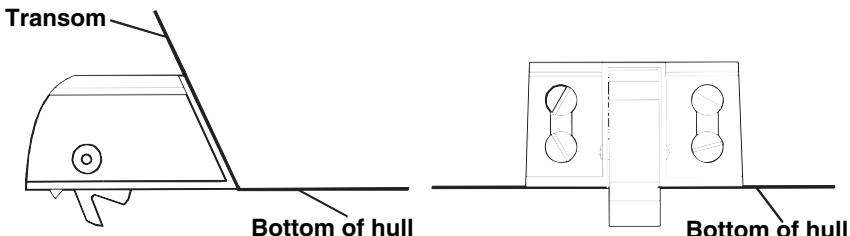
Mount the sensor to the hull with four #8 stainless steel screws. Use a good grade of caulking compound to seal the screws. Adjust the sensor so it is flush with the bottom of the hull and tighten the screws.

If the base of the transom has a radius, fill the gap between the transom and the sensor with caulking compound. This will help ensure a smooth water flow.

Route the sensor cable to the in-line connector on the MY-4X adapter cable. The speed sensor is now ready for use.



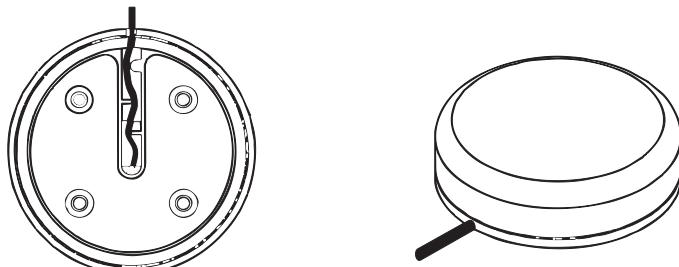
Stern view showing good location for mounting sensor on transom.



**Speed sensor mounting configuration:
side view (left) and rear view (right.)**

GPS Antenna/Receiver Module

The LMS-240 package includes the LGC-12w GPS module. This device contains the unit's external antenna and receiver for GPS and WAAS signals. The antenna/receiver module comes with a 25-foot extension cable. This module can be mounted on a flat surface or pole, or a magnet is included for temporary mounting on any ferrous surface. (The LGC-12s GPS module sold with earlier Lowrance equipment will work with your unit, but it will not receive WAAS signals.)



LGC-12 Module, bottom view (left) and top view (right).

You need to select an antenna installation location that has a clear, unobstructed view of the sky. After the module is installed, route the cable to the LMS-240, plug it in the center socket on the back and your system is ready to use. See the module's instruction sheet, publication part number 988-0147-39, for complete installation directions.

In an automobile, you may achieve good results by simply placing the external antenna on the top of the dash, at the base of the windshield. A piece of the rubber non-skid shelf liner material available in recreational vehicle supply stores will help hold the antenna in place. This may not work well if you have a cab-over design pickup truck camper or motor home. If dashboard reception is poor, simply relocate the antenna module elsewhere on the vehicle for a clearer view of the sky.

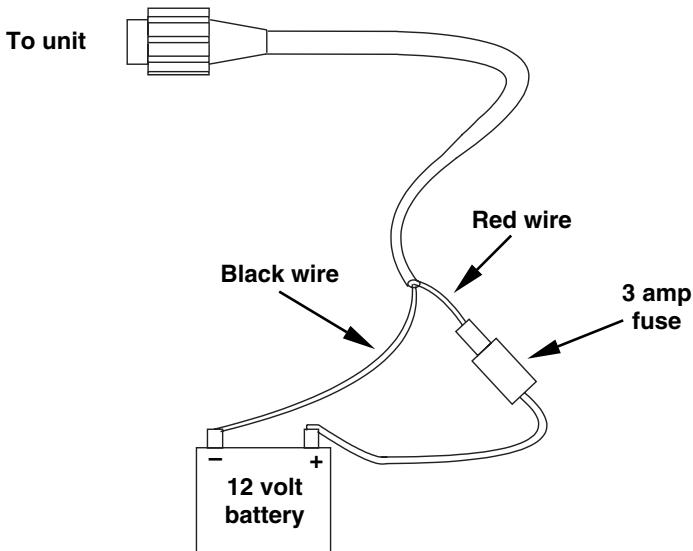
Power Connections

The unit operates from a 12-volt DC battery system. For the best results, attach the power cable directly to the battery. An optional 8-foot, CA-4 external power cable with a cigarette lighter adapter is available from Lowrance.

You can attach the power cable to an accessory or power buss, but you may have problems with electrical interference. Therefore, it's safer to go ahead and attach the power cable directly to the battery when possible.

If possible, keep the power cable away from other boat or vehicle wiring, especially the engine's wires. This will provide the best isolation from electrical noise. If the cable is not long enough, splice #18 gauge wire onto it. The power cable has two wires, red and black. Red is the positive lead, black is negative or ground. Make sure to attach the in-line fuse holder to the red lead *as close to the power source as possible*.

For example, if you have to extend the power cable to the battery or power buss, attach one end of the fuse holder directly to the battery or power buss. This will protect both the unit and the power cable in the event of a short. It uses a 3-amp fuse.



Power connections for the LMS-240 sonar/GPS unit. NOTE: for clarity, this drawing does not show the data wires, which are combined with the power cable. See them in the drawing on page 27.

CAUTION:

Do not use this product without a 3-amp fuse wired into the power cable! Failure to use a 3-amp fuse will void your warranty.

This unit has reverse polarity protection. No damage will occur if the power wires are reversed. However, the unit will not work until the wires are attached correctly.

NMEA/DGPS Cable Connections

NMEA is a standard communications format for marine electronic equipment. For example, an autopilot can connect to the NMEA interface on the LMS-240 and receive positioning information. The LMS-240 can exchange information with any device that transmits or receives NMEA 0183 data.

DGPS is an acronym for the Differential Global Positioning System. DGPS supplements and boosts the accuracy of basic GPS. DGPS was developed by the U.S. Coast Guard, which is responsible for the system's operation in the United States. Since it's creation, DGPS has become the international maritime standard for marine navigation.

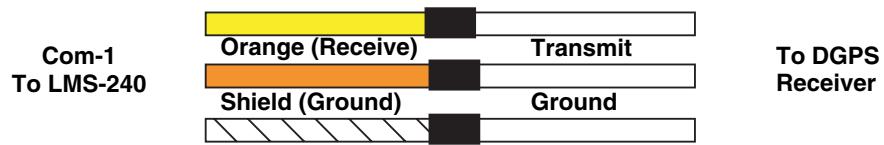
The most popular DGPS system relies on a grid of ground-based transmitters that send correction signals to DGPS receivers. These in turn, connect to the GPS receiver (such as the LMS-240). Lowrance offers an optional DGPS receiver for your unit.

See the diagrams on the following page for general wiring connections. Read your other product's owner's manual for more wiring information.

NMEA/DGPS Wiring

To exchange NMEA or DGPS data, the LMS-240 has one NMEA 0183 version 2.0 communication port. Com port one (Com-1) can be used to receive NMEA format GPS data or DGPS data. The com port can also transmit NMEA format GPS data to another device.

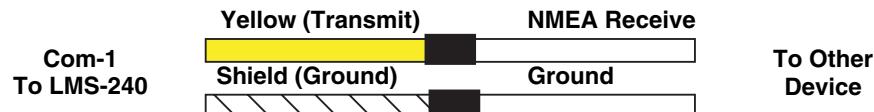
The three wires for the com port are combined with the two power wires to form the power/data cable (see the drawing on page 27). Com-1 uses the yellow wire to transmit, the orange wire to receive and the shield wire for signal ground.



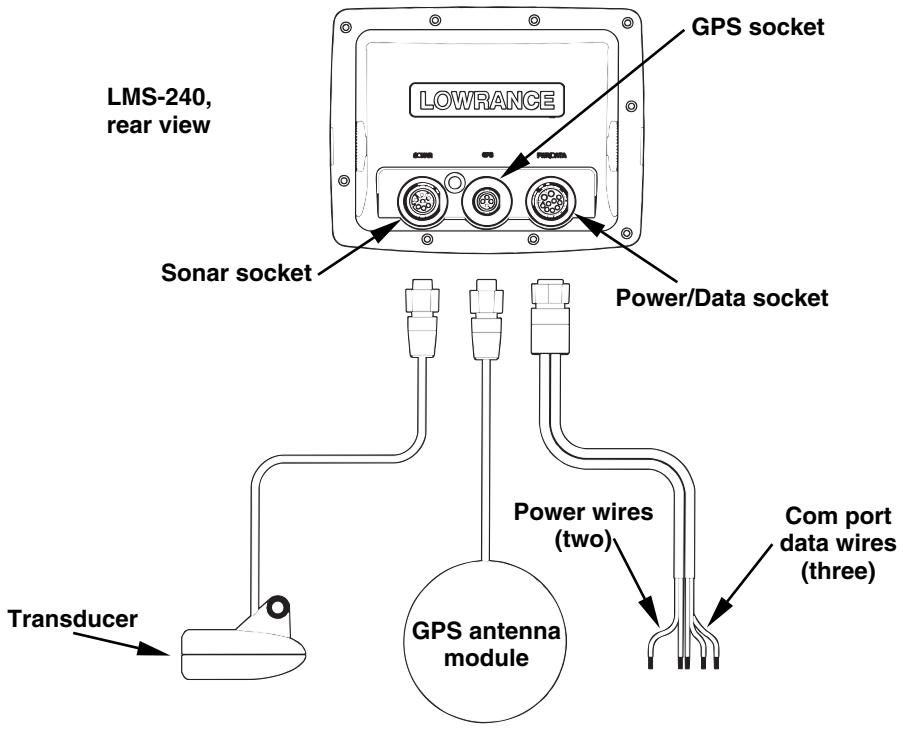
Com-1 wiring to receive DGPS position information from a DGPS receiver.



Com-1 wiring to receive NMEA position information from some other GPS receiver.



Com-1 wiring to transmit NMEA position information to another NMEA-compatible device.



LMS-240 cable connections.

Mounting the Unit: Bracket, In-Dash or Portable

You can install the LMS-240 on the top of a dash with the supplied gimbal bracket. It can also be installed in the dash or mounted on a portable power supply.

If you use the supplied bracket, you may be interested in the optional R-A-M® bracket mounting system. This converts the unit's gimbal bracket to a swivel mount, which can be used on the dash or overhead mounting positions. Installation instructions are supplied with the R-A-M mounting kits.

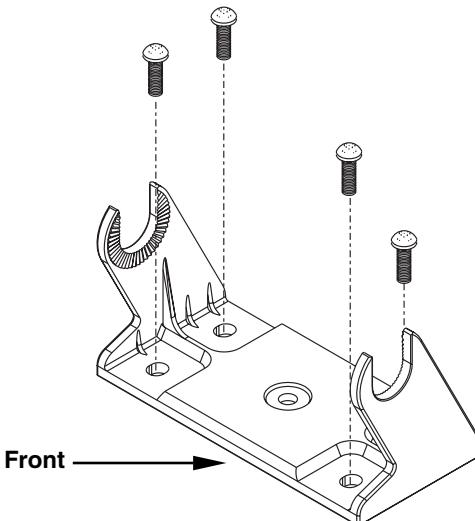


Optional R-A-M mounting system.

Bracket Installation

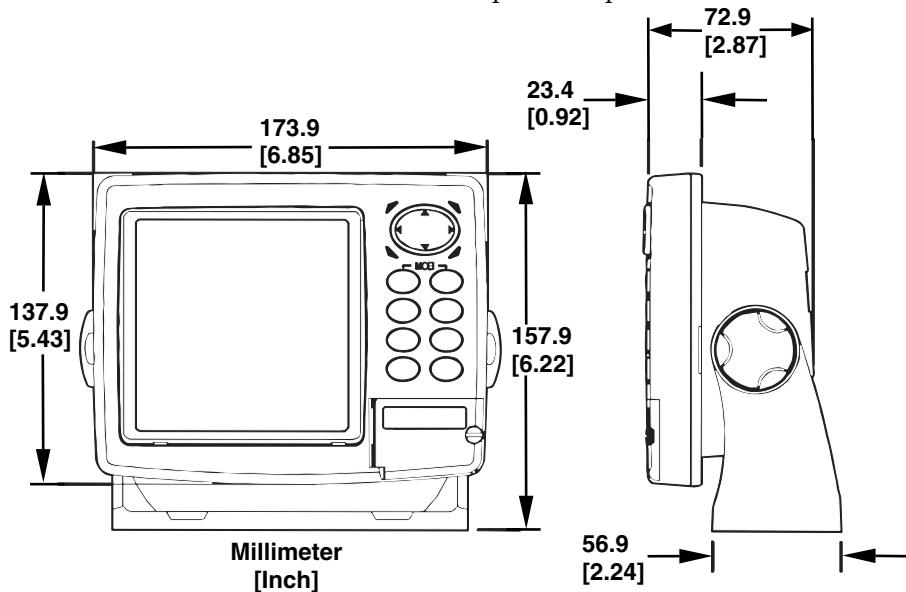
Mount the unit in any convenient location, provided there is clearance behind the unit when it's tilted for the best viewing angle. You should also make sure there is enough room behind the unit to attach the power, transducer and GPS antenna/receiver module cables. (A drawing on the next page shows the dimensions of a gimbal-mounted LMS-240 unit.)

Holes in the bracket's base allow wood screw or through-bolt mounting. You may need to place a piece of plywood on the back side of thin fiber-glass panels to reinforce the panel and secure the mounting hardware.



Install the gimbal bracket. Orient the bracket so the arms slope toward the front of your unit.

Drill a 1-inch (25.4 mm) hole in the dash for the power, transducer and antenna cables. The best location for this hole is immediately under the gimbal bracket location. This way, the bracket can be installed so that it covers the hole, holds the cables in position and results in a neat installation. Some customers, however, prefer to mount the bracket to the side of the cable hole — it's a matter of personal preference.



Front view (left) and side view (right) showing dimensions of LMS-240 sonar/GPS unit when mounted on gimbal bracket.

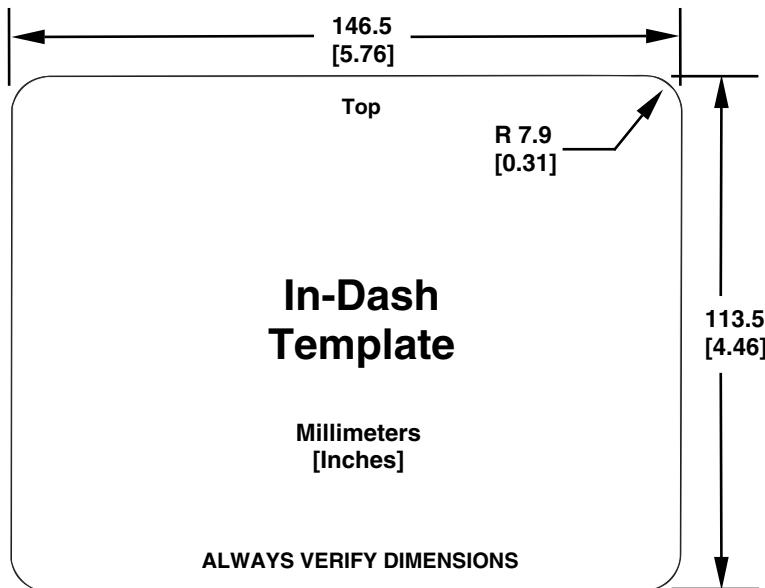
After drilling the hole, pass the transducer connector *up* through the hole from under the dash, followed by antenna connector. Pass the power cable's bare-wire end *down* through the hole from the top.

If you wish, you can fill in the hole around the cables with a good marine caulking compound. (Some marine dealers stock cable hole covers to conceal the opening.) No matter what type of installation you prefer, be sure to leave enough slack in the cables to allow tilting or swiveling the unit. If you choose to fill in the hole, be sure to position the cables against the rear edge of the hole as you apply the fill material.

Before positioning the bracket, be sure to hold the cables against the rear edge of the hole. Then, slide the bracket over the hole and butt the rear of the bracket base firmly against the cables, thus pinning them in place against the side of the hole. Finally, fasten the bracket to the dash. Attach the unit to the gimbal bracket using the supplied gimbal knobs and washers.

In-Dash Installation

You can mount the unit in the dash with an optional FM-5 In-Dash Adapter Kit. The kit includes mounting hardware, a template for cutting the hole and an instruction sheet, part 988-0147-43.

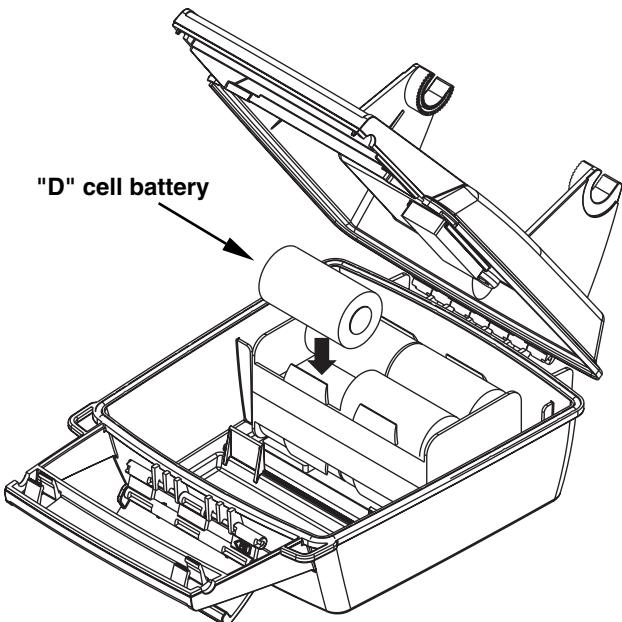


In-dash mounting template for LMS-240 sonar/GPS unit, showing dimensions. NOTE: The figure above is *not* printed to scale. A scaled template (FM-5 In-Dash Adapter Kit instructions) is available for free download from our web site, www.lowrance.com.

Portable Installation

Like many Lowrance products, the LMS-240 is capable of portable operation by using the optional PPP-11 portable power pack. The power pack, the magnet-equipped antenna module and an optional portable transducer expand the uses for your sonar/GPS unit. The PPP-11 makes it easy to transfer your unit from a boat to a car, recreational vehicle, airplane or other vehicle without drilling and mounting a second bracket. You can use your unit in your own car or boat, then take it along when riding in a friend's vehicle that's not equipped with sonar or GPS. (Or use it as a second sonar, one for each fisherman!)

The PPP-11 Portable Power Pack can be used with eight "D" cell alkaline batteries or an optional sealed, rechargeable battery. For set-up directions, refer to the pack's instruction sheet, part 988-0147-46.



Install batteries in power pack battery adapter.

MMC or SDC Memory Card Installation

Your LMS-240 uses a MultiMedia Card to store information, such as custom maps, waypoints, trails and other GPS data. The unit can also use Secure Digital Cards (SD card or SDC) to store data.

NOTE:

Throughout this manual, we will use the term MMC, but just remember that your unit can use an MMC or SDC to store data.

Both of these solid-state flash memory devices are about the size of a postage stamp. An SD card is slightly thicker than an MMC. As this manual went to press, MMCs were available in storage capacities of 8 MB, 16 MB, 32 MB and 64 MB. SD cards were available in capacities of 8 MB, 16 MB, 32 MB, 64 MB and 128 MB.

Additional MMC cards are available from LEI Extras; see ordering information inside the back cover of this manual. MMCs and SD cards are also available at many camera and consumer electronics stores.

The MMC slot is located in a compartment on the front of the case. The compartment door is located at the lower right corner. The figure on the next page shows a close-up with the door opened.



Memory card compartment with a 16 MB MMC card installed.

To remove an MMC

1. Open the card compartment door by unscrewing the thumb screw. The screw should only be finger tight. If it was over-tightened, use a thumbnail, a coin or a screwdriver to open the door.
2. Use a thumbnail or fingernail to grab the groove in the bottom of the MMC. See the figure above for the groove location.
3. Drag the MMC from the slot.

To add an MMC or SDC

1. Open the card compartment door.
2. Grasp the bottom of the MMC and push the top of the card into the slot. Once the card is started, use your fingernails to slide it the rest of the way to the left, until it is firmly seated in the slot.
3. Close the compartment door and fasten the thumb screw finger tight.

Other Accessories

Other LMS-240 accessories include MMC cards, MMC card readers and MapCreate™ 6 custom mapping software for your computer. MMC card readers are available in USB and parallel port versions.

If these accessories are not available from your dealer, see the accessory ordering information on the inside back cover of this manual.



MapCreate™ 6 CD-ROM, left; MMC card reader for USB ports, right.

Now that you have your unit installed, move on to Section 3, *Basic Sonar Operations*. There, we'll present a series of step-by-step tutorials to teach you the basics of LMS-240 sonar operation.

NOTE:

When you first turn the unit on, the Map Page appears. If you'd rather start learning about GPS operation first, turn over to Section 6, *Basic GPS Operations*. (Remember, you don't need to read this manual from cover-to-cover to get going. We designed it so you can skip around to the section *you* want to read.)

Face Cover

Your LMS-240 comes with a white protective cover that snaps on and off the front of the unit. This cover is intended for use when your unit and the vehicle it's mounted in are idle.

WARNING:

When the unit is mounted in an unprotected area, such as an open boat cockpit, the protective face cover must be removed when the vehicle is moving at high speed. This includes towing a boat on a trailer at highway speeds. Otherwise, wind blast can pop off the cover.

Notes

Section 3: Basic Sonar Operation

This section addresses the unit's *most basic* sonar operations. The instructions presented in Sec. 3 follow a chronological order. Sec. 4, *Sonar Options & Other Features*, will discuss other more advanced functions and utilities. Material in Sec. 4 is arranged in alphabetical order.

Before you turn on the LMS-240, it's a good idea to learn about the different keys, the Main Menu, the four Page screens and how they all work together. BUT, if you just can't wait to get on the water, turn to the one-page **Quick Reference** on page 43.

Keyboard



LMS-240 sonar/GPS unit, front view, showing map with sonar split screen, keyboard and access door for the MMC slot.

- 1. PWR/LIGHT** (Power & Light) – The PWR key turns the unit on and off and activates the backlight.
- 2. PAGES** – Pressing this and the $\leftarrow \rightarrow$ arrow keys switches the unit between the four different page screens. (Satellite Status Page, Navigation Page, Map Page and Sonar Page.) Each page represents one of the unit's major operation modes.

3. **MENU** – Press this key to show the menus and submenus, which allow you to select a command or adjust a feature. This also accesses search functions for streets, intersections, addresses and highway exits.

4. **ARROW KEYS** – These keys are used to navigate through the menus, make menu selections, move the map and sonar chart cursors and enter data.

5. **ENT/ICONS** (Enter & Icons) – This key allows you to save data, accept values or execute menu commands. It is also used to create event marker icons.

6. **EXIT** – The Exit key lets you return to the previous screen, clear data or erase a menu.

7. **WPT** – (Waypoint) The Waypoint key is used to save and recall waypoints, search for waypoints and access the waypoint list. It also launches the Point-of-Interest (POI) search menus and is involved in some navigation functions.

8. **ZOUT** – (Zoom Out) – This key lets you zoom the screen out. On the Sonar Page, this key returns you to a full sonar chart display, showing the entire water column from surface to bottom. On the Map Page, this lets you see a larger geographic area on the map. Less detail is seen as you zoom out.

9. **ZIN** – (Zoom In) – This key lets you zoom the screen in. On the Sonar Page, this key enlarges fish signals and bottom detail. On the Map Page, zooming in lets you see greater detail in a smaller geographic area on the map.

Power/lights on and off

To turn on the unit, press **PWR**. As the unit powers up, the Map Page is displayed first. To switch to the Sonar Page, press **PAGES** | → | **EXIT**.

To turn on the backlight, press **PWR** again. The unit has three backlight levels to select from. Repeatedly pressing **PWR** will cycle through the backlight settings and turn off the backlight.

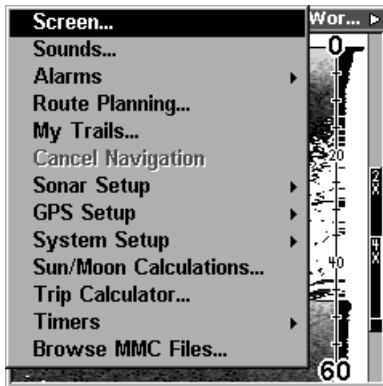
Turn off the unit by pressing and holding the **PWR** key for 3 seconds.

Main Menu

The LMS-240 has a Main Menu, which contains some function commands and some setup option commands. The instructions in this section will deal only with sonar functions, the basic commands that make LMS-240 show sonar signals on your screen. LMS-240 will work fine right out of the box with the factory default settings. But, if you want to

learn about the various sonar options, see Section 4, *Sonar Options & Other Features*. (For general system setup and GPS options, see Section 8, *System Setup and GPS Setup Options*.)

You can access the Main Menu from any of the four Page screens by pressing **MENU | MENU**. To clear the menu screen and return to the page display, press **EXIT**. (Remember, our text style for "**MENU | MENU**" means "press the Menu key twice." See a full explanation of our instruction text formatting on page 10, *Instructions = Menu Sequences*.)



Main Menu.

The Main Menu commands and their functions are:

Screen command: changes the contrast or brightness of the display screen.

Sounds command: enables or disables the sounds for key strokes and alarms and sets the alarm style.

Alarms command: turns GPS alarms on or off and changes alarm thresholds.

Route Planning command: used to plan, view or navigate a route.

My Trails command: shows, creates and deletes plot trails. Also used to navigate or backtrack a trail.

Cancel Navigation command: turns off the various navigation commands. Used to stop navigating after you have reached your destination waypoint, Point of Interest or map cursor location; or after you reach the end of a route or trail.

Sonar Setup command: sets various sonar options.

GPS Setup command: sets various GPS receiver options.

System Setup command: sets general configuration options.

Sun/Moon Calculations command: finds the rising and setting time of the sun and the moon.

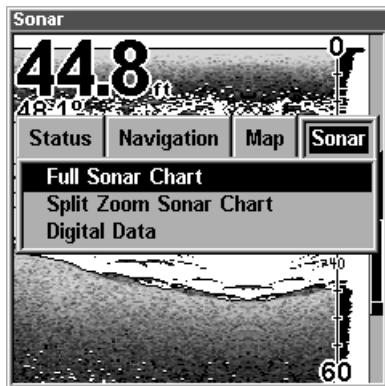
Trip Calculator command: shows trip status and statistics.

Timers command: controls the up timer, down timer and alarm clock settings.

Browse MMC Files command: this allows you to view the installed MMC card and the files it contains.

Pages

The unit has four Page displays that represent the four major operating modes. They are the Satellite Status Page, the Navigation Page, the Map Page and Sonar Page. They are accessed by pressing the **PAGES** key, then using → or ← to select a Page. (Clear the Pages Menu by pressing **EXIT**.)



Pages Menu, showing some Sonar display options.

Satellite Status Page

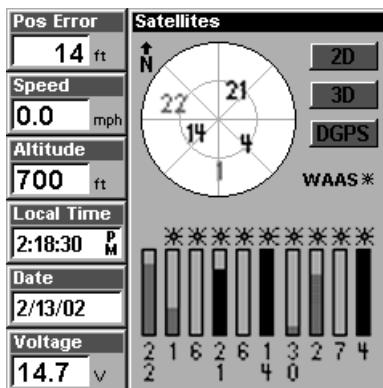
The Satellite Status Page provides detailed information on the status of LMS-240's satellite lock-on and position acquisition. To get to the Satellite Status Page: Press the **PAGES** key, then use → or ← to select **STATUS**. (Clear the Pages Menu by pressing **EXIT**.)

This page represents a GPS function, so it is discussed in much greater detail in Section 6.

No matter what Page you are on, a flashing current position indicator/question mark symbol and flashing GPS data displays indicate that satellite lock has been lost and there is no position confirmed.

WARNING:

Do not begin navigating with this unit until the numbers have stopped flashing!

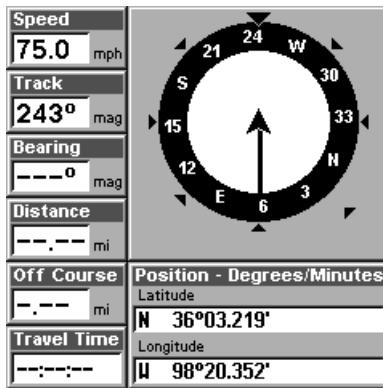


Satellite Status Page showing satellite-lock on with a 3D position acquired (latitude, longitude and altitude.)

Navigation Page

This screen has a compass rose that not only shows your direction of travel, but also the direction to a recalled waypoint. To get to the Navigation Page: Press **PAGES** | → or ← to **NAVIGATION** | **EXIT**.

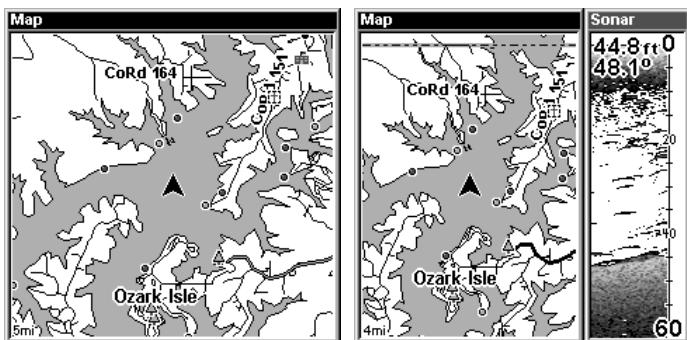
This page represents a GPS function, so it is discussed in much greater detail in Section 6.



Navigation Page, recording a trail, traveling southwest.

Map Page

The Map Page screens show your course and track from a "bird's-eye" view, on a moving map. By default, this unit shows the map with north always at the top of the screen. The arrow in the center of the screen is your present position. It points in the direction you're traveling.



Map Page, showing position on Bull Shoals Lake, Arkansas. At left is the full map option. At right, map with sonar option.

Map Page is also the default screen that appears when you turn on the unit. To get to the Map Page from another page: Press **PAGES** | → or ← to **MAP** | **EXIT**.

You can display a split screen showing both the Map and Sonar pages at the same time. This feature is discussed in Section 4, *Sonar Options & Other Features*.

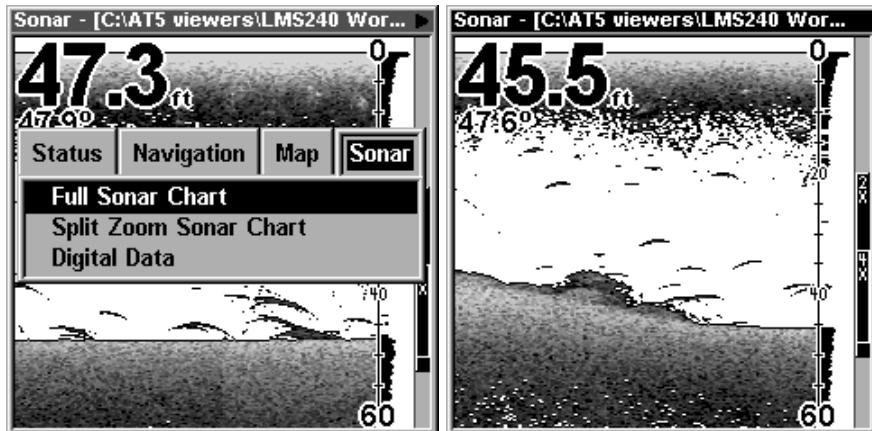
The Map Page represents a GPS function, so it is discussed in much greater detail in Section 6.

Sonar Page

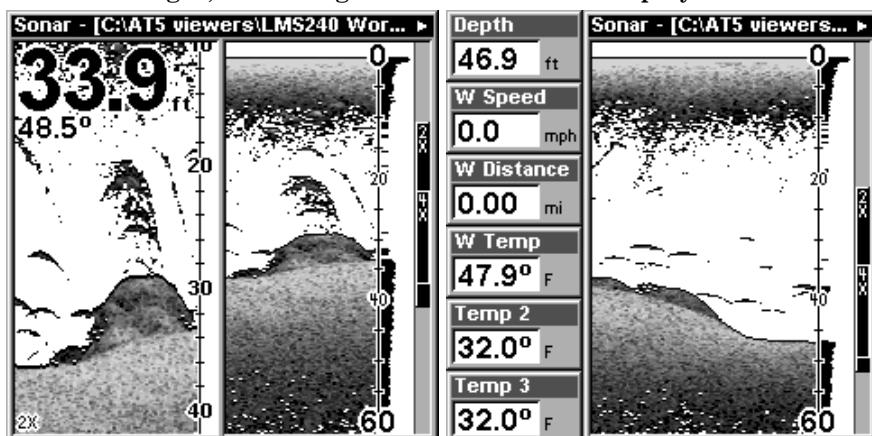
The Sonar Page displays the sonar chart. This is a "cross-section" view of the water column beneath the boat. The chart moves across the screen, displaying sonar signal echoes that represent fish, structure and the bottom.

To get to the Sonar Page: Press the **PAGES** key, then use → or ← to select **SONAR**. (Clear the Pages Menu by pressing **EXIT**.) The Pages Menu also offers three chart display options under the Sonar Page category. To access them, press **PAGES** | ← or → to **SONAR** | ↓ to *Option Name* | **EXIT**.

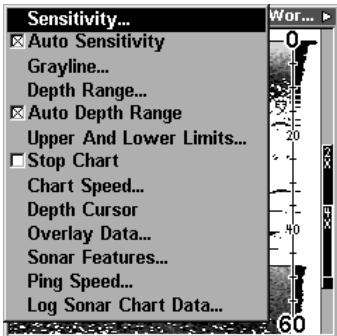
The Sonar Page also has its own menu, which is used for some advance functions and for setting various options. (Sonar Options and other features are discussed in Section 4.) To Access the Sonar Page menu, from the Sonar Page press **MENU**.



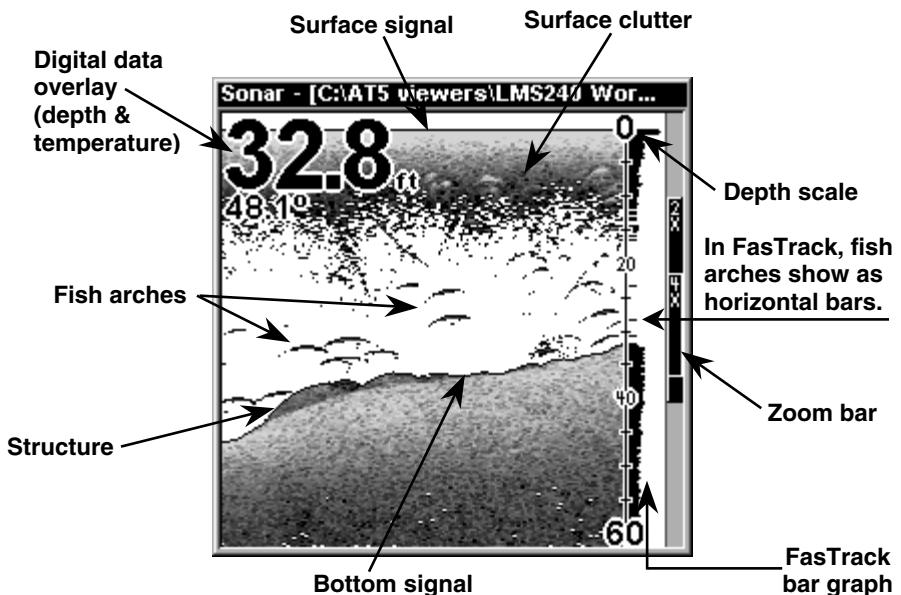
At left, Pages Menu, showing sonar chart display option commands.
At right, Sonar Page in full sonar chart display mode.



Other sonar chart display options include,
from left: split zoom sonar chart and digital data.



Sonar Page Menu. Most of these functions are discussed in Sec. 4.



Sonar Page, showing full sonar chart mode.

You can customize how the Sonar Page displays its pictures and other data in many ways. Your unit also includes several special sonar features and options that can help you better interpret the underwater scene.

We'll discuss all of those features and options in Section 4, but to show you how easy the LMS-240 is to operate, the following page contains a simplified, 10-step quick reference that will cover most fish finding situations. The quick reference describes how your unit will operate with all the sonar features in their automatic modes, which are set at the factory.

LMS-240™ Sonar Quick Reference

1. Mount the transducer, antenna and unit. Connect the unit to electric power and the transducer. (If GPS operation is desired, connect GPS antenna, too.) Make sure the MMC is in. (See complete installation details beginning on page 11.)
2. Launch your boat.
3. To turn on LMS-240, press and release **PWR** key.
4. Opening screen displays Map Page. Rotate through the four main Page screens (Map Page, Satellite Status Page, Navigation Page, Sonar Page) by pressing **PAGES** | \leftarrow or \rightarrow to select *Page Name* | **EXIT**. Switch Pages to display Sonar Page.
5. If GPS data is desired, wait while unit locates satellites and calculates current position. When the unit acquires position, a tone sounds and a position acquired message appears.
6. With position acquired (if desired), head for your fishing grounds. Your unit will automatically display digital depth and surface water temperature in the top left corner of the screen.

The auto settings will track the bottom, displaying it in the lower portion of the screen. The full sonar chart will scroll from right to left, showing you what's under the boat as you cruise across the water. You can change the display by:

Zoom in to enlarge the chart for more detail: press **ZIN**.
Zoom out to return to full chart mode: press **ZOUT**.

7. Watch the display for the appearance of fish arches. When you see arches, you've found fish! Stop the boat and get your lure or bait into the water at the depth indicated on the sonar chart.
8. Gauge the fish depth by visually comparing the fish arches with the depth scale on the right side of the screen, or get a more accurate measure with the Depth Cursor. Press **MENU** | \downarrow to **DEPTH CURSOR** | **ENT**. Press \downarrow to align the cursor line with the fish arch. The exact depth appears in a box at the right end of the cursor line. To clear the cursor, press **EXIT**.
9. If you are drifting at a very low speed or anchored, you are not moving fast enough for a fish to return the tell-tale fish arch signal. As you drift over a fish, or as a fish swims through the transducer's signal cone, the fish echo will appear as a straight line suspended between the surface and the bottom.
10. To turn off LMS-240, press and hold **PWR** key for three seconds.

Sonar Operations

As you can see from the quick reference on the previous page, basic operation is pretty easy, right out of the box. If you are a sonar novice, try operating the unit with the factory defaults until you get a feel for how it's working.

As you're learning the basics, there is one setting you might want to tinker with from time to time — Sensitivity.

Sensitivity controls the unit's ability to pick up echoes. If you want to see more detail, try increasing the sensitivity, a little at a time. There are situations when too much clutter appears on the screen. Decreasing the sensitivity can reduce the clutter and show the strongest fish echoes, if fish are present. As you change the sensitivity setting, you can see the difference on the chart as it scrolls.

Fig. 1

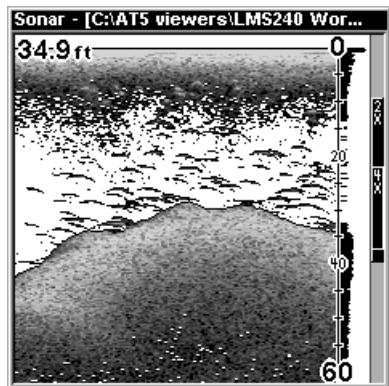


Fig. 2

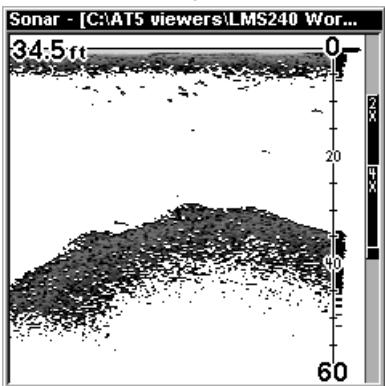


Fig. 3

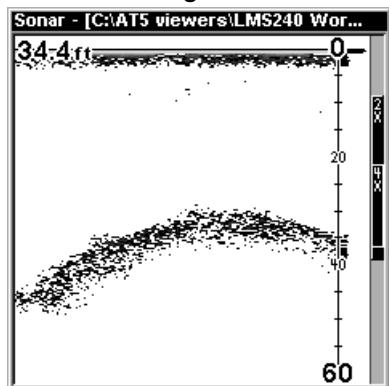
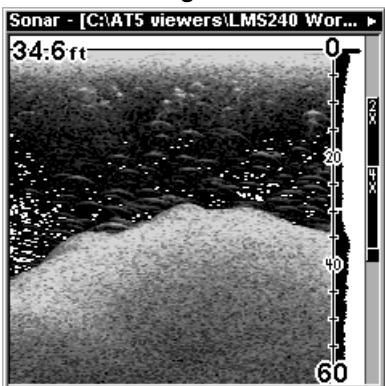


Fig. 4



These figures show results of different sensitivity levels on the same location. Fig. 1: Sensitivity at 98 percent, determined by Auto Sensitivity. Typical of full auto mode. Fig. 2: Sensitivity set at 70 percent. Fig. 3: Sensitivity set at 50 percent. Fig. 4: Sensitivity set at 100 percent.

You can change the sensitivity level whether you are in Auto Sensitivity mode or Manual Sensitivity mode. The adjustment method works the same in both modes, but it gives you slightly different results.

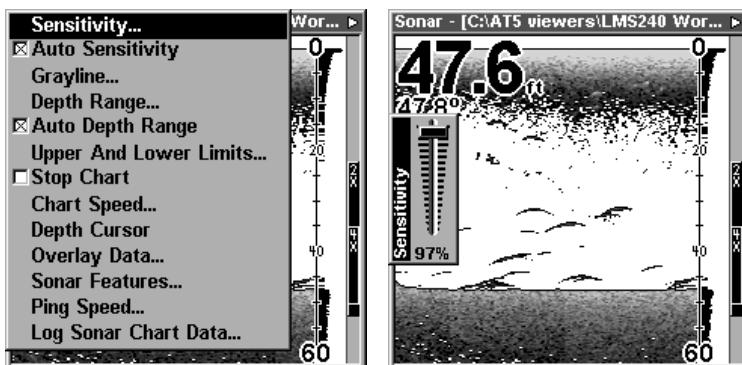
Adjusting sensitivity in Auto Sensitivity Mode is similar to manually adjusting a car's speed with the accelerator pedal while cruise control is on. You can tell the car to run faster, but when you let off the gas the cruise control *automatically* keeps you from running slower than the minimum speed setting. In the LMS-240, auto mode will let you increase sensitivity to 100 percent, but the unit will *limit* your *minimum* setting. This prevents you from turning sensitivity down too low to allow automatic bottom tracking. When you change the setting with auto turned on, the unit will continue to track the bottom and make minor adjustments to the sensitivity level, with a bias toward the setting you selected.

Adjusting sensitivity in Manual Sensitivity Mode is similar to driving a car without cruise control — you have *complete* manual control of the car's speed. In the LMS-240, manual mode allows you to set sensitivity at 100 percent (maximum) or zero percent (minimum.) Depending on water conditions, the bottom signal may completely disappear from the screen when you reduce sensitivity to about 50 percent or less!

Try adjusting sensitivity in both auto and manual modes to see how they work.

To adjust sensitivity:

1. Press **MENU | ENT**.
2. The Sensitivity Control Bar appears. Press \downarrow to decrease sensitivity; press \uparrow to increase sensitivity. When it's set at the desired level, press **EXIT**. (When you reach the maximum or minimum limit, a tone sounds.)



At left, Sonar Menu with Sensitivity command selected. At right, the Sensitivity Control Bar.

NOTE:

If you want to change the sensitivity in Manual Mode, first turn off Auto Sensitivity: from the Sonar Page, press **MENU** | **↓** to **AUTO SENSITIVITY** | **ENT** | **↑** to **SENSITIVITY** | **ENT**. Press **↓** or **↑** to pick a different sensitivity setting. When it's set at the desired level, press **EXIT**.

Important Tip:

While you are experimenting and learning, it's possible to scramble the settings so that the sonar picture disappears from your screen. If that happens, remember that it's easy to switch back to full automatic operation by simply restoring the factory auto settings. Here's how:

To Restore Factory Settings

1. Press **MENU** | **MENU** | **↓** to **SYSTEM SETUP** | **ENT** | **↓** to **RESET OPTIONS** | **ENT**.
2. The unit asks if you want to reset all the options. Press **←** to **YES** | **ENT**. All options are reset, and the unit reverts back to the Map Page at the 4000 mile zoom range. (Any recorded sonar logs or GPS data will be unchanged.)

Fish Symbols vs. Full Sonar Chart

You may have noticed in the quick reference that we used fish arches in full sonar chart mode for our example, and not the popular Fish I.D.™ fish symbol feature. Here's why.

Fish I.D. is an easier way for a sonar novice to recognize a fishy signal return when he sees it. However, locating fish by symbol *only* has some limitations.

Your sonar unit's microprocessor is remarkably powerful, but it can be fooled. Some of the echoes *calculated* to be fish could be tree limbs or turtles! *To see what's under your boat in maximum detail, we recommend you turn off Fish I.D. and begin learning to interpret fish arches.*

Fish I.D. is most handy when you're in another part of the boat or performing some task that prevents you from watching the sonar screen. Then, you can turn on Fish I.D. and the audible fish alarm. When that lunker swims under your boat, you'll hear it!

Fish I.D. can also be useful when you want to screen out some of the sonar detail gathered by your unit. For example, in one case fisherman in San Francisco Bay saw clouds of clutter in the water but no fish arches. When a down rigger was pulled up, it brought up several small jellyfish. The fisherman switched their Lowrance sonar to Fish I.D.,

which screened out the schools of jellyfish and clearly showed the game fish there as fish symbols.

Other Free Training Aids

The sonar options section discusses Fish I.D., fish alarms and other features in greater detail. If you or a friend has Internet access, you can also learn more about interpreting what you see on your sonar screen. Visit our web site, **WWW.LOWRANCE.COM**. Be sure to check out the free Sonar Tutorial, which includes animated illustrations and more pictures of actual sonar returns, all described in detail. There's even a "printer friendly" version of the tutorial available on our web site...it makes a great supplement to this operation manual!

You can also download a free copy of our sonar viewer software. This PC-based software application plays back any sonar file recorded with an LMS-240, LCX-15 or LCX-16 product. Features include:

- Adjustable range, zoom, sensitivity, color line, noise rejection, surface clarity, etc. of the recorded file.
- Color interpretation of sonar signals can be user defined.
- Operates like a Windows Multimedia Player with forward, reverse, pause, fast forward, fast reverse, and scroll buttons.
- Adjustments update the entire record displayed
- Can print in full color.
- Window can dynamically be sized on your monitor.
- Mouse cursor shows GPS position, depth and sounding number anywhere on the visible record.

Notes

Section 4: Sonar Options & Other Features

Material in this section is arranged in alphabetical order.

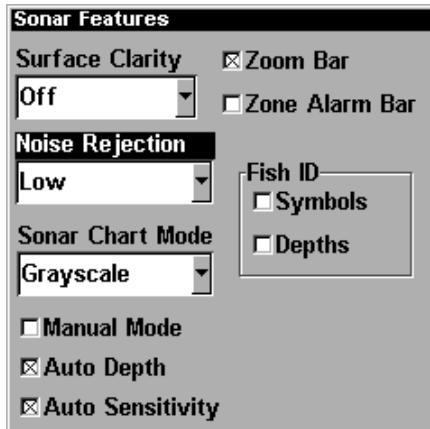
ASP™ (Advanced Signal Processing)

The ASP™ feature is a noise rejection system built into the sonar unit that constantly evaluates the effects of boat speed, water conditions and interference. This automatic feature gives you the best display possible under most conditions.

The ASP feature is an effective tool in combating noise. In sonar terms, noise is any undesired signal. It is caused by electrical and mechanical sources such as bilge pumps, engine ignition systems and wiring, air bubbles passing over the face of the transducer, even vibration from the engine. In all cases, noise can produce unwanted marks on the display.

The ASP feature has four settings — Off, Low, Medium and High. If you have high noise levels, try using the "High" ASP setting. However, if you are having trouble with noise, we suggest that you take steps to find the interference source and fix it, rather than continually using the unit with the high ASP setting.

There are times when you may want to turn the ASP feature off. This allows you to view all incoming echoes before they are processed by the ASP feature.



Change Advanced Signal Processing with the Noise Rejection command on the Sonar Features menu. In this example, ASP is in the default Low setting.

To change the ASP level:

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.

2. Press ↓ to **NOISE REJECTION | ENT**.
3. Press ↓ or ↑ to select a setting, then press **ENT**.
4. To return to the previous page, press **EXIT | EXIT**.

Alarms

This unit has three different types of sonar alarms. The first is the Fish Alarm. It sounds when the Fish I.D.TM feature determines that an echo or group of echoes is a fish.

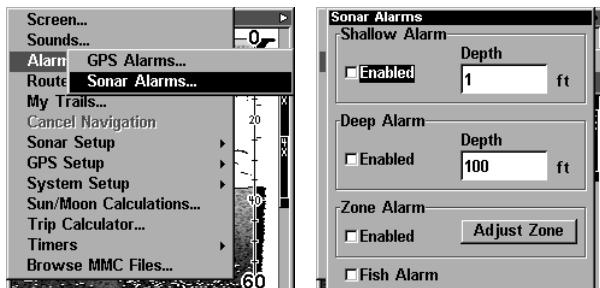
Another alarm is the Zone Alarm, which consists of a bar on the side of the screen. Any echo on the chart that appears inside this bar triggers this alarm.

The last alarm is the Depth Alarm, which has both a Shallow and a Deep setting. Only the bottom signal will trigger this alarm. This is useful as an anchor watch, a shallow water alert, or for navigation.

Depth Alarms

The depth alarms sound a tone when the bottom signal goes shallower than the shallow alarm's setting or deeper than the deep alarm's setting. For example, if you set the shallow alarm to 10 feet, the alarm will sound a tone if the bottom signal is less than 10 feet. It will continue to sound until the bottom goes deeper than 10 feet.

The deep alarm works just the opposite. It sounds a warning tone if the bottom depth goes deeper than the alarm's setting. Both depth alarms work only off the digital bottom depth signals. No other targets will trip these alarms. These alarms can be used at the same time or individually.



At left, Main Menu and Sonar Alarms command.

At right, the Sonar Alarms menu.

To adjust and turn on the shallow alarm:

1. Press **MENU | MENU | ↓ to ALARMS | ENT | ↓ to SONAR ALARMS | ENT**.
2. Press → to **SHALLOW ALARM DEPTH | ENT**.

3. Press ↑ or ↓ to change the first number, then press → to move the cursor to the next number and repeat until the depth is correct, then press ENT.

4. Press ← to SHALLOW ALARM ENABLED | ENT | EXIT | EXIT | EXIT.

5. To turn off the alarm, press MENU | MENU | ↓ to ALARMS | ENT | ↓ to SONAR ALARMS | ENT | ENT | EXIT | EXIT.

To switch to a different depth setting, open the Sonar Alarms menu and repeat the instructions in step 3 above.

To adjust and turn on the deep alarm:

1. Press MENU | MENU | ↓ to ALARMS | ENT | ↓ to SONAR ALARMS | ENT.

2. Press ↓ to DEEP ALARM ENABLED | → to DEEP ALARM DEPTH | ENT.

3. Press ↑ or ↓ to change the first number, then press → to move the cursor to the next number and repeat until the depth is correct, then press ENT.

4. Press ← to DEEP ALARM ENABLED | ENT | EXIT | EXIT | EXIT.

5. To turn off the alarm, press MENU | MENU | ↓ to ALARMS | ENT | ↓ to SONAR ALARMS | ENT | ↓ to DEEP ALARM ENABLED | ENT | EXIT | EXIT | EXIT.

To switch to a different depth setting, open the Sonar Alarms menu and repeat the instructions in step 3 above.

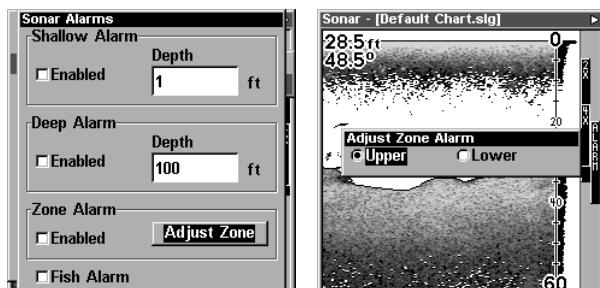
Zone Alarm

The zone alarm is triggered when any echo passes inside the zone alarm bar, shown on the right side of the screen.

To adjust and turn on the zone alarm:

1. Press MENU | MENU | ↓ to ALARMS | ENT | ↓ to SONAR ALARMS | ENT.

2. Press ↓ to ZONE ALARM ENABLED | → to ADJUST ZONE | ENT.



At left, Sonar Alarms menu, with Adjust Zone command selected.

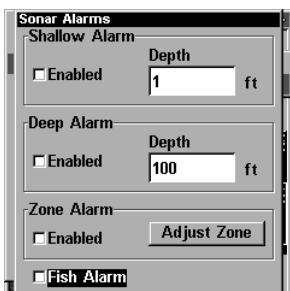
At right, Adjust Zone Alarm selection box, with Upper selected.

3. To set the upper boundary for the Zone Alarm, use **←** or **→** to select **UPPER**, then press **↑** or **↓** to move the top of the bar to the desired depth.
4. To set the lower boundary for the Zone Alarm, use **←** or **→** to select **LOWER**, then press **↑** or **↓** to move the bottom of the bar to the desired depth.
5. Press **EXIT** | **←** to **ZONE ALARM ENABLED** | **ENT** | **EXIT** | **EXIT** | **EXIT**. Now, any echo — fish, bottom, structure — within the zone alarm's depth range will trigger the zone alarm.
6. To turn off the alarm, press **MENU** | **MENU** | **↓** to **ALARMS** | **ENT** | **↓** to **SONAR ALARMS** | **ENT** | **↓** to **ZONE ALARM ENABLED** | **ENT** | **EXIT** | **EXIT** | **EXIT**.

To switch to a different depth setting, open the Sonar Alarms menu and repeat the instructions in steps 3 and 4 above.

Fish Alarm

Use the fish alarm for a distinctive audible alarm when fish or other suspended objects are detected by the Fish I.D.™ feature (Fish I.D. must be turned on for the Fish Alarm to work). A different tone sounds for each fish symbol size shown on the display.



Sonar Alarms menu with Fish Alarm selected. The check box to the left is blank, indicating the alarm is turned off.

To turn the fish alarm on:

1. Press **MENU** | **MENU** | **↓** to **ALARMS** | **ENT** | **↓** to **SONAR ALARMS** | **ENT**.
2. Press **↓** to **FISH ALARM** | **ENT** | **EXIT** | **EXIT**.
3. To turn off the alarm, press **MENU** | **MENU** | **↓** to **ALARMS** | **ENT** | **↓** to **SONAR ALARMS** | **ENT** | **↓** to **FISH ALARM** | **ENT** | **EXIT** | **EXIT**.

Calibrate Speed

The speed sensor can be calibrated to compensate for inaccuracies. Before you change the setting, first calculate the percentage that the speed is off. You will enter this percentage in a moment.

For example, if you figure the sensor is reading 10 percent faster than actual speed, you will enter -10 in the calibration window. If the sensor is reading 5 percent slower than true speed, you will enter $+5$ in the window.

A good way to gauge your speed sensor's performance is to compare its reading with the ground speed measured by your unit's GPS functions. When you make a run to compare GPS ground speed to speed sensor speed, perform your test in relatively calm water free of current, if possible. (Unless, of course, you are taking the current speed into consideration when making your calculation.) After you have a correction figure, here's how to enter it:

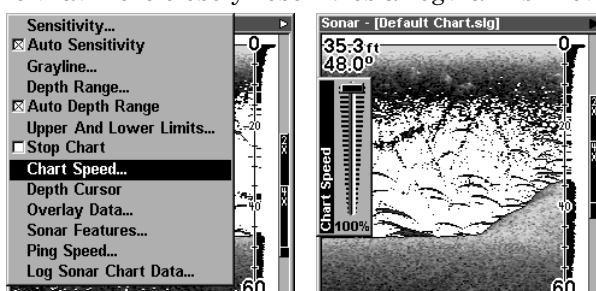
1. Press **MENU | MENU | ↓** to **SONAR SETUP | ENT | ↓** to **CALIBRATE WATER SPEED | ENT**.
2. Enter the number you calculated earlier: press \uparrow or \downarrow to change the first character (+ or -), then press \rightarrow to move the cursor to the next number and repeat until the percentage is correct, then press **EXIT**.

Chart Speed

The rate that echoes scroll across the screen is called the chart speed. The default is maximum; we recommend that you leave the speed set there for virtually all fishing conditions.

However, you might consider experimenting with chart speed when you are stationary or drifting very slowly. You may sometimes achieve better images as you slow down the chart speed to match how fast you are moving across the bottom.

If you are at anchor, ice fishing or fishing from a dock, experiment with a chart speed around 50 percent. If you are drifting slowly, try a chart speed around 75 percent. When you are stationary and a fish swims through the sonar signal cone, the image appears on the screen as a long line instead of a fish arch. Reducing the chart speed may result in a shorter line that more closely resembles a regular fish return.



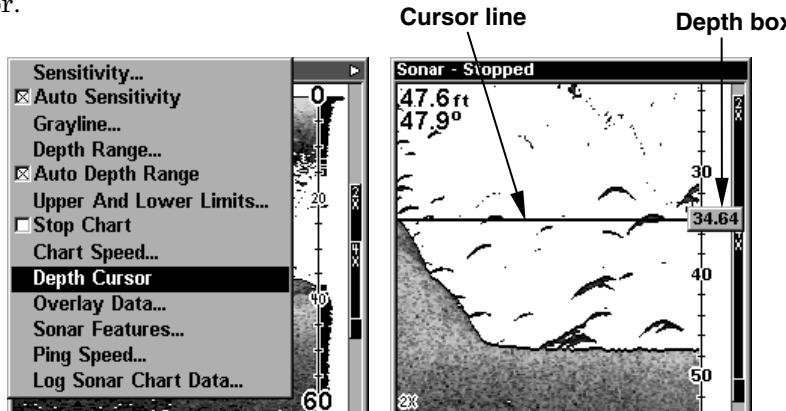
At left, Sonar Page menu with Chart Speed command selected.
At right, Chart Speed Control Bar.

If you do experiment with chart speed, remember to reset it to maximum when you resume trolling or moving across the water at higher speed. To change chart speed:

1. From the Sonar Page, press **MENU** | **↓** to **CHART SPEED** | **ENT**.
2. The Chart Speed Control Bar appears. Press **↓** to decrease chart speed; press **↑** to increase chart speed.
3. When it's set at the desired level, press **EXIT**.

Depth Cursor

The depth cursor consists of a horizontal line with a digital depth box on the right side. The numbers inside the box show the depth of the cursor.



At left, Sonar Page menu with Depth Cursor command selected. At right, sonar chart with the depth cursor active. The line indicates the large fish is 34.64 feet deep.

The cursor can be moved to any location on the screen, letting you pinpoint the depth of a target.

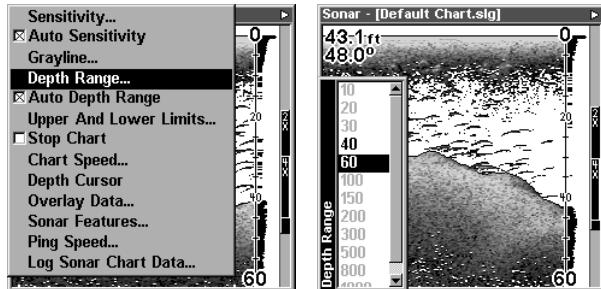
1. From the Sonar Page, press **MENU** | **↓** to **DEPTH CURSOR** | **ENT**.
2. The depth cursor appears. Press **↓** to lower the cursor line; press **↑** to raise the cursor line.
3. To clear the depth cursor, press **EXIT**.

Depth Range - Automatic

When turned on for the first time, the bottom signal is automatically placed in the lower half of the screen. This is called Auto Ranging and is part of the automatic function. However, depending upon the bottom

depth and the current range, you can change the range to a different depth. To do this:

1. From the Sonar Page, press **MENU** | **↓** to **DEPTH RANGE** | **ENT**.



At left, Sonar Page menu with Depth Range command selected. At right, the Depth Range Control Scale.

2. The Depth Range Control Scale appears. Press **↑** or **↓** to select a different depth range. A black bar highlights the selected range. Range numbers in gray cannot be selected.

3. When the new range is selected, press **EXIT** to clear the menu.

Depth Range - Manual

You have complete control over the range when the unit is in the manual mode. The available ranges are 0-10, 20, 30, 40, 60, 100, 150, 200, 300, 500, 800 and 1000 feet.

To switch to Manual Depth Range:

1. First, turn off automatic depth range. From the Sonar Page, press **MENU** | **↓** to **AUTO DEPTH RANGE** | **ENT**.
2. Press **↑** to **DEPTH RANGE** | **ENT** and the Depth Range Control Scale appears.
3. Press **↓** or **↑** to select a different depth range. A horizontal black bar highlights the selected range.
4. When the new range is selected, press **EXIT** to clear the menu.

To turn Auto Depth Range on again:

1. From the Sonar Page, press **MENU** | **↓** to **AUTO DEPTH RANGE** | **ENT** | **EXIT**.

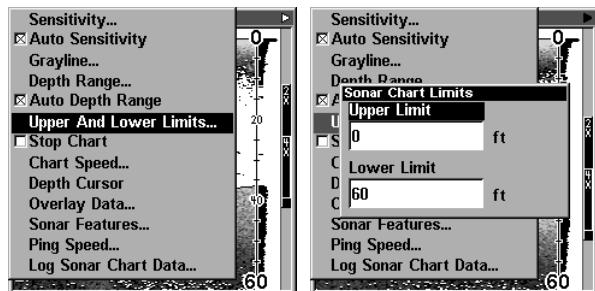
NOTE:

The sonar's depth capability depends on the transducer installation, water and bottom conditions, and other factors.

Depth Range - Upper and Lower Limits

Virtually any segment of the water column can be displayed by using the upper and lower limit feature. This lets you pick the shallow and deep depth range limits that are shown on the screen, provided there is at least 10 feet between the upper and lower limit you select. For example, a range from 12 feet to 34 feet could be used.

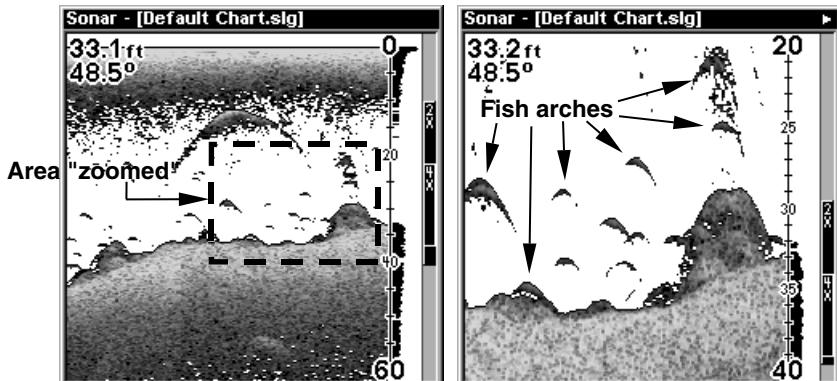
Changing the upper and lower limits gives you far greater control over the depth range. This feature lets you "zoom in" the display in almost unlimited combinations. Nearly any segment of the water column, from the surface to the bottom can be shown. This enlarges the sonar targets to best suit your fishing needs and water conditions.



At left, Sonar Page Menu with Upper and Lower Limits command selected. At right, Sonar Chart Limits menu, with Upper Limit selected.

To change the upper and lower limits:

1. From the Sonar Page, press **MENU** | **↓** to **UPPER AND LOWER LIMITS** | **ENT**. The Sonar Chart Limits menu appears, with Upper Limit selected.
2. To set the upper limit, press **ENT**. Press **↑** or **↓** to change the first number, then press **→** to move the cursor to the next number and repeat until the depth is correct, then press **EXIT**.
3. To set the lower limit, press **↓** to **LOWER LIMIT** | **ENT**. Press **↑** or **↓** to change the first number, then press **→** to move the cursor to the next number and repeat until the depth is correct, then press **EXIT** | **EXIT** | **EXIT**.



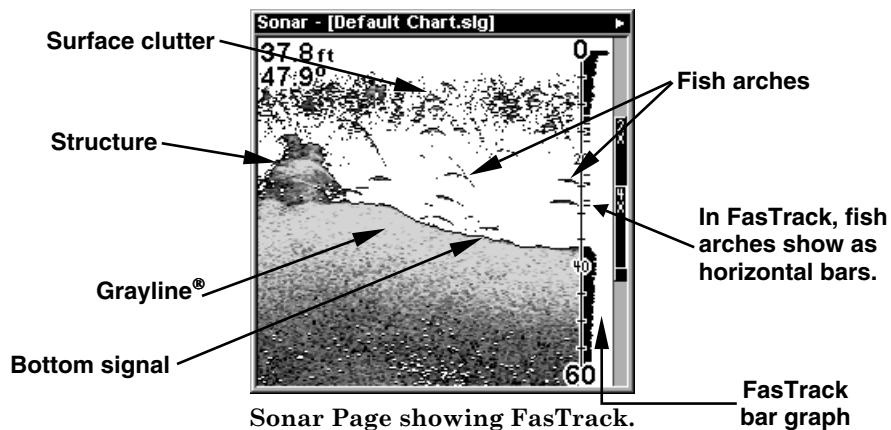
Normal display, in auto depth range mode, left. At right, display "zoomed" with Upper and Lower Limits focusing on the portion of the water column from 20 feet to 40 feet deep. In the "zoomed" image, note the target definition at lower left, showing a fish holding just above the structure. At top right, two game fish are attacking a school of bait fish.

To turn off upper and lower limits:

1. From the Sonar Page, press **MENU** | **↓** to **AUTO DEPTH RANGE** | **ENT** | **EXIT**.

FasTrack™

This feature automatically converts all echoes to short horizontal lines on the display's far right side. The graph on the rest of the screen continues to operate normally. FasTrack gives you a rapid update of conditions directly under the boat. This makes it useful for ice fishing, or when you're fishing at anchor. When the boat is not moving, fish signals are long, drawn out lines on a normal chart display. FasTrack converts the graph to a vertical bar graph that, with practice, makes a useful addition to fishing at a stationary location.



Fish I.D.TM (Fish Symbols & Depths)

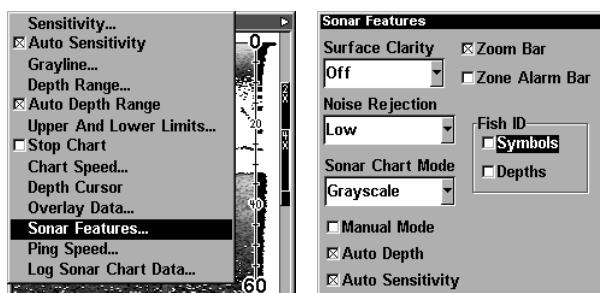
The Fish I.D. feature identifies targets that meet certain conditions as fish. The microcomputer analyses all echoes and eliminates surface clutter, thermoclines, and other signals that are undesirable. In most instances, remaining targets are fish. The Fish I.D. feature displays fish symbols on the screen in place of the actual fish echoes.

There are several fish symbol sizes. These are used to designate the relative size between targets. In other words, Fish I.D. displays a small fish symbol when it thinks a target is a small fish, a medium fish symbol on a larger target and so on.

The sonar's microcomputer is sophisticated, but it can be fooled. It can't distinguish between fish and other suspended objects such as trotlines, turtles, submerged floats, air bubbles, etc. Individual tree limbs extending outwards from a group of limbs is the hardest object for the Fish I.D. feature to distinguish from fish.

You may see fish symbols on the screen when actually, there are no fish. The reverse is also true. The illustrations on the next page show how Fish I.D. can actually *miss* fish that *are* present.

Does that mean Fish I.D. is broken? No — the feature is simply interpreting sonar returns in a specific way to help take some of the work out of reading the screen. Remember: Fish I.D. is one of the many tools we provide so you can analyze your sonar returns for maximum fish finding information. This and other features can help you successfully "see" beneath the boat under varied water and fishing conditions. So, practice with the unit in both the Fish I.D. mode and without to become more familiar with the feature. The default for Fish I.D. is off.



At left, Sonar Page menu with Sonar Features selected. At right, the Sonar Features menu with the Fish ID Symbols command selected. The check box to the left is blank, indicating the feature is off.

Fig. 1 A

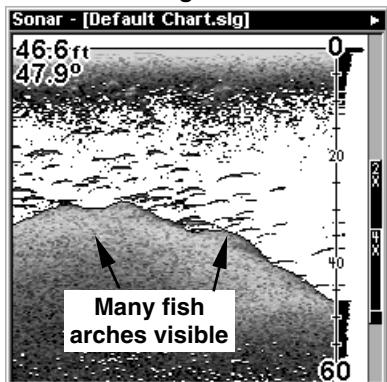


Fig. 1 B

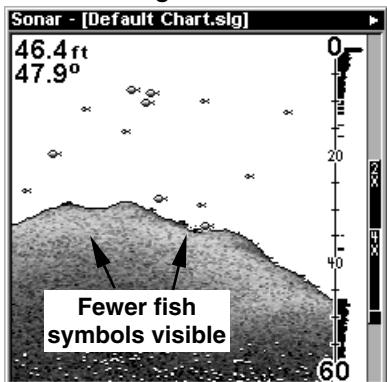


Fig. 2 A

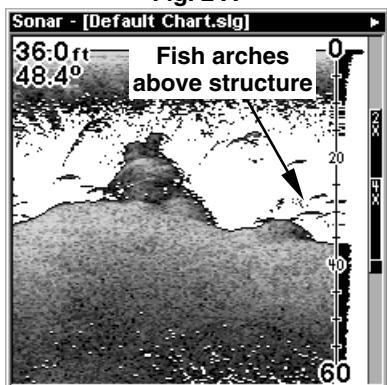
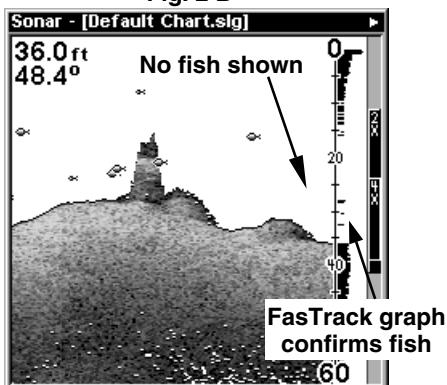


Fig. 2 B



At left, figures 1A and 2A show Sonar Page in normal chart mode. At right, figures 1B and 2B show the same underwater scene with Fish I.D. turned on. Note how arches are replaced with symbols.

To turn the Fish I.D. feature on:

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT** | **→** to **ZONE ALARM BAR** | **↓** to **FISH ID SYMBOLS** | **ENT** | **EXIT** | **EXIT**.

To turn off Fish I.D., repeat the instructions in step 1.

FishTrack™

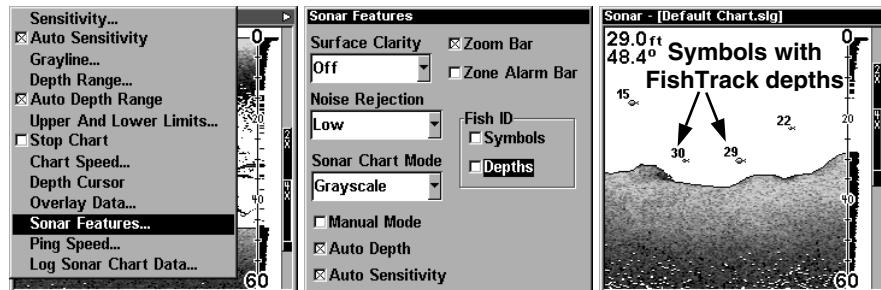
The FishTrack feature shows the depth of a fish symbol when it appears on the display. This lets you accurately gauge the depth of targets. This feature is available only when the Fish I.D. feature is on. The default setting for FishTrack is off.

To turn on FishTrack:

(Note: These instructions will turn on FishTrack *and* Fish I.D. at the same time.)

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT** | **→** to **ZONE ALARM BAR** | **↓** to **FISH ID DEPTHS** | **ENT** | **EXIT** | **EXIT**.

To turn off FishTrack, repeat the instructions in step 1. Turning off FishTrack in this manner will not turn off Fish I.D. symbols.



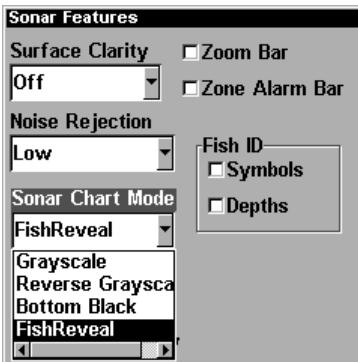
At left, Sonar Page menu with Sonar Features command selected. Center, Sonar Features menu with Fish I.D. Depths selected. The check box to the left is blank, indicating the feature is off. At right, Sonar Page showing Fish I.D. symbols and FishTrack depths turned on.

FishReveal™

When displaying actual sonar returns, the FishReveal feature helps show fish targets hidden by surface clutter, thermoclines, weed beds and other cover with 10 levels of gray tones.

The normal mode of operation (with FishReveal turned off) shows the weakest echoes as black and the strongest echoes in light gray. Since all weak echoes are black, fish arches show boldly against the white background. The drawback is that all weak echoes such as thermoclines are also emphasized. This can make it hard to distinguish fish signals inside thermoclines or other cover.

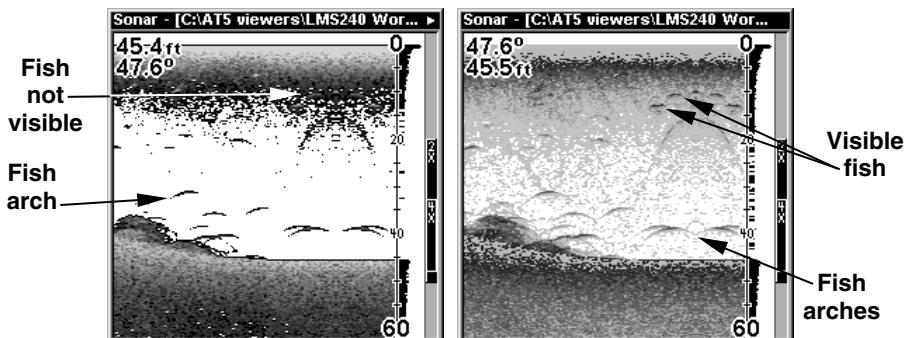
In FishReveal mode, the weakest echoes are white and the strongest echoes are black. Echoes in between vary in gray in proportion to their signal strength. The Grayline control determines the range for black to white. Also note that when using FishReveal, we recommend that you turn off Auto Sensitivity and turn up Sensitivity to near maximum.



Sonar Chart Mode command with FishReveal selected.

To turn FishReveal on:

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.
2. Press **↓** to **SONAR CHART MODE** | **ENT** | **↓** to **FISHREVEAL** | **ENT**.
3. Press **EXIT** | **↑** to **AUTO SENSITIVITY** | **ENT** | **↑** to **SENSITIVITY** | **ENT**.
4. Press **↑** until the Sensitivity Control Bar reads 100% (or close to it), then press **EXIT**. (If you reach the maximum limit, a tone sounds.)



Sonar chart in regular grayscale mode, left, and in FishReveal mode, right. Notice how shallow fish formerly hidden in the surface clutter become visible in FishReveal mode.

NOTE:

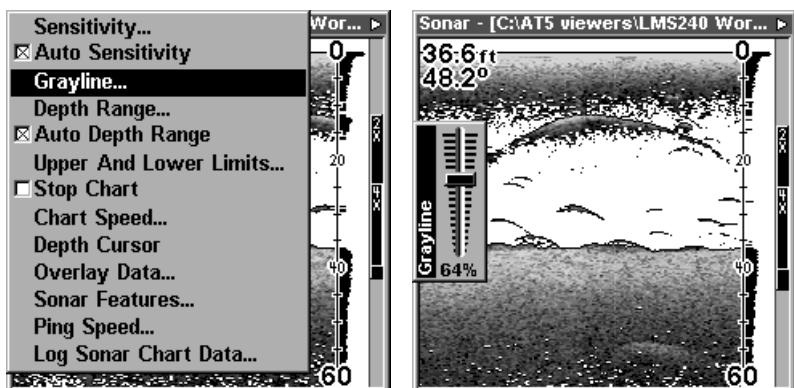
Water conditions vary greatly, and that affects sonar performance. Under certain conditions, FishReveal will show you more fish than normal grayscale mode, but the reverse will be true in other circumstances. We suggest you become familiar with both modes so you can best match your sonar's performance to the current water conditions.

Grayline®

Grayline lets you distinguish between strong and weak echoes. It "paints" gray on targets that are stronger than a preset value. This allows you to tell the difference between a hard and soft bottom. For example, a soft, muddy or weedy bottom returns a weaker signal which is shown with a narrow or no gray line. A hard bottom returns a strong signal which causes a wide gray line.

If you have two signals of equal size, one with gray and the other without, then the target with gray is the stronger signal. This helps distinguish weeds from trees on the bottom, or fish from structure.

Grayline is adjustable. Experiment with your unit to find the Grayline setting that's best for you.



Sonar Page Menu

To adjust the Grayline level:

1. From the Sonar Page, press **MENU** | **↓** to **GRAYLINE** | **ENT**.
2. The Grayline Control Bar appears. Press **↓** to decrease Grayline; press **↑** to increase Grayline.
3. When it's set at the desired level, press **EXIT**.

Fig. 1A

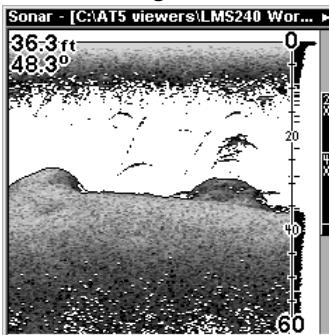


Fig. 1B

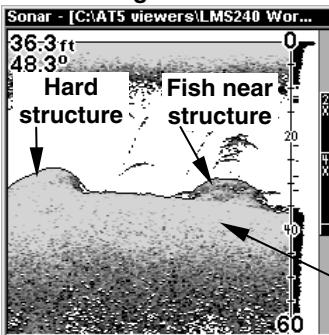


Fig. 2A

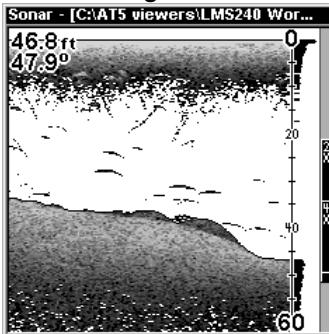


Fig. 2B

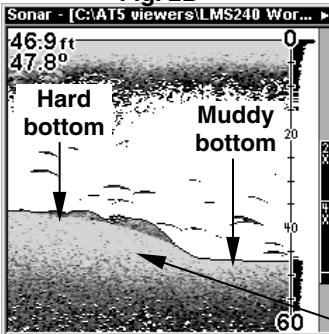


Fig. 3A

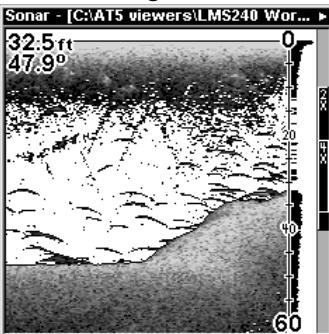
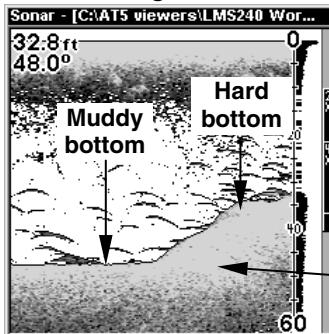


Fig. 3B



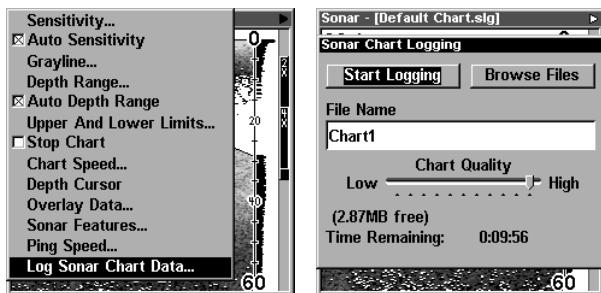
This series of figures shows how different Grayline settings can reveal more information. The "A" figures to the left show locations with Grayline set at the factory level of 64 percent. At right, the "B" figures show the same locations with Grayline increased to 84 percent. In Figure 1B, no fish are near the left structure, but the right structure shows fish holding next to the structure. Notice in figures 2B and 3B how Grayline displays a hard, rocky bottom (the drop-offs) with a wider gray line. The muddier bottom below those drop-offs appears as a narrower gray line.

HyperScroll™

See the entry on Ping Speed, which controls the HyperScroll feature.

Log Sonar Chart Data

If you have an MMC installed in the unit, the sonar data shown on the screen can be saved to the MMC. This can be played back at any time (to play a recorded sonar chart log, see the entry in this section for Sonar Simulator). If you have a personal computer and Internet access, visit our web site, www.lowrance.com, and download the free Sonar Viewer. This program will allow you to replay sonar logs on your personal computer.



At left, the Sonar Page menu with the Log Sonar Chart Data command selected. At right, Sonar Chart Logging menu, with the Start Logging command selected. The menu says the MMC has 2.87 MB of free space, which will record the scrolling chart for 9 minutes and 56 seconds.

To record or log chart data:

1. Press **MENU** | **↓** to **LOG SONAR CHART DATA** | **ENT**.
2. To record data using the default settings, press **ENT**. The menu clears and the Sonar Page title bar shows the name of the file you are recording. Warning messages will appear as recording time begins to run out.

NOTE:

You can change any of the settings by using the cursor arrows to highlight different commands. Select **FILE NAME** if you want to change the name. Select **CHART QUALITY** if you want to lower the file quality and record for a longer period of time. After you've changed the settings, select **START LOGGING**.

Noise Rejection

See the entry on Advanced Signal Processing in this section.

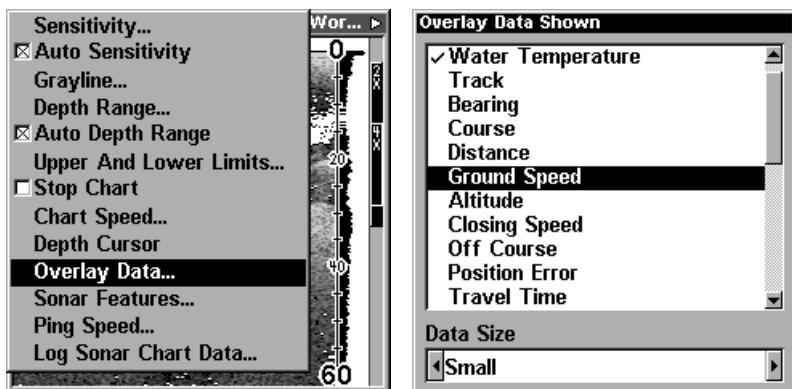
Overlay Data

To change the digital data shown on top of the Sonar Page or the Map Page:

First, press **PAGES**, use → or ← to select a *Page Name*, then press **EXIT**.

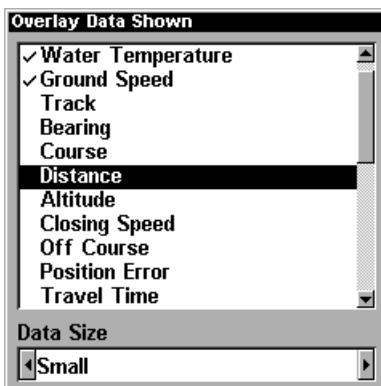
To select data for display:

1. From the Map or Sonar page, press **MENU** | ↓ to **OVERLAY DATA** | **ENT**.
2. Press ↓ or ↑ to select *Data Type* | **ENT**.



Overlay Data command on the Sonar Menu, at left. Overlay Data Shown selection menu, right. In this example, we scrolled down the data list to highlight "Ground Speed."

When selected, the data type shifts to the top of the data list and a check mark appears beside the data type. (If you wish, you may now use ↓ or ↑ to select other Data Types for display.)



Data list showing "Ground Speed" selected to display on Sonar Page.

3. To return to the previous page, press **EXIT** | **EXIT**.

To turn off displayed data:

1. From the Map or Sonar page, press **MENU** | **↓** to **OVERLAY DATA** | **ENT**.
2. Press **↓** or **↑** to select *Data Type* | **ENT**. The selected data type disappears from the top of the list and reverts to its previous, unchecked position. (If you wish, you may now use **↓** or **↑** to select other Data Types to turn off.)
2. To return to the previous page, press **EXIT** | **EXIT**.

To change displayed data font size:

1. From the Map or Sonar page, press **MENU** | **↓** to **OVERLAY DATA** | **ENT**.
2. Press **↓** or **↑** to select *Data Type* | press **→** or **←** to *Font Size* | **ENT**.

The selected data type will be displayed in the new size. (To change the font size for another Data Type, press **ENT** and repeat these steps, beginning with step two above.)

2. To return to the previous page, press **EXIT**.

Tip:

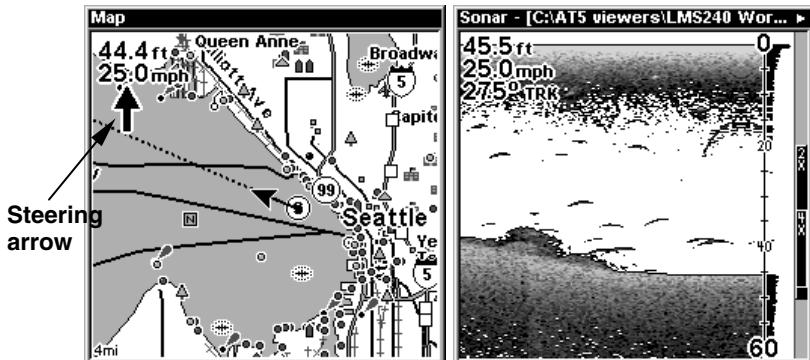
If you wish, you can change the displayed data font size when you select a data type:

1. From the Map or Sonar page, press **MENU** | **↓** to **OVERLAY DATA** | **ENT**.
2. Press **↓** or **↑** to select *Data Type* | press **→** or **←** to select *Data Size* | **ENT**.

The data will be shown in the new font size. To return to the previous page, press **EXIT** | **EXIT**.

NOTE:

Some data types can be displayed in only one font size. If that is the case, the Data Size box will not be displayed for that data type.



At left, Map Page showing boat cruising Puget Sound, Washington, with Overlay Data turned on. This example shows Depth, Ground Speed and the Steering Arrow. Note that the Steering Arrow always points directly to the destination you are navigating toward. In this case, the boater is headed on a northwesterly course of 275°. Since the helmsman is on course, the Steering Arrow is pointing straight ahead. If the helmsman veered off course, the arrow would show which direction to steer to get back on course toward the destination. At right, Sonar Page with Overlay Data turned on. This example shows Depth, Ground Speed and the Track the boat is following.

Ping Speed & HyperScroll™

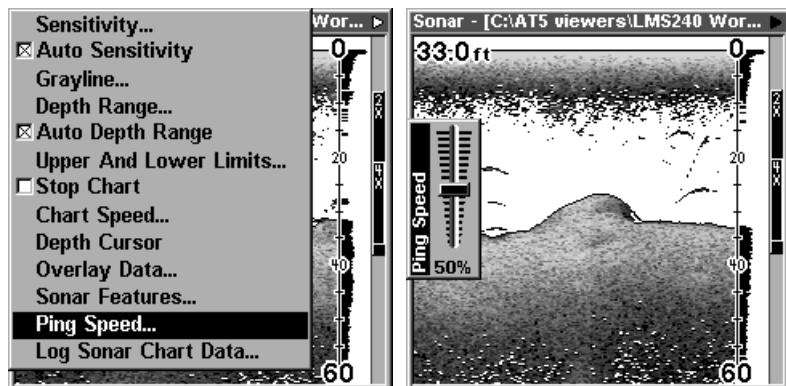
Ping Speed controls the rate at which the transmitter and transducer broadcast sonar sound waves — pings — into the water. The unit has a default ping speed of 50 percent. At normal boating speeds, this automatically provides enough return echoes to refresh the screen and scroll the chart at maximum chart speed.

However, when you are running at high speeds, or just want the fastest possible screen update, you may want to use the HyperScroll™ feature. When you change the Ping Speed to any setting greater than 50 percent, the unit automatically enters HyperScroll mode.

These faster ping rates allow you to maintain a high-detail picture on the screen, and the screen refresh rate and chart scroll speed can keep pace with the boat as it moves quickly over the bottom terrain.

When using HyperScroll, you may also need to manually decrease the sensitivity for optimum performance. Depending on water depth and other conditions, HyperScroll may cause a second bottom echo to return to the transducer during the next ping cycle, or sounding. This can result in a large amount of clutter appearing on the screen. If this occurs, just

decrease the sensitivity to a level that eliminates the clutter. When you turn HyperScroll off, you can return to your original sensitivity level.



Ping Speed command on the Sonar Menu, left.
Ping Speed Control Bar, right, at default setting.

To change Ping Speed:

1. From the Sonar Page, press **MENU** | **↓** to **PING SPEED** | **ENT**.
2. The Ping Speed Control Bar appears. Press **↑** to increase ping speed; press **↓** to decrease ping speed. When it's set at the desired level, press **EXIT**.

To adjust Sensitivity:

1. From the Sonar Page, press **MENU** | **ENT**.
2. The Sensitivity Control Bar appears. Press **↓** to decrease sensitivity; press **↑** to increase sensitivity. When it's set at the desired level, press **EXIT**. (When you reach the maximum or minimum limit, a tone sounds.)

To turn off HyperScroll:

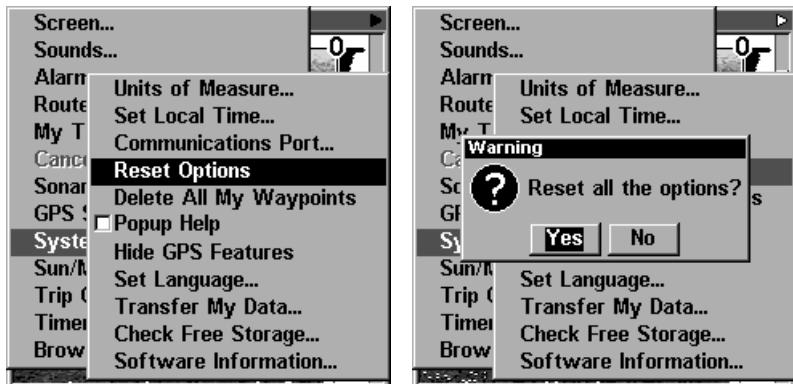
1. From the Sonar Page, press **MENU** | **↓** to **PING SPEED** | **ENT**.
2. The Ping Speed Control Bar appears. Press **↓** to decrease ping speed to 50 percent. When it's set at the desired level, press **EXIT**.

When you boost ping speed and switch into HyperScroll, the width of the FasTrack bar graph display doubles in width at the right side of the screen. This allows you to better see the virtually instantaneous sonar returns, just as you would on a flasher sonar unit. For more information on FasTrack, see its entry in this section.

Reset Options

This command is used to reset all features, options and settings to their original factory defaults. This is useful when you have changed several settings and want to return the unit to basic automatic operation.

1. Press **MENU | MENU | ↓ to SYSTEM SETUP | ENT | ↓ to RESET OPTIONS | ENT.**
2. Press **← to YES | ENT.**
3. All the menus are cleared and the unit reverts to the Map Page at the 4000 mile zoom range, just as if you had turned it on for the first time. All options have been returned to the factory settings.



At left, System Setup menu with Reset Options command selected. At right, the Reset Options dialog box, with "Yes" selected.

NOTE:

Reset Options does *not* erase any waypoints, routes, or plot trails.

Reset Water Distance

The sonar chart's Digital Data display option includes a window that shows distance traveled, called Water Distance ("W Distance"). This information is calculated from an optional water speed sensor, not the GPS. The Water Distance window can be reset to zero using the Reset Water Distance command.

1. Press **MENU | MENU | ↓ to SONAR SETUP | ENT | ↓ to RESET WATER DISTANCE | ENT.** The menus are cleared and the water distance is reset to 0.00.

Set Keel Offset

This unit measures water depth from the face of the transducer. Since the transducer is installed below the water surface, the distance displayed by the digital depth, chart depth scale, chart cursor or fish symbols is *not* the exact water depth. If the transducer is 1 foot below the

surface, and the screen shows the water depth as 30 feet, then the actual depth is 31 feet.

On sailboats or other large vessels with deep drafts, the distance between the transducer installation and the keel or lower engine unit can be several feet. In those cases, an inexact depth reading could result in grounding or striking underwater structure. The Keel Offset feature eliminates the need for the navigator to mentally calculate how much water is under his keel.

Keel Offset lets you calibrate the *digital depth* displayed on the screen (Chart depth scale, chart cursor depth and fish symbol depth are unchanged by this feature.) To calibrate the digital depth, first measure the distance from the face of the transducer to the lowest part of the boat. In this example, we will use 3.5 feet. This will be entered as a *negative* 3.5 feet, which makes the digital depth perform as if it's lower in the water than it really is.

1. Press **MENU | MENU | ↓ to SONAR SETUP | ENT | ENT**.
2. The Keel Offset dialog box appears. Press **↓** to change the plus (+) sign to a minus (-) sign.
3. Press **→** to the first number, then press **↑** to change the number to 3
4. Press **→** to the second number, then press **↑** to change the number to 5, then press **EXIT**. The digital depth now accurately shows the depth of water beneath the keel.

NOTE:

If knowing the exact depth of water beneath the keel is less important, you can calibrate the digital depth so that it shows the actual water depth from surface to bottom. To do this, first measure the distance from the face of the transducer up to the surface (the water line on the boat). In this example, we will use 1.5 feet. This will be entered as a *positive* 1.5 feet, which makes the digital depth perform as if it's higher in the water than it really is.

1. Press **MENU | MENU | ↓ to SONAR SETUP | ENT | ENT**.
2. The Keel Offset dialog box appears with a plus (+) sign at the front of the box.
3. Press **→** to the first number, then press **↑** to change the number to 1.
4. Press **→** to the second number, then press **↑** to change the number to 5, then press **EXIT**. The digital depth now accurately shows

the water depth from surface to bottom.

(Chart depth scale, chart cursor depth and fish symbol depth are unchanged by this setting.)

Sensitivity & Auto Sensitivity

The sensitivity controls the ability of the unit to pick up echoes. Sensitivity can be adjusted, because water conditions vary greatly. A low sensitivity level (from zero to 50 percent) excludes much of the bottom information, fish signals, and other target information.

High sensitivity levels let you see this detail, but it can also clutter the screen with many undesired signals. Typically, the best sensitivity level shows a good solid bottom signal with Grayline and some surface clutter.

Automatic Sensitivity

The default sensitivity mode is automatic. The unit bases the sensitivity level on water depth and conditions. When the unit is in the automatic mode, sensitivity is automatically adjusted to keep a solid bottom signal displayed, plus a little more power. This gives it the capability to show fish and other detail.

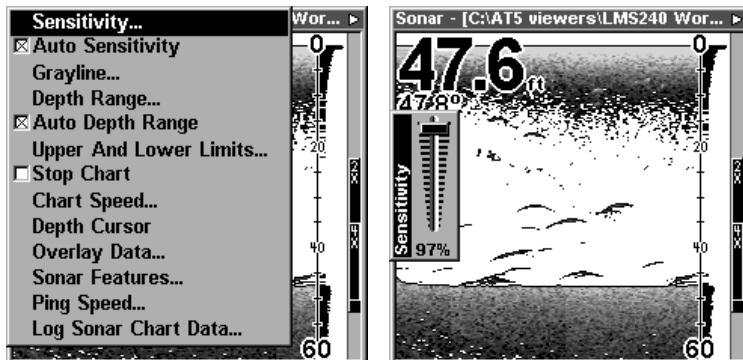
However, situations occur when it becomes necessary to increase or decrease the sensitivity. This typically happens when you wish to see more detail, so an increase in sensitivity is indicated. Or, wave action and boat wakes can create enough tiny air bubbles to clutter much of the water column. In that case, a decrease in sensitivity is indicated to reduce some of the clutter.

The control bar used to adjust sensitivity up or down is the same whether the unit is in the automatic or manual mode. In automatic you can adjust sensitivity up to 100 percent but the unit will limit your *minimum* setting. In auto, the unit will continue to make small adjustments, allowing for the setting you selected.

In manual mode, you have *complete* control over sensitivity, with the ability to set it anywhere from zero to 100 percent. Once you select a level in manual, the unit will continue to use that exact sensitivity setting until you change it or revert to auto mode.

To adjust sensitivity in auto mode:

1. Press **MENU | ENT**.
2. The Sensitivity Control Bar appears. Press **↓** to decrease sensitivity; press **↑** to increase sensitivity. When it's set at the desired level, press **EXIT**. (When you reach the maximum or minimum limit, a tone sounds.)



At left, Sonar Menu with Sensitivity command selected. At right, the Sensitivity Control Bar.

To adjust sensitivity in manual mode:

1. First, turn off Auto Sensitivity: from the Sonar Page, press **MENU** | **↓** to **AUTO SENSITIVITY** | **ENT**.
2. Press **↑** to **SENSITIVITY** | **ENT** and the Sensitivity Control Bar appears. Press **↓** or **↑** to pick a different sensitivity setting. When it's set at the desired level, press **EXIT**.

To turn Auto Sensitivity back on:

1. From the Sonar Page, press **MENU** | **↓** to **AUTO SENSITIVITY** | **ENT** | **EXIT**.

NOTE:

To return to the original factory setting for Auto Sensitivity, see the entry in this section on Reset Options. If sensitivity is in manual mode, the Reset Options command will switch back to Auto and reset the factory setting at the same time.

Tip:

For quicker sensitivity adjustments, try leaving the Sensitivity Control Bar on the screen as the chart scrolls. You can see the changes on the screen as you press the up or down arrows. This is handy when there's a lot of clutter in the water, and you are matching the sensitivity to rapidly changing water conditions.

Surface Clarity

The markings extending downward from the zero line on the chart are called "surface clutter." These markings are caused by wave action, boat wakes, temperature inversion, and more.

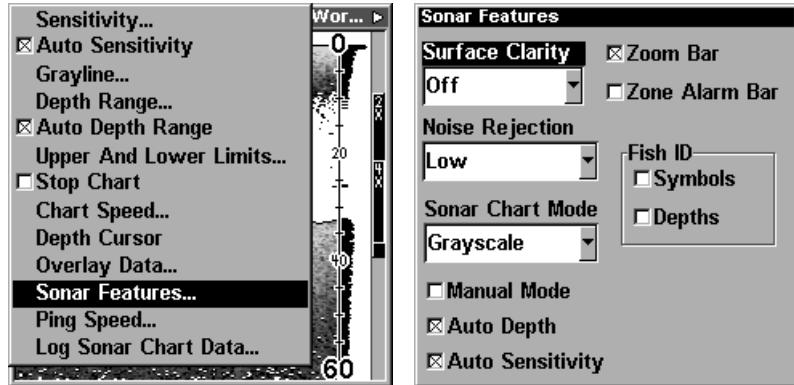
The surface clarity control reduces or eliminates surface clutter signals from the display. It does this by changing the sensitivity of the receiver,

decreasing it near the surface and gradually increasing it as the depth increases.

There are three levels of surface clarity available: low, medium, or high. It can also be turned off. The default level is off.

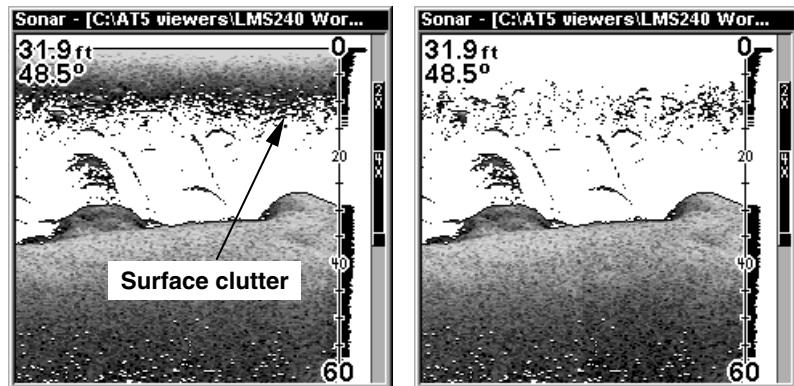
To adjust the Surface Clarity level:

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.



Sonar Page menu with Sonar Features command selected, left. Sonar Features menu with Surface Clarity command selected, right.

2. Press **ENT** | **↓** or **↑** to select *clarity level* | **EXIT** | **EXIT** | **EXIT**.



In the illustration at left, Surface Clarity is turned off.
The right view shows Surface Clarity set at High.

Sonar Chart Mode

The default color scheme for the sonar chart is grayscale, but we offer other variations to suit your viewing preferences. You can select the chart to be displayed in reverse grayscale, bottom black or FishReveal

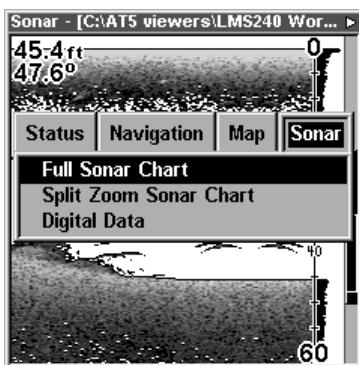
mode. (For more information on FishReveal, see the entry on that topic elsewhere in this section.)

To change the chart mode color scheme:

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.
2. Press **↓** to **SONAR CHART MODE** | **ENT**.
3. Press **↓** or **↑** to *Mode Name* | **ENT**.
4. Press **EXIT** | **EXIT** to return to the Sonar Page.

Sonar Page & Sonar Chart Display Options

The Pages Menu offers three chart display options under the Sonar Page category. To access them, press **PAGES** | **←** or **→** to **SONAR** | **↓** to *Option Name* | **EXIT**.



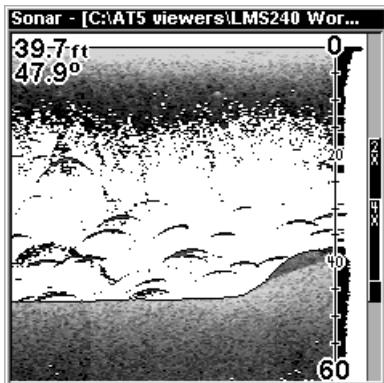
Pages Menu, showing sonar chart display options.

Full Sonar Chart

This is the default mode used when the unit is turned on for the first time or when it's reset to the factory defaults.

The bottom signal scrolls across the screen from right to left. Depth scales on the right side of the screen aid in determining the depth of targets. The line at the top of the screen represents the surface. The bottom depth and surface temperature (if equipped with a temperature sensor or a transducer with a temp sensor built in) show at the top left corner of the screen.

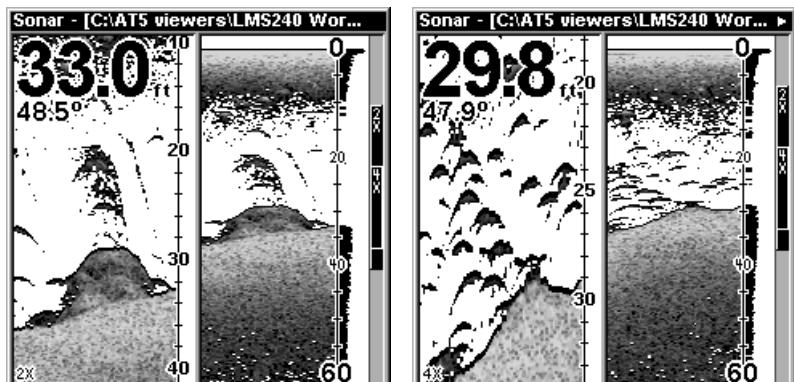
The FasTrack™ display shows just to the right of the scale. This changes all echoes into short horizontal bars, replicating a flasher sonar. The zoom bar on the far right shows the area that's zoomed when the zoom is in use. (See the Zoom section for more information.)



Full Sonar Chart. The Overlay Data (depth and water temperature) are both set to the small text size.

Split Zoom Sonar Chart

A split chart shows the underwater world from the surface to the bottom on the right side of the screen. The left side shows an enlarged version of the right side. The zoom range shows at the bottom left corner of the screen.

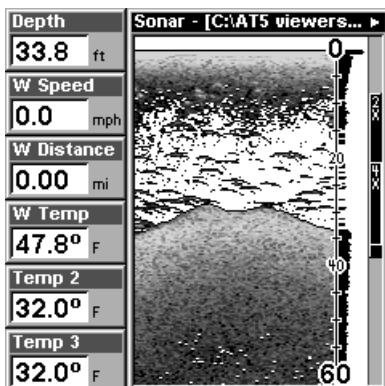


Split Zoom Sonar Chart. Image at left shows the left window zoomed to 2X. The right image shows the left window zoomed to 4X. The depth overlay data is set to the default large text size; the water temperature is set to the small text size.

Digital Data/Chart

This mode shows the chart on the right side of the screen. The left side has six large digital boxes or windows containing: Water Depth; Water Speed (from an optional speed sensor); Water Distance (distance traveled or log, it also requires a speed sensor); Surface Water Temperature; Temperature #2

and Temperature #3. (Note: Temperature #2 and #3 require additional optional temperature sensors.)

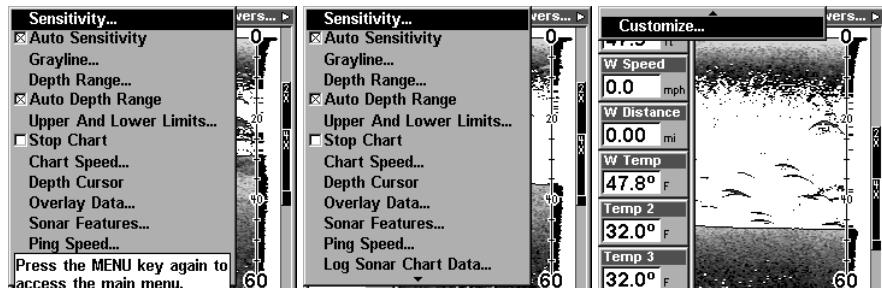


Digital Data/Chart

Customizing the Digital Data/Chart Screen

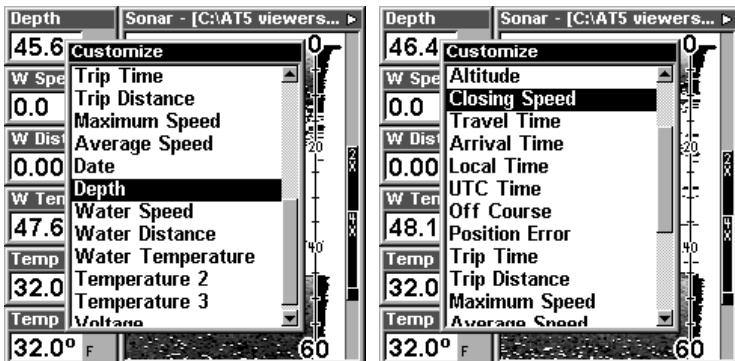
The Digital Data/Chart screen can be customized to show digital data different from the defaults first shown. To customize this screen:

1. From the Sonar Page (in Digital Data mode), press **MENU** | **↓** to **CUSTOMIZE** | **ENT**. (Keep scrolling down and Customize will appear.)



The Customize command will not appear until you scroll to the very bottom of the Sonar Page menu. At far left, the pop-up help box conceals part of the menu. In the center illustration, the down arrow symbol visible just below the "Log Sonar Chart Data" command indicates there is another command — "Customize" — further down the menu list.

2. The Depth window title bar flashes, indicating the window contents can be changed. Press **ENT** | **↑** or **↓** to select *data type* | **ENT** | **EXIT**.



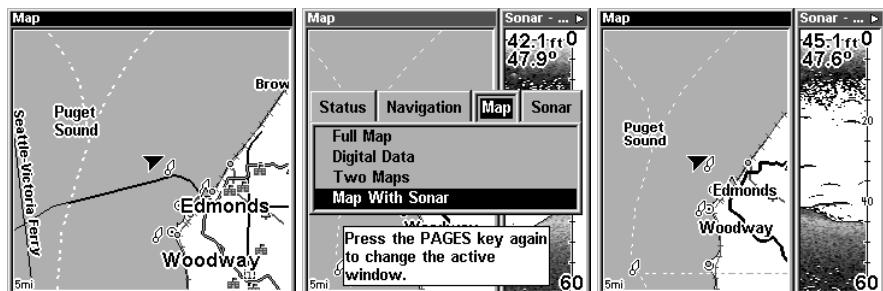
Options List for customizing Digital Data windows. At left, the list first appears with Depth selected. At right, Closing Speed has been picked to replace Depth in the top digital data window.

Tip:

You can customize other digital data windows before returning to the Sonar Page. After changing the first window by selecting the Data Type and pressing Enter, use the ↓ key to select another window to change. When the selected window title bar flashes, press **ENT** | ↑ or ↓ to select *data type* | **ENT**. Repeat these steps until you're finished customizing, then press **EXIT** to return to the Sonar Page.

Map With Sonar Split Screen

There is a page mode that splits the screen in half, with the map on the left and the sonar on the right. This screen option can be found on the Pages Menu under the Map Page category.



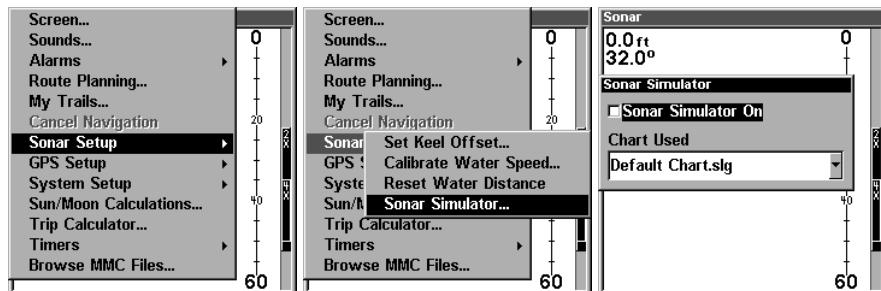
Map With Sonar split screen option. At far right, the full Map Page is shown. The Pages Menu with the Map option list is shown in the center. At right, the Map With Sonar split screen is shown.

When this screen is activated, you need to specify which side the Menu, Zoom In and Zoom Out keys correspond to. To do this, press **PAGES** | **PAGES**. The window with the black title bar at the top of the screen is the active window. To switch back, just press **PAGES** | **PAGES** again.

Sonar Simulator

This unit has a built-in simulator that lets you run it as if you were on the water. All sonar features and functions are useable. When in simulator mode, you will see the chart file name in the Sonar Page title bar and a play symbol will flash on and off at the right end of the title bar. To use the simulator:

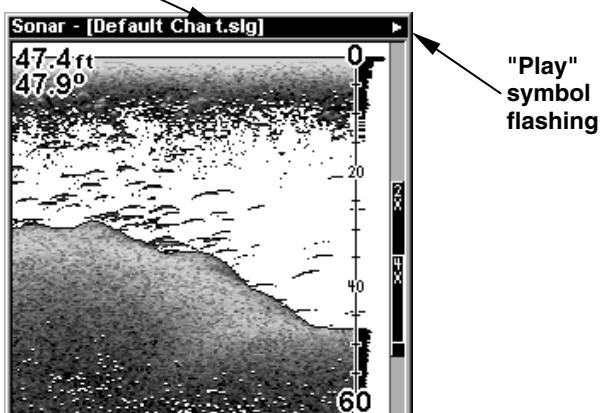
1. From the Sonar Page, press **MENU | MENU | ↓** to **SONAR SETUP | ENT | ↓** to **SONAR SIMULATOR | ENT**.



At left, Main Menu with Sonar Setup command selected. Center, sub-menu with Sonar Simulator command selected. At right, Sonar Simulator menu, with simulator turned off (check box is unchecked).

2. To use the default sonar chart log stored in the unit, press **ENT | EXIT**. The recorded chart begins scrolling across the screen, just as if you were on the water.
3. Turn off Sonar Simulator by pressing **MENU | MENU | ↓** to **SONAR SETUP | ENT | ↓** to **SONAR SIMULATOR | ENT | ENT | EXIT**.

Title bar with chart file name



Sonar Page, playing a recorded sonar chart in Sonar Simulator mode.

Tip:

The Sonar Simulator can use sonar charts that you or a friend have recorded (logged) on an MMC card. (To see how, read the entry in this section on Log Sonar Chart Data.) To play back your own sonar chart, make sure the MMC containing the chart is installed, then:

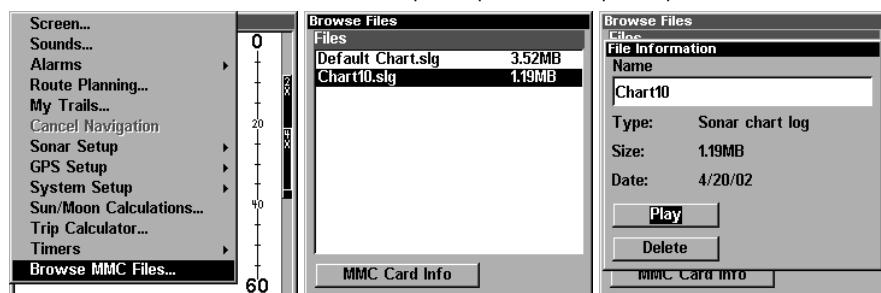
1. Press **MENU | MENU | ↓ to SONAR SETUP | ENT | ↓ to SONAR SIMULATOR | ENT.**
2. Press **↓ to CHART USED | ENT.**
3. Press **↓ or ↑ to select *chart name* | ENT | ↑ to SONAR SIMULATOR ON | ENT | EXIT.**

While the simulator is running, you can switch from one chart log to another by opening the Sonar Simulator menu and using the instructions in step 2 to select a different chart.

Tip:

There's more than one way to play a recorded sonar chart. You can also turn on the simulator from the MMC files list. Here's how:

1. Press **MENU | MENU | ↓ to BROWSE MMC FILES | ENT | ENT.**
2. Press **↓ or ↑ to *chart name* | ENT | ↓ to PLAY | ENT | EXIT.**



Menu sequence for playing a sonar chart log from the MMC File List.

NOTE:

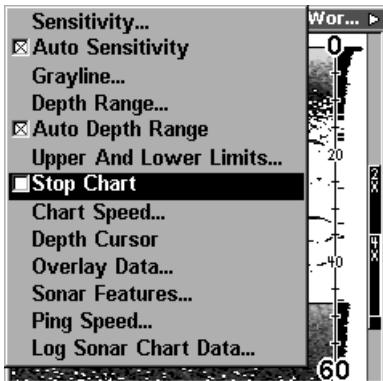
For some great practice, try running the Sonar Simulator and the GPS Simulator at the same time. This will really give you a feel for how the unit will work in the field.

Stop Chart

If you are running multiple units on a boat or using this unit in a car, there are times when you may want to turn off the sonar. This command turns off the sonar and stops the chart from scrolling. Sonar restarts automatically each time you turn on your unit.

1. Press **MENU | ↓ to STOP CHART | ENT | EXIT.**

To turn on sonar and start the chart scrolling again, repeat the above steps.



Sonar Menu with Stop Chart command selected. The box is unchecked, indicating that the chart is scrolling across the screen.

Upper and Lower Limits

See the entry in this section for Depth Range - Upper and Lower Limits

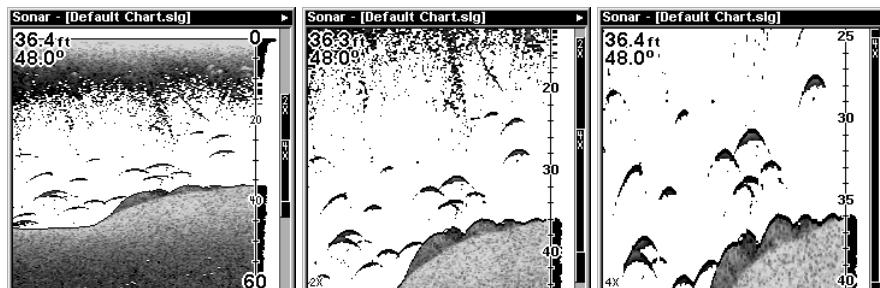
Zoom & Zoom Bar

"Zooming" the display is a common, fast and easy method used to enlarge small detail, fish signals and the bottom with its associated structure. This unit lets you zoom the display quickly and easily by pressing the Zoom In key, **ZIN**.

Pressing **ZIN** once doubles the size (2X) of all echoes on the screen. Pressing it again quadruples the size of the echoes (4X). The zoom bar on the far right side of the screen shows which echoes will be displayed on the screen when the **ZIN** key is pressed.

For example, pressing the **ZIN** key once will enable a 2X zoom which will show all echoes that are between the top and bottom of the 2X zoom bar. Pressing the key again will give a 4X zoom and only the echoes between the top and bottom of the 4X bar will show on the screen.

Press the Zoom Out key, **ZOUT**, to return the display to the normal mode.



At left, Sonar Page, normal view. Center, same view zoomed to 2X.
Right, same view zoomed to 4X

Section 5: Sonar Troubleshooting

If your unit is not working, or if you need technical help, please use the following troubleshooting section before contacting the factory customer service department. It may save you the trouble of returning your unit for repair. For contact information, refer to the last page, just inside the back cover of this manual.

Unit won't turn on:

1. Check the power cable's connection at the unit. Also check the wiring.
2. Make certain the power cable is wired properly. The red wire connects to the positive battery terminal, black to negative or ground.
3. Check the fuse.
4. Measure the battery voltage at the unit's power connector. It should be at least 11 volts. If it isn't, the wiring to the unit is defective, the battery terminals or wiring on the terminals are corroded, or the battery needs charging.

Unit freezes, locks up, or operates erratically:

1. Electrical noise from the boat's motor, trolling motor, or an accessory may be interfering with the sonar unit. Rerouting the power and transducer cables away from other electrical wiring on the boat may help. Route the sonar unit's power cable directly to the battery instead of through a fuse block or ignition switch
2. Inspect the transducer cable for breaks, cuts, or pinched wires.
3. Check both the transducer and power connectors. Make certain both are securely plugged in to the unit.

Weak bottom echo, digital readings erratic, or no fish signals:

1. Make certain the transducer is pointing straight down. Clean the face of the transducer. Oil, dirt, and fuel can cause a film to form on the transducer, reducing its effectiveness. If the transducer is mounted inside the hull, be sure it is shooting through only one layer of fiberglass and that it is securely bonded to the hull. Do NOT use RTV silicone rubber adhesive or Marine-Tex™ epoxy.
2. Electrical noise from the boat's motor can interfere with the sonar. This causes the sonar to automatically increase its Discrimination or noise rejection feature. This can cause the unit to eliminate weaker signals such as fish or even structure from the display.

3. The water may be deeper than the sonar's ability to find the bottom. If the sonar can't find the bottom signal while it's in the automatic mode, the digital sonar display will flash continuously. It may change the range to limits far greater than the water you are in. If this happens, place the unit in the manual mode, then change the range to a realistic one, (for example, 0-100 feet) and increase the sensitivity. As you move into shallower water, a bottom signal should appear.

4. Check the battery voltage. If the voltage drops, the unit's transmitter power also drops, reducing its ability to find the bottom or targets.

Bottom echo disappears at high speeds or erratic digital reading or weak bottom echo while boat is moving

1. The transducer may be in turbulent water. It must be mounted in a smooth flow of water in order for the sonar to work at all boat speeds. Air bubbles in the water disrupt the sonar signals, interfering with its ability to find the bottom or other targets. The technical term for this is cavitation.

2. Electrical noise from the boat's motor can interfere with the sonar. This causes the sonar to automatically increase its Discrimination or noise rejection feature. This can cause the unit to eliminate weaker signals such as fish or even structure from the display. Try using resistor spark plugs or routing the sonar unit's power and transducer cables away from other electrical wiring on the boat.

No fish arches when the Fish I.D. feature is off:

1. Make certain the transducer is pointing straight down. This is the most common problem if a partial arch is displayed.

2. The sensitivity may not be high enough. In order for the unit to display a fish arch, it has to be able to receive the fish's echo from the time it enters the cone until it leaves. If the sensitivity is not high enough, the unit shows the fish only when it is in the center of the cone.

3. Use the Zoom feature. It is much easier to display fish arches when zoomed in on a small range of water than a large one. For example, you will have much better luck seeing fish arches with a 30 to 60 foot range than a 0 to 60 foot range. This enlarges the targets, allowing the display to show much more detail.

4. The boat must be moving at a slow trolling speed to see fish arches. If the boat is motionless, fish stay in the cone, showing on the screen as straight horizontal lines.

NOISE

A major cause of sonar problems is electrical noise. This usually appears on the sonar's display as random patterns of dots or lines. In severe cases, it can completely cover the screen with black dots, or cause the unit operate erratically, or not at all.

To eliminate or minimize the effects of electrical noise, first try to determine the cause. With the boat at rest in the water, the first thing you should do is turn all electrical equipment on the boat off. Make certain the engine is off, also. Turn your sonar unit on, then turn off ASP (Advanced Signal Processing). Sensitivity should be set at 90-95 percent. There should be a steady bottom signal on the display. Now turn on each piece of electrical equipment on the boat and view the effect on the sonar's display. For example, turn on the bilge pump and view the sonar display for noise. If no noise is present, turn the pump off, then turn on the VHF radio and transmit. Keep doing this until all electrical equipment has been turned on, their effect on the sonar display noted, then turned off.

If you find noise interference from an electrical instrument, trolling motor, pump, or radio, try to isolate the problem. You can usually reroute the sonar unit's power cable and transducer cable away from the wiring that is causing the interference. VHF radio antenna cables radiate noise when transmitting, so be certain to keep the sonar's wires away from it. You may need to route the sonar unit's power cable directly to the battery to isolate it from other wiring on the boat.

If no noise displays on the sonar unit from electrical equipment, then make certain everything except the sonar unit is turned off, then start the engine. Increase the RPM with the gearshift in neutral. If noise appears on the display, the problem could be one of three things; spark plugs, alternator or tachometer wiring. Try using resistor spark plugs, alternator filters, or routing the sonar unit's power cable away from engine wiring. Again, routing the power cable directly to the battery helps eliminate noise problems. Make certain to use the in-line fuse supplied with the unit when wiring the power cable to the battery.

When no noise appears on the sonar unit after all of the above tests, then the noise source is probably cavitation. Many novices or persons with limited experience make hasty sonar installations which function perfectly in shallow water, or when the boat is at rest. In nearly all cases, the cause of the malfunction will be the location and/or angle of the transducer. The face of the transducer must be placed in a location that has a smooth flow of water at all boat speeds. Read your transducer owner's manual for the best mounting position.

Notes

Section 6: Basic GPS Operations

This section addresses the unit's *most basic* GPS operations. The tutorials presented in Sec. 6 follow a chronological order. Sec. 7, *Advanced GPS Operations*, will discuss other more advanced functions and utilities. Material in Sec. 7 is arranged in alphabetical order.

Before you turn on LMS-240 and find where you are, it's a good idea to learn about the different keys, the four Page screens and how they all work together. BUT, if you just can't wait to get outside, turn to the one-page **Quick Reference** on page 96.

Keyboard



LMS-240 sonar/GPS unit, front view, showing map with sonar split screen, keyboard and access door for the MMC slot.

1. **PWR/LIGHT** (Power & Light) – The PWR key turns the unit on and off and activates the backlight.
2. **PAGES** – Pressing this and the $\leftarrow \rightarrow$ arrow keys switches the unit between the four different page screens. (Satellite Status Page, Naviga-

tion Page, Map Page and Sonar Page.) Each page represents one of the unit's major operation modes.

3. **MENU** – Press this key to show the menus and submenus, which allow you to select a command or adjust a feature. This also accesses search functions for streets, intersections, addresses and highway exits.

4. **ARROW KEYS** – These keys are used to navigate through the menus, make menu selections, move the map and sonar chart cursors and enter data.

5. **ENT/ICONS** (Enter & Icons) – This key allows you to save data, accept values or execute menu commands. It is also used to create event marker icons.

6. **EXIT** – The Exit key lets you return to the previous screen, clear data or erase a menu.

7. **WPT** – (Waypoint) The Waypoint key is used to save and recall waypoints, search for waypoints and access the waypoint list. It also launches the Point-of-Interest (POI) search menus and is involved in some navigation functions.

8. **ZOUT** – (Zoom Out) – This key lets you zoom the screen out. On the Sonar Page, this key returns you to a full sonar chart display, showing the entire water column from surface to bottom. On the Map Page, this lets you see a larger geographic area on the map. Less detail is seen as you zoom out.

9. **ZIN** – (Zoom In) – This key lets you zoom the screen in. On the Sonar Page, this key enlarges fish signals and bottom detail. On the Map Page, zooming in lets you see greater detail in a smaller geographic area on the map.

Power/lights on and off

To turn on the unit, press **PWR**. As the unit powers up, the Map Page is displayed first. (To switch to another page, press **PAGES** | **←** or **→** to *Page Name* | **EXIT**.)

To turn on the backlight, press **PWR** again. The unit has three backlight levels to select from. Repeatedly pressing **PWR** will cycle through the backlight settings and turn off the backlight.

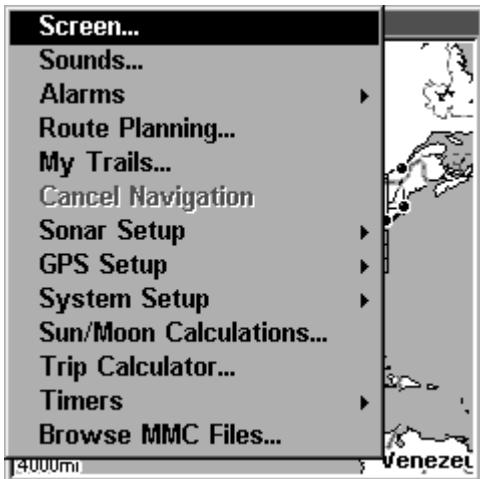
Turn off the unit by pressing and holding the **PWR** key for 3 seconds.

Main Menu

The LMS-240 has a Main Menu, which contains some function commands and some setup option commands. The tutorial lessons in this

section will deal only with functions, the basic commands that make LMS-240 do something. LMS-240 will work fine for these lessons right out of the box with the factory default settings. But, if you want to learn about the various options, see Section 8, *System Setup and GPS Setup Options*.

You can access the Main Menu from any of the four Page screens by pressing **MENU | MENU**. To clear the menu screen and return to the page display, press **EXIT**.



Main Menu.

The Main Menu commands and their functions are:

Screen command: changes the contrast or brightness of the display screen.

Sounds command: enables or disables the sounds for key strokes and alarms and sets the alarm style.

Alarms command: turns GPS or sonar alarms on or off and changes alarm thresholds.

Route Planning command: used to plan, view or navigate a route.

My Trails command: shows, creates and deletes plot trails. Also used to navigate or backtrack a trail.

Cancel Navigation command: turns off the various navigation commands. Used to stop navigating after you have reached your destination waypoint, Point of Interest or map cursor location; or after you reach the end of a route or trail.

Sonar Setup command: sets various sonar options.

GPS Setup command: sets various GPS receiver options.

System Setup command: sets general configuration options.

Sun/Moon Calculations command: finds the rising and setting time of the sun and the moon.

Trip Calculator command: shows trip status and statistics.

Timers command: controls the up timer, down timer and alarm clock settings.

Browse MMC Files command: this allows you to view the installed MMC card and the files it contains.

Pages

The unit has four Page displays that represent the four major operating modes. They are the Satellite Status Page, the Navigation Page, Map Page and the Sonar Page. They are accessed by pressing the **PAGES** key, then using → or ← to select a Page. (Clear the Pages Menu by pressing **EXIT**.)



Pages Menu, showing some Map display options.

Sonar Page

The Sonar Page displays the sonar chart, a view of the water column from the surface to the bottom. The chart scrolls across the screen from right to left, displaying signal echoes that represent fish, structure and the bottom. The Sonar Page is discussed in detail in Section 3. To get to the Sonar Page: Press the **PAGES** key, then use → or ← to select **SONAR**. (Clear the Pages Menu by pressing **EXIT**.)

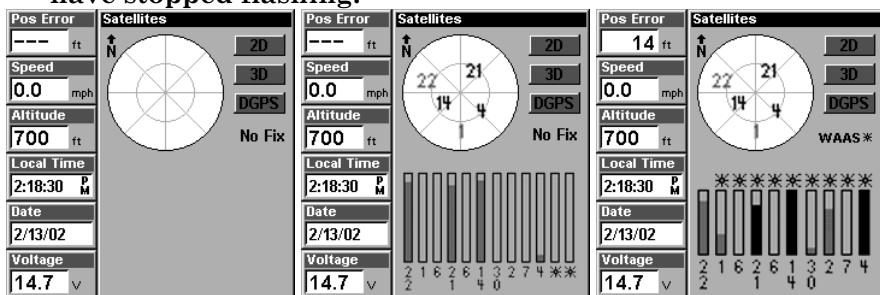
Satellite Status Page

The Satellite Status Page, shown, provides detailed information on the status of LMS-240's satellite lock-on and position acquisition. To get to the Satellite Status Page: Press the **PAGES** key, then use → or ← to select **STATUS**. (Clear the Pages Menu by pressing **EXIT**.)

No matter what Page you are on, a flashing current position indicator/question mark symbol and flashing GPS data displays indicate that satellite lock has been lost and there is no position confirmed. The Satellite Status Page shows you the quality and accuracy of the current satellite lock-on and position calculation.

WARNING:

Do not begin navigating with this unit until the numbers have stopped flashing!



Satellite Status Page. Left view indicates unit has not locked on to any satellites and does not have a fix on its position. Center view shows satellites being scanned. Right view shows satellite-lock on with a 3D position acquired (latitude, longitude and altitude.)

This screen shows a graphical view of the satellites that are in view. Each satellite is shown on the circular chart relative to your position. The point in the center of the chart is directly overhead. The small inner ring represents 45° above the horizon and the large ring represents the horizon. North is at the top of the screen. You can use this to see which satellites are obstructed by obstacles in your immediate area if the unit is facing north.

The GPS receiver is tracking satellites that are in bold type. The receiver hasn't locked onto a satellite if the number is grayed out, therefore it isn't being used to solve the position.

Beneath the circular graph are the bar graphs, one for each satellite in view. Since the unit has twelve channels, it can dedicate one channel per visible satellite. The taller the bar on the graph, the better the unit is receiving the signals from the satellite.

The "Estimated Position Error" (horizontal position error) shown in the upper left corner of the screen is the expected error from a benchmark

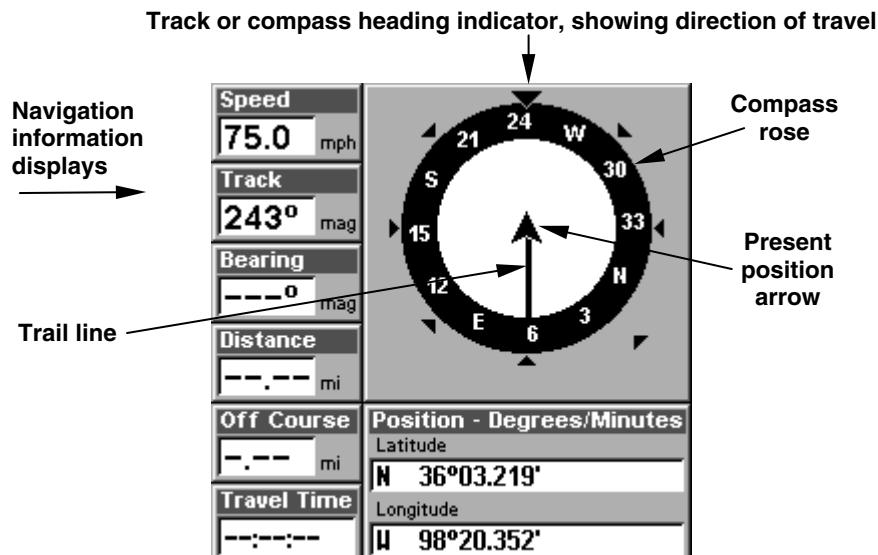
location. In other words, if the EPE shows 50 feet, then the position shown by the unit is estimated to be within 50 feet of the actual location. This also gives you an indicator of the fix quality the unit currently has. The smaller the position error number, the better (and more accurate) the fix is. If the position error flashes dashes, then the unit hasn't locked onto the satellites, and the number shown isn't valid.

The Satellite Status Page has its own menu, which is used for setting various options. (Options and setup are discussed in Sec. 8). To access the Satellite Status Page Menu, from the Status Page, press **MENU**.

Navigation Page

This screen has a compass rose that not only shows your direction of travel, but also the direction to a recalled waypoint. To get to the Navigation Page: Press **PAGES** | → or ← to **NAVIGATION** | **EXIT**.

The navigation screen looks like the one below when you're *not* navigating to a waypoint or following a route or trail. Your position is shown by an arrow in the center of the screen. Your trail history, or path you've just taken, is depicted by the line extending from the arrow. The arrow pointing down at the top of the compass rose indicates the current track (direction of travel) you are taking.



Navigation Page, recording a trail, traveling southwest. Page looks like this when LMS-240 is not navigating to a waypoint, following a route, or backtracking a trail.

When navigating to a waypoint, the Navigation screen looks like the one shown on the next page. Your ground speed, track, distance and bearing to waypoint, and course are all shown digitally on this screen.

NOTE:

Remember, when the Speed, Track and Position information displays are flashing, satellite lock has not been achieved and no position fix has been determined. A question mark will also flash on the present position arrow in the center of the compass rose.

Speed (ground speed) is the velocity you are making over the ground. (If you wish, you can customize the Speed window to display Closing Speed instead. Closing Speed is also known as velocity made good. It's the speed that you're making toward the waypoint. For instructions, see the Customize Page Displays entry in Sec. 8.)

Track is the heading, or the current direction you are actually traveling. Bearing is the direction of a line-of-sight from your present position to the destination. No matter what direction you are steering, the Bearing window shows the compass direction straight to the destination from your location at the moment. Distance shows how far it is to the waypoint you're navigating toward.

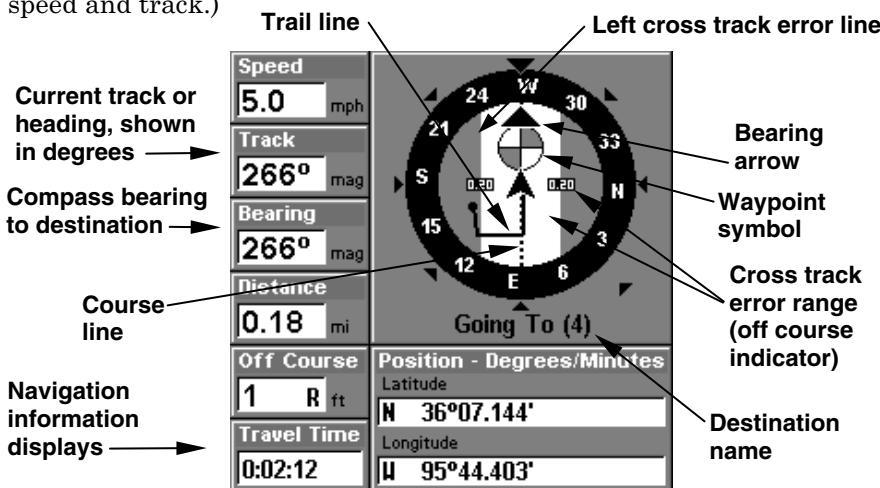
The Off Course window shows the current cross track error. This shows the distance you are off-course to the side of the desired course line. The course line is an imaginary line drawn from your position when you started navigating to the destination waypoint. The course line is shown on the Navigation Page screen (and the Map Page screen) as a dotted line.

The cross track error range is shown on the compass rose as a wide, white, corridor enclosing the course line. The outer edges of this white corridor represent lines that show the current cross track error range. The default for the cross track error range is 0.20 mile.

For example, if the present position symbol touches the right cross track error line, then you are .20 mile to the right of the desired course. You need to steer left to return to the desired course. You can use the **ZIN** or **ZOUT** keys to change the cross track error range.

A circular symbol depicting your destination (waypoint) appears on the screen as you approach the waypoint, as shown on the screen on the next page.

Travel Time is the time that it will take to reach your destination at your present closing speed. (You can also customize the time window to show Arrival Time instead. Arrival Time is the local time it will be when you arrive at the destination, based upon your present closing speed and track.)



Navigation Page, backtracking a trail while creating a new trail.

In the example figure above, the driver is headed west (a 266° track) toward a waypoint 266° (bearing) away. The cross track error range (white corridor) is 0.20 miles either side of the course. The driver is headed toward trail waypoint 4, which is 0.18 miles away. The vehicle is virtually on course (off course 1 foot to the right). Traveling at a speed of 5 mph, the driver will arrive at the waypoint in 2 minutes and 12 seconds.

The Navigation Page has its own menu, which is used for some advance functions and for setting various options. (Options and setup are discussed in Sec. 5.) To access the Navigation Page Menu, from the Navigation Page, press **MENU**.

Map Page

The Map Page screens show your course and track from a "bird's-eye" view. By default, this unit shows the map with north always at the top of the screen. (This can be changed. See the topic *Map Orientation*, in Section 5.) If you're navigating to a waypoint, the map also shows your starting location, present position, course line and destination. You don't have to navigate to a waypoint, however, to use the map.

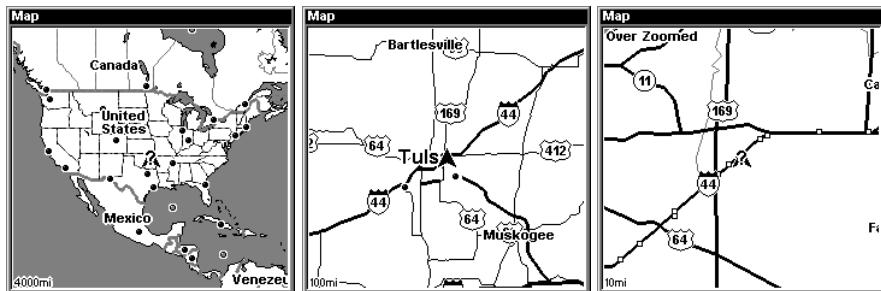
Map Page is the default screen that appears when you turn on the unit. To get to the Map Page from another page: Press **PAGES** | → or ← to

MAP | EXIT. When the Map Page is displayed, a screen similar to those on the next page appears.

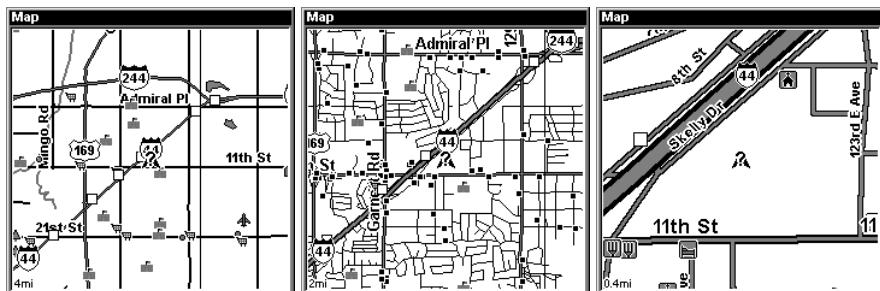
The arrow in the center of the screen is your present position. It points in the direction you're traveling. The solid line extending from the back of the arrow is your plot trail, or path you've taken.

The map zoom range is the distance across the screen. This number shows in the lower left corner of the screen. In the first example figure below, the range is 4,000 miles from the left edge of the map to the right edge of the map.

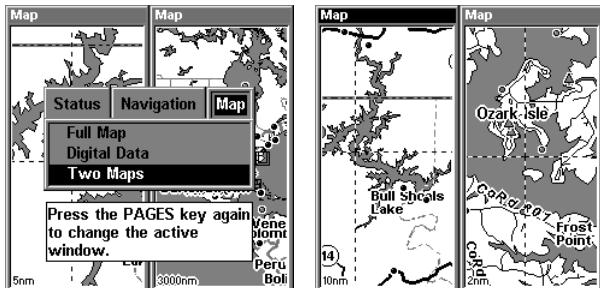
The Zoom In and Zoom Out keys zoom the map to enlarge or reduce its coverage area and the amount of mapping detail shown. There are 37 available map zoom ranges, from 0.05 miles to 4,000 miles.



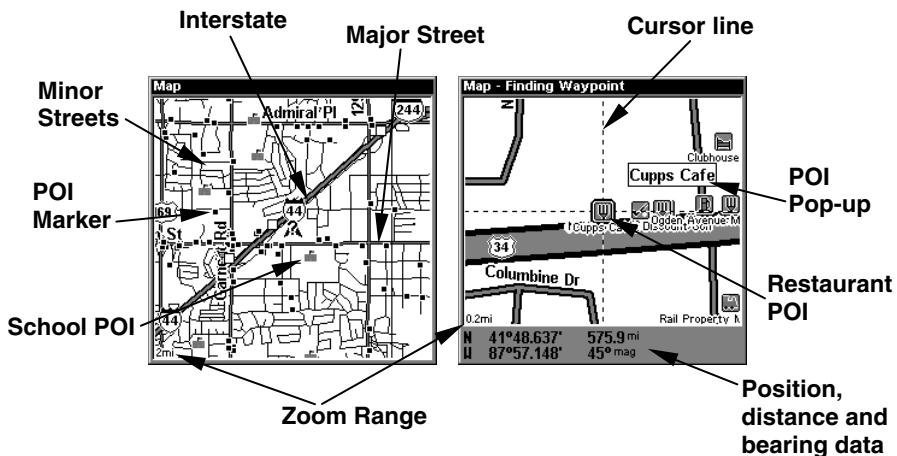
Far left, Map Page opening screen. Center, zoomed to 100 miles and right, zoomed to 10 miles. Over Zoomed means you have reached the detail limits in an area covered only by the basic background map. Zooming in any closer will reveal no more map details because a high-detail custom map has not been loaded on the MMC for this area.



Map Pages with high-detail map of an urban area loaded on the MMC. At left, arterial streets appear at the 4 mile zoom range, with a few Point of Interest icons visible. Center, numerous dots representing Points of Interest become visible at the 2 mile range, along with minor streets. Right, at the 0.4 mile zoom, you can see an interstate highway with an exit, major and minor streets as well as Point of Interest icons.



Pages Menu with Two Map option selected, left.
Map Page with two map windows, at right. The left map is active.



When the map is zoomed out far enough, most POIs appear as square dots. As you zoom in closer, the symbols become readable icons. In the 0.2 mile zoom example at right, the cursor has selected the Cupps Café POI, which triggers a pop-up box with the POI name. This pop-up box works on POIs at any zoom range.

The Map Page has its own menu, which is used for several functions and for setting various options. (Options and setup are discussed in Sec. 5). To access the Map Page Menu, from the Map Page, press **MENU**.

The Pages Menu also offers several map display options under the Map Page category. To access them, press **PAGES** | \leftarrow or \rightarrow to **MAP** | \downarrow to *Option* | **EXIT**. One of the options is showing two maps at the same time in different windows.

In pages that have two major windows (such as two maps) you can toggle back and forth between the two windows by pressing **PAGES | PAGES**. This allows you to change which map your cursor moves on, and which map the menu operates on. A black title bar denotes the active window.

The following page contains a 12-step quick reference for the most basic GPS operations. If you don't want to carry the manual with you as you practice with LMS-240, you might consider photocopying this quick reference page and tucking it into your pocket.

LMS-240 GPS Quick Reference

Start outdoors, with a clear view of the open sky. As you practice, try navigating to a location at least a few blocks away. While you're learning, navigation in too small an area will constantly trigger arrival alarms.

1. Connect the unit to electric power and the antenna module. Make sure the MMC is in. (See complete installation details beginning on page 11.)
2. To turn on LMS-240, press and release **PWR** key.
3. Opening screen displays map of North America at the 4,000 mile zoom range. Rotate through the four main Page screens (Map Page, Satellite Status Page, Navigation Page and Sonar Page) by pressing **PAGES** | ← or → to select *Page Name* | **EXIT**. Switch Pages to display Satellite Status Page.
4. Wait while unit locates satellites and calculates current position. Process is visible on Satellite Page. This takes an average of 1 minute or less under clear sky conditions (unobstructed by terrain or structures.) When the unit acquires position, a tone sounds and a position acquired message appears.
5. With position acquired, press **PAGES** key to display Map Page, which shows a bird's eye view of the earth. You can move around the map by:

Zoom in closer to see greater detail: press **ZIN** (zoom in key.)

Zoom out to see more area, less detail: press **ZOUT** (zoom out key.)

Scroll map north, south, east or west using arrow keys ↑ ↓ → ← .

To stop scrolling and return to current position on map, press **EXIT** key.

6. Set a waypoint (*Wpt 001*) at your current position so you can navigate back here: press **WPT** | **WPT**. Waypoint symbol and "001" appears.
7. Zoom/scroll map to find a nearby object or location to go to. Use arrow keys to center cursor cross-hair over the map object or location.
8. Navigate to the selected destination: press **MENU** | **ENT** | **EXIT**. Follow dotted course line on Map Page or compass bearing arrow on Navigation Page.
9. At destination, Arrival Alarm goes off; to clear it, press **EXIT**. Cancel navigation: press **MENU** | **MENU** | ↓ to **CANCEL NAVIGATION** | **ENT** | ← to **YES** | **ENT**.
10. Return to Wpt 1 by Navigate To Waypoint or Backtrack Trail. **To Waypoint**: press **WPT** | → to **SAVED** | **ENT** | **ENT** | **ENT**. Use ↑ or ↓ to select *Wpt 001*, press **ENT** | **ENT**; follow navigation displays. **Trail**: press **MENU** | **MENU** | ↓ to **MY TRAILS** | **ENT**. Press ↓ to *Trail 1* | **ENT** | → | ↓ to **NAVIGATE** | **ENT** | → to **ACTION** | **ENT** | → to **REVERSE** | **ENT** | ← to **NAVIGATE** | **ENT**. (If arrival alarm sounds, press **EXIT**.) Follow navigation displays.
11. Back home, Arrival Alarm goes off; press **EXIT**. Cancel navigation: press **MENU** | **MENU** | ↓ to **CANCEL NAVIGATION** | **ENT** | ← to **YES** | **ENT**.
12. To turn off LMS-240, press and hold **PWR** key for three seconds.

Find Your Current Position

Finding your current position is as simple as turning LMS-240 on. Under clear sky conditions, the unit automatically searches for satellites and calculates its position in approximately one minute or less.

NOTE:

"Clear sky" means open sky, unobstructed by terrain, dense foliage or structures. Clouds do not restrict GPS signal reception.

If for some reason satellite acquisition takes longer, you may be inside a structure or vehicle or in terrain that is blocking signal reception. To correct this, be sure you are positioned so that the unit's antenna module has as clear a view of the sky as possible, then turn the unit off and back on again.

Moving Around the Map: Zoom & Cursor Arrow Keys

The map is presented from a bird's eye view perspective. The current zoom range shows in the lower left corner of the screen.

1. Press the **ZIN** key (zoom in) to move in closer and see greater detail in a smaller geographic area.
2. Press the **ZOUT** key (zoom out) to move farther away and see less map detail, but a larger geographic area.

When you are traveling, the map will automatically move as you move. This keeps your current location roughly centered on the screen.

You can manually pan or scroll the map northward, southward, eastward or westward by using the arrow keys, which launch the cross-hair map cursor. This allows you to look at map places other than your current position. To clear the cursor, press **EXIT**, which jumps the map back to the current position or the last known position.

Tip:

Use the cursor to determine the distance from your current position (or last known position, when working indoors) to any map object or location. Simply use the arrow keys to position the cursor over the object or place. The distance, measured in a straight line, appears in the data box at the bottom of the map. Press **EXIT** to clear the cursor.



The selected airport to the northwest is 4.2 miles away.

Selecting Any Map Item With the Cursor

1. Use the zoom keys and the arrow keys to move around the map and find the item you wish to select.
2. Use the arrow keys and center the cursor cross-hair on the desired object. On most items, a pop-up box will give the name of the selected item.

Searching

Now that you've seen how LMS-240 can find where *you* are, let's search for something somewhere else. Searching is one of the most powerful new features in the Lowrance GPS product line.

In this example, we'll look for the *nearest* fast-food restaurant. For more information on different types of searches, refer to *Section 6, Searching*.

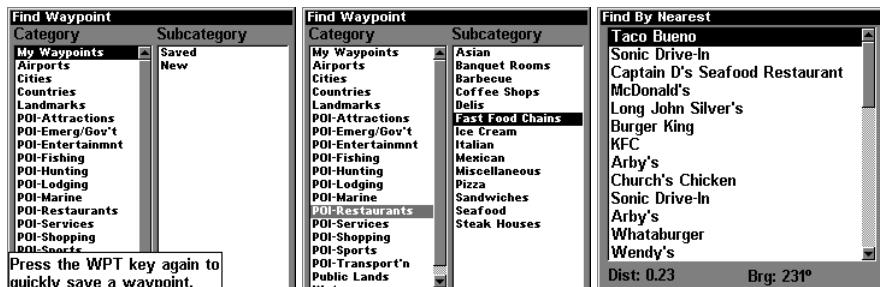
NOTE:

This example requires the Point of Interest (POI) database included with MapCreate 6.

After LMS-240 has acquired a position:

1. Press **WPT** | **↓** to **RESTAURANTS**.
2. You could search the entire restaurant category, but in this example we will narrow our search. Press **→** to **SUBCATEGORY** column | **↓** to **FAST FOOD CHAINS** | **ENT** | **↓** to **NEAREST** | **ENT**.

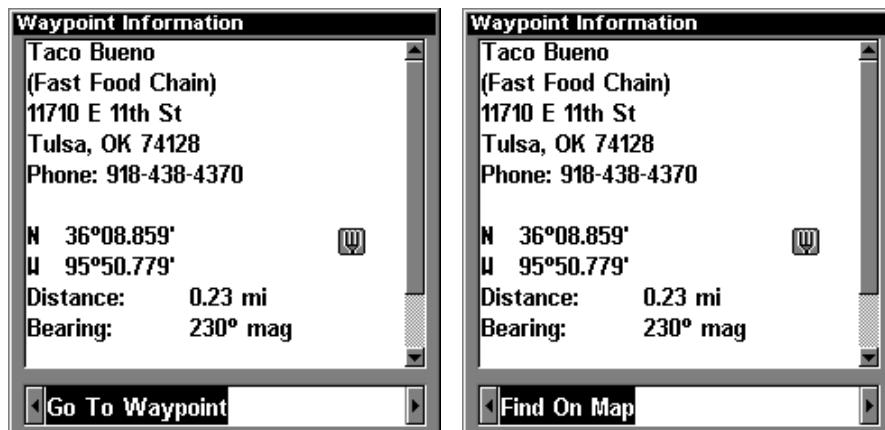
3. LMS-240 says it is calculating, then a list of restaurants appears, with the closest at the top of the list, and the farthest at the bottom of the list. The nearest is highlighted.



Find Waypoint Menu, left; Category Selection menu, center; and list of the nearest restaurants, right.

4. If you wish, you could scroll \uparrow or \downarrow here to select another restaurant, but for now we will just accept the nearest one. Press **ENT**.

5. The POI information screen appears. (This is how you can use LMS-240 as a business phone directory!) If you wanted to navigate there, you could press Enter, since the Go To Waypoint command is highlighted. But we just want to see it on the map, so press \rightarrow to **FIND ON MAP | ENT**.



POI information screen on fast food restaurant nearest this position. Screen shows name, street address, phone number, latitude/longitude, distance to restaurant and its compass bearing. Figure at left shows Go To Waypoint command; right figure shows Find On Map command.

6. LMS-240's map appears, with the cross-hair cursor highlighting the restaurant's POI symbol. A pop-up name box identifies the POI. A data box at the bottom of the screen continues to display the location's latitude and longitude, distance and bearing.



Map screen showing Finding Waypoint,
the result of a restaurant search.

7. To clear the search and return to the last page displayed, press **EXIT | EXIT | EXIT | EXIT**. (Before you completely exited out of the Search menus, you could have gone looking for another place.)

NOTE:

Search works from mapping and POI data loaded in LMS-240. If you do not have a high-detailed custom map (containing POI data) for the area you are searching loaded on the MMC, you may not find anything.

Set a Waypoint

A waypoint is simply an electronic "address," based on the latitude and longitude of a position on the earth. A waypoint represents a location, spot, or destination that can be stored in memory, then be recalled and used later on for navigation purposes.

You can create a waypoint at the cursor position on the map, or at your current position while you are navigating. You can create a waypoint at any location by manually entering the position's latitude and longitude. You can copy waypoints from your unit to your personal computer with MapCreate software. When you want to repeat a trip, these archived waypoints can be reloaded into your GPS unit.

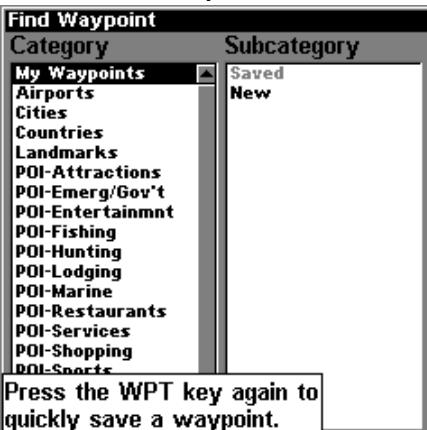
To create and save a Waypoint:

These first two techniques use the Quick Save method, the fastest and easiest way to create a waypoint.

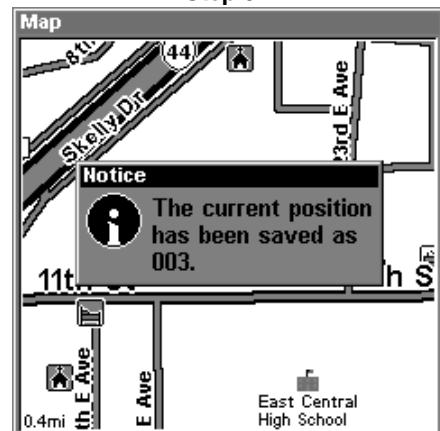
Create Waypoint at Current Position

1. While you are traveling, press **WPT | WPT**. The waypoint is saved and automatically given a name with a sequential number, such as "waypoint 003." The waypoint symbol and number appear on the map.

Step 1.



Step 3.



Sequence for setting a waypoint. Step 1: while traveling, *quickly* press **WPT twice** to call up Find Waypoint screen (seen in Step 2) and set a point. Step 3: a message says the waypoint has been saved. Step 4: vehicle continues on its way; number waypoint symbol is visible on map.

Create Waypoint on Map

1. Use the arrow keys to move the cursor to the place where you want to make a waypoint.
2. Press **WPT | WPT**. The waypoint is saved and automatically given a name with a sequential number, such as "waypoint 001." The waypoint symbol and number appear on the map.

Create Waypoint by Entering a Position

1. Press **WPT | →** to **SUBCATEGORY** column | **↓** to **NEW | ENT**.
2. Press **↓** to **ENTERED POSITION | ENT | →** to **CREATE | ENT**.
3. Press **→** to **LATITUDE | ENT**. Enter the latitude by pressing **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the latitude is correct. Press **ENT**.
4. Press **↓** to **LONGITUDE | ENT**. Enter the longitude by pressing **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the longitude is correct. Press **ENT**, then **EXIT | EXIT** to return to the previous page display. The waypoint is saved and automatically given a name with a sequential number, such as "waypoint 001." The waypoint symbol and number appear on the map and in the waypoint list.

Navigate To a Waypoint

You can select any waypoint visible on the Map Page with the cursor, then use the Navigate to Cursor command (we'll describe how later in this section.) However, you can avoid scrolling the map to pick your waypoint if you use the Find Waypoint commands:

1. Press **WPT | →** to **SAVED | ENT**. To look up the nearest waypoint, press **↓** to **NEAREST | ENT**; or, to look by name (and scroll through the entire waypoint list), press **ENT**. For this example, look by name.
2. If your waypoint list is a long one, you can spell out the waypoint name in the **FIND BY NAME** box to search for it. (Press **↑** or **↓** to change the first character, then press **→** to move the cursor to the next character and repeat until the name is correct, then press **ENT** to jump to the list below.)
3. If the list is short, you can jump directly to the **FIND IN LIST** box by pressing **ENT**. Use **↑** or **↓** to select the waypoint name, press **ENT** and the waypoint information screen appears with the **Go To** command selected.
4. To begin navigating to the waypoint, press **ENT**.



Navigation Page, navigating toward waypoint 002 and leaving a trail.

Set Man Overboard (MOB) Waypoint

One of boating's most terrifying events is having a friend or family member fall overboard. This situation can be deadly on any body of water — fresh or salt. It's particularly dangerous at night or if you're out of sight of land. Of course, the first thing to do is remain calm and then use all standard safety procedures to rescue the person.

This unit has a man overboard feature that shows navigation data to the location where the feature was activated. To activate it, press the **ZOUT** and **ZIN** keys at the same time. Your position at the time these keys are pressed is used as the man overboard position.

Caution:

Saving a new "Man Overboard" waypoint will overwrite and erase the previous "Man Overboard" waypoint.

Navigate Back to MOB Waypoint

Find your way back to the accident position with the Navigation Page or Map Page. When MOB is activated, the Navigation Page automatically shows the compass rose with its bearing arrow pointing toward the man overboard position, and the destination name says "Going To Man Overboard." The Map Page displays a Man Overboard waypoint, represented by a human figure, and the steering arrow points where to steer to reach that position.



Navigating to Man Overboard: Navigation Page, left, and Map Page, right. The victim is astern of the vessel; the GPS shows which direction to steer to for the rescue.

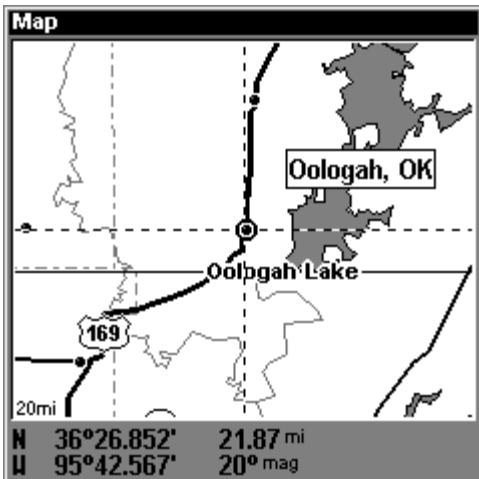
The man overboard position is also stored in the waypoint list for future reference. It can be edited the same as any other waypoint in Advanced Mode. This prevents the inadvertent loss of the current Man Overboard position.

To cancel navigation to MOB, press **MENU | MENU | ↓** to **CANCEL NAVIGATION | ENT | ←** to **YES | ENT**. LMS-240 stops showing navigation information.

Navigate to Cursor Position on Map

The **Go To Cursor** command: navigates to the current cursor position on the map. It's a quick and handy way to navigate to anything you can see on the map display.

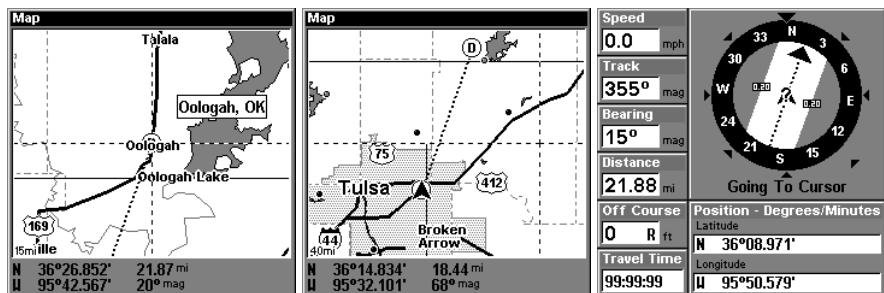
1. Use the cursor (controlled by the arrow keys) with the zoom in and zoom out keys to maneuver around the map until you find a location you want to go to.
2. Center the cursor over the location to select it. See the example below. (Many map items such as waypoints, Points of Interest, towns, etc. can be "selected," and appear "highlighted" with a pop-up box. Other features, such as a river or a street intersection will not appear "highlighted," but the cursor will take you to those locations just the same.)



Navigate to cursor. In this example, the cursor has selected the town of Oologah, Oklahoma.

3. Press **MENU | ENT** and LMS-240 will begin navigating to the cursor location.

The Map Page will display a dotted line from your current position to the cursor position. The Navigation Page displays a compass rose showing navigation information to your destination. See examples below.



The 15-mile zoom figure at left clearly shows the dotted course line connecting your current position to your destination. The 40-mile zoom, center, shows both current position and destination on screen.

The Navigation Page, right, will also show navigation information.

To stop navigating to the cursor, use the Cancel Navigation command: press **MENU | MENU | ↓ to CANCEL NAVIGATION | ENT | ← to YES | ENT**. LMS-240 stops showing navigation information.

Navigate to a Point of Interest

For POIs that are in view on the map, you can easily use the Navigate to Cursor command above; just use the cursor to select the POI.

The other method involves searching for POIs with the Find Waypoint command, launched with the **WPT** key. (See the searching example earlier in this section, or turn to Sec. 6, *Searching*, for detailed instructions on POI searches.)

After you have looked up an item with the Find Waypoint command, use the **←** to make sure the **Go To** command is highlighted at the bottom of the screen, then press **ENT**. LMS-240 begins showing navigation information to the item.

To cancel navigation, press **MENU | MENU | ↓** to **CANCEL NAVIGATION | ENT | ←** to **Yes | ENT**. LMS-240 stops showing navigation information.

Creating and Saving a Trail

A trail, or plot trail, is a string of position points plotted by LMS-240 as you travel. It's a travel history, a record of the path you have taken. Trails are useful for repeating a journey along the same track. They are particularly handy when you are trying to retrace your trip and go back the way you came. On the screen, trails are represented by a solid line extending from the back of the current position arrow.

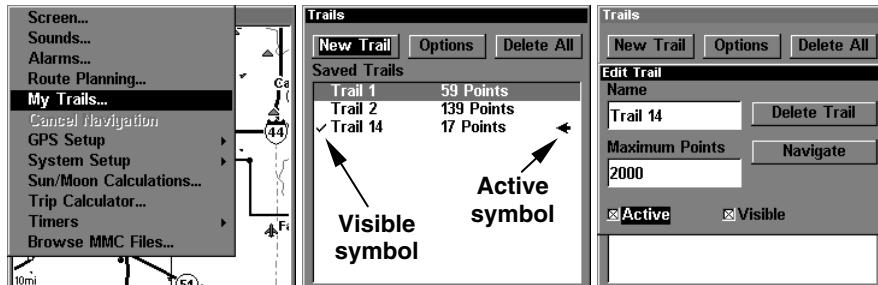
LMS-240 is set at the factory to automatically create and record a trail while the unit is turned on. The unit will continue recording the trail until the length reaches the maximum trail point setting (default is 2,000, but the unit can record trails 9,999 points long). When the point limit is reached, LMS-240 begins recording the trail over itself.

By default, the trail flashes once a second, making it easier to see against the background map. With the default auto setting, LMS-240 creates a trail by placing a dot (trail point) on the screen every time you change directions. (The methods used for creating a trail and the trail update rate can both be adjusted or even turned off. See Section for 5 for *Trail Options*.)

To preserve a trail from point A to point B, you must :"turn off" the trail by making it *inactive* before heading to point C or even back to point A. When the current trail is set inactive, LMS-240 *automatically* creates and begins recording a new trail.

To Save a Trail

1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT**.



Sequence for saving a trail and beginning a new one. At left, My Trails command. Center, the Trails Menu. The arrow to the right of Trail 14 indicates the trail is "active," and the check to the left indicates the trail is visible on the map display. The right figure shows the Edit Trail menu, with the Active command selected.

2. Press ↓ to the *Active Trail Name* | ENT.
3. Press ↓ to **ACTIVE** | ENT.
4. To return to the previous page, press **EXIT** | **EXIT** | **EXIT** | **EXIT**. As you left the Edit Trail menu, you will notice that a new trail was started with a new sequential number. In the example figure below, the new trail is number 15, showing zero points. Note that Trail 14 is inactive, but it is still visible on the map.



New trail, named "Trail 15," is created when Trail 14 is made inactive. Any new travel will be recorded in this trail, which is active and visible. Trails do not need to be visible in order to be active.

You can save and recall up to 10 different plot trails, which can also be copied to your MMC for archiving.

Tip:

Another quick way to stop recording one trail and begin a new one

is to use the New Trail command: Press **MENU | MENU | ↓** to **MY TRAILS | ENT | ENT**.

Caution:

You also have the option of completely turning off trail recording, under the trail Options command. However, if the Update Active Trail option is left turned off, it will cancel the automatic trail creation feature.

Displaying a Saved Trail

The active trail is automatically displayed on the map (the "Visible" option) with the factory default settings. You can selectively turn trail display off and on for any saved or active trail. In the Saved Trails List, visible trails have a check mark in front of the trail name.

To turn off trail display:

1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT**.
2. Press **↓ | ↓** to enter the Saved Trail list, then use **↑** or **↓** to select the desired **Trail Name | ENT**.
3. Press **↓** to **ACTIVE | →** to **VISIBLE | ENT**. To return to the previous page, press **EXIT | EXIT | EXIT | EXIT**.

To turn on trail display:

1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT**.
2. Press **↓ | ↓** to enter the Saved Trail list, then use **↑** or **↓** to select the desired **Trail Name | ENT**.
3. Press **↓** to **ACTIVE | →** to **VISIBLE | ENT**. To return to the previous page, press **EXIT | EXIT | EXIT | EXIT**.

Navigating Trails

There are three methods for following a trail: visual trailing, navigating a trail (forward) and backtracking a trail (backward). Try each method to see which you prefer.

Visual trailing is the simplest method. It uses only the Map Page and requires no menu commands at all. The technique works the same if you are running a trail forward (from start to end) or backward (from end to start.) However, visual trailing provides no navigation information during the trip, such as the time to your destination.

The other two methods provide a full range of navigation data and work with both the Map Page and Navigation Page. The only difference between them is "navigating a trail" follows a trail forward (from start to

end) while "backtracking" follows a trail in reverse (from end to start.)

When hiking at walking speed, we often just use visual back trailing because it is better at following each little turn on a foot path. At faster speeds, such as the highway or on the water, the Navigate Trail and Backtrack Trail commands are handy.

Visual Trailing

1. On the Map Page, zoom (**ZIN** or **ZOUT**) so your flashing trail is visible.
2. Begin moving and watch the Map Page. Simply walk or steer so that your current position arrow traces along the trail you have just made.

Tip:

Generally, when using this method, the smaller the zoom range, the more accurately you will be able to steer along the trail.

Navigate a Trail (forward)

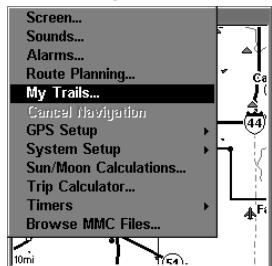
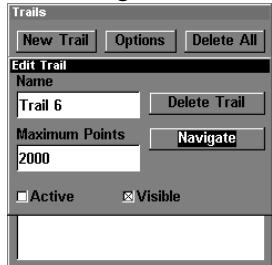
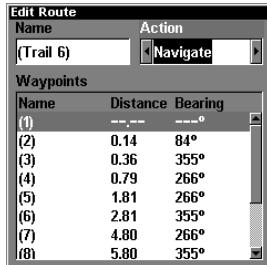
Figures depicting the menu sequence for navigating a trail appear on the next page.

1. Press **MENU | MENU | ↓ to MY TRAILS | ENT.**
2. Press **↓ | ↓** to enter the Saved Trail list, then use **↑** or **↓** to select the desired *Trail Name* | **ENT.**
3. Press **→** to **DELETE TRAIL | ↓ to NAVIGATE | ENT.**
4. Press **→** to **ACTION | ENT | ENT.** The unit begins showing navigation information along the trail.

NOTE:

If you are already located at or near the beginning of your trail, the arrival alarm will go off as soon as you hit Enter. Just press **EXIT** to clear the alarm and proceed.

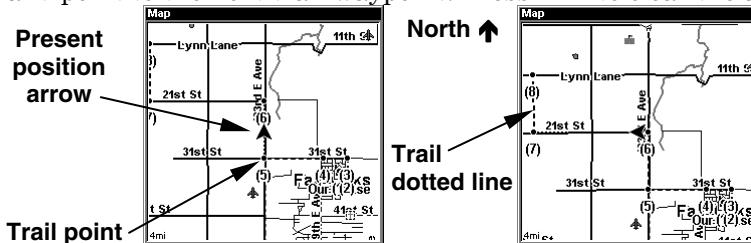
5. Now, begin moving and follow your LMS-240.
6. When you reach your destination, be sure to cancel your navigation: press **MENU | MENU | ↓ to CANCEL NAVIGATION | ENT.** LMS-240 asks if you're sure; press **← | ENT.**

Figure 1.**Figure 2.****Figure 3.****Figure 4.**

Navigate a trail menu sequence: Fig. 1, My Trails command. Fig. 2, Trails Menu. Fig. 3, Edit Trail Menu. Fig. 4, Edit Route Menu with Navigate command highlighted for Trail 6. A trail is always converted to a "route" when you navigate the trail.

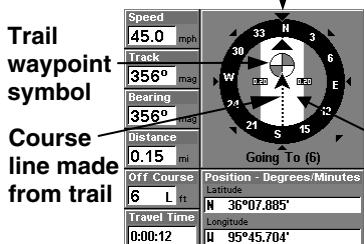
On the Map Page, the trail you are navigating is represented by a dotted line that alternates with a flashing solid line. The Navigation Page will also show the navigated trail as a dotted line. The bearing arrow on the compass rose points to the next waypoint on the trail.

As you travel, the arrival alarm will go off when you near a trail waypoint, and the bearing arrow on the compass rose will swing around and point to the next trail waypoint. Press **EXIT** to clear the alarm.



Navigate trail, map views: at left driver is northbound heading straight toward trail point 6. At right, northbound driver has reached point 6 and has turned west to follow trail.

Track or compass heading indicator

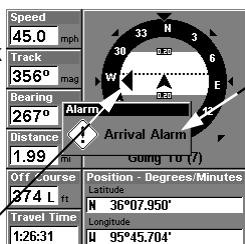


Trail
waypoint
symbol

Course
line made
from trail

Cross track
error range
(off course
indicator)

Bearing
arrow



Arrival
alarm

Navigate trail, navigation page (compass rose) views: at left, driver is northbound heading straight toward trail point 6; bearing arrow shows the trail point is due north (straight ahead.) At right, driver has reached trail point 6 and must turn west to follow the trail. Arrival alarm goes off and bearing arrow swings around to say turn left (west), toward the next waypoint, trail point 7. LMS-240 now shows navigation information to point 7, which is 1.99 miles away.

Navigate a Back Trail (backtrack, or reverse)

1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT**.
2. Press **↓ | ↓** to enter the Saved Trail list, then use **↑** or **↓** to select the desired *Trail Name* | **ENT**.
3. Press **→** to **DELETE TRAIL | ↓** to **NAVIGATE | ENT**.
4. Press **→** to **ACTION | ENT** | **→** to **REVERSE | ENT** | **←** to **NAVIGATE | ENT**. The unit begins showing navigation information along the trail, in reverse.

NOTE:

If you are already located at or near the end of your trail, the arrival alarm will go off as soon as you hit Enter. Just press **EXIT** to clear the alarm and proceed.

5. Now, begin moving and follow your LMS-240.
6. When you reach your destination, be sure to cancel your navigation: press **MENU | MENU | ↓** to **CANCEL NAVIGATION | ENT**. LMS-240 asks if you're sure; press **← | ENT**.

Transfer Custom Maps and GPS Data Files

Custom Maps:

Custom maps work only from the MMC card or SDC card. When a card containing a Custom Map File is loaded into the unit, LMS-240 automatically loads the map into memory when the unit is turned on.

Instructions for copying Custom Map Files to an MMC are contained in the instruction manual for your MMC card reader and MapCreate 6

software. For instructions on inserting an MMC into LMS-240, see *Section 2, Installation/Accessories*.

NOTE:

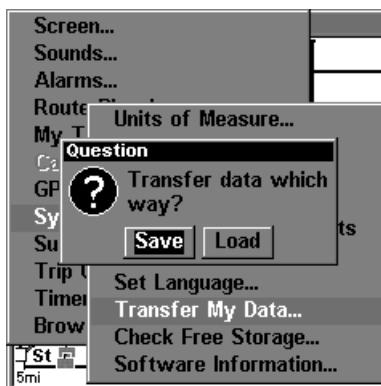
To load a Navionics® chart, see Sec. 5 for the entry *Navionics Charts*.

GPS Data files:

GPS Data Files contain waypoints, routes, trails and event marker icons. Instructions for copying GPS Data Files between your computer and an MMC are contained in the instruction manual for your MMC card reader and MapCreate 6 software.

GPS data automatically recorded in the unit's internal memory must be saved to the MMC (as a GPS Data File) in order to store it on your personal computer. GPS Data Files stored on an MMC must be copied from the card to LMS-240's internal memory before the unit can read them. Here's how:

1. Insert the MMC into your unit. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ↓** to **TRANSFER MY DATA | ENT** and the screen below appears.



The Transfer My Data submenu asks if you want to save data to the MMC or load data from the MMC into LMS-240's memory.

2. The Transfer My Data menu includes a message which tells you if an MMC is present or not. If no MMC is present, you must first insert a card into LMS-240 in order to activate the Load or Save commands.

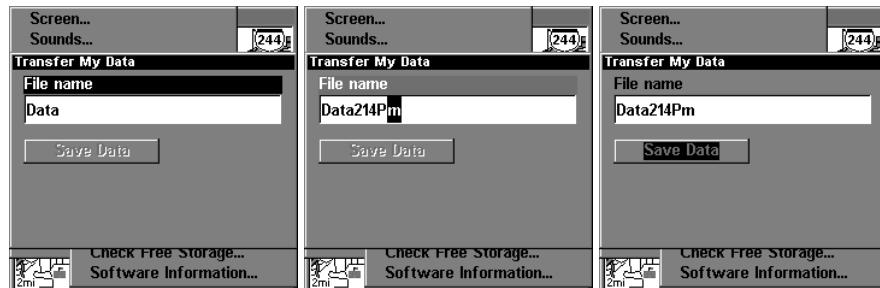
To transfer data *from LMS-240 to the MMC*: press **ENT** (for **SAVE**.)

To transfer data *from the MMC to LMS-240*: press **→** to **LOAD | ENT**.

3. **Saving to MMC:** To accept the default name "Data" for the GPS Data File, press **↓** to **SAVE DATA | ENT**. If you wish to rename the file (as in the example on the next page), press **ENT** to activate the selection

box. Press \uparrow or \downarrow to change the first character, then press \rightarrow to the next character and repeat until the name is correct. Then, press **ENT** | \downarrow to **SAVE DATA | ENT**.

The unit will display first a progress then a completion message when the data transfer is finished. To return to the Page view, repeatedly press **EXIT**.



From left to right, these figures show the menu sequence for naming and saving a GPS Data File from LMS-240's memory to an MMC.

4. Loading to unit memory: There may be more than one GPS Data File (*.USR) on the card. To select a file, press **ENT** to activate the selection box, use \downarrow or \uparrow to highlight the file, then press **ENT** to accept the selection. Next, press \downarrow to **LOAD | ENT**. The unit will display a completion message when the data transfer is finished. To return to the Page view, press **EXIT | EXIT | EXIT | EXIT**.

Figure 1.

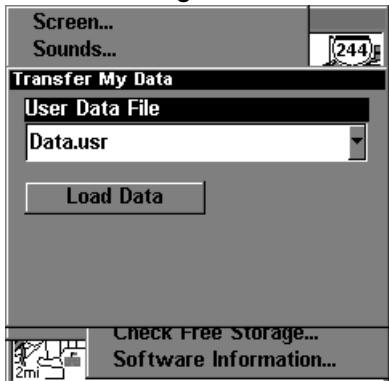


Figure 2.



Figure 3.

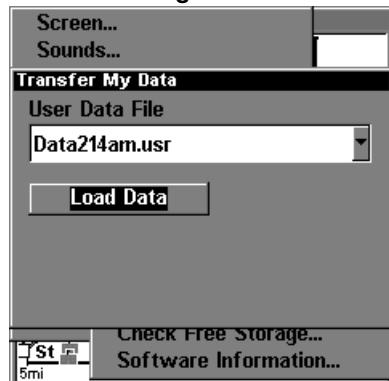


Figure 4.



These figures show the menu sequence for loading a GPS Data File from an MMC into LMS-240's memory.

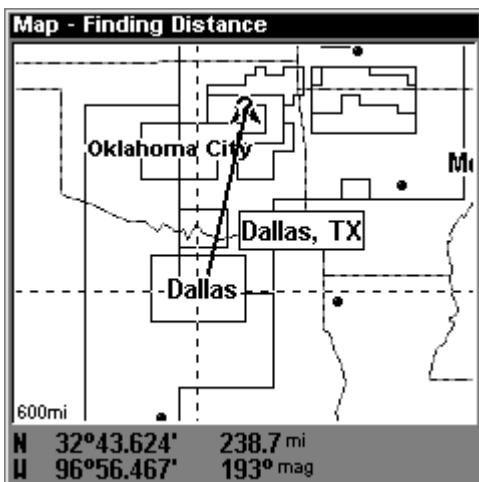
Cancel Navigation

You can turn off any of the navigation commands after you reach your destination or at any other time by using the Cancel Navigation command. Press **MENU** | **MENU** | **↓** to **CANCEL NAVIGATION** | **ENT** | **←** to **YES** | **ENT**.

Section 7: Advanced GPS Operations

Find Distance From Current Position To Another Location

1. While on the Map Page press: **MENU** | **↓** to **FIND DISTANCE** | **ENT**.
2. Center your cursor over the position you want to find the distance to. A rubber band line appears, connecting your current position to the cursor's location. The distance along that line will appear in the lower portion of the screen.
3. Press **EXIT** to return to regular operation.



The distance to Dallas from the starting point is 238.7 miles.

Find Distance From Point to Point

You can also measure distance between two other points on the map.

1. While on the Map Page press: **MENU** | **↓** to **FIND DISTANCE** | **ENT**.
2. Center your cursor over the first position. (A rubber band line appears, connecting your *current* position to the cursor's location.) Press **ENT** to set the first point, and the rubber band line disappears.
3. Move the cursor to the second position. The rubber band line reappears, connecting the first point you set to the cursor. The distance along that line will appear in the lower portion of the screen.
4. Press **EXIT** to clear the command and return to the page screen.

Icons

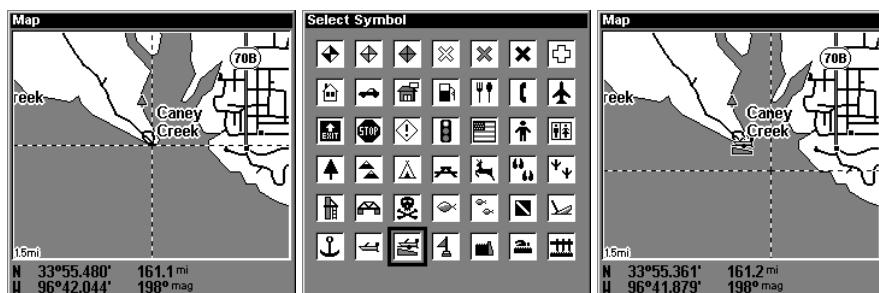
Icons are graphic symbols used to mark some location, personal point of interest or event. They can be placed on the map screen, saved and recalled later for navigation purposes. These are sometimes referred to as event marker icons. LMS-240 has 42 different symbols you can pick from when creating an icon.

Icons are similar to waypoints, but they do not store as much information (like names) as waypoints do. You can't use a menu to navigate to icons as you can with waypoints. (But, you *can* use the map cursor and navigate to any icon on the map.)

You can create an icon at the cursor position on the map, or at your current position while you are navigating.

Create Icon on Map

1. Use the arrow keys to move the cursor to the place where you want to make an icon.
2. Press **ENT** and the screen shows a "Select Icon Symbol" menu.
3. Press \leftarrow or \uparrow or \rightarrow or \downarrow to select your icon symbol, then press **ENT**. The icon appears on the map.



Cursor selects icon location, left; Select Icon Symbol menu, center; Boat Ramp icon on map, right. (Cursor has been moved for clarity.)

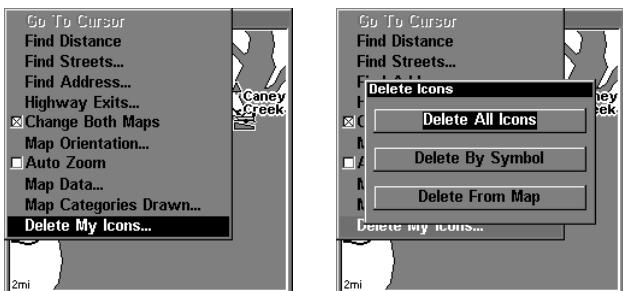
Create Icon at Current Position

1. While you are traveling, press **ENT** and the screen shows a "Select Icon Symbol" menu.
3. Press \leftarrow or \uparrow or \rightarrow or \downarrow to select your icon symbol, then press **ENT**. The icon appears on the map.

Delete an Icon

You can delete all the icons at one time, you can delete all icons represented by a particular symbol, or you can use the cursor to delete a selected icon from the map.

1. Press **MENU** | **↓** to **DELETE MY ICONS** | **ENT**.
2. Press **↓** to **DELETE ALL ICONS**, **DELETE BY SYMBOL**, or **DELETE FROM MAP** and press **ENT**.



Delete icons menu.

The Delete All Icons command will ask if you are sure. Press **←** to **Yes** | **ENT**. All icons will be deleted from the map.

The Delete by Symbol command will launch the Select Symbol menu. Press **←** or **↑** or **→** or **↓** to select the icon symbol to delete, then press **ENT**. A message appears saying all icons with the selected symbol have been deleted.

The Delete From Map command will prompt you to move the cursor over an icon to select it. After selecting the icon, press **ENT** and it disappears from the map.

Navigate to an Icon

Use the Navigate to Cursor command, and use the cursor to select the desired icon on the map.

1. Use arrow keys to center cursor cross-hair over the icon.
2. To navigate to the selected icon location: press **MENU** | **ENT** | **EXIT**. Follow course line on the Map Page or the compass bearing arrow on the Navigation Page.

Routes

A route is a series of waypoints, linked together in an ordered sequence, that's used to mark a course of travel. You can visualize a route as a string of beads: The beads represent waypoints and the string represents the course of travel connecting waypoint to waypoint.

The course from one waypoint to the next is a leg; routes are composed of one or more legs. The legs of all GPS routes are based on straight lines between waypoints.

A route provides the automatic capability to navigate through several waypoints without having to reprogram the unit after arriving at each waypoint. Once programmed into the GPS unit, a route provides the option of navigating forward through the route waypoints or in reverse order (you can even begin navigating in the middle of a route!)

Create and Save a Route

You have the option of creating and editing a route in the unit, or you can make a route on your computer with our MapCreate 6 software.

PC-created Routes

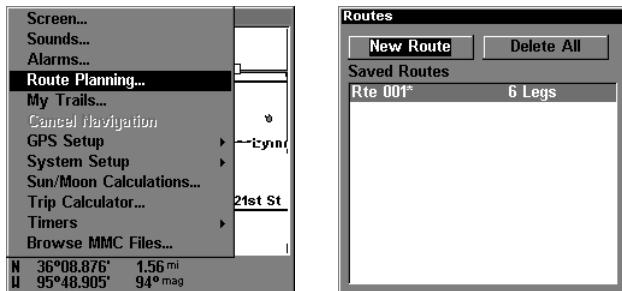
MapCreate is the easiest method for preparing a route, simply because your PC's larger screen, keyboard and mouse are easier to manipulate than the gimbal-mounted LMS-240.

To load a MapCreate route into LMS-240, follow instructions in MapCreate's manual for creating a route and saving it as part of a GPS Data File (file format *.usr). Copy the GPS Data File to an MMC and insert the MMC in LMS-240. (See Section 2 for instructions on installing MMCs. To load the GPS Data File into LMS-240 memory, see the entry on *Transfer Custom Maps & GPS Data Files* in Sec. 3, *Basic Operations*.)

Routes Created in LMS-240

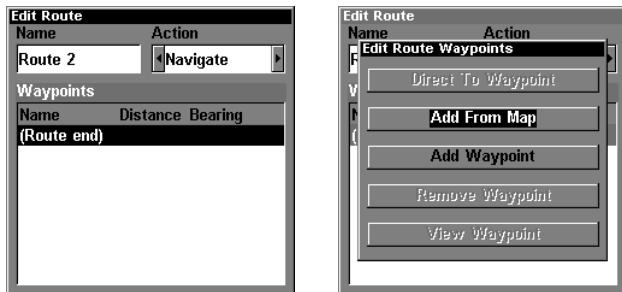
You can create a route by selecting existing waypoints from the waypoint list or you can set a series of route waypoints on the map with cursor arrows and the Enter key. In this example, we'll create a route from the map.

1. From the **NAVIGATION PAGE**, press **MENU | ENT** or from the **MAP PAGE**, press **MENU | MENU | ↓** to **ROUTE PLANNING | ENT**.



**Route Planning command on Main Menu, left,
will open the Route List screen, right.**

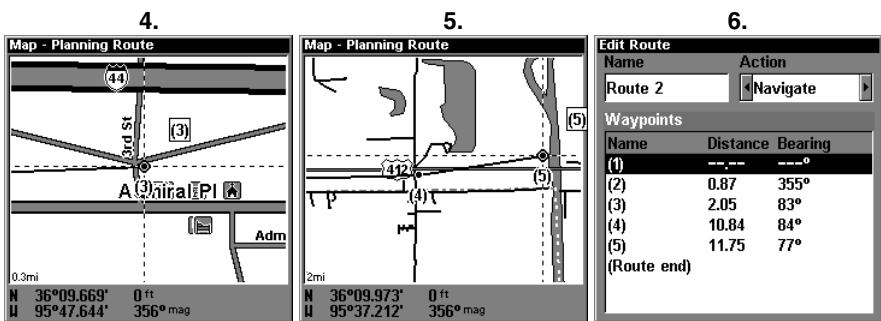
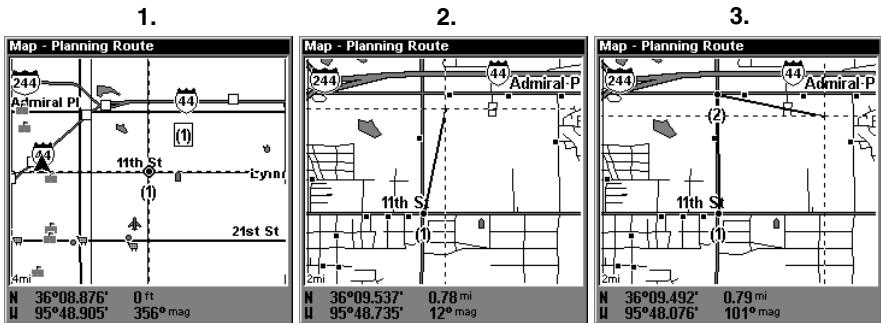
2. Press **ENT** | **↓** to **(ROUTE END)** | **ENT** | **↓** to **ADD FROM MAP** | **ENT**. The Map Page appears with the cursor showing.



**Edit Route menu, left. Edit Route Waypoints menu, right,
with Add From Map command selected.**

3. Use the Zoom keys and arrow keys to move the map and cursor until the cursor is centered on the spot where you want your route to begin. (If you are starting at your current position or the current cursor position, you are already at the starting spot.)

4. Set the first route waypoint: press **ENT**. In this example, we moved to the intersection of 11th Street and 145th E. Ave. to start our route to a public hunting area next to a river. (Creating this example route is illustrated in the figures on the next page.)



5. Move the cursor to the next point in the route, a spot where you need to turn or change direction, and press **ENT** to set the next waypoint.
6. Repeat step five until the route reaches your destination.
7. To save your route, press **EXIT**. LMS-240 reverts to the Edit Route screen, with the route automatically named "Route 1" and stored in LMS-240's internal memory. (In our example, Route 1 already existed, so the unit automatically made "Route 2.")

You can edit the route and run other commands, but if you are finished with the route for now, return to the last page displayed by pressing **EXIT** | **EXIT** | **EXIT** | **EXIT** | **EXIT**.

Delete a Route

1. From the **NAVIGATION PAGE**, press **MENU|ENT** or from the **MAP PAGE** press **MENU|MENU|↓ to ROUTE PLANNING|ENT**.
2. Press **↓** to *route name|ENT*.
3. Press **→** to **ACTION|ENT|→ to DELETE|ENT|← to YES|ENT**.

Tip:

You can also delete all routes at once:

1. From the **NAVIGATION PAGE**, press **MENU|ENT** or from the **MAP PAGE** press **MENU|MENU|↓ to ROUTE PLANNING|ENT**.
2. Press **→** to **DELETE ALL|ENT|← to YES|ENT**.

Edit a Route

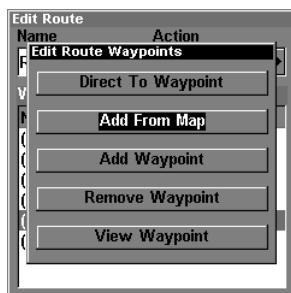
You can edit the route name if you wish.

1. From the **NAVIGATION PAGE**, press **MENU|ENT** or from the **MAP PAGE** press **MENU|MENU|↓ to ROUTE PLANNING|ENT**.
2. Press **↓** to *route name|ENT|ENT*.

3. Press **↑** or **↓** to change the first character, then press **→** to move the cursor to the next character and repeat until the name is correct, then press **ENT**. Return to the previous page by pressing **EXIT|EXIT|EXIT|EXIT**.

You can edit the route by adding and removing waypoints.

1. From the **NAVIGATION PAGE**, press **MENU|ENT** or from the **MAP PAGE** press **MENU|MENU|↓ to ROUTE PLANNING|ENT**.
2. Press **↓** to *route name|ENT|↓ to ROUTE WAYPOINTS LIST*. Use **↓** and **↑** to select a waypoint, then press **ENT**.



Edit Route Waypoints menu.

3. Use **↓** and **↑** to select a command from the **Edit Route Waypoints menu** and press **ENT**. **Add From Map** lets you insert a waypoint in the

route by clicking on a map location with the cursor. Add Waypoint calls up the Waypoint List so you can insert a waypoint from the list. Remove Waypoint will delete the waypoint from the route. View Waypoint will show you where the selected waypoint is on the map.

Navigate a Route

1. From the **NAVIGATION PAGE**, press **MENU | ENT** or from the **MAP PAGE**, press **MENU | MENU | ↓** to **ROUTE PLANNING | ENT**.



Route Planning command on Main Menu, left; Routes menu, center; Edit Route menu, right. Navigate command is selected in the Action box.

2. Press **↓** to select *route name | ENT | →* to **ACTION | ENT | ENT**.
3. Upon arrival at your destination, cancel navigation:
press **MENU | MENU | ↓** to **CANCEL NAVIGATION | ENT | ←** to **YES | ENT**.

Figures on the next page show what the Navigation Page and Map Page look like while navigating a route.

Navigate a Route in Reverse

Here's how you run a route backward, from the end waypoint to the beginning waypoint:

1. From the **NAVIGATION PAGE**, press **MENU | ENT** or from the **MAP PAGE**, press **MENU | MENU | ↓** to **ROUTE PLANNING | ENT**.
2. Press **↓** to select *route name | ENT | →* to **ACTION | ENT | →** to **REVERSE | ENT | ←** to **NAVIGATE | ENT**.
3. Upon arrival at your destination, cancel navigation:
press **MENU | MENU | ↓** to **CANCEL NAVIGATION | ENT | ←** to **YES | ENT**.

Figure 1.



Figure 2.

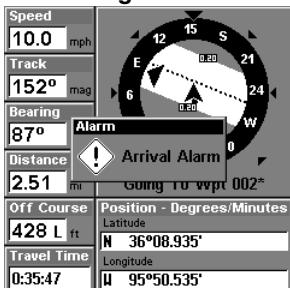
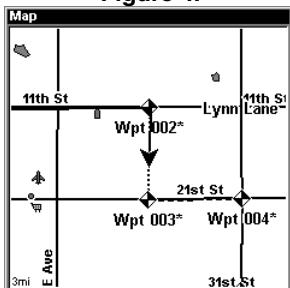


Figure 3.



Figure 4.



Navigating along a route: Fig. 1 shows the Navigation Page at the start of a route, heading straight for the first waypoint (Wpt 1). In Fig. 2, the traveler has arrived at Wpt 1; the arrival alarm has been triggered and the bearing arrow on the compass rose has turned to point toward Wpt 2, off to the east. In Fig. 3 the traveler has turned east on his new course and is heading straight for Wpt 2, which is 2.25 miles away. Fig. 4 shows route navigation on the Map Page. In this figure, the traveler has reached Wpt 2 and is half-way along the leg between Wpts 2 and 3.

Trails

Delete a Trail

This is the command used to erase or delete a trail: Press **MENU** | **MENU** | **↓** to **MY TRAILS** | **ENT** | **↓** to *trail name* | **ENT** | **→** to **DELETE TRAIL** | **ENT** | **←** to **YES** | **ENT**.

Tip:

You can also delete all trails at once:

1. Press **MENU** | **MENU** | **↓** to **MY TRAILS** | **ENT**.
2. Press **→** to **DELETE ALL** | **ENT** | **←** to **YES** | **ENT**.

Edit a Trail Name

To edit a trail name: press **MENU** | **MENU** | **↓** to **MY TRAILS** | **ENT** | **↓** to *trail name* | **ENT** | **ENT**. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the name is correct. Press **ENT**

then **EXIT | EXIT | EXIT | EXIT** to return to the previous page display.

Utilities

Utilities are useful tools for traveling or for outdoor activities.

Alarm Clock

To get to the alarm clock menu: press **MENU | MENU | ↓** to **TIMERS | ENT | ↓** to **ALARM CLOCK | ENT**.

Sun/Moon Rise & Set Calculator

To get to the Sun/Moon menu: press **MENU | MENU | ↓** to **SUN/MOON CALCULATIONS | ENT**.

Trip Calculator

To get to the Calculator menu: press **MENU | MENU | ↓** to **TRIP CALCULATOR | ENT**.

Trip Down Timer

To get to the Down Timer menu: press **MENU | MENU | ↓** to **TIMERS | ENT | ↓** to **DOWN TIMER | ENT**.

Trip Up Timer

To get to the Up Timer menu: press **MENU | MENU | ↓** to **TIMERS | ENT | ENT**.

Waypoints

Delete a Waypoint

To delete a waypoint from the waypoint list: press **WPT | ENT | ENT | ENT | ↓** to *waypoint name* | **ENT | →** to **DELETE WAYPOINT | ENT | ←** to **YES | ENT**. To return to the previous page, press **EXIT | EXIT**.

To delete a waypoint from the map:

1. Use the arrow keys to select the waypoint with the cursor.

2. Press **WPT | →** to **DELETE WAYPOINT | ENT | ←** to **YES | ENT**. To return to the previous page and clear the cursor, press **EXIT**.

To delete all waypoints at one time: press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ↓** to **DELETE ALL MY WAYPOINTS | ENT | ←** to **YES | ENT**. To return to the previous page, press **EXIT | EXIT**.

Edit a Waypoint

Waypoint Name

To edit waypoint name: 1. Press **WPT | ENT | ENT | ENT | ↓** to *waypoint name* | **ENT | →** to **EDIT WAYPOINT | ENT | ENT**.

2. Press **↑** or **↓** to change the first character, then press **→** to the next

character and repeat until the name is correct. Press **ENT** then **EXIT | EXIT | EXIT | EXIT** to return to the previous page display.

Waypoint Symbol

To edit waypoint symbol: 1. Press **WPT | ENT | ENT | ENT | ↓** to *waypoint name* | **ENT | →** to **EDIT WAYPOINT | ENT | ↓** to **CHOOSE SYMBOL | ENT**.

2. Use arrow keys to select desired symbol and press **ENT**. To return to the previous page, press **EXIT | EXIT | EXIT | EXIT**.

Waypoint Position

To edit waypoint position: 1. Press **WPT | ENT | ENT | ENT | ↓** to *waypoint name* | **ENT | →** to **EDIT WAYPOINT | ENT**.

2. Latitude: press **→** to **LATITUDE | ENT**. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the latitude is correct. Press **EXIT**.

3. Longitude: press **↓** to **LONGITUDE | ENT**. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the longitude is correct. Press **EXIT**.

4. When latitude and longitude are correct, return to the previous page: press **EXIT | EXIT | EXIT | EXIT**.

Selecting a Waypoint

To select a waypoint on the map (for navigating to, for editing, etc.,) use the arrow keys and center the cursor over the waypoint. A highlighted halo will appear around the waypoint.

Set a Waypoint by Average Position

This feature sets a waypoint at the current position after taking several position readings and averaging them. This boosts waypoint position accuracy by helping to eliminate errors caused by atmospheric conditions and other factors.

1. Press **WPT | →** to **SUBCATEGORY** column | **↓** to **NEW | ENT**.
2. Wait while the unit takes points to average for the position. (The greater the number of points, the greater the accuracy.) When the desired number of points accumulates, press **ENT** to create and save the waypoint.
3. The Edit Waypoint menu appears. You can simply save the waypoint by pressing **EXIT | EXIT** or you can edit the waypoint. (Press **EXIT | ENT** if you want to immediately begin navigating to the new waypoint.)

Set a Waypoint by Projecting a Position

This feature sets a waypoint at a point located a specific distance and

bearing from a reference position. The reference position can be selected from your waypoint list, a map feature or from the Points of Interest list.

1. Press **WPT** | **→** to **SUBCATEGORY** column | **↓** to **NEW** | **ENT**.
2. Press **↓** to **PROJECTED POSITION** | **→** to **CREATE** | **ENT**.
3. Press **→** to **CHOOSE REFERENCE** | **ENT**. Use **↑** and **↓** to select a waypoint, map feature or Point of Interest. When the point has been selected, press **ENT** and the point's position appears as the reference position.
4. Press **↓** to **DISTANCE** | **ENT**. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the distance is correct. Press **ENT**.
5. Press **↓** to **BEARING** | **ENT**. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the bearing is correct. Press **ENT**.
6. Press **↑** to **PROJECTION** | **ENT**. The Edit Waypoint menu appears. You can simply save the new projected waypoint by pressing **EXIT** | **EXIT** or you can edit the waypoint. (Press **EXIT** | **ENT** if you want to immediately begin navigating to the new waypoint.)

Section 8: System & GPS Setup Options

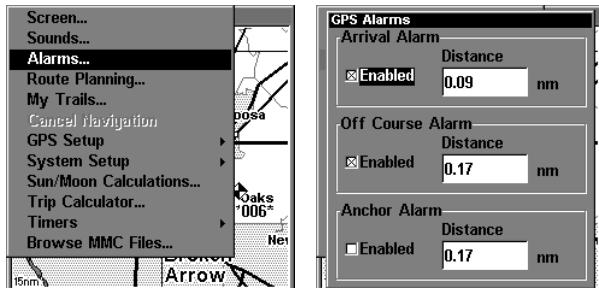
Alarms

This unit has several GPS alarms. The factory default setting has all the alarms turned on. You can turn the alarms off and on and change their distance settings.

You can set an arrival alarm to flash a warning message and sound a tone when you cross a preset distance from a waypoint. For example, if you have the arrival alarm set to .1 mile, then the alarm will flash a message when you come within .1 mile of the recalled waypoint.

The off course alarm warns you when your track drifts too far to the right or left of the course line to the waypoint. For example, if the alarm is set to .1 mile, then the alarm flashes a message if you drift .1 of a mile or more to the right or left of the line to the waypoint.

The anchor alarm is triggered when you drift outside of a preset radius. Again, using the .1 mile as an example, if you're anchored and your boat moves more than .1 of a mile, the alarm will flash a message and sound a tone.



Alarms command, left; Alarm menu, right.

To change alarm settings:

1. Press **MENU | MENU | ↓ to ALARMS | ENT.**
2. Scroll **↓** or **↑** to select the desired category, then press **ENT** to check or clear the Enabled box. This turns the alarm on (checked) or off (unchecked.)
3. To change distance settings, scroll **↓** or **↑** to select the desired category, then press **→ | ENT** to activate the distance dialog box. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the name is correct.

3. When your adjustments are finished, return to the last page displayed by repeatedly pressing **EXIT**.

IMPORTANT ALARM NOTES:

Anchor Alarm - The anchor alarm may be triggered even when you're sitting still. This typically happens when using small (less than .05 mile) anchor alarm ranges.

Arrival Alarm - If you set the arrival alarm's distance to a small number and you run a route (see the Navigate Routes segment), this unit may not show navigation data to the next waypoint, once you arrive at the first one, since you may not be able to come close enough to the first waypoint to trip the arrival alarm.

Auto Satellite Search

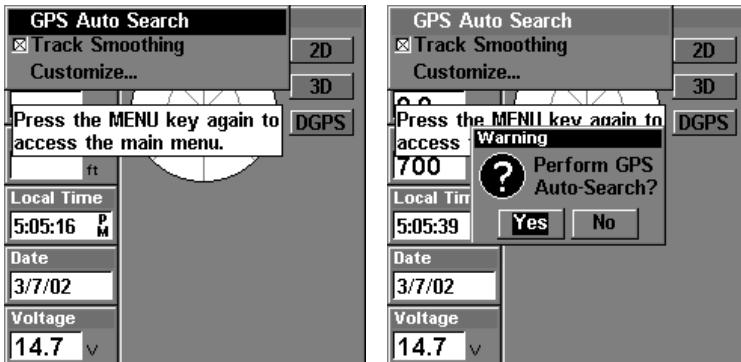
To lock onto the satellites, the GPS receiver needs to know it's current position, UTC time and date. (Elevation (altitude) is also used in the equation, but it's rarely required to determine a position.) It needs this data so that it can calculate which satellites should be in view. It then searches for only those satellites.

When your GPS receiver is turned on for the first time, it doesn't know what your position or elevation (altitude) is. It does know the current UTC time and date since these were programmed into it at the factory and an internal clock keeps the time while the unit is turned off. (If the time and/or date are incorrect, you can set it using the "Set Local Time" menu.)

The unit begins searching for the satellites using the above data that it acquired the last time it was turned on. This probably was at the factory. Since it's almost certain that you're not at our factory, it's probably looking for the wrong satellites.

If it doesn't find the satellites it's looking for after approximately one minute, it switches to Auto Search. The receiver looks for any satellite in the sky. Due to advanced technology, the auto search time has shrunk significantly from the early days of GPS.

Once the unit locks onto the satellites, it should take less than a minute to find your position the next time it's turned on, provided you haven't moved more than approximately 100 miles from the last location it was used.



Satellite Status Menu.

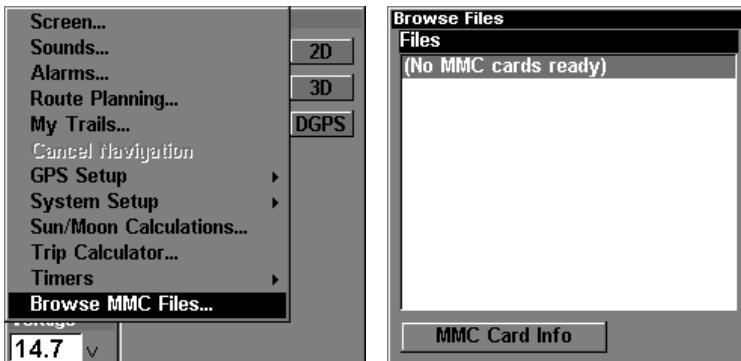
You can force the unit to immediately kick into auto search mode. Here's how:

1. Press **PAGES** until you are on the "Satellite Status" screen.
2. Press **MENU | ENT | ← to YES | ENT.**

Check MMC Files and Storage Space

To check MMC Files:

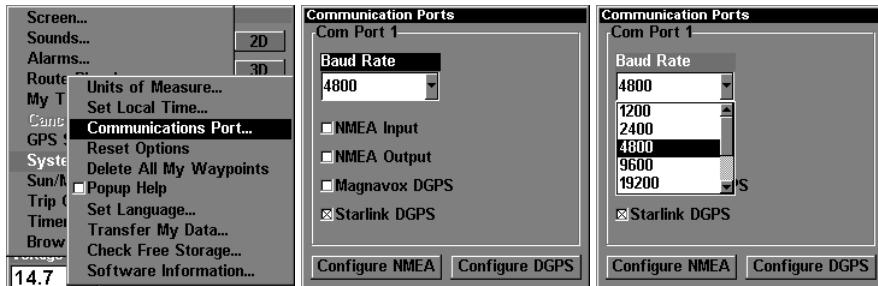
1. Press **MENU | MENU | ↓ to BROWSE MMC FILES | ENT.**



Main Menu, left, MMC File Browser, right.

Communications Port Configuration

LMS-240 has one NMEA 0183 version 2.0 compatible communication port, or com port for short. The Com Port Menu, which is accessed from the System Setup Menu, allows you to configure the communications port to send or receive data to another electronic device, such as an autopilot. The com port can be used for either NMEA, DGPS or SiRF Binary data transfer.



Menus for changing Com Port settings.

For connectors and wiring information for another device, see page 26. For assistance in configuring the unit to communicate with another device, consult the factory; customer service phone numbers are in the back of this manual. Also see the entries below for *Configure DGPS* and *Configure NMEA*. To set Com Port Configuration:

1. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT.**
2. Press **↓** to **COMMUNICATIONS PORT | ENT.**

Configure DGPS

This unit will recognize Starlink®, Magnavox® and Lowrance DGPS receivers.

1. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT.**
2. Press **↓** to **COMMUNICATIONS PORT | ENT.**
 - A. If you have a Magnavox receiver, press **↓** to **MAGNAVOX | ENT.**
 - B. If you have a Lowrance or Starlink receiver, press **↓** to **STARLINK | ENT.**
 - C. If you have a Magnavox or Starlink, press **EXIT | EXIT | EXIT**. This is the only setup necessary. If you have a Lowrance receiver or another Magnavox- or Starlink- compatible brand, continue with these steps:
3. Press **↓** to **CONFIGURE NMEA | →** to **CONFIGURE DGPS | ENT.**
4. Press **ENT**, then use **↑ ↓ → ←** to enter the station frequency, then press **ENT**.
5. Press **→** to **BIT RATE | ENT** then use **↑ ↓** to select the station bit rate, then press **ENT**.
6. A. If you are *not* using a Starlink DGPS receiver, press **EXIT | EXIT | EXIT | EXIT** to return to the previous page.
 - B. If you *are* using a Starlink DGPS receiver, press **↓** to **STARLINK AUTO TUNING MODE |** press **ENT** | press **EXIT | EXIT | EXIT | EXIT** to return to the previous page.

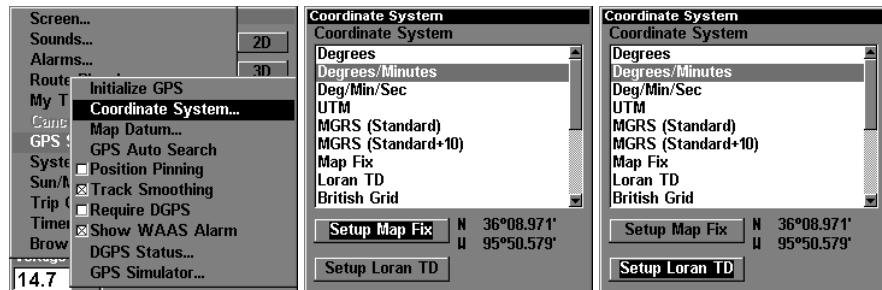
Configure NMEA

You can configure the unit to use specific NMEA sentences.

1. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT**.
2. Press **↓** to **COMMUNICATIONS PORT | ENT | ↓** to **CONFIGURE NMEA | ENT**.
3. A menu appears showing the prefixes of the available NMEA sentences. A check mark next to a prefix means the prefix is in use. Use **↑ ↓ → ←** to select a prefix, then press **ENT** to turn off the prefix. (Press **ENT** again to check the box and turn a prefix on.)
4. When the desired prefixes are checked or unchecked, press **EXIT | EXIT | EXIT | EXIT** to return to the previous page.

Coordinate System Selection

The Coordinate System Menu lets you select the coordinate system to use when displaying and entering position coordinates.



Menus for changing coordinate system used to display positions.

To get to Coordinate System Selection:

1. Press **MENU | MENU | ↓** to **GPS SETUP | ENT**.
2. Press **↓** to **COORDINATE SYSTEM | ENT**.

This unit can show a position in degrees (36.14952°); degrees, minutes and thousandths of a minute ($36^\circ 28.700'$); or degrees, minutes, seconds and tenths of a second ($36^\circ 28' 40.9''$). It can also show position in: UTM (Universal Transverse Mercator) projection; MGRS (Standard); MGRS (Standard + 10); Map Fix; Loran TD; British, Irish, Finnish, German, New Zealand, Swedish, Swiss, Taiwan, Greek and Military grids.

UTM's are marked on USGS topographic charts. This system divides the Earth into 60 zones, each 6 degrees wide in longitude.

British, Irish, Finnish, German, New Zealand, Swedish, Swiss, Taiwan, and Greek grid systems are the national coordinate system used only in

their respective countries. In order to use these grid systems, you must be in the respective country. This unit will pick the matching datum for you when you select the grid. See the entry on Map Datum Selection for more information.

The military grid reference system (MGRS) uses two grid lettering schemes, which are referred to as standard and standard + 10 MGRS on this unit. Your position and datum in use determines which one to use. If you use standard, and your position is off significantly, then try the alternate.

NOTE: When the position format is changed, it affects the way all positions are shown on all screens. This includes waypoints.

To change the coordinate system, press **ENT** while **COORDINATE SYSTEM** is highlighted. Press the **↑** or **↓** arrow keys to highlight the desired format. Press **ENT** to select it. Press **EXIT** to erase the menus.

To setup Loran TD:

NOTE:

If the Loran TD conversion is chosen, you must enter the local Loran chain identification for the master and slaves. Do this by selecting "Setup Loran TD" at the bottom of the "Coordinate System" menu and select the ID. Press **EXIT** to erase this menu.



Configure Loran TD menu.

Map Fix

Map Fix is used with charts or maps. This system asks for a reference position in latitude/longitude, which you take from a marked location on the map. It then shows the present position as distance on the map from that reference point.

For example, if it shows a distance of UP 4.00" and LEFT 0.50", you then measure up four inches and to the left a half-inch from the reference point on the map to find your location.

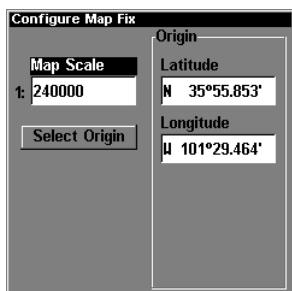
To configure a map fix:

To use this format, you need to follow these steps in order. First, take your map of the area and determine a reference latitude/longitude. (Note: in order for this system to work, the latitude/longitude lines must be parallel with the edge of the map. USGS maps are parallel, others may not be. Also, this works better with smaller scale maps.) The reference position can be anywhere on the map, but the closer it is to your location, the smaller the numbers will be that you'll have to deal with.

Once you've decided on a reference position, you can save it as a waypoint. See the waypoint section for information on saving a waypoint. Save the reference position as a waypoint. Exit from the waypoint screens.

1. Press **MENU | MENU | ↓ to GPS SETUP | ENT.**
2. Press **↓ to COORDINATE SYSTEM | ENT.**
3. Press **↓ to SETUP MAP FIX | ENT.**

The screen below appears, and **MAP SCALE** is highlighted. Press **ENT** and enter the map's scale. This is generally at the bottom of the paper map. It's shown as a ratio, for example 1:24000. Press **EXIT** and the unit returns to the Configure Map Fix screen.



Configure a map fix so LMS-240 can find your position on a printed chart or topographical map.

Press ↓ to **SELECT ORIGIN | ENT | ENT | ENT** to bring up the waypoint list. Select the waypoint that you saved the reference point under and press **ENT**. The unit displays a waypoint information screen with the command **SET AS ORIGIN** selected; press **ENT** and the unit returns to the Configure Map Fix menu. Finally, press **EXIT** to erase this menu. Now press ↑ to **COORD SYSTEM | ENT**, select **MAP FIX** from the list and press **ENT | EXIT**. All position information now shows as a distance from the reference point you chose.

Customize Page Displays

The Position, Navigation, and Map pages all have customizable options. These options decide which information is viewable on each page.

Customize Satellite Status Page

While on the Satellite Status Page, press **MENU | ↓** to **CUSTOMIZE | ENT**. Press ↓ or ↑ to select a display option window. With the display window highlighted and flashing, press **ENT** to open a list of options. Scroll ↑ and ↓ to select a different display option, then press **ENT**. After all options are set, press **EXIT** to return to the page display.

Customize Navigation Page

While on the Navigation Page, press **MENU | ↓** to **CUSTOMIZE | ENT**. Press ↓ or ↑ to select a display option window. With the display window highlighted and flashing, press **ENT** to open a list of options. Scroll ↑ and ↓ to select a different display option, then press **ENT**. After all options are set, press **EXIT** to return to the page display.

Customize Map Page

While on the Map Page, press **PAGES | ↓** or ↑ to select *Option Name* | **ENT**.

DGPS Status

The DGPS Status screen shows whether DGPS is off or on, and it describes the quality of the DGPS signal. This screen is useful if you have to diagnose a DGPS problem.

1. Press **MENU | MENU | ↓** to **GPS SETUP | ENT | ↓** to **DGPS STATUS | ENT**.
2. The DGPS Status screen is displayed. To return to the previous page, press **EXIT | EXIT | EXIT**.

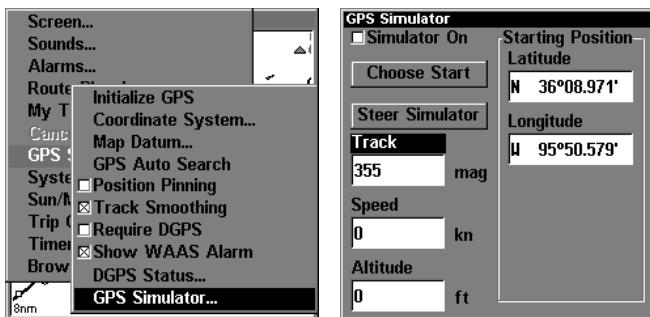
GPS Simulator

The GPS simulator lets you use the unit as if you were outdoors navigating somewhere. It's a great way to practice using your unit. You can set the starting location by entering latitude/longitude (Starting Posi-

tion) or from a stored waypoint, map place or POI location (**CHOOSE START** command). You can steer your position and change speed on the map by using the arrow keys (**STEER SIMULATOR** command) or by setting the track and speed in the dialog boxes provided on the simulator menu screen.

To get to the GPS Simulator:

1. Press **MENU | MENU | ↓ to GPS SETUP | ENT.**
2. Press ↓ to **GPS SIMULATOR | ENT.** The GPS Simulator Menu appears.



GPS Setup Menu, left; GPS Simulator menu, right.

Make the desired settings, then turn the simulator on by highlighting the **SIMULATOR ON** box and pressing **ENT** key. Press **EXIT | EXIT | EXIT** to erase this menu. A message and tone appears periodically, warning you that the simulator is on. To turn the simulator off, repeat the above steps or turn the unit off.

While in simulator mode, you can press **EXIT** to clear the steering and speed boxes from the screen while continuing the simulation. This will allow you to use the map cursor during a simulation. To turn steering and speed boxes back on again, return to the GPS Simulator menu, select the **STEER SIMULATOR** command, press **ENT**, then Press **EXIT | EXIT | EXIT** to return to the previous page.

Simulating Trail or Route Navigation

In Simulator mode, your unit can automatically follow a trail or route without manual steering if you use these steps:

1. From the Map Page, go to the simulator menu. Pick a **STARTING POSITION** at or near the beginning of your trail/route. Enter an approximate **TRACK** (shown in compass degrees) that will point you toward the start of the trail/route.
2. Set **SPEED** to zero. Select **STEER SIMULATOR** command and press **ENT**, which turns on the simulator and returns you to the Map Page.

3. Begin navigating along the trail/route. (If you are close enough to the first waypoint, the arrival alarm will usually go off as soon as navigation begins. Press **EXIT** to clear the alarm.) When navigation starts, press **↑** to increase speed to the desired setting.
4. Press **EXIT** to turn off the steering and speed boxes. The unit will now automatically "steer" along the trail or route. When you arrive at your "destination," cancel navigation as you normally do.

Tip:

You can pick any spot on the map to begin your simulation session by using the Initialize GPS command. This makes your unit think it's located at the position you select. See it's entry following the entry for *Hide GPS Features*.

Hide GPS Features

If there is no GPS antenna/receiver module attached to this unit, the GPS menus and features can be hidden from view with this command. The default setting is off, allowing you to rotate between the Sonar Page and the GPS pages and features. To hide GPS features:

1. Press **MENU | MENU | ↓** to **HIDE GPS FEATURES | ENT**. The GPS menus and pages are now hidden.

To restore GPS Features, press **MENU | MENU | ↓** to **SHOW GPS FEATURES | ENT**. The GPS menus and pages are available once again.

Initialize GPS

This command is handy when you are practicing in simulator mode. (See the entry in this section for *GPS Simulator*.) In simulator mode, this command makes the unit operate as if it sitting someplace other than its actual location. So, you and your unit could be located in Kansas City, but easily practice navigating in the ocean off Islamorada, Florida.

1. Press **MENU | MENU | ↓** to **GPS SETUP | ENT | ENT**.
2. A message appears, telling you to move the cursor near the desired location and press **ENT**. When the message automatically clears, follow the message instructions.
3. In a moment, your present position marker arrow appears on the map in the location you selected with the cursor. The unit will consider that spot as it's last known position until changed by either a live satellite lock-on or a new simulator location.

Map Auto Zoom

This receiver has an auto zoom feature that eliminates much of the button pushing that other brands of GPS receivers force you to make. It works in conjunction with the navigation features.

First, start navigation to a waypoint. (See the waypoint section for more information on navigating to a waypoint.) Then, with the auto zoom mode on, the unit zooms out until the entire course shows, from the present position to the destination waypoint. As you travel toward the destination, the unit automatically begins zooming in — one zoom range at a time — always keeping the destination on the screen.

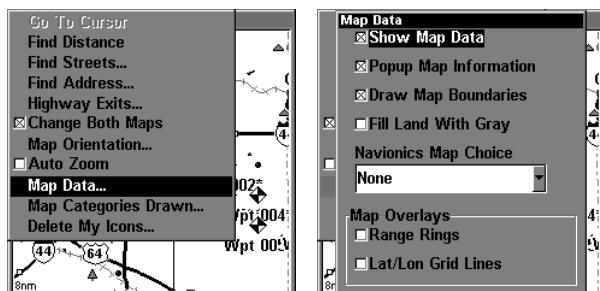
To turn this feature on, from the **MAP PAGE**, press **MENU** | **↓** to **AUTO ZOOM** | **ENT** | **EXIT**. Repeat these steps to turn it off.

Map Data

This menu lets you turn the map off, if desired (which turns the map screen into a GPS plotter); turn off or on the pop-up map info boxes; draw the map boundaries or boxes around the areas of detail; or fill land areas with gray. You can also turn on or off Map Overlays, which display latitude and longitude grid lines or range rings on the map. This menu lets you select Navionics Maps; for instructions, see the *Navionics Charts* entry in this section.

To get to Map Data:

1. From the Map Page, press **MENU** | **↓** to **MAP DATA** | **ENT**.



Map Menu, left, Map Data Menu, right.

Show Map Data

From the Map Page, press **MENU** | **↓** to **MAP DATA** | **ENT**. Press **ENT** to check **SHOW MAP DATA** (turn on) and uncheck it (turn off.) After the option is set, press **EXIT** | **EXIT** to return to the page display.

Pop-up Map Info

From the Map Page, press **MENU** | **↓** to **MAP DATA** | **ENT**. Press **↓** to **POPUP**

MAP INFO. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

Map Boundaries

From the Map Page, press **MENU|↓** to **MAP DATA|ENT**. Press **↓** to **MAP BOUNDARIES**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

Fill Land Gray

From the Map Page, press **MENU|↓** to **MAP DATA|ENT**. Press **↓** to **FILL LAND GRAY**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

Map Overlays (Range Rings; Lat/Long Grid)

The map screen can be customized with rings that are 1/2 and 1/4 of the zoom range and/or grids that divide the plotter into equal segments of latitude and longitude.

To set range rings: From the Map Page, press **MENU|↓** to **MAP DATA|ENT**. Press **↓** to **RANGE RINGS**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

To set Lat/Lon Grid: From the Map Page, press **MENU|↓** to **MAP DATA|ENT**. Press **↓** to **LAT/LON GRID LINES**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

Map Datum Selection

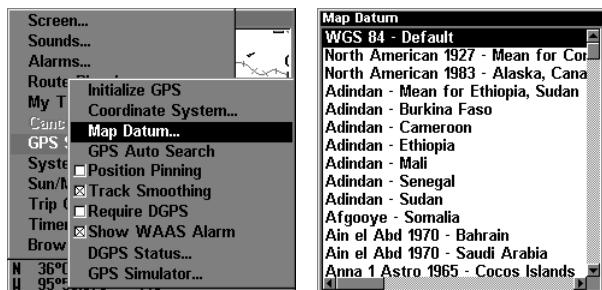
Maps and charts are based on a survey of the area that's covered by the map or chart. These surveys are called "Datums." Maps that are created using different datums will show the same latitude/longitude in slightly different locations.

All datums are named. The GPS system is based on the WGS-84 datum, which covers the entire world. Other datums may also cover the entire world, or just a small portion of it. By default, your position shows using the WGS-84 datum. However, it can show your position using one of 191 different datums. Different datums can be selected; to change the datum:

1. Press **MENU|MENU|↓** to **GPS SETUP|ENT|↓** to **MAP DATUM|ENT**.
2. Scroll **↓** or **↑** to select the desired datum, then press **ENT**.

3. To return to the last page displayed, press **EXIT | EXIT**.

A list of the datums used by this unit is in the back of this manual.



GPS Setup Menu, left, Map Datum Menu, right.

Map Detail Category Selection

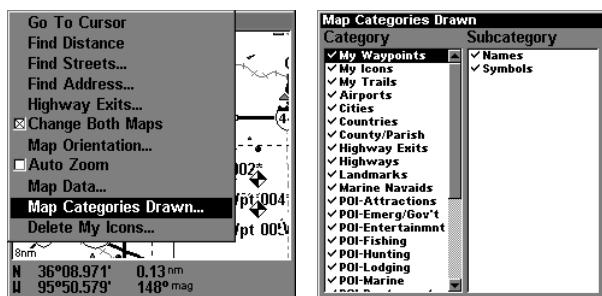
This menu determines which of the mapping features are shown on the screen. This includes, waypoints, trails, icons, cities, highways, etc. You can selectively turn on or off any of these items, customizing the map to your needs.

To get to Map Categories:

1. From the Map Page, press **MENU | ↓** to **MAP CATEGORIES DRAWN | ENT**.

2. Press **↑** or **↓** to select a category or subcategory. Press **ENT** to turn it off (no check) or on (checked.)

3. To return to the last page displayed, press **EXIT | EXIT**.

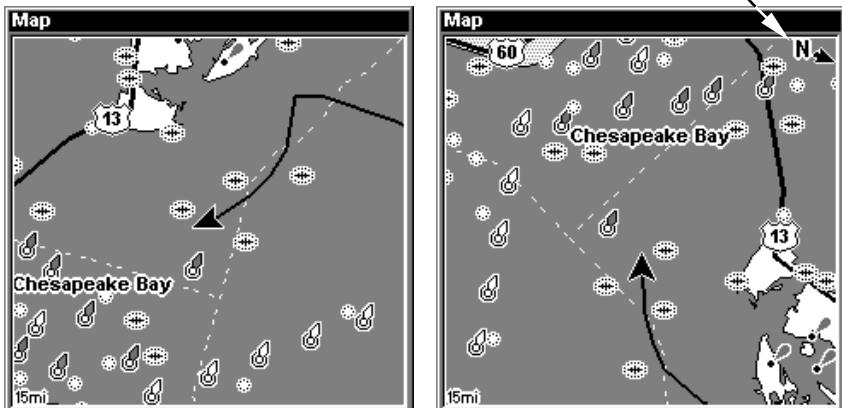


Map Menu, left, Map Categories Drawn Menu, right.

Map Orientation

By default, this receiver shows the map with north always at the top of the screen. This is the way most maps and charts are printed on paper.

In Track Up mode, map shows "N" and arrow to indicate north.



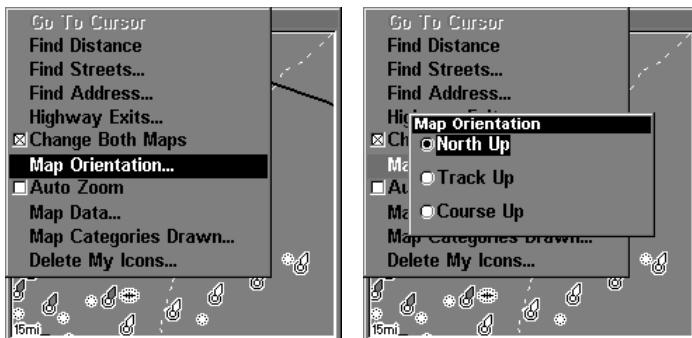
Map orientation at left is shown in north up and at right, track up.

This is fine if you're always traveling due north. What you see to your left corresponds to the left side of the map, to your right is shown on the right side of the map, and so on. However, if you travel any other direction, the map doesn't line up with your view of the world.

To correct this problem, a track-up mode rotates the map as you turn. Thus, what you see on the left side of the screen should always be to your left, and so on.

Another option is course-up mode, which keeps the map at the same orientation as the initial bearing to the waypoint. When either the track-up or course-up mode is on, an "N" shows on the map screen to help you see which direction is north.

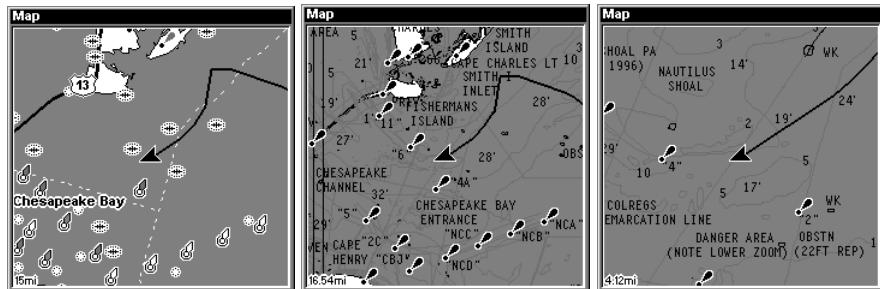
To change map orientation: from the Map Page, press **MENU** | **↓** to **MAP ORIENTATION** | **ENT**. Use **↑** or **↓** to select the desired mode, then press **ENT**. Press **EXIT** | **EXIT** to return to the page display.



Map Menu, left, Map Orientation menu with the North Up map orientation option selected.

Navionics® Charts

Your LMS-240 can display Navionics® electronic charts on MMCs. They work just like a MapCreate custom map on an MMC.



Left, entrance to Chesapeake Bay in a MapCreate 6 custom map, 15 mile zoom. Center, same position on Navionics chart at 16.54 mile zoom and right, 4.12 mile zoom.

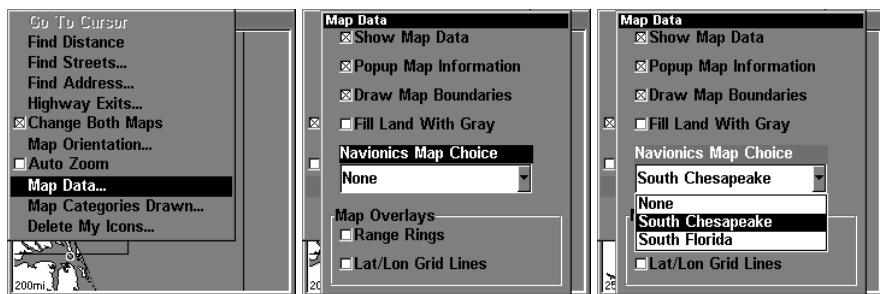
To display a Navionics chart:

1. Install the Navionics MMC in the memory card compartment and turn on the unit. (For full card install instructions, see Sec. 2.)

WARNING:

You should never format the MMC containing your Navionics chart. Formatting the MMC will permanently erase the chart from the card.

2. From the Map Page, press **MENU** | **↓** to **MAP DATA** | **ENT** | **↓** to **NAVIONICS MAP CHOICE** | **ENT**. Use **↑** or **↓** to select the *Map Name*, then press **ENT** | **EXIT** | **EXIT**.



These figures show menu sequence (from left to right) for selecting a Navionics chart for the South Chesapeake Bay area.

3. To turn off a Navionics chart, From the Map Page, press **MENU** | **↓** to **MAP DATA** | **ENT** | **↓** to **NAVIONICS MAP CHOICE** | **ENT**. Use **↑** or **↓** to select **NONE**, then press **ENT** | **EXIT** | **EXIT**.

Port Information

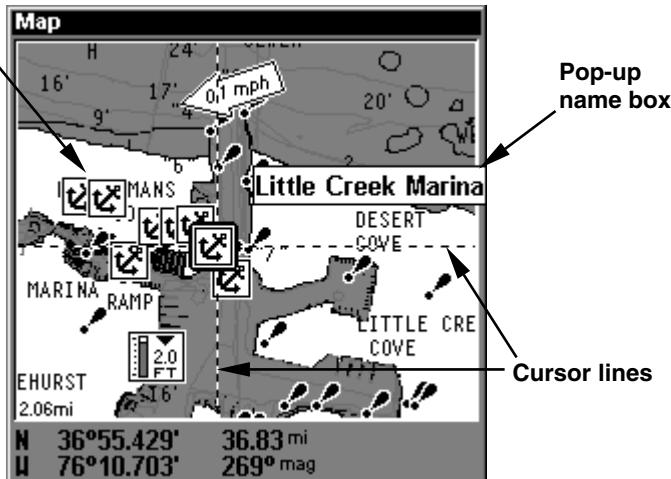
Navionics charts contain Port Services information, represented by anchor icons on the map display. An example is displayed below.

To view Port Services information:

1. Use the arrow keys to move the cursor over a Port Services icon. When selected, a pop-up name box appears.
2. Press **WPT** to display the Port Services Information screen.

The Port Services information screen has two windows. The top window lists the various service categories. The lower window lists the detailed services available in each basic category.

Port Services icons



Navionics chart showing Port Services icon selected by cursor.

3. To scroll through the Service Categories window: press **ENT** then use **↑** or **↓** to see the types of services available. As you highlight a different category, the list in the lower window changes. To return to the Map Page, press **EXIT | EXIT**.
4. The General Services category includes a long list of items in the Detailed Services window. To scroll through the Detailed Services window: from **GENERAL SERVICES**, press **ENT** to highlight **SERVICE CATEGORIES** | press **↓** to **DETAILED SERVICES** | **ENT**, then use **↑** or **↓** to read the list of available services. To return to the Map Page, press **EXIT | EXIT**. To return to the top service category window, press **ENT | ↑**.

Little Creek Marina	Little Creek Marina	Little Creek Marina
Service Categories	Service Categories	Service Categories
General Services	General Services	General Services
Repair Services	Repair Services	Repair Services
Other Utilities On The Pier	Other Utilities On The Pier	Other Utilities On The Pier
Fuel	Fuel	Fuel
Other Information	Other Information	Other Information
Detailed Services		
Launderettes	Launderettes	Hotels
General Stores	General Stores	Fishing/Diving
Restaurants	Restaurants	Accessories Shops
Hotels	Hotels	Ice
Fishing/Diving	Fishing/Diving	Groceries Stores

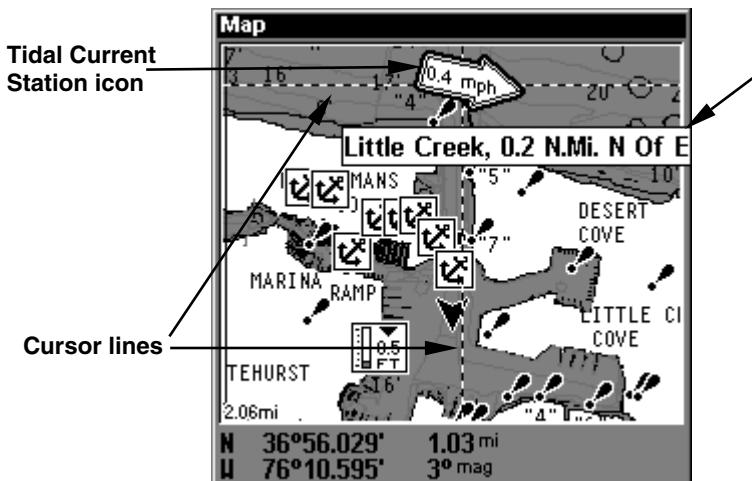
Port Services information screens.

Tidal Current Information

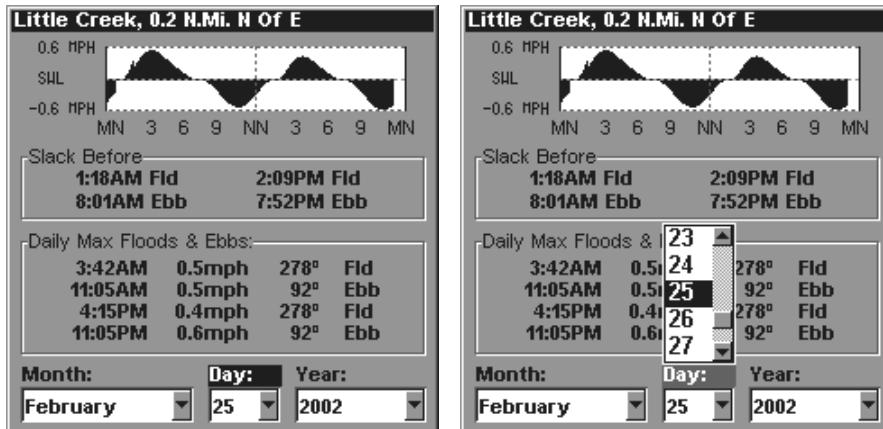
Navionics charts contain Tidal Current information, represented by large arrow icons on the map display. The icon stands for a Tidal Current Station location. An example is displayed below.

To view Tidal Current information:

1. Use the arrow keys to move the cursor over a Tidal Current Station icon. When selected, a pop-up name box appears. (When you zoom in to a sufficiently small zoom range, the icon itself becomes animated and shows tidal current velocity and direction *for the selected tidal station at the present time*.)
2. Press **WPT** to display the Tidal Current Information screen.



Navionics chart showing Tidal Current Station icon selected by cursor. In the example above, the tidal current is ebbing, with the current flowing to the southeast at 0.4 mph.



Current Information screen.

The Tidal Current Information screen displays daily tidal current data for this station on this date. The graph at the top of the screen is an approximate view of the flood and ebb pattern for the day, from midnight (MN), to noon (NN) to midnight (MN). The velocity scale at the left side of the graph changes dynamically based upon the maximum velocity of the current for that day.

Slack water, the period of little or no current, is represented by the Slack Water Line (SWL). The flood appears above the SWL and the ebb appears below the SWL.

You can look up tidal current data for other dates by changing the month, day and year selection boxes. To select another date:

1. Use → and ← to highlight month, day or year, then press **ENT**.
2. Use ↑ and ↓ to select the desired month, day or year, then press **ENT**.

To clear the information screen, press **EXIT**.

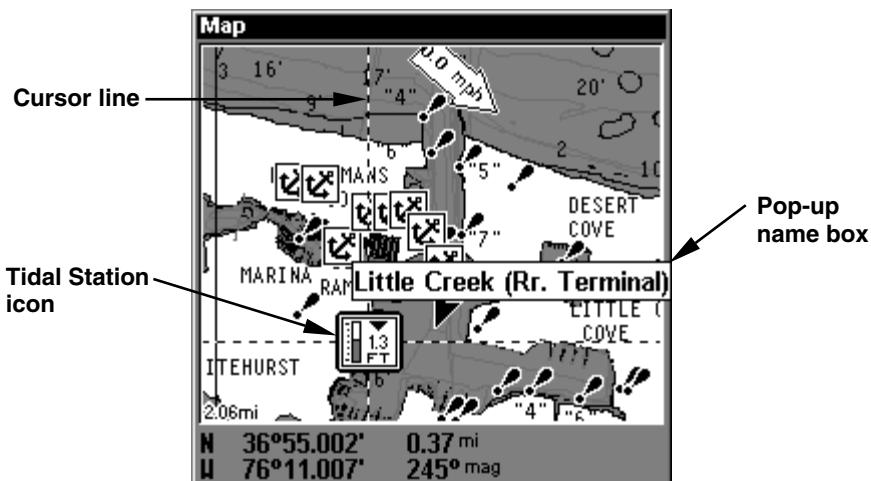
Tide Information

Navionics charts contain Tide Information, represented by tidal gauge icons on the map display. The icon stands for a Tidal Station location. An example is displayed on the next page. (When you zoom in to a sufficiently small zoom range, the icon itself becomes animated and shows a rising or falling tidal height *for the selected station* at the present time.)

To view tide information:

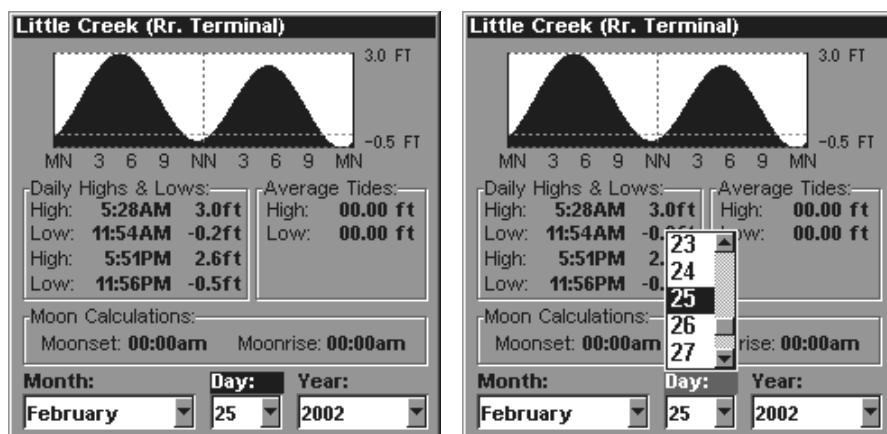
1. Select a Tide Station icon: use the arrow keys to move the cursor over an icon. When it is selected, a pop-up name box appears.

2. After selecting the Tide Station icon, press **WPT** to display the Tide Information screen.



Navionics chart showing Tide Station icon selected by cursor.

In the example above, the tide is at 1.3 feet and falling, as shown by the down arrow at the top of the icon.



Tide Information screen.

The Tide Information screen displays daily tidal data for this station on this date. The graph at the top of the screen is an approximate view of the tidal range pattern for the day, from midnight (MN), to noon (NN) to midnight (MN). The dotted line across the graph is the Mean Lower Low Water line (MLLW).

The height scale on the right side of the graph changes, based upon the maximum *range* of the tide for that day. The MLLW line also adjusts its position as the height scale changes.

You can look up tidal data for other dates by changing the month, day and year selection boxes. To select another date:

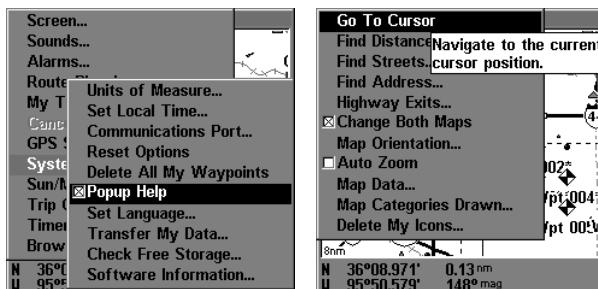
1. Use → and ← to highlight month, day or year, then press **ENT**.
2. Use ↑ and ↓ to select the desired month, day or year, then press **ENT**.

To clear the information screen, press **EXIT**.

Pop-up Help

Help is available for virtually all of the menu labels on this unit. By highlighting a menu item and leaving it highlighted for a few seconds, a "pop-up" message appears that describes the function of the menu item. This feature is on by default.

To set up Pop-up Help: Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ↓** to **POPUP HELP**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT | EXIT** to return to the page display.



System Setup menu, left, with Pop-up Help command highlighted. At right, this example shows the Pop-up Help message for the Go To Cursor command, located on the Map Menu.

Position Pinning

When you are standing still or moving at extremely slow speed, a GPS receiver can have trouble determining the direction you are traveling. In the past, this resulted in a "wandering" plot trail that moved around the map, even if you were standing still.

The Position Pinning feature was developed so that when you stopped, the unit locked the present position on the GPS plotter until you moved a short distance or exceeded a very slow speed.

The command remains available in the unit's software, but we recommend that you leave it in the default off (unchecked) mode. The "wandering" plot trail issue has now been corrected by the Track Smoothing feature. Turning on Position Pinning could actually result in an inaccurate plot trail if you are moving around in a relatively small area. If you want to experiment with Position Pinning, the same instructions are used to turn the feature on (checked) and off (unchecked.)

1. Press **MENU | MENU | ↓ to GPS SETUP | ENT | ↓ to POSITION PINNING | ENT.**
2. Press **EXIT | EXIT** to return to the previous page.

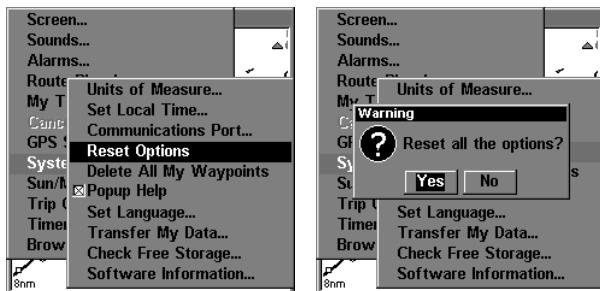
Reset Options

To reset all features to their factory defaults:

1. Press **MENU | MENU | ↓ to SYSTEM SETUP | ENT | ↓ to RESET OPTIONS | ENT | ← to YES | ENT.**

NOTE:

Reset Options does *not* erase any waypoints, routes, icons or plot trails.

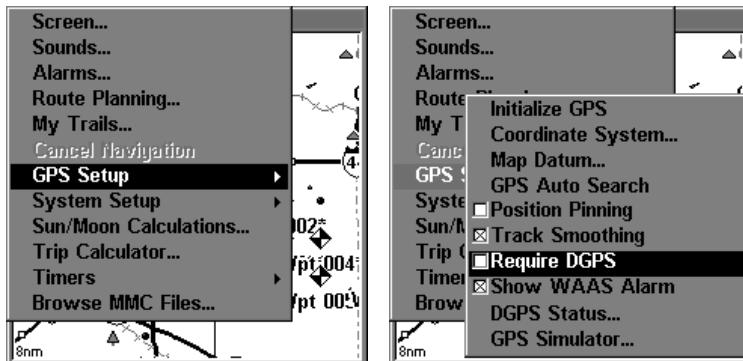


Reset Options command, left,
and the Reset Options Menu, right.

Require DGPS

You can force LMS-240 to require DGPS for reporting a valid position. (The default setting, off, uses DGPS automatically when an optional DGPS beacon receiver is connected. However, this auto mode doesn't *require* DGPS reception to yield a position.) Here's how to turn *mandatory* DGPS on and off.

1. Press **MENU | MENU | ↓ to GPS SETUP | ENT | ↓ to REQUIRE DGPS | ENT.**
2. To return to the last page displayed, press **EXIT | EXIT**.
3. You can return to this command and press **ENT** again to turn the feature off.



GPS Setup command, left; Require DGPS command on the GPS Setup Menu, right.

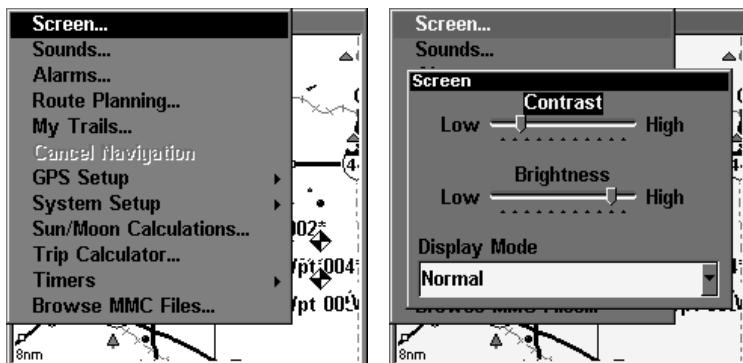
Screen Contrast and Brightness

To access the Screen menu, press **MENU | MENU | ENT**.

Once in the Screen menu:

To adjust the display's contrast:

1. The **CONTRAST** slider bar is already selected. Press **→** or **←** to move the bar. The left end of the scale is minimum contrast; the right end is maximum contrast.



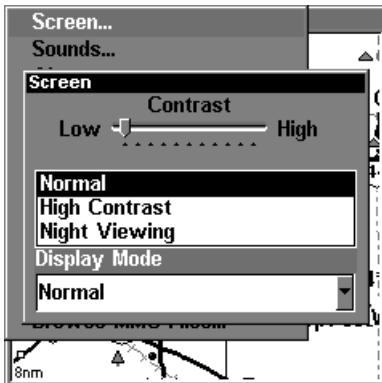
Screen Command, left, and Screen Menu with Contrast bar selected, right.

To adjust the display's brightness:

1. Press **↓** to **BRIGHTNESS**. Press **→** or **←** to move the bar. The left end of the scale is minimum contrast; the right end is maximum contrast.

To adjust the screen's display mode:

1. Press **↓** to **DISPLAY MODE | ENT | press ↑ or ↓ to select mode | EXIT**.



Display Mode menu.

Set Language

This unit's menus are available in 10 languages: English, French, German, Spanish, Italian, Danish, Swedish, Russian, Dutch and Finnish. To select a different language:

1. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT**.
2. Press **↓** to **SET LANGUAGE... | ENT**.
3. Use **↓** or **↑** to select a different language and press **ENT**. All menus now appear in the language you selected.

Set Local Time

Using the correct local time setting is handy when estimating local arrival time while navigating. Also, the time and date are saved when a waypoint is created.

To access the Set Local Time menu, you must first acquire your position. Once that is done: press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ↓** to **SET LOCAL TIME | ENT**.

Once in the Time Settings menu:

To set Local Time: Press **ENT**. Press **↑** or **↓** to change the first character, then press **→** to move the cursor to the next character. Repeat until the time is correct, then press **ENT**.

To set the Month: Press **↓** to **MONTH | ENT**. Press **↑** or **↓** to select the month, then press **ENT**.

To set the Day: Press **↓** to **DAY | ENT**. Press **↑** or **↓** to select the day, then press **ENT**.

To set the Year: Press **↓** to **YEAR | ENT**. Press **↑** or **↓** to select the year, then press **ENT**.

Once you have each field set the way you want, press **EXIT** repeatedly until you return to the previous page.

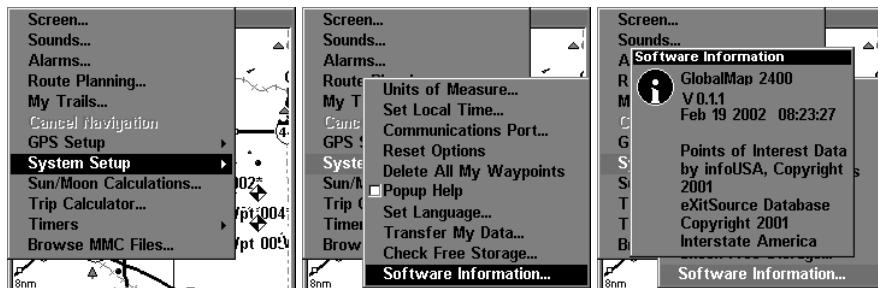
Show WAAS Alarm

When the signal is available, your unit will automatically use WAAS to boost the accuracy of the position fix. When the WAAS signal is lost or acquired, a alarm message appears. Since the U.S. government is still developing the WAAS system, it's not unusual for a GPS/WAAS receiver to frequently lose and reacquire its lock on a WAAS satellite. That can result in the alarm repeatedly going on and off. If you want, you have the option of turning off the WAAS Acquired/Lost alarm without affecting how the unit uses WAAS. Here's how:

1. Press **MENU | MENU | ↓** to **GPS SETUP | ENT | ↓** to **SHOW WAAS ALARM**.
2. With the option highlighted, press **ENT** to uncheck it (turn off) and check it (turn on.) After the option is set, press **EXIT | EXIT** to return to the page display.
3. You can return to this command and press **ENT** again to turn the feature on.

Software Version Information

From time to time, Lowrance updates the operating system software in some of its products. These software upgrades are usually offered to customers as free downloads from our web site, www.lowrance.com. These upgrades make the unit perform better or introduce a new feature or function. You can find out what software version is running in your LMS-240 by using the Software Information command.



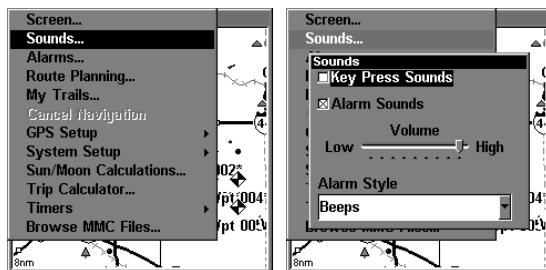
System Setup command left; Software Information command, center.
At right, the Software Information screen.

1. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ↓** to **SOFTWARE INFO | ENT**.
2. Read the information displayed on the screen.
3. To return to the last page displayed, press **EXIT | EXIT | EXIT**.

Sounds and Alarm Sound Styles

Sounds triggered by key strokes and alarms can be adjusted:

You first press **MENU | MENU | ↓ to SOUNDS | ENT.**



Sounds command, left. At right, the Sounds menu.

Once in the Sounds menu:

To set Key Press Sounds: With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT | EXIT** to return to the page display.

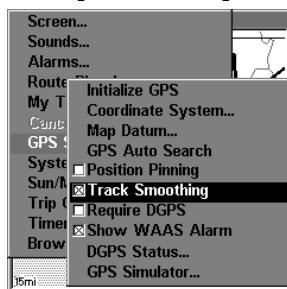
To set Alarm Sounds: Press **↓** to **ALARM SOUNDS**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT | EXIT** to return to the page display.

To set Alarm Volume: Press **↓** to **VOLUME**. Press **→** or **←** to move the bar. The left end of the scale is low volume; the right end is high volume. After the option is set, press **EXIT | EXIT** to return to the page display.

To set Alarm Style: Press **↓** to **ALARM STYLE | ENT**. Press **↑** or **↓** to change the style, then press **ENT**. After the option is set, press **EXIT | EXIT** to return to the page display.

Track Smoothing

This is a factory setting on the GPS Setup menu that *should always be left on*. When stopped or traveling at slow speeds (such as walking or trolling), Track Smoothing prevents wandering of trails, the steering arrow, compass rose and a map in track-up mode.



Track Smoothing option, turned on.

Trail Options

There are several options you can use with trails. Some affect all trails, other options can be applied to a particular trail. You can change the way trails are updated, you can display or hide trails, make them flash on the screen or not flash, create a new trail, delete a trail, etc.

General Trail Options

To access the Trails Menu:

1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT.**



Main Menu, left, Trails Menu, center, Trail Options, right.

Delete All Trails

To remove all of the trails from memory: from the Trails Menu, press → to **DELETE ALL | ENT | ←** to **YES | ENT.**

Flash Trails on Screen Option

From the Trails Menu, press → to **OPTIONS | ENT | ↓** to **FLASH TRAILS**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.)

Update Trail Option

This menu lets you change the way the trail updates occur.

WARNING:

If you uncheck the Update Trail option, automatic trail creation and recording will be turned off. You must turn it back on to record trails. The default setting is on.

From the Trails Menu, press → to **OPTIONS | ENT**. With **UPDATE ACTIVE TRAIL** highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.)

Update Trail Criteria (Auto, Time, Distance)

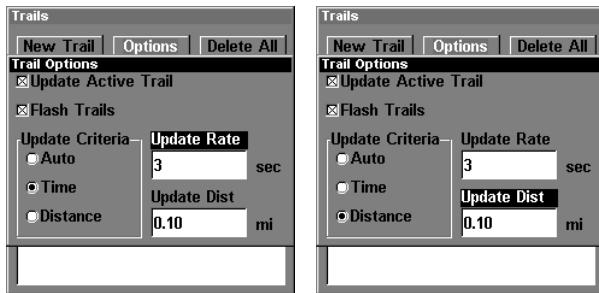
The options are automatic, time, or distance. When it's in the default automatic mode, the unit doesn't update the plot trail while you're traveling in a straight line. Once you deviate from a straight line, the unit "drops" a plot point (trail waypoint) onto the trail. This conserves plot trail points. If a plot trail uses all of the available points allotted to

it, the beginning points are taken away and placed at the end of the trail. From the Trails Menu, press → to **OPTIONS** | **ENT** | ↓ to **UPDATE CRITERIA**. Press ↓ or ↑ to select *criteria type* | **ENT**.

Trail Update Rate (Time, Distance)

You can update a trail by time, with a range from 1 sec to 9999 seconds; the default is 3 seconds. You can update by distance, with a range from 0.01 mile/nm/km to 9.99 mile/nm/km; the default is 0.10 mi.

With one of the Update Criteria selected, use the cursor arrows to highlight either the **UPDATE RATE** or **UPDATE DISTANCE** data entry boxes and press **ENT**. Press ↑ or ↓ to change the first character, then press → to the next character and repeat until the entry is correct. Press **EXIT** to return to the Trail Options Menu.

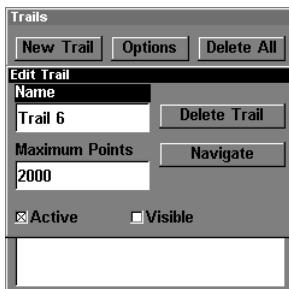


Trail Options menu: Update Time Rate setting, left, and Update Distance setting, right.

Specific Trail Options

Delete Trail

To delete a specific trail: From the Trails Menu, press ↓ to *Trail Name* | **ENT**. The Edit Trail menu appears as seen at the top of the next page. Press → to **DELETE TRAIL** | **ENT** | ← to **YES** | **ENT**.



Edit Trail menu.

New Trail

To manually start a new trail, in the Trails Menu, make sure **NEW TRAIL** is highlighted and press **ENT**.

Trail Visible/Invisible and Other Trail Options

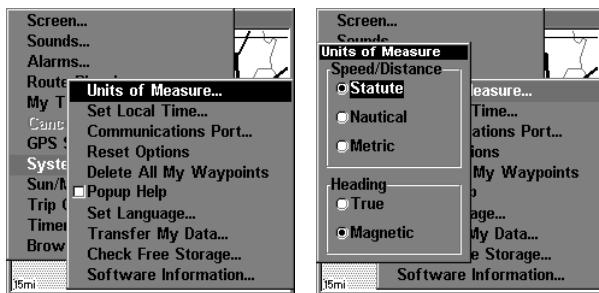
The name, maximum number of points in the trail, activity, and visibility are all changed on the Edit Trail menu screen. The Active setting determines whether or not LMS-240 is recording new points for a particular trail.

On the Edit Trail menu, press **↓** or **↑** to highlight the section you wish to change, then press **ENT**. Press **EXIT** to erase this menu.

Units of Measure

This menu sets the speed and distance (statute or nautical miles, meters), depth (feet, fathoms, or meters), temperature (degrees Fahrenheit or Celsius) and heading (true or magnetic) units. To change the units:

Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ENT**.



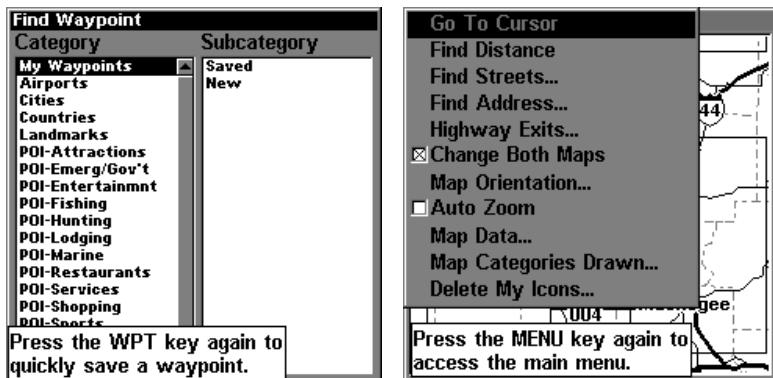
System Setup Menu, left, Units of Measure Menu, right.

To set Speed/Distance Unit of Measure: Press **↑** or **↓** to change the Speed/Distance, then press **ENT**. After the option is set, press **EXIT | EXIT | EXIT** to return to the page display.

To set Heading: Press **↑** or **↓** to change the heading type, then press **ENT**. After the option is set, press **EXIT | EXIT | EXIT** to return to the page display.

Section 9: Searching

LMS-240's varied search functions all begin with either the Find Waypoint menu or the Map Page menu. Press **WPT** and the Find Waypoint menu appears for waypoints and Points of Interest (POI). From the Map Page, press **MENU** and the Map Page menu appears for streets, addresses and highway exits.



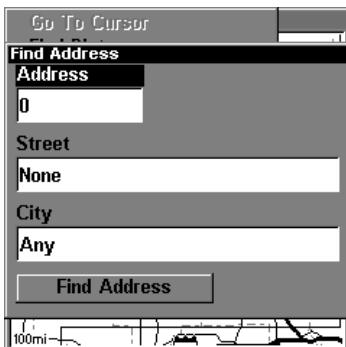
Find Waypoint menu, left and Map Page menu, right.

NOTE:

You can search for items after LMS-240 has acquired a position, or while using LMS-240 in the "indoor" mode. Distance and bearing to the selected item will be calculated from LMS-240's current position, or the last known position if operating indoors (without a position determined). You can look up items by name, or search for the item nearest to you.

Find Addresses

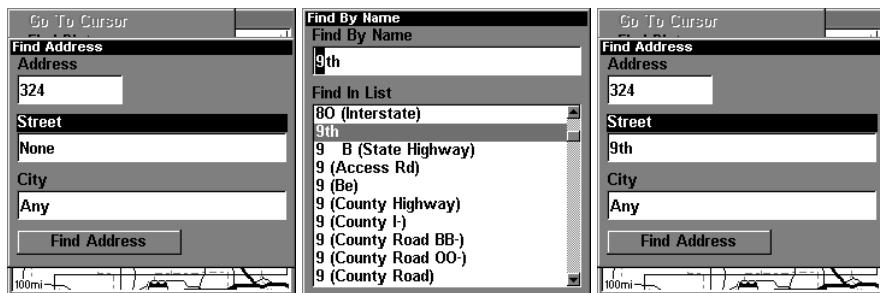
1. From the Map Page, press **MENU** | **↓** to **FIND ADDRESS** | **ENT**.
2. Press **ENT** to search in the Address field.



Find Address Menu.

3. To enter an address number, press \uparrow or \downarrow to change the first number, then press \rightarrow to move the cursor to the next number and repeat until the number is correct, then press **ENT**.

4. To enter a street name, press \downarrow to **STREET|ENT**. There are two options: **A**. You can **spell out** the name in the top selection box. Press \uparrow or \downarrow to change the first letter, then press \rightarrow to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B**. Jump down to the lower selection list by pressing **ENT**, then press \downarrow or \uparrow to select a street name from the list, then press **ENT**. The street name you selected is now in the street field.



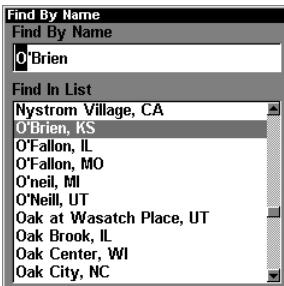
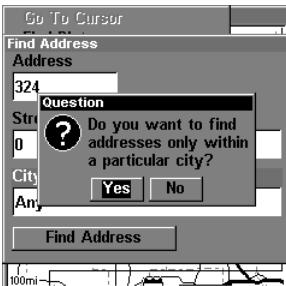
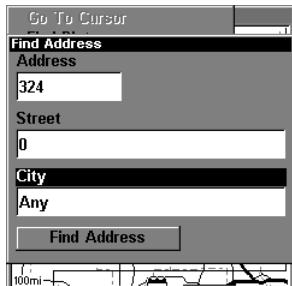
Find Address menu, left; Find Street menu, center,
with Find By Name field active; street name entry complete, right.

5. To enter a city name, press \downarrow to **CITY|ENT**. You will be asked if you want to find addresses only within a particular city. This option is designed so you can limit an address search to a single city if necessary (see the note below.)

If you select yes, there are two options: **A**. You can **spell out** the city name in the top selection box. Press \uparrow or \downarrow to change the first letter, then press \rightarrow to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B**. Jump down to the lower selection list by pressing **ENT**, then press \downarrow or \uparrow to select a city name from the list, then press **ENT**. The city name you selected is now in the city field.

NOTE:

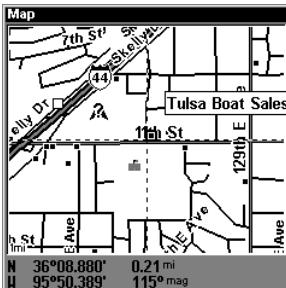
We recommend that you do *not* enter a city name unless the list you are given is too large when searching without it. LMS-240 can actually search quicker without a city and you save time by not entering a city name.



Find city field, left, Search in particular city only option, center; Find City by name, right.

6. When the necessary search fields are filled in, press ↓ to **FIND ADDRESS | ENT**. Your unit asks you to wait while it searches for the address. (If an address is not in the database, a message appears saying the address could not be found.)

7. The unit will display a list of addresses. If the address you are looking for is highlighted at the top of the list, press **ENT**. If not, use ↓ and ↑ to select the correct address from the list, then press **ENT**. The Map Page will then appear with the location selected by the cursor. (In the example below, we are looking for 12303 East 11th Street in Tulsa, not 11th Court, so we had to scroll down the list to select the right one.)



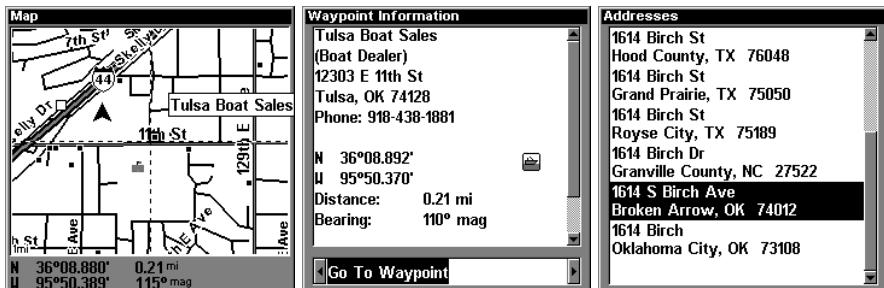
Address search result list, left. At center, Map Page showing location of the address on the map, highlighted by cursor. At right, after the address is located, you can navigate to it ("D" symbol for destination).

8. To navigate to the address, press **MENU | ENT | EXIT** and LMS-240 will begin showing navigation information to the address pointed out by the cursor. If you are only looking up an address (not navigating), just press **EXIT** to return to the previous page.

Tip:

If the address also happens to be an item in the Point of Interest database, you can look up the item's phone number in the Waypoint

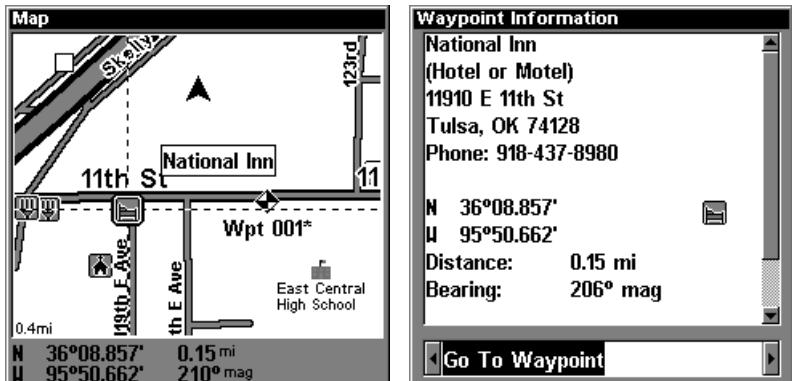
Information list. With the address location selected by the cursor on the map, press **WPT**. The POI's Waypoint Information window appears, with the Go To Waypoint command highlighted. If you want to go ahead and navigate to the POI address, just press **ENT|EXIT**.



Left, Map Page showing location of the address on the map, highlighted by cursor. Center, this address is a business in the POI database, so you can display the POI information window, then navigate to it. At right, this address is not in the POI database, so the Waypoint key will not display any information for this address.

Find Any Item Selected by Map Cursor

1. On the Map Page: with a POI or map feature selected by the cursor press **WPT**. To return to the previous page, press **EXIT**.



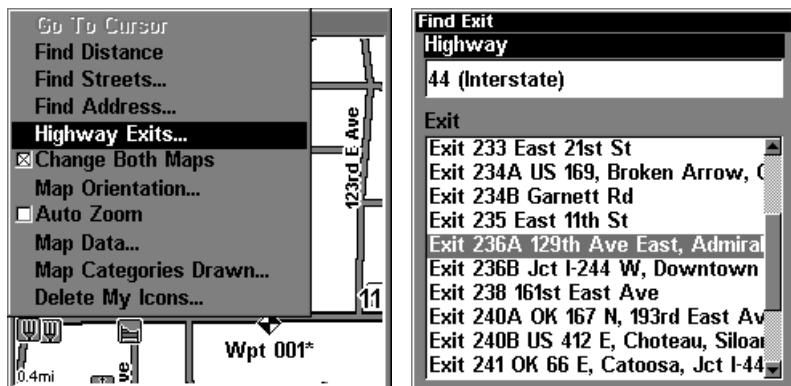
A POI selected by the cursor, left, POI information screen, right.

NOTE:

Since the Go To Waypoint command is highlighted, you can navigate to the selected POI by pressing **ENT|EXIT** while in the POI Waypoint Information screen.

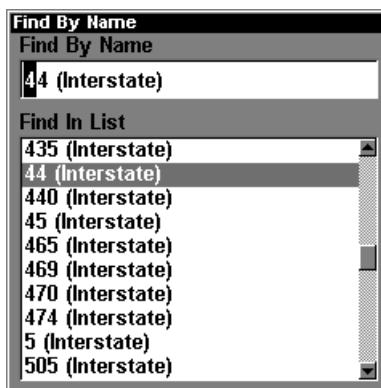
Find Interstate Highway Exits

1. From the Map Page, press **MENU** | **↓** to **HIGHWAY EXITS** | **ENT**, which calls up the Find Exit menu.



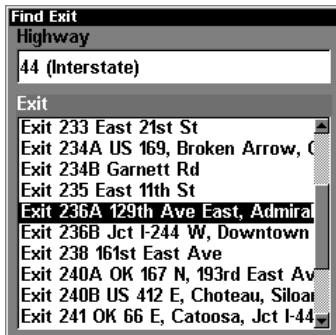
Find Highway Exits command, left, and Find Exit menu, right.

2. First, select a highway name by pressing **ENT**, which calls up the Find By Name menu. There are two highway search options: **A**. You can **spell out** the highway name in the top selection box. Press **↑** or **↓** to change the first letter, then press **→** to move the cursor to the next letter and repeat until the name is correct, then press **ENT** | **ENT**. **B**. Jump down to the lower selection list by pressing **ENT**, then press **↓** or **↑** to select a highway from the list, then press **ENT**.



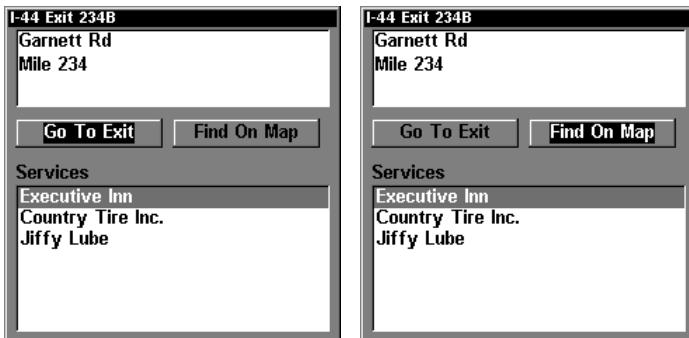
Find By Name menu, right.

2. Once you have selected a highway name you can then select an exit. Press **↓** to switch to the Exit List, then press **↓** or **↑** until you highlight the exit, then press **ENT**.



Find Exit menu, with an exit selected in the Exit List.

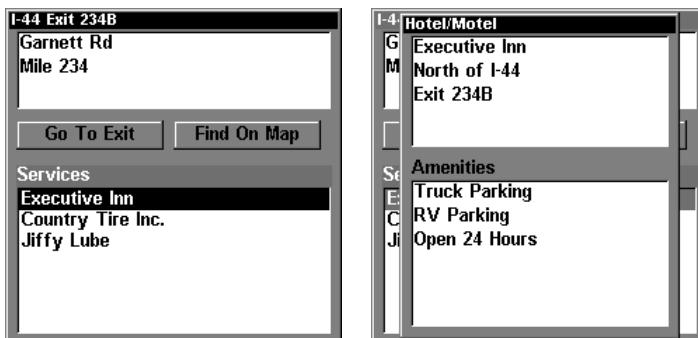
3. In the Exit Information screen you have two choices. **A.** Press **ENT** to navigate or "go to" the exit. **B.** Press **→|ENT** to find the exit on the map.



"Go To Exit" option, left, "Find On Map" option, right.

Tip:

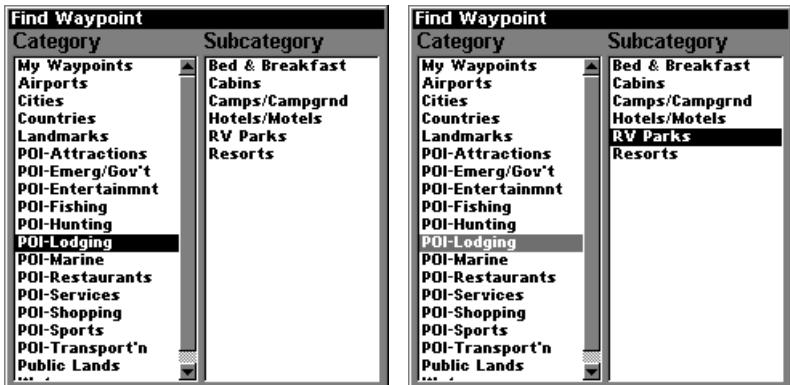
You can also look up some additional information on the Exit Services located near this exit. Press **↓** to **SERVICES** | press **↓** or **↑** to select **Service Name** | **ENT**.



Exit Information screen, left; general location and amenities information, at right.

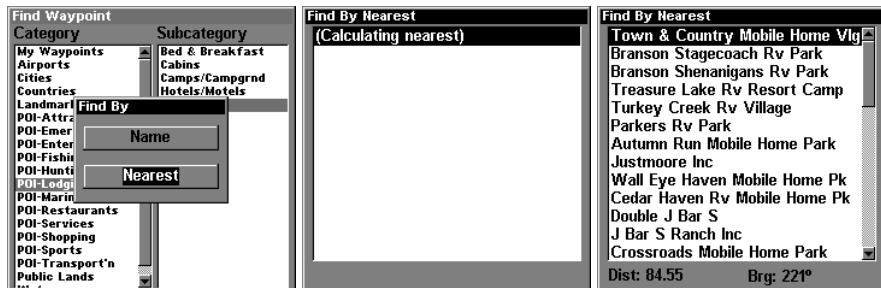
Find Map Places or Points of Interest (POI)

1. Press **WPT**, press **↓** or **↑** to select a map place or POI category, then press **ENT**. (To narrow your search, press **→** then press **↓** or **↑** to select a subcategory before pressing **ENT**.) You will be given two options; Search By Name or By Nearest.



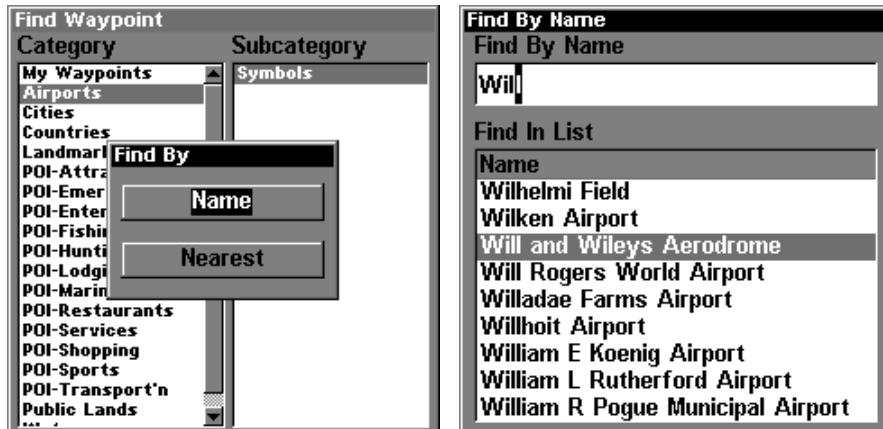
Find Waypoint menu with Lodging POI category selected, left, and with the RV Parks subcategory selected, right.

2. **Search by nearest POI.** Press **↓|ENT**. The "find by nearest" menu will show a "calculating" screen, then a list of the nearest POI's will appear. Press **↓** or **↑** to the selected POI and press **ENT** to call up the POI's Waypoint Information screen.



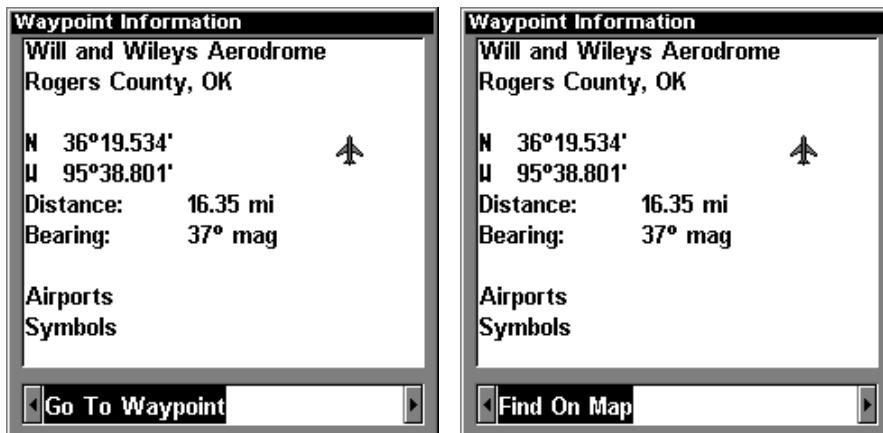
Find by nearest option, left, Calculating screen, center, POI list, right.

3. **Search by name of POI.** Press **ENT**. There are two options: **A.** You can **spell out** the POI in the top selection box. Press **↑** or **↓** to change the first letter, then press **→** to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B.** Jump down to the lower selection list by pressing **ENT**, then press **↓** or **↑** to select a POI from the list, then press **ENT** to call up the POI's Waypoint Information screen.



Find by name option, left, Find by name menu, right.

4. When the POI's Waypoint Information screen is displayed, you can choose to "Go To" the POI waypoint by pressing **ENT** or find it on the map by pressing **→|ENT**.

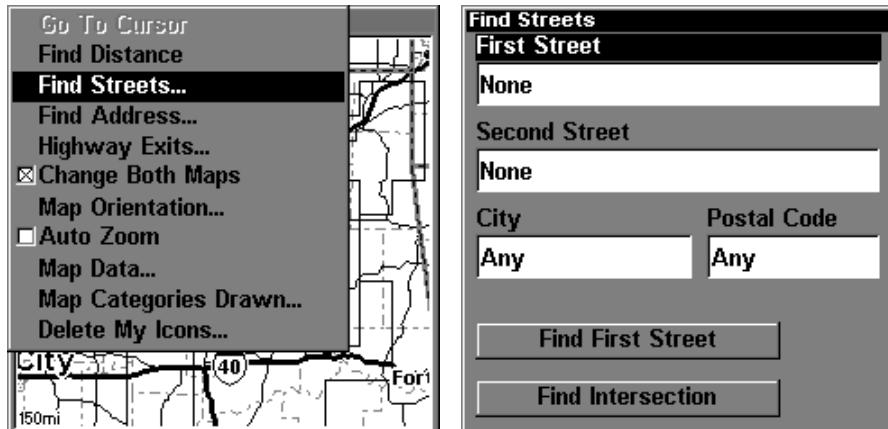


"Go To" POI option, left, "Find on Map" POI option, right.

Find Streets or Intersections

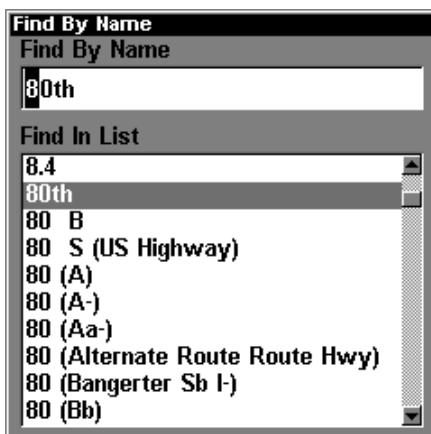
Find a Street

1. From the Map Page, press **MENU |↓** to **FIND STREETS | ENT** and the Find Streets Menu appears.



Find Streets command, left, Find Streets menu, right.

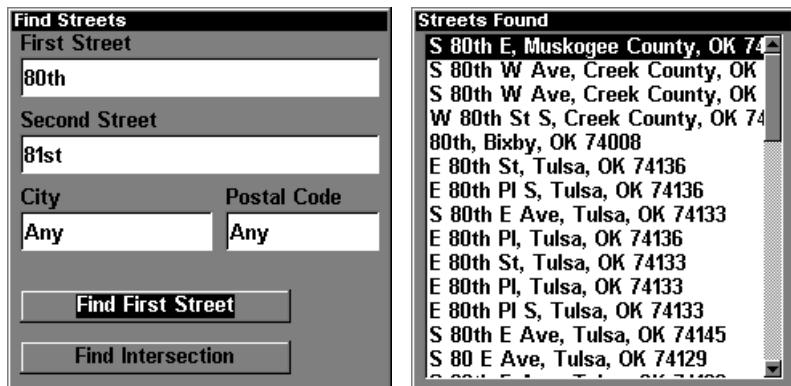
2. You must first fill in a street name in the First Street dialog box. Press **ENT** to display the Find By Name menu. There are two options: **A.** You can **spell out** the street in the top selection box. Press **↑** or **↓** to change the first letter, then press **→** to move the cursor to the next letter and repeat until the name is correct, then press **ENT | ENT**. **B.** Or you can jump down to the lower box and pick a street from the **selection list**. Press **ENT**, then press **↓** or **↑** to select a street from the list and press **ENT**.



Find Street By Name menu. Spell out name in the top box, or select from the list in the lower box.

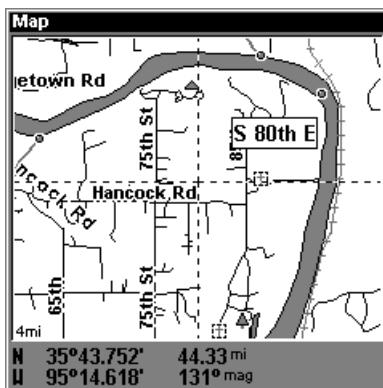
3. The Find Streets menu reappears with the street you're searching for in the First Street box. (In this example, it's 80th Street.) To search for that street, press **↓** to **FIND FIRST STREET | ENT**. A message appears asking

you to wait while the unit finds the street. When the Streets Found list appears, press **↑** or **↓** to select the street you are searching for and press **ENT**.



At left, the Find Streets menu with the Find First Street command highlighted. At right, Streets Found list.

4. The Map Page appears, with the cursor pointing to the found street.



Map Page showing results of a street search.
The cursor points to the located street.

If you want to navigate to the found street at the cursor location, just press **MENU** | **ENT** | **EXIT**.

Find an Intersection

You must enter one street in the First Street dialog box and enter the next street in the Second Street dialog box.

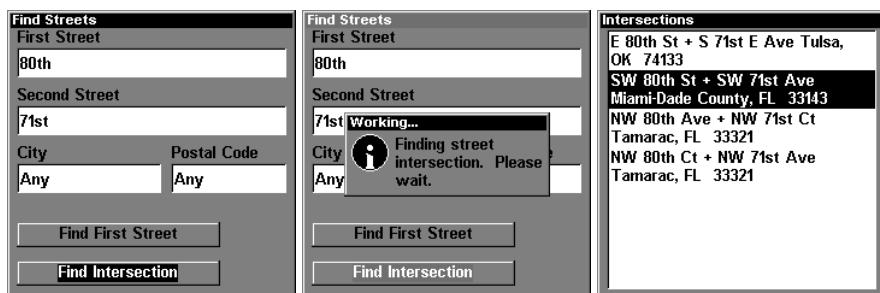
1. From the Map Page, press **MENU** | **↓** to **FIND STREETS** | **ENT** and the Find Streets Menu appears.

2. You must fill in a street name in the First Street dialog box. Press **ENT** to display the Find By Name menu. There are two options: **A**. You can **spell out** the street in the top selection box. Press \uparrow or \downarrow to change the first letter, then press \rightarrow to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B**. Or you can jump down to the lower box and pick a street from the **selection list**. Press **ENT**, then press \downarrow or \uparrow to select a street from the list and press **ENT**.

3. The Find Streets menu reappears with the street you're searching for in the First Street box. (In this example, it's 80th Street.)

4. Now fill in the second street. Press \downarrow to **SECOND STREET|ENT** and the Find By Name menu appears again. Just like before, there are two options: **A**. You can **spell out** the second street in the top selection box. Press \uparrow or \downarrow to change the first letter, then press \rightarrow to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B**. Or you can jump down to the lower box and pick the second street from the **selection list**. Press **ENT**, then press \downarrow or \uparrow to select a street from the list and press **ENT**.

5. The Find Streets menu reappears with the first and second street dialog boxes filled in. In this example, we selected 71st Street as our second street. You could now use similar techniques to select a city or Zip code, but your search will probably be faster if you leave those boxes blank. (You can specify a city and/or Zip code later on to narrow the search, if the resulting list is too long.)

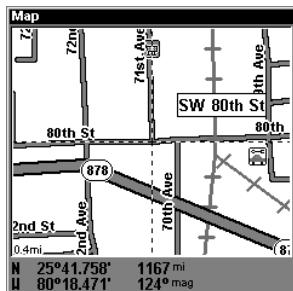


Find Intersection command highlighted, left, and "Working" message, center. At right is the Intersections Found list.

6. To search for the intersection of the two streets, press \downarrow to **FIND INTERSECTION|ENT**. A message appears asking you to wait while the unit finds the intersection. When the Intersections Found list appears, press \uparrow or \downarrow to select the intersection you are searching for and press **ENT**. (In

the example on the previous page, we selected the intersection of SW 80th Street and SW 71st Avenue in Miami, Fla.)

7. The Map Page appears, with the cursor pointing to the found intersection. The intersection in our example is shown below.



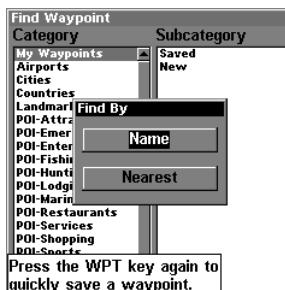
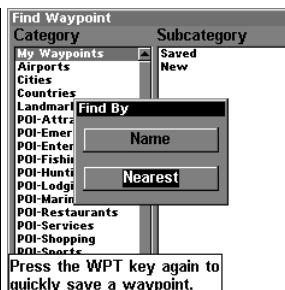
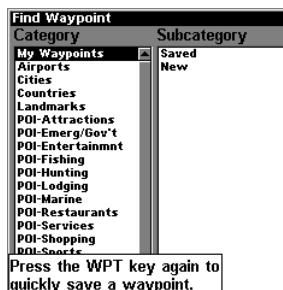
**Map Page showing results of an intersection search.
The cursor points to the located intersection.**

If you want to navigate to the found intersection, just press **MENU | ENT | EXIT**.

Find Waypoints

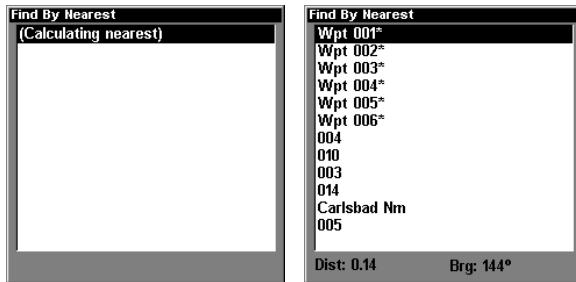
1. Press **WPT | ENT**.

2. If searching for the waypoint **By Name**, press **ENT**. If searching for the **Nearest** waypoint, press **↓** to **NEAREST | ENT**. (To search by name, jump to step 5 below.)



Find Waypoint menu, left; **Find By Nearest** command, center,
Find by Name command, right.

3. If you're looking for nearest, LMS-240 says it is calculating, then a list of waypoints appears. The closest is highlighted at the top of the list and the farthest at the bottom of the list.

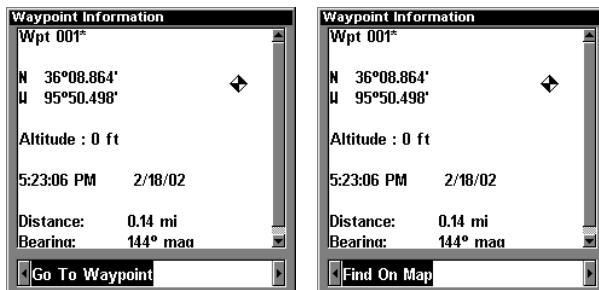


Calculating message, left, and list of the nearest waypoints, right.

4. To see location information on the closest (highlighted) waypoint, press **ENT** and the Waypoint Information screen appears. (If you wanted to, you could select another waypoint from the list with the \uparrow or \downarrow keys.)

A. **To navigate** to the waypoint, press **ENT**. (The Go To Waypoint command is already highlighted.) The unit will show navigation information to the waypoint.

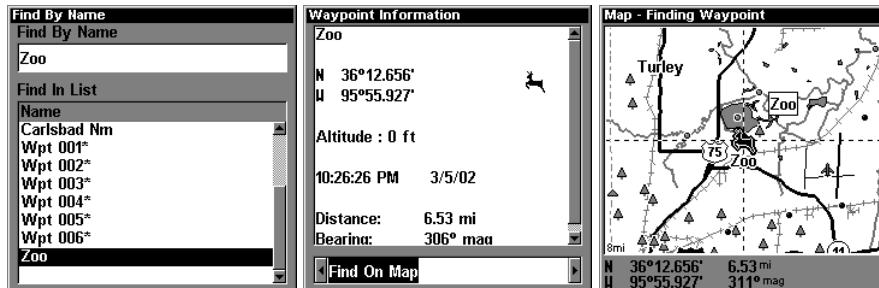
B. **To find** the waypoint, press \rightarrow to **FIND ON MAP|ENT**. The Map Page appears with the cursor highlighting the found waypoint.



Waypoint Information screens with the Go To Waypoint command selected, left, and the Find on Map command selected, right.

To clear these menus and return to the previous page, press **EXIT** repeatedly.

5. **If you're looking by name**, there are two options: A. You can **spell out** the name in the top selection box. Press \uparrow or \downarrow to change the first letter, then press \rightarrow to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. B. Or you can jump down to the lower selection list by pressing **ENT**, then press \downarrow or \uparrow to select a waypoint from the list, then press **ENT**. The waypoint information screen appears.



Find By Name menu, left. Waypoint Information screen, center. At right, the found waypoint is highlighted by the cursor on the Map Page.

A. **To navigate** to the waypoint, press **ENT**. (Go To Waypoint command is already highlighted.) The unit will show navigation information to the waypoint.

B. **To find** the waypoint, press → to **FIND ON MAP|ENT**. The Map Page appears with the cursor highlighting the found waypoint.

To clear these menus and return to the previous page, press **EXIT** repeatedly.

Section 10: Supplemental Material

Datums Used by LMS-240

WGS 1984	Arc 1950 - Botswana	Bermuda 1957 - Bermuda
Default	Arc 1950 - Burundi	Bissau - Guinea-Bissau
Adindan	Arc 1950 - Lesotho	Bogota Observatory - Colombia
Mean for Ethiopia, Sudan	Arc 1950 - Malawi	Bukit Rimpah - Indonesia (Bangka & Belitung Islands)
Adindan	Arc 1950 - Swaziland	Camp Area Astro - Antarctica (McMurdo Camp Area)
Burkina Faso	Arc 1950 - Zaire	Campo Inchauspe - Argentina
Adindan	Arc 1950 - Zambia	Canton Astro 1966 - Phoenix Islands
Cameroon	Arc 1950 - Zimbabwe	Cape - South Africa
Adindan	Arc 1960 - Mean for Kenya, Tanzania	Cape Canaveral - Bahamas, Florida
Mali	Ascension Island 1958 - Ascension Island	Carthage - Tunisia
Adindan	Astro Beacon E 1945 - Iwo Jima	Carthage - Tunisia
Senegal	Astro DOS 71/4 - St. Helena Island	Carthage - Tunisia
Adindan	Astro Tern Island (FRIG) 1961 - Tern Island	Chatham Island Astro 1971; New Zealand (Chatham Island)
Sudan	Astronomical Station 1952 - Marcus Island	Chua Astro Paraguay
Afgooye	Australian Geodetic 1966 - Australia & Tasmania	Corrego Alegre Brazil
Somalia	Australian Geodetic 1984 - Australia & Tasmania	Dabola Guinea
Ain el Abd 1970	Ayabelle Lighthouse - Djibouti	Djakarta (Batavia) Indonesia (Sumatra)
Bahrain	Bellevue (IGN) - Efate & Erromango Islands	
Ain el Abd 1970		
Saudi Arabia		
Anna 1 Astro 1965		
Cocos Islands		
Antigua Island Astro 1943; Antigua (Leeward Islands)		
Arc 1950; Mean for Botswana, Lesotho, Malawi, Swaziland, Zaire, Zambia and Zimbabwe		

DOS 1968	European 1950	Mahe Island
New Georgia Islands (Gizo Island)	Italy (Sardinia)	Massawa Ethiopia (Eritrea)
Easter Island 1967	European 1950	Merchich
Easter Island	(Sicily)	Malta Morocco
European 1950	Ireland 1965	Midway Astro 1961
Mean for Austria, Belgium, Denmark, Finland, France, West Germany, Gibraltar, Greece, Italy, Luxembourg, Netherlands, Norway, Portugal, Spain, Sweden, Switzerland	Ireland	Midway Islands
European 1950	ISTS 061 Astro 1968	Minna
Mean for Austria, Denmark, France, West Germany, Netherlands, Switzerland	South Georgia Islands	Cameroon
European 1950	ISTS 073 Astro 1969	Minna
Mean for Austria, Denmark, France, West Germany, Netherlands, Switzerland	Diego Garcia	Nigeria
European 1950	Johnston Island 1961	Montserrat Island Astro
Mean for Iraq, Israel, Jordan, Lebanon, Kuwait, Saudi Arabia, Syria	Johnston Island	1958; Montserrat (Leeward Islands)
European 1950	Kandawala	M'Poraloko
Mean for Austria, Denmark, France, West Germany, Netherlands, Switzerland	Sri Lanka	Gabon, Nahrwan, Oman (Masirah Island)
European 1950	Kerguelen Island 1949	Nahrwan
Mean for Iraq, Israel, Jordan, Lebanon, Kuwait, Saudi Arabia, Syria	Kerguelen Island	Saudi Arabia
European 1950	Kertau 1948	Nahrwan
Cyprus	West Malaysia & Singapore	United Arab Emirates
European 1950	Kusaie Astro 1951	Naparima BWI
Egypt	Caroline Islands	Trinidad & Tobago
European 1950	L.C. 5 Astro 1961	North American 1927
England, Channel Islands, Ireland, Scotland, Shetland Islands	Cayman Brac Island	Mean for Antigua, Barbados, Barbuda, Caicos Islands, Cuba, Dominican Republic, Grand Cayman, Jamaica, Turks Islands
European 1950	Leigon	
Finland, Norway	Ghana	
European 1950	Liberia 1964	
Greece	Liberia	
European 1950	Luzon	North American 1927
Iran	Philippines (Excluding Mindanao)	Mean for Belize, Costa Rica, El Salvador, Guatemala, Honduras, Nicaragua
European 1950	Luzon	
	Philippines (Mindanao)	
	Mahe 1971	North American 1927
		Mean for Canada

North American 1927 Mean for CONUS (Continental United States)	North American 1927 Cuba	Great Britain 1936 - England
North American 1927 Mean for CONUS (East of Mississippi River) including Louisiana, Missouri, Minnesota	North American 1927 Greenland (Hayes Peninsula)	Ordinance Survey Great Britain 1936 - England, Isle of Man, Wales
North American 1927 Mean for CONUS (West of Mississippi River)	North American 1927 Mexico	Ordinance Survey Great Britain 1936 - Scotland, Shetland Islands
North American 1927 Alaska	North American 1983 Alaska, Canada, CONUS	Ordinance Survey Great Britain 1936 - Wales
North American 1927 Bahamas (Except San Salvador Island)	North American 1983 Central America, Mexico	Pico de las Nieves Canary Islands
North American 1927 Bahamas (San Salvador Island)	Observatorio Meteorológico 1939; Azores (Corvo & Flores Islands)	Pitcairn Astro 1967 Pitcairn Island
North American 1927 Canada (Alberta, British Columbia)	Old Egyptian 1907 Egypt	Point 58
North American 1927 Canada (Manitoba, Ontario)	Old Hawaiian Mean for Hawaii, Kauai, Maui, Oahu	Sweden
North American 1927 Canada (New Brunswick, Newfoundland, Nova Scotia, Quebec)	Old Hawaiian Hawaii	Santo (DOS) 1965 Espírito Santo Island
North American 1927 Canada (Northwest Territories, Saskatchewan)	Old Hawaiian Kauai	Sao Braz Azores (Sao Miguel, Santa Maria Islands)
North American 1927 Canada (Yukon)	Old Hawaiian Maui	Sapper Hill 1943 East Falkland Island
North American 1927 Canal Zone	Old Hawaiian Oahu	Schwarzeck Nambia
	Oman	Selvagem Grande Salvage Islands
	Ordinance Survey Great Britain 1936 - Mean for England, Isle of Man, Scotland, Shetland Islands, Wales	SGS 85 Soviet Geodetic System 1985
	Ordinance Survey	South American 1969 Mean for Argentina,

Bolivia, Brazil, Chile, Colombia, Ecuador, Guyana, Paraguay, Peru, Trinidad & Tobago, and Venezuela	South American 1969 Paraguay South American 1969 Peru	Tokyo Okinawa
South American 1969 Argentina	South American 1969 Trinidad & Tobago	Tristan Astro 1968 Tristan da Cunha
South American 1969 Bolivia	South American 1969 Venezuela	Viti Levu 1916 Fiji (Viti Levu Island)
South American 1969 Brazil	South Asia Singapore	Wake Eniwetok 1960
South American 1969 Chile	Tananarive Observatory 1925; Madagascar	Marshall Islands
South American 1969 Colombia	Timbalai 1948 Brunei, East Malaysia (Sabah, Sarawak)	Wake Island Astro 1952 Wake Atoll
South American 1969 Ecuador	Tokyo Mean for Japan, Korea, Okinawa	WGS 1972 Global Definition
South American 1969 Ecuador (Baltra, Galapagos)	Tokyo Japan	Yacare Uruguay
South American 1969 Guyana	Tokyo Korea	Zanderij Suriname

FCC Compliance

This device complies with Part 15 of the U.S. Federal Communications Commission (FCC) Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the manufacturer could void the user's authority to operate the equipment.

Note:

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the factory customer service department for help.

Notes

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"We", "our", or "us" refers to Lowrance Electronics, Inc., the manufacturer of this product. "You" or "your" refers to the first person who purchases the product as a consumer item for personal, family, or household use. The Databases Limited Warranty applies to the one or more databases that your product may contain. We refer to each of these as a "Database" or together as the "Databases." Your product may thus include the "WBS Database" which contains worldwide background surface mapping data, the "SmartMap Database" which contains inland mapping data, or other Databases.

We warrant to you that we have accurately compiled, processed, and reproduced the portions of the source material on which the Databases are based. However, we are under no obligation to provide updates to the Databases, and the data contained in the Databases may be incomplete when compared to the source material. **WE MAKE NO EXPRESS OR IMPLIED WARRANTY OF ANY KIND ABOUT THE ACCURACY OF THE SOURCE MATERIAL ITSELF, INCLUDING BUT NOT LIMITED TO IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE.**

If there is a defect in any Database, your exclusive remedy shall be, at our option, either a refund of the price you paid for the product containing the defective Database or a replacement of such product. **WE WILL NOT UNDER ANY CIRCUMSTANCES BE LIABLE TO ANYONE FOR ANY SPECIAL, CONSEQUENTIAL, INCIDENTAL, OR OTHER INDIRECT DAMAGE OF ANY KIND.**

Some states do not allow the exclusion or limitation of incidental or consequential damages, so the above limitations or exclusions may not apply to you.

This warranty does NOT apply in the following circumstances: (1) when the product has been serviced or repaired by anyone other than us, (2) when the product has been connected, installed, combined, altered, adjusted, or handled in a manner other than according to the instructions furnished with the product, (3) when any serial number has been effaced, altered, or removed, or (4) when any defect, problem, loss, or damage has resulted from any accident, misuse, negligence, or carelessness, or from any failure to provide reasonable and necessary maintenance in accordance with the instructions of the owner's manual for the product.

We reserve the right to make changes or improvements in our products from time to time without incurring the obligation to install such improvements or changes on equipment or items previously manufactured.

This warranty gives you specific legal rights and you may also have other rights which may vary from state to state.

Your remedies under this warranty will be available so long as you can show in a reasonable manner that the defect occurred within one (1) year from the date of your original purchase, and we must receive your warranty claim no later than 30 days after such 1-year period expires. Your claim must be substantiated by a dated sales receipt or sales slip.

LOWRANCE ELECTRONICS FULL ONE-YEAR WARRANTY

"We," "our," or "us" refers to LOWRANCE ELECTRONICS, INC., the manufacturer of this product. "You" or "your" refers to the first person who purchases this product as a consumer item for personal, family or household use.

We warrant this product against defects or malfunctions in materials and workmanship, and against failure to conform to this product's written specifications, all for one (1) year from the date of original purchase by you. **WE MAKE NO OTHER EXPRESS WARRANTY OR REPRESENTATION OF ANY KIND WHATSOEVER CONCERNING THIS PRODUCT.** Your remedies under this warranty will be available so long as you can show in a reasonable manner that any defect or malfunction in materials or workmanship, or any non-conformity with the product's written specifications, occurred within one year from the date of your original purchase, which must be substantiated by a dated sales receipt or sales slip. Any such defect, malfunction, or non-conformity which occurs within one year from your original purchase date will either be repaired without charge or be replaced with a new product identical or reasonably equivalent to this product, at our option, within a reasonable time after our receipt of the product. If such defect, malfunction, or non-conformity remains after a reasonable number of attempts to repair by us, you may elect to obtain without charge a replacement of the product or a refund for the product. **THIS REPAIR, OR REPLACEMENT OR REFUND (AS JUST DESCRIBED) IS THE EXCLUSIVE REMEDY AVAILABLE TO YOU AGAINST US FOR ANY DEFECT, MALFUNCTION, OR NON-CONFORMITY CONCERNING THE PRODUCT OR FOR ANY LOSS OR DAMAGE RESULTING FROM ANY OTHER CAUSE WHATSOEVER. WE WILL NOT UNDER ANY CIRCUMSTANCES BE LIABLE TO ANYONE FOR ANY SPECIAL, CONSEQUENTIAL, INCIDENTAL, OR OTHER INDIRECT DAMAGE OF ANY KIND.**

Some states do not allow the exclusion or limitation of incidental or consequential damages, so the above limitations or exclusions may not apply to you.

This warranty does NOT apply in the following circumstances: (1) when the product has been serviced or repaired by anyone other than us; (2) when the product has been connected, installed, combined, altered, adjusted, or handled in a manner other than according to the instructions furnished with the product; (3) when any serial number has been effaced, altered, or removed; or (4) when any defect, problem, loss, or damage has resulted from any accident, misuse, negligence, or carelessness, or from any failure to provide reasonable and necessary maintenance in accordance with the instructions of the owner's manual for the product.

We reserve the right to make changes or improvements in our products from time to time without incurring the obligation to install such improvements or changes on equipment or items previously manufactured.

This warranty gives you specific legal rights and you may also have other rights which may vary from state to state.

REMINDER: You must retain the sales slip or sales receipt proving the date of your original purchase in case warranty service is ever required.

**LOWRANCE ELECTRONICS
12000 E. SKELLY DRIVE, TULSA, OK 74128
(800) 324-1356**

How to Obtain Service... ...in the USA:

We back your investment in quality products with quick, expert service and genuine Lowrance parts. If you're in the United States and you have technical, return or repair questions, please contact the Factory Customer Service Department. Before any product can be returned, you must call customer service to determine if a return is necessary. Many times, customer service can resolve your problem over the phone without sending your product to the factory. To call us, use the following toll-free number:

800-324-1356

8 a.m. to 5 p.m. Central Standard Time, M-F

Lowrance Electronics may find it necessary to change or end our shipping policies, regulations, and special offers at any time. We reserve the right to do so without notice.

...in Canada:

If you're in Canada and you have technical, return or repair questions, please contact the Factory Customer Service Department. Before any product can be returned, you must call customer service to determine if a return is necessary. Many times, customer service can resolve your problem over the phone without sending your product to the factory. To call us, use the following toll-free number:

800-661-3983

905-629-1614 (not toll-free)

8 a.m. to 5 p.m. Eastern Standard Time, M-F

...outside Canada and the USA:

If you have technical, return or repair questions, contact the dealer in the country where you purchased your unit. To locate a dealer near you, visit our web site, www.lowrance.com and click on Support and then click Dealer Locator.

Accessory Ordering Information for all countries

To order Lowrance GPS accessories such as computer cables or MMC cards, please contact:

1) Your local marine dealer or consumer electronics store. Most quality dealers that handle marine electronic equipment or other consumer electronics should be able to assist you with these items.

To locate a Lowrance dealer near you, visit our web site, www.lowrance.com and click on Support and then click Dealer Locator. Or, you can consult your telephone directory for listings.

2) U.S. customers: LEI Extras Inc., PO Box 129, Catoosa, OK 74015-0129 Call 1-800-324-0045 or visit our web site www.lei-extras.com.

3) Canadian customers can write:

Lowrance/Eagle Canada, 919 Matheson Blvd. E. Mississauga, Ontario L4W2R7 or fax 905-629-3118.

Shipping Information

If it becomes necessary to send a product for repair or replacement, you must first receive a return authorization number from Customer Service. Products shipped without a return authorization will not be accepted. When shipping, we recommend you do the following:

1. Always use the original shipping container and filler material the product was packed in.
2. Always insure the parcel against damage or loss during shipment. Lowrance does not assume responsibility for goods lost or damaged in transit.
3. For proper testing, include a brief note with the product describing the problem. Be sure to include your name, return shipping address and a daytime telephone number.

Visit our web site:

lowrance.com

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