



# LCX-20C

## Fish-finding Sonar & Mapping GPS Operation Instructions

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**WARNING!**

**A CAREFUL NAVIGATOR NEVER RELIES ON ONLY ONE METHOD TO OBTAIN POSITION INFORMATION.**

***CAUTION***

*When showing navigation data to a position (waypoint), a GPS unit will show the shortest, most direct path to the waypoint. It provides navigation data to the waypoint regardless of obstructions. Therefore, the prudent navigator will not only take advantage of all available navigation tools when traveling to a waypoint, but will also visually check to make sure a clear, safe path to the waypoint is always available.*

**WARNING!**

**When a GPS unit is used in a vehicle, the vehicle operator is solely responsible for operating the vehicle in a safe manner. Vehicle operators must maintain full surveillance of all pertinent driving, boating or flying conditions at all times. An accident or collision resulting in damage to property, personal injury or death could occur if the operator of a GPS-equipped vehicle fails to pay full attention to travel conditions and vehicle operation while the vehicle is in motion.**

# Section 1:

## Read Me First!

### ***How this manual can get you out on the road, fast!***

Welcome to the exciting world of digital sonar and GPS! We know you're anxious to begin navigating and finding fish, but we have a favor to ask. Before you grab the unit and begin installing it, please give us a moment or two to explain how our manual can help you get the best performance from your combination fish finder and GPS receiver.

First, we want to thank you for buying a Lowrance sonar/GPS unit. Whether you're a first time user or a professional fisherman, you'll discover that your unit is easy to use, yet capable of handling demanding navigation and sonar tasks. When you team your unit with our custom mapping software MapCreate™ 6, you have an incredible combination. With a full VGA color display, recording capability and remarkable resolution, you won't find another GPS/sonar unit with this much power and this many features for this price!

Our goal for this book is to get you on the water. Like you, we'd rather spend more time boating or fishing and less time reading the manual!

So, we designed our book so you *don't* have to read the *whole thing* from front to back to find the information you want. At the start (or end) of each segment, we'll tell you what content is coming up next. If it's a concept you're already familiar with, we'll show you how and where to skip ahead for the next important topic. We've also made it easy to look up any tips you may need from time to time. Here's how:

The manual is organized into 10 sections. This first section is an introduction to the LCX-20C sonar and GPS. It tells you the basics you need to know so you'll easily be able to make the unit, not only tell you where you are, but also where to find fish.

Section 2 will help you install your unit, the transducer and the GPS antenna module. We'll also show you how to install the MultiMedia Card (MMC) and give you some information on available accessories.

Section 3 covers *Basic Sonar Operation*. It will show you how easy it is to run your sonar, right out of the box. This section features a one-page Sonar Quick Reference. (If you've already jumped ahead and figured out how to install the unit yourself, and you just *can't* wait any longer, turn to the Quick Reference on page 51 and head for the water with your unit!)

After you've gained some experience with your sonar, you'll want to check out Section 4, which discusses advanced *Sonar Options and Other Features*.

When you come to a sonar menu command on the unit's screen, you can look it up in the manual by skimming over the table of contents, flipping through Section 3, or scanning through the sonar options in Section 4.

If you're having difficulty with your sonar, you can find an answer to the most common problems in Section 5, *Sonar Troubleshooting*.

The manual switches from sonar to navigation in Section 6, which introduces you to *Basic GPS Operations*. **This section features a one-page GPS Quick Reference on page 107.**

Section 6 contains short, easy-to-scan GPS lessons that follow one another in chronological order. They're all you'll need to know to find your way on the water quickly.

After you've learned the basics (or if you already have some GPS experience), you may want to try out some of the unit's many advanced navigation features. That brings us to Section 7, *Advanced GPS Operations*. This section contains the rest of the unit's GPS command functions, organized in alphabetical order.

When you come to a GPS menu command on the screen, you can look it up in the manual by skimming over the table of contents, flipping through Section 6, or scanning through the command portion of Section 7.

This unit is ready to use right out of the box, but you can fine tune and customize its operation with dozens of options. Since sonar is the unit's key feature, we put the main sonar options in Section 4. Some options, such as screen brightness settings, affect both sonar and GPS operations. We describe how to use those common options along with GPS options in Section 8, *System Setup and GPS Setup Options*. Section 8 is organized in alphabetical order.

In Section 9, we go into more detail on one of the unit's most remarkable GPS capabilities — Searching. We'll introduce a search example in the Basic GPS Operation section, but there are so many map items you can search for, we had to give this function its own section in the manual! For example, did you know your unit can look up business phone numbers, like a virtual Yellow Pages? We'll show you how in Section 9.

Finally, in Section 10, we offer *Supplemental Material*, including a list of the GPS datums, warranties and customer service information.

Now, if you're into the fine details, glance over the next segment on specifications to see how much sonar and GPS power your unit contains. It's important to *us* (and our power users), but, if *you* don't care how many watts of power the unit has, or how many waypoints it can store, skip ahead to important information on how sonar works, on page 5. (Background on GPS begins on page 6.)

## Capabilities and Specifications: LCX-20C

### General

**Display:**..... High-brightness LCD; programmable to viewing preference.  
**LCX-20C:** 6.0" (15.2 cm) diagonal.

**Resolution:**..... **LCX-20C:** 320 pixel x 240 pixel resolution; 76,800 total pixels; 256-color, full VGA.

**Backlighting:**..... Fluorescent cold cathode backlit screen with multiple lighting levels; backlit keypad.

**Input power:**..... 10 to 15 volts DC.

**Current drain:** ..... Sonar only: 500 ma lights off; 600 ma lights on. With GPS and lights on: 700 ma.

**Case size:**..... 7.3" H x 9.6" W x 3.7" D (18.5 x 24.4 x 9.4 cm); sealed and waterproof; suitable for saltwater use.

**MMC slots:** ..... Two in waterproof compartment (SD card compatible).

**Back-up memory:** ..... Built-in memory stores sonar records and GPS data for decades. User settings are stored when unit is turned off.

**Languages:**..... 10 languages selectable by user.

### Sonar

**Frequency:**..... Depending on transducer, either 50/200 kHz dual-frequency or 200 kHz single-frequency.

**Transducers:** ..... Skimmer® transducer with built-in temperature sensor available. Use either a dual-frequency transducer with 35°/12° cone angles or a single-frequency transducer with a 20° cone angle. Both transducers operate at speeds up to 70 mph (61 kts).

**Transmitter:** ..... **Dual-frequency:** 8,000 watts peak-to-peak/1 kW RMS.  
**Single-frequency:** 3,000 watts peak-to-peak/375 watts RMS.

### Sonar sounding

**Depth capability:**..... **Dual-frequency:** 3,000 feet (915 meters).  
**Single-frequency:** 1,000 feet (305 meters)

**Depth display:**..... Continuous display.

**Graph recording:** ..... Up to 1 GB on one MMC (or SD) card

**Audible alarms:** ..... Deep/shallow/fish/zone.

**Automatic ranging:** ..... Yes, with instant screen updates.

**Auto bottom track:** ..... Yes

**Zoom bottom track:** ..... Yes.

**Split-screen zoom:** ..... Yes.

**Surface water temp:** ..... Yes, built into transducer.

**Speed/distance log:** ..... Yes, with optional speed sensor.

## GPS

**Receiver/antenna:** ..... External; LGC-2000.

**Recording:** ..... MMC & SD memory cards for recording GPS trip details and displaying charts or custom maps.

**Background map:** ..... Built-in custom, detailed Lowrance map.

Contains: enhanced detail of continental U.S. and Hawaii.

**Custom mapping:** ..... MapCreate™ 6 software optional; optional plug and play LEI FreedomMaps™ offer the same high-detail without the computer work of MapCreate. Other plug and play mapping options include IMS™ Fishing Hot Spots®, LEI NauticPaths™ charts and Navionics® charts.

**Mapping memory:** ..... Up to 1 GB on one MMC (or SD) card.

**Position updates:** ..... Every second.

**Position points:** ..... 1,000 waypoints; 1,000 event marker icons.

**Audible alarms:** ..... Arrival/off-course/anchor.

## Symbols for

**waypoints or icons:** ..... 42.

**Routes:** ..... 100; up to 100 waypoints per route.

**Plot Trails:** ..... 10 savable; up to 9,999 points per trail.

**Zoom range:** ..... 37 ranges; 0.05 to 4,000 miles.

## NOTE:

The above memory capacities refer only to the unit's on-board memory. The amount of GPS or sonar data you can record and save for recall later is only limited by the number of MMC cards you have.

## NOTICE!

The storage and operation temperature range for your unit is from -4 degrees to +167 degrees Fahrenheit (-20 degrees to +75 degrees Celsius). *Extended storage or operation in temperatures higher or lower than specified will damage the liquid crystal display in your unit. This type of damage is not covered by the warranty.* For more information, contact the factory's Customer Service Department. Phone numbers are listed on the last page.

## How Your Sonar Works

Sonar has been around since the 1940s, so if you already know how it works, skip down to read about the relatively new technology of GPS. But, if you've never owned a sonar fish finder, this segment will tell you the underwater basics.

Sonar is an abbreviation for SQund NAvigation and Ranging, a technology developed during World War II for tracking enemy submarines. (Lowrance developed the world's *first* transistorized *sportfishing* sonar in 1957.) A sonar consists of a transmitter, transducer, receiver and display. Here's a simple explanation of how it finds the bottom and the fish.

The transmitter emits an electrical impulse, which the transducer converts into a sound wave and sends into the water. (The sound frequency can't be heard by humans or fish.) The sound wave strikes an object (fish, structure, bottom) and bounces back to the transducer, which converts the sound back into an electrical signal.

The receiver amplifies this return signal, or echo, and sends it to the display, where an image of the object appears on the scrolling sonar chart. The sonar's microprocessor calculates the time lapse between the transmitted signal and echo return to determine the distance to the object. The whole process repeats itself several times each second.

Your sonar unit can record a log of the sonar signals that scroll across the screen and save them to the MMC memory card. (These recordings are also called sonar charts or sonar graphs.) You can replay this sonar log in the unit using the Sonar Simulator function, or play it back on a personal computer using our free Sonar Viewer. The viewer is available for download from the Lowrance web site, [www.lowrance.com](http://www.lowrance.com).

You can save several different sonar log files, erase 'em and record new ones, over and over again. The size of your sonar recordings are only limited by the free space available on your MMC.

## How Your GPS Works

You'll navigate faster and easier if you understand how this unit scans the sky to tell you where you are on the earth — and, where you're going. (But if you already have a working understanding of GPS receivers and the GPS navigation system, skip on ahead to Section 2, *Installation & Accessories* on page 11. If you're new to GPS, read on, and you can later impress your friends with your new-found knowledge.)

First, think of your unit as a small but powerful computer. (But don't worry — we made the series easy to use, so you don't need to be a computer expert to find your way!) The unit includes a keypad and a screen with menus so you can tell it what to do. The screen also lets the unit show your location on a moving map, as well as point the way to your destination.

This gimbal-mounted unit uses an external antenna/receiver module, which makes the whole system work something like your car radio. But instead of your favorite dance tunes, this receiver tunes in to a couple of dozen GPS satellites circling the earth. (It will also listen in to the WAAS satellites in orbit, but more about that in the upcoming segment introducing you to GPS and WAAS.)

Your unit listens to signals from as many satellites as it can "see" above the horizon, eliminates the weakest signals, then computes its location in relation to those satellites. Once it figures its latitude and longitude, the unit plots that position on the moving map shown on the screen. The whole process takes place several times a second!

The performance doesn't stop there. Stored in the permanent memory of every unit is a basic background map of the *entire* world. We lock it in here at the factory — you can't change or erase this map.

The background map is suitable for many navigation chores, but for maximum accuracy and much more detail, you need our optional map-making software, MapCreate™ 6. Some unit features — such as searching for businesses and addresses — won't work without a custom MapCreate map. There is so much detail in our background map (and even more in MapCreate) that we'll describe its contents and differences in Section 6, *Basic GPS Operations*, on page 95.

Another portion of the unit's onboard memory is devoted to *recording* GPS navigation information, which includes waypoints, event marker icons, trails and routes. This lets you look back the way you came. Think of this data storage like the hard drive memory in a computer or a tape in a cassette tape recorder. You can save several different GPS data files,

erase 'em and record new ones, over and over again. Like any computer file, these **GPS Data Files** (file format \*.usr) can be shared between other Lowrance GPS or sonar/GPS units and even personal computers.

Your unit has one more thing in common with a personal computer. Just as computers have a floppy disk drive for storing and exchanging files, this unit has a slot for an MMC (MultiMedia Card) or SDC (Secure Digital card) flash memory card. These solid-state memory devices are about the size of a postage stamp, but can hold data ranging from 8 MB to 1 GB in size. (Compare that to a floppy disk's 1.44 MB capacity!) The unit uses all that MMC space for two key GPS purposes. (The MMC is also used to record sonar logs. See page 5.)

First, you can backup your onboard GPS Data Files by copying them to the MMC. Since the MMC is removable (like a floppy disk or a cassette tape), you can store these GPS Data Files on a personal computer equipped with an MMC card reader. (Or store them on a pocketful of MMCs, if you don't have a computer.) Our MapCreate mapping software can save, edit or create its own GPS Data Files, which can be copied to the MMC and then loaded from the MMC into the unit's memory. (**NOTE:** No matter where they come from, GPS Data Files *must* be loaded from the MMC into memory before the unit can use them.)

The other key GPS use for MMCs is storage of special high-detail, custom maps, which you can produce on your computer with our MapCreate software. These MapCreate custom maps contain much greater detail than the basic background map. These **Custom Map Files** (file format \*.lcm) can also be shared between other Lowrance GPS or sonar/GPS units and personal computers. (For example, the exact same MMC, custom map files and GPS data files can be used interchangeably between your gimbal-mounted LCX-20C and the hand-held iFINDER™ GPS receiver.)

The unit automatically reads Custom Map Files directly from the MMC or SDC. To use a custom map, all you need to do is slide an MMC containing a map into the unit.

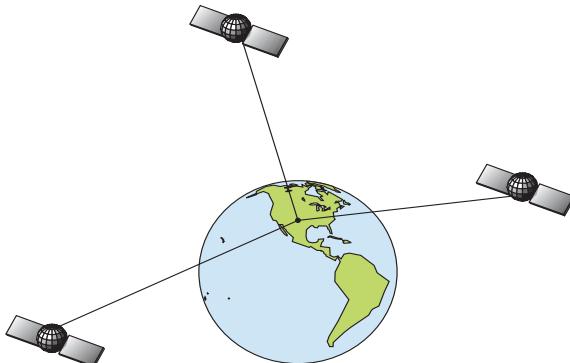
## Introduction to GPS and WAAS

Well, now you know the basics of how the unit does its work. You might be ready to jump ahead to Section 2, *Installation & Accessories*, on page 11, so you can mount your unit and plug in the power. Or you might want to see how our text formatting makes the manual tutorials easy to skim. If that's the case, move on to "How to Use This Manual" on page 10. But, if you want to understand the current state of satellite navigation, look over this segment describing how GPS and its new companion WAAS work together to get you where you're going.

The Global Positioning System (GPS) was launched July 17, 1995 by the United States Department of Defense. It was designed as a 24-hour-a-day, 365-days-a-year, all weather global navigation system for the armed forces of the U.S. and its allies. Civilian use was also available, but it was less accurate because the military scrambled the signal somewhat, using a process called Selective Availability (SA.)

GPS proved so useful for civilian navigation that the federal government discontinued SA on May 2, 2000, after the military developed other methods to deny GPS service to enemy forces. Reliable accuracy for civilian users jumped from 100 meters (330 feet) under SA to the present level of 10 to 20 meters (about 30 to 60 feet.)

Twenty-four satellites orbit 10,900 nautical miles above the Earth, passing overhead twice daily. A series of ground stations (with precisely surveyed locations) controls the satellites and monitors their exact locations in the sky. Each satellite broadcasts a low-power signal that identifies the satellite and its position above the earth. Three of these satellites are spares, unused until needed. The rest virtually guarantee at least four satellites are in view nearly anywhere on Earth at all times.



**A minimum of three satellites are required to determine a 2D fix.**

The system requires signal reception from three satellites in order to determine a position. This is called a 2D fix. It takes four satellites to determine both position and elevation (your height above sea level — also called altitude). This is called a 3D fix.

Remember, the unit must have a clear view of the satellites in order to receive their signals. Unlike radio or television signals, GPS works at very high frequencies. These signals can be easily blocked by trees, buildings, an automobile roof, even your body.

Like most GPS receivers, this unit doesn't have a compass or any other navigation aid built inside. It relies solely on the signals from the satellites to calculate a position. Speed, direction of travel, and distance are all calculated from position information. Therefore, in order for the unit to determine direction of travel, you must be moving and the faster, the better. This is not to say that it won't work at walking or trolling speeds — it will. There will simply be more "wandering" of the data shown on the display.

GPS is plenty accurate for route navigation, but the U.S. Federal Aviation Administration has special needs for aircraft traffic control that go beyond basic GPS. The FAA has a plan under way to boost GPS performance even further with its Wide Area Augmentation System, or WAAS. This GPS add-on will include a time control element that will help airliners fly closer together while avoiding collisions. In addition to carefully spacing airplanes along travel corridors, WAAS will eventually make instrument landings and takeoffs more accurate as it replaces existing aviation navigation systems.

Non-aviators can use WAAS signals to make their GPS navigation even more accurate. Your unit receives both GPS and WAAS signals. WAAS, however, has some limits you should know about.

First, the U.S. government has not completed construction of the WAAS system, so it is not yet fully operational. The ground stations are in place, but only a few of the needed WAAS satellites have been launched.

WAAS *can* boost the accuracy of land GPS navigation, but the system is designed for aircraft. The satellites are in a fixed orbit around the Equator, so they appear very low in the sky to someone on the ground in North America. Aircraft and vessels on open water can get consistently good WAAS reception, but terrain, foliage or even large man-made structures frequently block the WAAS signal from ground receivers.

You'll find that using your GPS receiver is both easy and amazingly accurate. It's easily the most accurate method of electronic navigation available to the general public today. But remember this receiver is only a tool. Always have another method of navigation available, such as a map or chart and a compass.

Also remember this unit will always show navigation information in the shortest line from your present position to a waypoint, regardless of terrain! It only calculates position, it can't know what's between you and your destination. It's up to you to safely navigate around obstacles, no matter how you're using this product.

## How to use this manual: typographical conventions

Many instructions are listed as numbered steps. The keypad and arrow "keystrokes" appear as boldface type, so you can easily skim the instructions and pick out what menu command to use.

### Arrow Keys

The arrow keys control the movement of dotted cross-hair lines on your mapping screen called the cursor. The arrow keys also control a horizontal line depth cursor on the sonar screen. The arrow keys also help you move around the menus so you can execute different commands. They are represented by symbols like these, which denote the down arrow, up arrow, left arrow and right arrow: ↓ ↑ ← →.

### Keyboard

The other keys perform a variety of functions. When the text refers to a key to press, the key is shown in bold. For example, the "Enter/Icons" key is shown as **ENT** and the "Menu" key is shown as **MENU**.

### Menu Commands

A menu command or a menu option will appear in small capital letters, in a bold sans serif type like this: **ROUTE PLANNING**. These indicate that you are to select this command or option from a menu or take an action of some kind with the menu item. Text that you may need to enter or file names you need to select are shown in italic type, such as *trail name*.

### Instructions = Menu Sequences

Most functions you perform with this unit are described as a sequence of key strokes and selecting menu commands. We've written them in a condensed manner for quick and easy reading.

For example, instructions for navigating a trail would look like this:

1. From the Map Page, press **MENU** | **MENU** | ↓ to **MY TRAILS** | **ENT**.
2. Press ↓ to *Trail 1* | **ENT** | → | ↓ to **NAVIGATE** | **ENT**.
3. You are asked to wait while it converts the trail into a route.
4. The wait message disappears and the unit begins showing navigation information along the trail. Now, begin moving and follow your unit's directions.

In clearer terms, step 1 (above) means: "Start on the Map Page. Press the Menu key twice. Next, repeatedly press (or press and hold) the down arrow key to scroll down the menu and select (highlight) the My Trails menu command. Finally, press the Enter key."

Step 2: "Press the down arrow key repeatedly to scroll to the trail named Trail 1, and press Enter. Next, press the right arrow key and then the down arrow key to highlight the Navigate command, then press Enter."

## Section 2: Installation & Accessories

### Preparations

You can install the sonar and GPS systems in some other order if you prefer, but we recommend this installation sequence:

#### **CAUTION:**

*You should read over this entire installation section before drilling any holes in your vehicle or vessel!*

1. Determine the approximate location for the sonar/GPS unit, so you can plan how and where to route the cables for the antenna, transducer and power. This will help you make sure you have enough cable length for the desired configuration.
2. Determine the approximate location for the transducer and its cable route.
3. Determine the approximate location for the GPS antenna module and its cable route.
4. Determine the location of your battery or other power connection, along with the power cable route.
5. Install the transducer and route the transducer cable to the sonar/GPS unit.
6. Install the GPS antenna and route the antenna cable to the sonar/GPS unit.
7. Install the power cable and route it to the sonar/GPS unit.
8. Mount the sonar/GPS unit.

### Transducer Installation

These instructions will help you install your Skimmer® transducer on a transom, on a trolling motor or inside a hull. These instructions cover both single- and dual-frequency Skimmer transducers. Please read all instructions before proceeding with any installation.

The smaller single-frequency Skimmers typically use a one-piece, stainless steel mounting bracket. The larger dual-frequency Skimmers typically use a two-piece, plastic mounting bracket. The trolling motor mount uses a one-piece plastic bracket with an adjustable strap.

These are all "kick-up" mounting brackets. They help prevent damage if the transducer strikes an object while the boat is moving. If the transducer does "kick-up," the bracket can easily be pushed back into place without tools.

Read these instructions carefully *before* attempting the installation. Determine which of the mounting positions is right for your boat. Use extreme care if mounting the transducer inside the hull, because once the epoxy is applied and it is set into position, the transducer cannot be removed. ***Remember, the transducer installation is the most critical part of a sonar installation.***

## **Recommended Tools and supplies**

If you prefer the option of routing the cable through the transom, you will need a 1" drill bit. A transom mount requires use of a *high quality, marine grade* above- or below-waterline caulking compound.

## **NOTE**

The following installation types also call for these recommended tools and required supplies (supplies are *not* included):

### **Single-frequency transom installations**

Tools include: two adjustable wrenches, drill, #29 (0.136") drill bit, flat-head screwdriver. Supplies: *high quality, marine grade* above- or below-waterline sealant/adhesive compound.

### **Dual-frequency transom installations**

Tools: two adjustable wrenches, drill, #20 (0.161") drill bit, flat-head screwdriver. Supplies: four, 1" long, #12 stainless steel slotted wood screws, *high quality, marine grade* above- or below-waterline sealant/adhesive compound.

### **Single-frequency trolling motor installations**

Tools: two adjustable wrenches, flat-head screwdriver. Supplies: plastic cable ties.

### **Shoot-through hull installations**

Tools: these will vary depending on your hull's composition. Consult your boat dealer or manufacturer. Other tools are a wooden craft stick or similar tool for stirring and applying epoxy, and a paper plate or piece of cardboard to mix the epoxy on. Supplies: rubbing alcohol, 100 grit sandpaper, specially formulated epoxy adhesive available from LEI (see ordering information on the inside back cover). A sandwich hull also requires polyester resin.

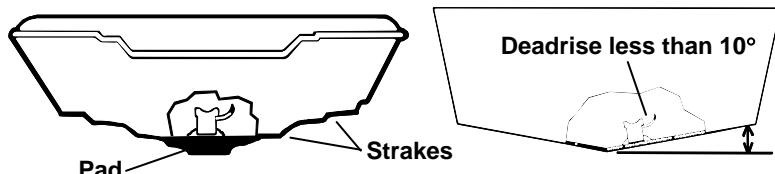
## **Selecting a Transducer Location**

1. The location must be in the water at all times, at all operating speeds.
2. The transducer must be placed in a location that has a *smooth flow* of water at all times. If the transducer is not placed in a smooth flow of water, interference caused by bubbles and turbulence will show on the sonar's display in the form of random lines or dots whenever the boat is moving.

## NOTE:

Some aluminum boats with strakes or ribs on the outside of the hull create large amounts of turbulence at high speed. These boats typically have large outboard motors capable of propelling the boat at speeds faster than 35 mph. Typically, a good transom location on aluminum boats is between the ribs closest to the engine.

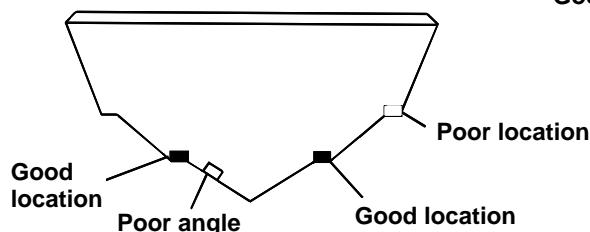
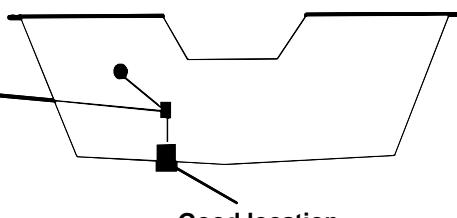
3. The transducer should be installed with its face pointing straight down, if possible. *For shoot-thru applications:* Many popular fishing boat hulls have a flat keel pad that offers a good mounting surface. On vee hulls, try to place the transducer where the deadrise is 10° or less.



Left, vee pad hull; right, vee hull. A pod style transducer is shown here, but the principle is the same for Skimmers inside a hull.

4. If the transducer is mounted on the transom, make sure it doesn't interfere with the trailer or hauling of the boat. Also, don't mount it closer than approximately one foot from the engine's lower unit. This will prevent cavitation (bubble) interference with propeller operation.
5. If possible, route the transducer cable away from other wiring on the boat. Electrical noise from engine wiring, bilge pumps and aerators can be displayed on the sonar's screen. Use caution when routing the transducer cable around these wires.

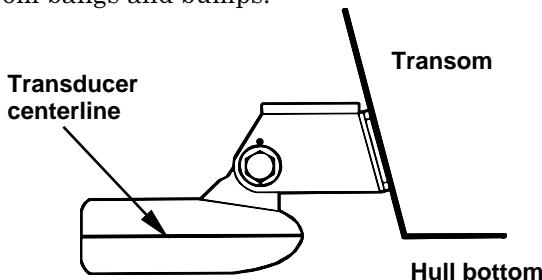
**CAUTION: Clamp the transducer cable to transom near the transducer. This will help prevent the transducer from entering the boat if it is knocked off at high speed.**



Good and poor transducer locations.

## How low should you go?

For most situations, you should install your Skimmer transducer so that its centerline is level with the bottom of the boat hull. This will usually give you the best combination of smooth water flow and protection from bangs and bumps.



**Align transducer centerline with hull bottom.**

However, there are times when you may need to adjust the transducer slightly higher or lower. (The slots in the mounting brackets allow you to loosen the screws and slide the transducer up or down.) If you frequently lose bottom signal lock while running at high speed, the transducer may be coming out of the water as you cross waves or wakes. Move the transducer a little lower to help prevent this.

If you cruise or fish around lots of structure and cover, your transducer may be frequently kicking up from object strikes. If you wish, you may move the transducer a little higher for more protection.

There are two extremes you should avoid. Never let the edge of the mounting bracket extend below the bottom of the hull. Never let the bottom – the face – of the transducer rise above the bottom of the hull.

## Shoot-thru-hull vs. Transom Mounting

In a shoot-thru-hull installation, the transducer is bonded to the *inside* of the hull with epoxy. The sonar "ping" signal actually passes through the hull and into the water. This differs from a bolt-thru-hull installation (often called simply "thru-hull"). In that case, a hole is cut in the hull and a specially designed transducer is mounted *through* the hull with a threaded shaft and nut. This puts the transducer in direct contact with the water.

Typically, shoot-thru-hull installations give excellent high speed operation and good to excellent depth capability. There is no possibility of transducer damage from floating objects, as there is with a transom-mounted transducer. A transducer mounted inside the hull can't be knocked off when docking or loading on a trailer.

However, the shoot-thru-hull installation does have its drawbacks. First, some loss of sensitivity does occur, even on the best hulls. This varies from hull to hull, even from different installations on the same hull. This is caused by differences in hull lay-up and construction.

Second, the transducer angle cannot be adjusted for the best fish arches on your sonar display. (This is not an issue for flasher-style sonars.) Lack of angle adjustment can be particularly troublesome on hulls that sit with the bow high when at rest or at slow trolling speeds.

Third, a transducer **CAN NOT** shoot through wood and metal hulls. Those hulls require either a transom mount or a thru-hull installation.

Fourth, if your Skimmer transducer has a built in temp sensor, it will only show the temperature of the bilge, not the water surface temp.

Follow the testing procedures listed in the shoot-thru-hull installation section at the end of this lesson to determine if you can satisfactorily shoot through the hull.

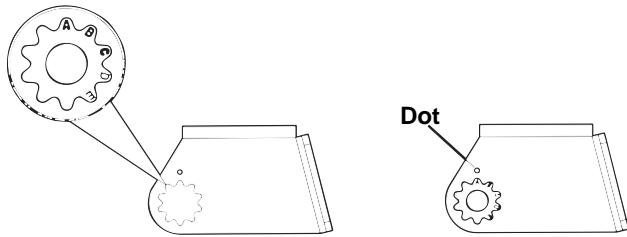
### **Transom Transducer Assembly And Mounting**

The best way to install these transducers is to loosely assemble all of the parts first, place the transducer's bracket against the transom and see if you can move the transducer so that it's parallel with the ground.

The following instructions sometimes vary depending on the mounting bracket that came with your transducer. Single-frequency Skimmers come with a one-piece stainless steel bracket, while dual-frequency Skimmers come with a two-piece plastic mounting bracket. Use the set of instructions that fits your model.

#### **1. Assembling the bracket.**

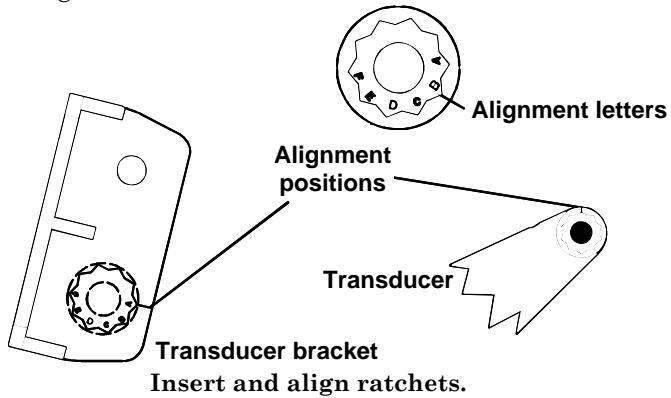
**A. One-piece bracket:** Press the two small plastic ratchets into the sides of the metal bracket as shown in the following illustration. Notice there are letters molded into each ratchet. Place each ratchet into the bracket with the letter "A" aligned with the dot stamped into the metal bracket. This position sets the transducer's coarse angle adjustment for a 14° transom. Most outboard and stern-drive transoms have a 14° angle.

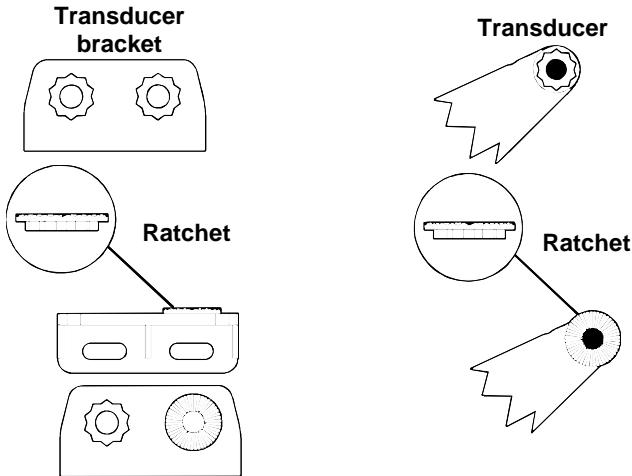


**Align plastic ratchets in bracket.**

**B. Two-piece bracket:** Locate the four plastic ratchets in the transducer's hardware package. Press two ratchets into the sides of the plastic bracket and two on either side of the transducer as shown in the following illustrations. Notice there are letters molded into each ratchet.

Place the ratchets into the bracket with the letter "A" aligned with the alignment mark molded into the bracket. Place the ratchets onto the transducer with the letter "A" aligned with the 12 o'clock position on the transducer stem. These positions set the transducer's coarse angle adjustment for a 14° transom. Most outboard and stern-drive transoms have a 14° angle.





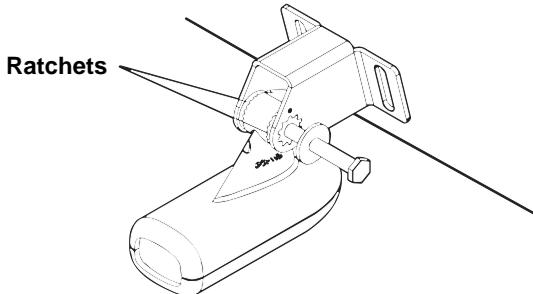
**Add ratchets to bracket and transducer.**

## 2. Aligning the transducer on the transom.

**A. One-piece bracket:** Slide the transducer between the two ratchets. Temporarily slide the bolt though the transducer assembly and hold it against the transom. Looking at the transducer from the side, check to see if it will adjust so that its face is parallel to the ground. If it does, then the "A" position is correct for your hull.

If the transducer's face isn't parallel with the ground, remove the transducer and ratchets from the bracket. Place the ratchets into the holes in the bracket with the letter "B" aligned with the dot stamped in the bracket.

Reassemble the transducer and bracket and place them against the transom. Again, check to see if you can move the transducer so it's parallel with the ground. If you can, then go to step 3A. If it doesn't, repeat step 2A, but use a different alignment letter until you can place the transducer on the transom correctly.

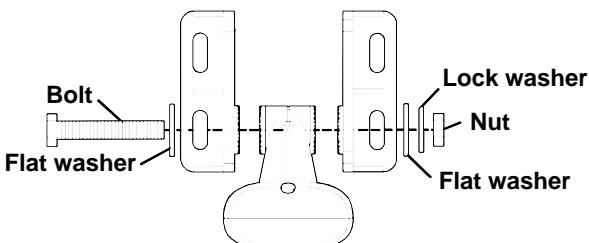


**Insert bolt and check transducer position on transom.**

**B. Two-piece bracket:** Assemble the transducer and bracket as shown in the following figure. Temporarily slide the bolt though the transducer assembly but don't tighten the nut at this time. Hold the assembled transducer and bracket against the transom. Looking at the transducer from the side, check to see if it will adjust so that its face is parallel to the ground. If it does, then the "A" positions are correct for your hull.

If the transducer's face isn't parallel with the ground, remove and disassemble the transducer and ratchets. Place the ratchets into the bracket holes with the letter "B" aligned with the bracket alignment mark. Place them on the transducer aligned with the 12 o'clock position on the transducer stem.

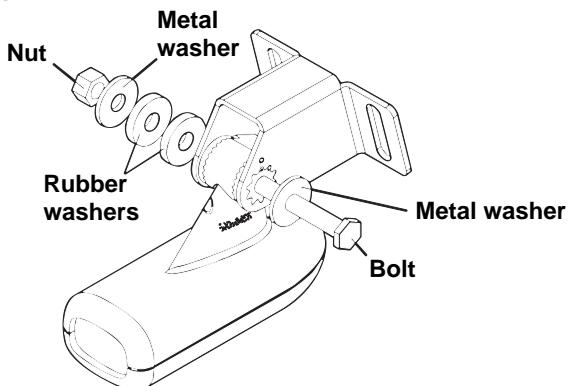
Reassemble the transducer and bracket and place them against the transom. Again, check to see if you can move the transducer so it's parallel with the ground. If you can, then go to step 3B. If it doesn't, repeat step 2B, but use a different alignment letter until you can place the transducer on the transom correctly.



Assemble transducer and bracket.

### 3. Assembling the transducer.

**A. One-piece bracket:** Once you determine the correct position for the ratchets, assemble the transducer as shown in the following figure. Don't tighten the lock nut at this time.



Assemble transducer and bracket.

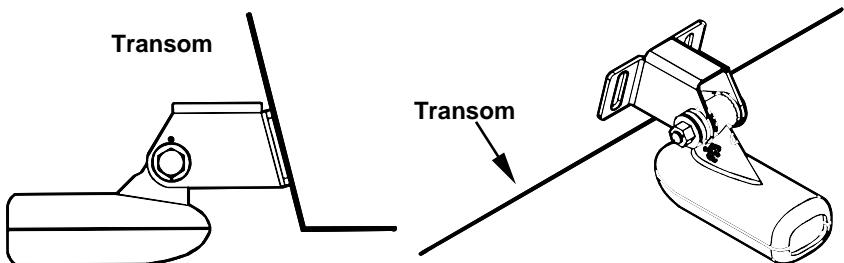
**B. Two-piece bracket:** Once you determine the correct position for the ratchets, assemble the transducer as shown in the figure in step 2B. Don't tighten the lock nut at this time.

#### 4. Drilling mounting holes.

Hold the transducer and bracket assembly against the transom. The transducer should be roughly parallel to the ground. The transducer's centerline should be in line with the bottom of the hull. Don't let the bracket extend below the hull!

Mark the center of each slot for the mounting screw pilot holes. You will drill one hole in the center of each slot.

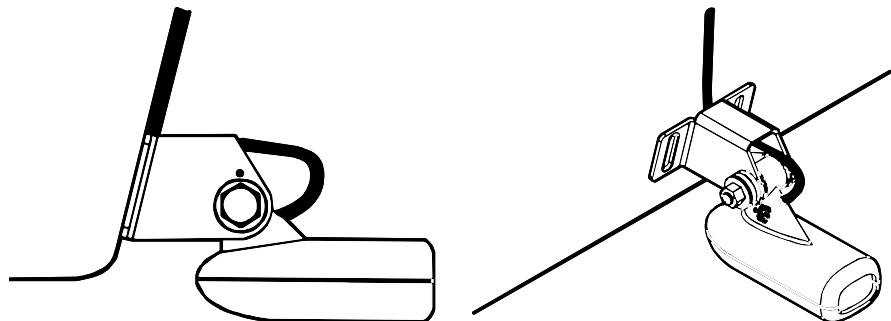
Drill the holes. For the one-piece bracket, use the #29 bit (for the #10 screws). For the two-piece bracket, use the #20 bit (for the #12 screws).



Position transducer mount on transom and mark mounting holes.  
Side view shown (left) and seen from above (right).

#### 5. Attaching transducer to transom.

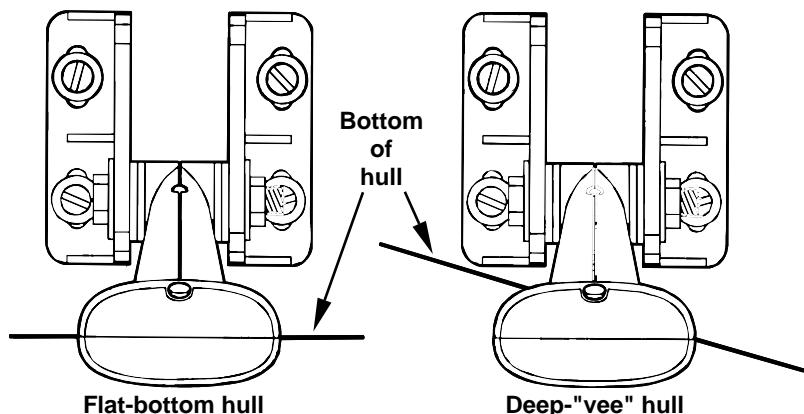
**A. One-piece bracket:** Remove the transducer from the bracket and re-assemble it with the cable passing through the bracket over the bolt as shown in the following figures.



For single-frequency Skimmer, route cable over bolt and through bracket. Side view shown (left) and seen from above (right).

**Both bracket types:** Attach the transducer to the transom. Slide the transducer up or down until it's aligned properly with the bottom of the hull as shown in the preceding and following figures. Tighten the bracket's mounting screws, sealing them with the caulking compound.

Adjust the transducer so that it's parallel to the ground and tighten the nut until it touches the outer washer, then add 1/4 turn. *Don't over tighten the lock nut!* If you do, the transducer won't "kick-up" if it strikes an object in the water.



**Align transducer centerline with hull bottom and attach transducer to transom. Rear view of dual-frequency Skimmer shown.**

6. Route the transducer cable through or over the transom to the sonar unit. Make sure to leave some slack in the cable at the transducer. If possible, route the transducer cable away from other wiring on the boat. Electrical noise from the engine's wiring, bilge pumps, VHF radio wires and cables, and aerators can be picked up by the sonar. Use caution when routing the transducer cable around these wires.

**WARNING:**

**Clamp the transducer cable to the transom close to the transducer. This can prevent the transducer from entering the boat if it is knocked off at high speed.**

If you need to drill a hole in the transom to pass the connector through, the required hole size be 1".

**CAUTION:**

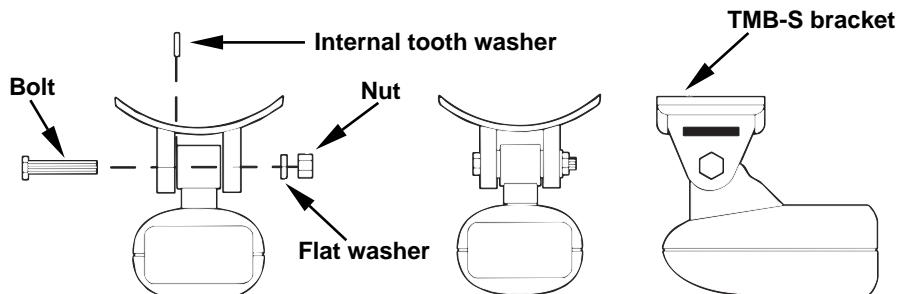
*If you drill a hole in the transom for the cable, make sure it is located above the waterline. After installation, be sure to seal the hole with the same marine grade above- or below-waterline sealant used for the mounting screws.*

**7. Make a test run to determine the results.** If the bottom is lost at high speed, or if noise appears on the display, try sliding the transducer bracket down. This puts the transducer deeper into the water, hopefully, below the turbulence causing the noise. Be careful not to install the transducer bracket below the bottom of the hull!

## TROLLING MOTOR BRACKET INSTALLATION

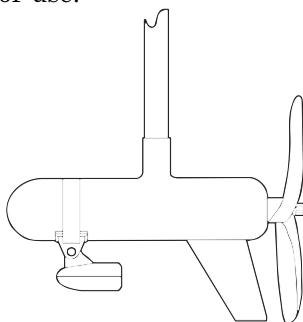
(single-frequency only)

1. Attach the optional TMB-S bracket to the transducer as shown in the following figure, using the hardware supplied with the transducer. (Note: The internal tooth washer is supplied with the TMB-S.)



Attach motor mounting bracket to transducer.

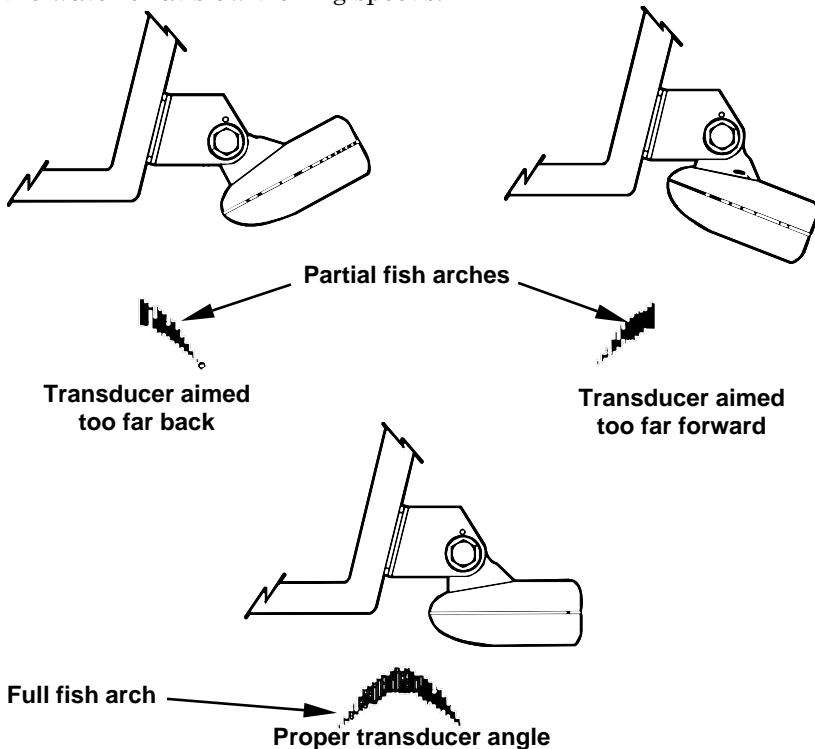
2. Slide the adjustable strap supplied with the TMB-S through the slot in the transducer bracket and wrap it around the trolling motor. Position the transducer to aim straight down when the motor is in the water. Tighten the strap securely.
3. Route the transducer cable alongside the trolling motor shaft. Use plastic ties (not included) to attach the transducer cable to the trolling motor shaft. Make sure there is enough slack in the cable for the motor to turn freely. Route the cable to the sonar unit and the transducer is ready for use.



Transducer mounted on trolling motor, side view.

## TRANSDUCER ORIENTATION AND FISH ARCHES

If you do not get good fish arches on your display, it could be because the transducer is not parallel with the ground when the boat is at rest in the water or at slow trolling speeds.



Transducer angles and their effects on fish arches.

If the arch slopes up – but not back down – then the front of the transducer is too high and needs to be lowered. If only the back half of the arch is printed, then the nose of the transducer is angled too far down and needs to be raised.

### NOTE:

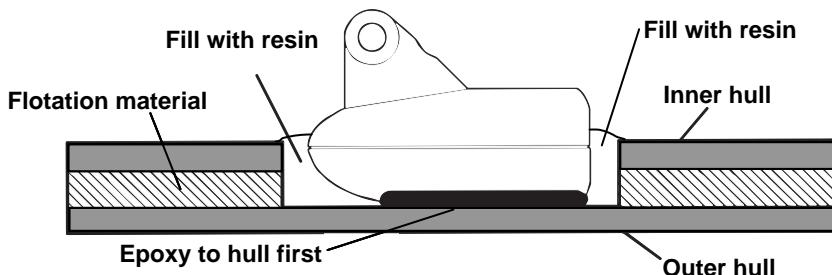
Periodically wash the transducer's face with soap and water to remove any oil film. Oil and dirt on the face will reduce the sensitivity or may even prevent operation.

## SHOOT-THRU-HULL PREPARATION

### Hulls With Floatation Materials

The transducer installation inside a fiberglass hull must be in an area that does not have air bubbles in the resin or separated fiberglass

layers. The sonar signal must pass through solid fiberglass. A successful transducer installation can be made on hulls with flotation materials (such as plywood, balsa wood or foam) between layers of fiberglass if the material is removed from the chosen area.



**Use epoxy to place the transducer in a solid portion of the hull.**

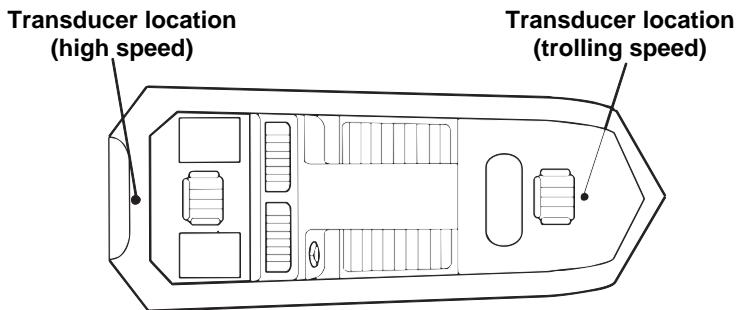
For example, some (but not all) manufacturers use a layer of fiberglass, then a core of balsa wood, finishing with an outer layer of fiberglass. Removing the inner layer of fiberglass and the balsa wood core exposes the outer layer of fiberglass. The transducer can then be epoxied directly to the outer layer of fiberglass. After the epoxy cures for 24 hours, fill the remaining space with polyester resin. When the job is finished, the hull is watertight and structurally sound. Remember, the sonar signal must pass through *solid* fiberglass. Any air bubbles in the fiberglass or the epoxy will reduce or eliminate the sonar signals.

#### **WARNING:**

**Do not remove any material from your inner hull unless you know the hull's composition. Careless grinding or cutting on your hull can result in damage that could sink your boat. Contact your boat dealer or manufacturer to confirm your hull specifications.**

#### **Testing Determines Best Location**

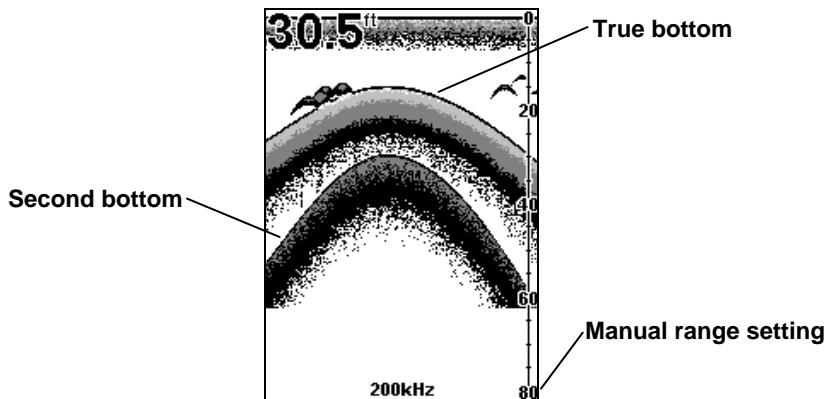
Ideally, the shoot-thru transducer should be installed as close to the transom as possible, close to the centerline. This will give you the best performance during high speed maneuvers.



**Shoot-thru-hull transducer locations for high speed or trolling speed operation.**

To choose the proper location for shoot-thru-hull mounting, follow these testing procedures: (You may need a helper to complete these steps.)

1. Anchor the boat in about 30 feet of water. Add a little water to the sump of the boat. Plug the transducer into the sonar unit, turn it on, then hold the transducer over the side of the boat in the water. Adjust the sensitivity and range controls until a second bottom echo is seen on the display. (You'll need to turn off Auto Sensitivity, Auto Depth Range and ASP™. Try a range setting that is two to three times the water depth. The harder (more rocky) the bottom, the easier it will be to get a second bottom signal.) Don't touch the controls once they've been set.



**Example of a second bottom signal.** Unit is in 30 feet of water, with range set at 80 feet and sensitivity set at 87 percent.

2. Next, take the transducer out of the water and place it in the water in the sump of the boat, face down. (The transducer face is shown in the figure on the following page.) Notice how the signal strength decreases. The second bottom signal will probably disappear and the bottom signal intensity will likely decrease.

3. Now move the transducer around to find the best location with the strongest possible bottom signal. If you find a spot with an acceptable bottom signal, mark the location and move on to step 4.

If you can't get an acceptable bottom signal, try turning up the sensitivity by three or five keystrokes and then move the transducer around once more. If you find a spot that works, mark it and move on to step 4.

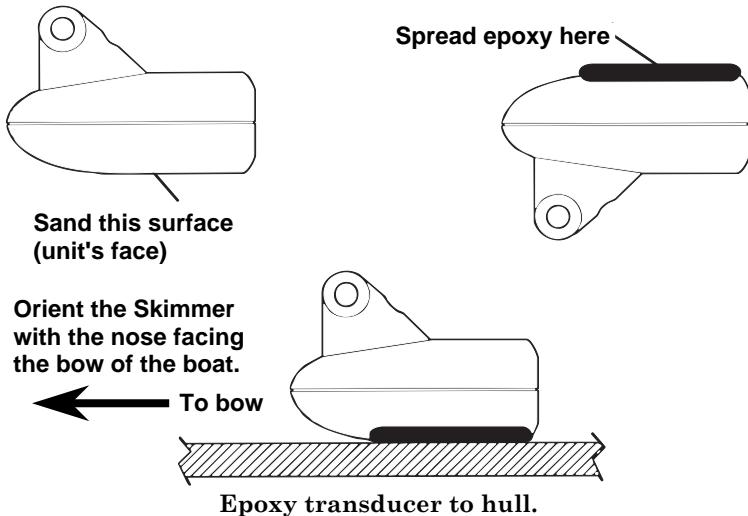
If you have to turn up sensitivity by more than five keystrokes to get a good signal, the transducer should be mounted on the outside of the hull. This is especially true if you have to turn sensitivity all the way up to get a decent bottom signal.

4. Most people can get good results by following steps 1 through 3, so this step is *optional*. If you want to make an extra effort to be absolutely sure that your selected location will work under all conditions, make a test run with the boat on plane and observe the bottom signal. You'll need to figure some way to prop the transducer into position while you make your test run. (A brick or two might be sufficient to hold it in place.)
5. When you're satisfied with a location, mark it and proceed with the installation.

### **Shoot-thru-hull Installation**

If you are installing the transducer on a hull with floatation material sandwiched within the hull, refer to the text "Hulls With Flotation Materials" beginning on page 22.

1. Make sure the area is clean, dry and free of oil or grease, then sand both the inside surface of the hull and the face of the transducer with 100 grit sandpaper. The sanded hull area should be about 1-1/2 times the diameter of the transducer. The surface of the hull must be flat so the entire transducer face is in contact with the hull prior to bonding. After sanding, clean the hull and transducer with rubbing alcohol to remove any sanding debris.



## WARNING:

Use *only* the epoxy available from LEI. It has been formulated to work with these installation procedures. Other epoxy types may be too thin or may not cure to the right consistency for optimum transducer performance.

2. The epoxy consists of the epoxy itself and a hardener. Remove the two compounds from the package and place them on the paper plate. Thoroughly stir the two compounds together until the mixture has a uniform color and consistency. Do not mix too fast or bubbles will form in the epoxy. After mixing, you have 20 minutes to complete the installation before the epoxy becomes unworkable. Spread a thin layer of epoxy (about 1/16" or 1.5 mm thick) on the face of the transducer as shown in the previous figure. *Make sure there are no air pockets in the epoxy layer!* Then, apply the remaining epoxy to the sanded area on the hull.
3. Press the transducer into the epoxy, twisting and turning it to force any air bubbles out from under the transducer face. Stop pressing when you bottom out on the hull. When you're finished, the face of the transducer should be parallel with the hull, with a minimum amount of epoxy between the hull and transducer.
4. Apply a weight, such as a brick, to hold the transducer in place while the epoxy cures. Be careful not to bump the transducer while the epoxy is wet. Leave the weight in place for a minimum of three hours. Allow the epoxy to cure for 24 hours before moving the boat.
5. After the epoxy has cured, route the cable to the sonar unit and it's ready to use.

# Speed/Temperature Sensors

## Optional Speed Sensor Installation

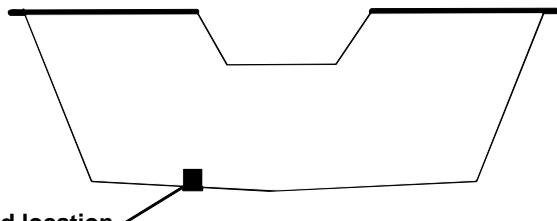
All the units in this series can display speed and distance traveled, but only the LCX-20C comes packed with a speed sensor. If you wish to purchase an optional additional sensor for your unit, refer to the accessory ordering information inside the back cover of this manual. The following instructions describe how to install the speed sensor.

Recommended tools for this job include: drill, 7/8" drill bit, 1/8" drill bit for pilot holes, screwdriver. Required supplies for this job include: four #8 stainless steel wood screws (3/4" long), *high quality, marine grade* above- or below-waterline sealant.

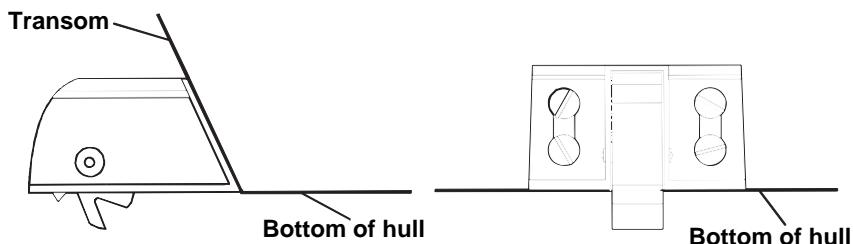
First find a location on the boat's transom where the water flow is smoothest. Don't mount the sensor behind strakes or ribs. These will disturb the water flow to the speed sensor. Make sure the sensor will remain in the water when the boat is on plane. Also make sure the location doesn't interfere with the boat's trailer. Typically, the sensor is mounted about one foot to the side of the transom's centerline.

Once you've determined the proper location for the unit, place the sensor on the transom. The bottom of the bracket should be flush with the hull's bottom. Using the sensor as a template, mark the hull for the screws' pilot holes. Drill four 1/8" holes, one in each end of the slots.

Mount the sensor to the hull using #8 stainless steel wood screws (not included). Use a *high quality, marine grade* above- or below-waterline sealant to seal the screws. Make sure the sensor is flush with the bottom of the hull and tighten the screws.



Stern view showing good location for mounting sensor on transom.



Speed sensor mounting configuration:  
side view (left) and rear view (right.)

If the base of the transom has a radius, fill the gap between the transom and the sensor with the sealant. This will help ensure a smooth water flow.

Route the sensor's cable through or over the transom to the sonar unit. If you need to drill a hole in the transom to pass the connector through, the required hole size is 7/8".

#### **CAUTION:**

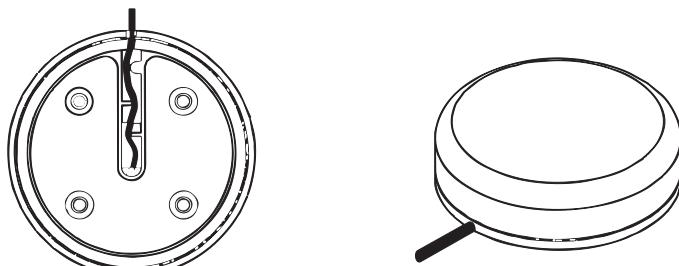
*If you drill a hole in the transom for the cable, make sure it is located above the waterline. After installation, be sure to seal the hole with the same marine grade above- or below-waterline sealant used for the screws.*

The sensor is now ready for use. Connect the sensor to the sonar socket on the back of your unit and connect the transducer to the speed sensor's socket. If you have any questions concerning the installation of the sensor, please contact your local boat dealer.

#### **GPS Antenna/Receiver Module**

The LCX-20C packages include the LGC-2000 GPS module. This device contains the unit's external antenna and receiver for GPS and WAAS

signals. The antenna/receiver module comes with a 25-foot Y-adapter extension cable. This module can be mounted on a flat surface or pole, or an optional magnet is available for temporary mounting on any ferrous surface.



**LGC-2000 Module, bottom view (left) and top view (right).**

You need to select an antenna installation location that has a clear, unobstructed view of the sky. After the module is installed, connect it to the unit. The LGC-2000 can communicate with your GPS unit either directly (using the supplied extension cable) or through a NMEA 2000 network.

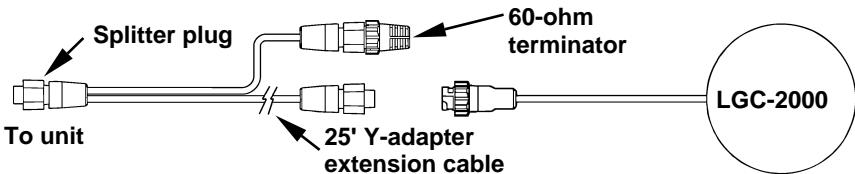
#### **NOTE**

See the module's instruction sheet, publication part number 988-0147-981, for complete installation instructions.

In an automobile, you may achieve good results by simply placing the external antenna on the top of the dash, at the base of the windshield. A piece of the rubber non-skid shelf liner material available in recreational vehicle supply stores will help hold the antenna in place. This may not work well if you have a cab-over design pickup truck camper or motor home. If dashboard reception is poor, simply relocate the antenna module elsewhere on the vehicle for a clearer view of the sky.

#### **Connecting Directly to the Unit**

After the module is installed, attach it to the end of the Y-adapter extension cable as shown in the following diagram. To connect it to the unit, insert the extension cable's splitter plug into the Network socket on the back of the unit and your system is ready to use.



LGC-2000 direct connection to GPS unit.

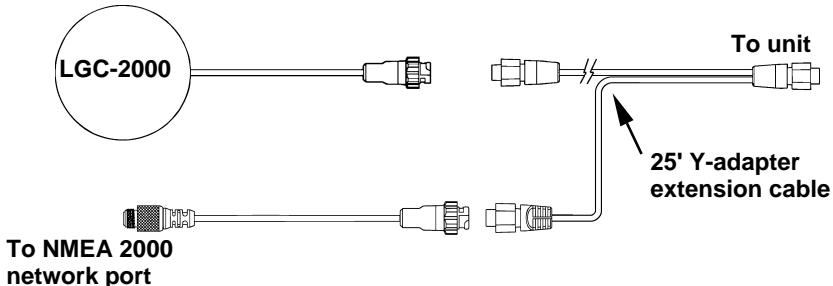
**NOTE:**

The extension cable's shorter branch will have a 60-ohm terminator attached to it. ***Do not remove this terminator.*** When you're not connecting to a NMEA 2000 buss, you must leave the terminator connected to this socket for your antenna/receiver to function correctly.

### Connecting to a NMEA 2000 Network

The LGC-2000 can be connected to a NMEA 2000 buss, providing GPS information to any Lowrance GPS units attached to the buss. Contact LEI Extras (look inside back cover for accessory ordering information) for a NMEA 2000 buss adapter cable if you would like to do this.

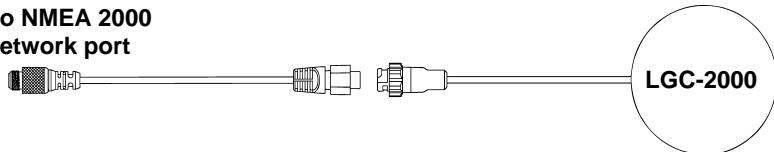
There are two ways to connect the antenna to a NMEA 2000 network port. One method (shown in the following image) is to use the extension cable's Y-adapter to connect both the antenna and the unit to the same network port. To do this, simply remove the 60-ohm terminator shown in the previous image and attach the NMEA 2000 buss adapter cable to the shorter branch of the extension cable's Y-adapter. Connect the NMEA 2000 buss adapter cable's other end to an available network port.



LGC-2000 and GPS unit connection to NMEA 2000 buss.

You can also attach the antenna to a remote port on the network, and pass position information along the network. To do this, simply attach the LGC-2000's connector to one end of the buss adapter cable and attach the other to an available port on the NMEA 2000 buss, as shown in the following image. (You will have to use a similar adapter cable to connect the GPS unit to the NMEA buss as described later in this section.)

To NMEA 2000  
network port



LGC-2000 remote connection to NMEA 2000 buss.

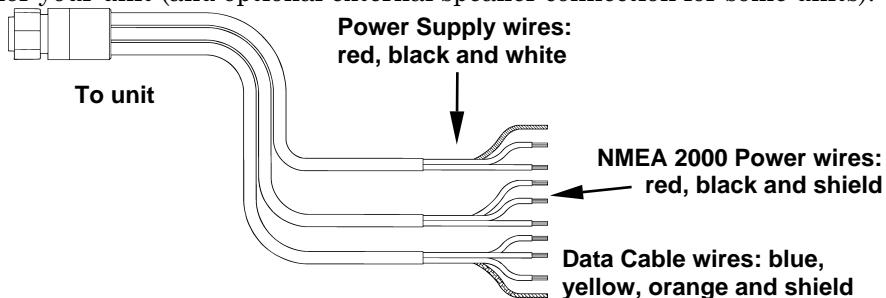
#### NOTE:

An existing operational NMEA 2000 buss will already have terminators in place and will already be powered. If you're connecting to such a network, you won't need the terminators or extension cable provided. **Do not add** terminators or power to a functional NMEA 2000 buss!

When the LGC-2000 is connected to the unit (directly or indirectly), it will begin providing GPS signal information.

### Power Connections

Your unit comes with a power/data cable that splits into three ends, each with several exposed wires (shown in the following figure). The end with 4 wires (blue, yellow, orange and shield) is a Data cable that connects to a NMEA 0183 interface. The end with three wires (red, black and shield) is a power cable that connects to a NMEA 2000 buss. The thicker three-wire cable (red, black and white) is the Power Supply for your unit (and optional external speaker connection for some units).



The Power/Data cable for this unit.

Depending on your configuration, you may not use all of these wires. The following segments include instructions for installing all the wires that you will use with this unit.

#### Caution

*All of the wires in the power/data cable have bare ends for easier installation. The bare ends on any unused wires could cause an electrical short if left exposed. To prevent this, you should cover the individual wire ends – either by capping them with wire nuts or wrapping them with electrical tape. (You should cut off the bare wire before taping off the ends.)*

## Powering a NMEA 2000 Buss

### (NMEA 2000 Power cable)

A NMEA 2000 buss must be connected to a power source to operate. If you have a pre-existing NMEA 2000 installation, it may already be connected to another power source. *If* your NMEA 2000 buss is already powered, you can ignore the NMEA 2000 Power cable. **Never attach two power sources to a single NMEA 2000 buss.**

If you do need to power your NMEA 2000 buss, attach the NMEA 2000 Power cable to your boat's battery just as indicated in the following segment for connecting your unit's Power Supply cable. The NMEA 2000 Power cable's red wire should be attached (with provided 3-amp fuse) to the boat battery's positive terminal, and the NMEA 2000 Power cable's black and shield wires should both be attached to the battery's negative terminal.

#### NOTE:

If the NMEA 2000 buss draws power directly from the boat's battery, the LGC-2000 will remain on (drawing power) all the time. The LGC-2000's current draw is very small and shouldn't decrease the boat's storage battery life, but if this small draw is a concern, you can install a switch between the NMEA 2000 buss and the battery.

## Powering Your Unit

### (Power Supply cable – red and black wires)

The unit works from a 12-volt battery system. For the best results, attach the power cable directly to the battery. You can attach the power cable to an accessory or power buss, however you may have problems with electrical interference. Therefore, it's safer to go ahead and attach the power cable directly to the battery.

#### CAUTION:

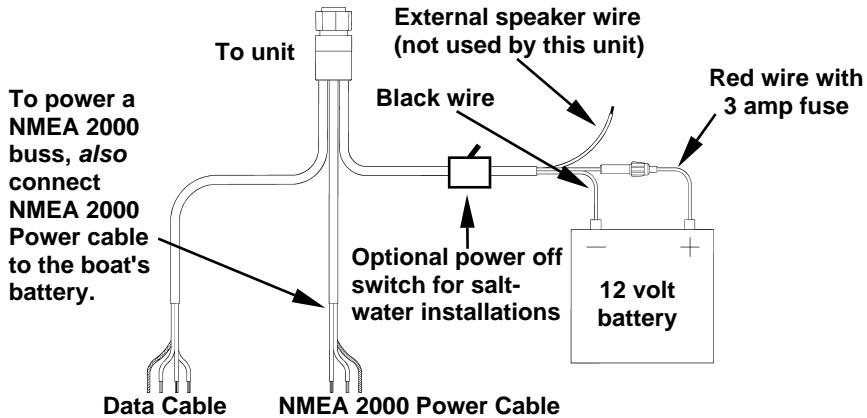
*When using the unit in a saltwater environment, we strongly recommend that you shut off the power supply to the power cable when the unit is not in use. When the unit is turned off but still connected to a power supply, electrolysis can occur in the power cable plug. This may result in corrosion of the plug body along with the electrical contacts in the cable and the unit's power socket.*

*In saltwater environments we recommend you connect the power cable to the auxiliary power switch included in most boat designs. If that results in electrical interference, or if such a switch is not available, we recommend connecting direct to the battery and installing an inline switch. This will let you shut off power to the*

power cable when the unit is not in use. When you are not using the unit, you should always shut off power to the power cable, especially when the power cable is disconnected from the unit.

If possible, keep the power cable away from other boat wiring, especially the engine's wires. This will provide the best isolation from electrical noise. If the cable is not long enough, splice #18 gauge wire onto it. The power cable has two wires, red and black. Red is the positive lead, black is negative or ground. (There is also a white wire to power an optional external speaker for some units.) Make sure to attach the in-line fuse holder to the red lead *as close to the power source as possible*.

For example, if you have to extend the power cable to the battery or power buss, attach one end of the fuse holder directly to the battery or power buss. This will protect both the unit and the power cable in the event of a short. It uses a 3-amp fuse.



#### Power connections for LCX-20C sonar/GPS unit.

#### NOTE:

If you're powering a NMEA 2000 buss, you will attach *both* the NMEA 2000 Power cable *and* the unit's Power Supply cable to the boat's battery. To attach the NMEA 2000 Power cable, connect the red wire to battery's + and black and shield wires to battery's -.

#### WARNING:

This product *must* be independently fused with the enclosed 3-amp fuse (or equivalent), even if you connect to a fused accessory or power buss.

*If a malfunction happens inside the unit, extensive damage can occur if the enclosed fuse is not used. As with*

*all electrical devices, this unit could be damaged to a point that it is unrepairable and could even cause harm to the user when not properly fused.*

**CAUTION:**

*Do not use this product without a 3-amp fuse wired into the power cable! Failure to use a 3-amp fuse will void your warranty.*

This unit has reverse polarity protection. No damage will occur if the power wires are reversed. However, the unit will not work until the wires are attached correctly.

An optional 8-foot, CA-4 external power cable with a cigarette lighter adapter is available from Lowrance.

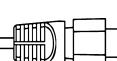
## **NMEA 2000 Cable Connections**

NMEA 2000 is a new buss network specifically designed for boats. This is a very young industry standard and, at the time of printing, few boats being built now have a NMEA 2000 buss installed. Over the next few years, however, NMEA 2000 will become much more common. To help you get the most out of this technology, your Lowrance unit is designed to work with a NMEA 2000 network as soon as it becomes available.

### **Connecting to a NMEA 2000 Network**

Your unit can be connected to a NMEA 2000 buss, receiving sensor information from any Lowrance units attached to the buss. Contact LEI Extras (look inside back cover for accessory ordering information) for a NMEA 2000 buss adapter cable if you would like to do this. You can connect both the unit and antenna module through the antenna's extension cable (as described earlier), or you can connect the unit directly to a network port. To do so, attach the adapter cable's manual locking collar connector to the Network port on the back of the sonar unit and attach the other end to an available port on the NMEA 2000 buss, as shown in the following image.

**To NMEA 2000  
network port**



**To sonar  
unit's Network  
socket**

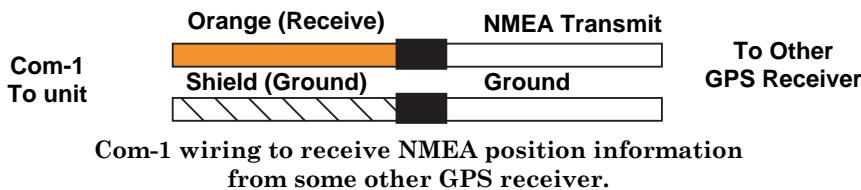
**Lowrance unit direct connection to NMEA 2000 buss.**

As soon as the unit is connected to the network, it will begin receiving shared information. Please note the buss *must* be powered to operate. (See instructions in this section for more on powering NMEA 2000 buss.)

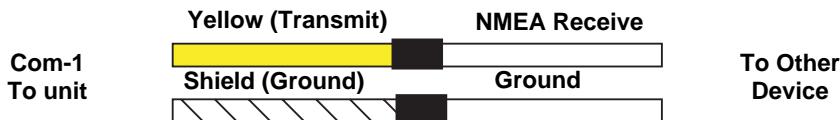
## NMEA 0183 Wiring (Data cable)

To exchange NMEA 0183 data, this unit has one NMEA 0183 version 2.0 communication port. Com port one (Com-1) can be used to receive NMEA format GPS data. The com port can also transmit NMEA format GPS data to another device.

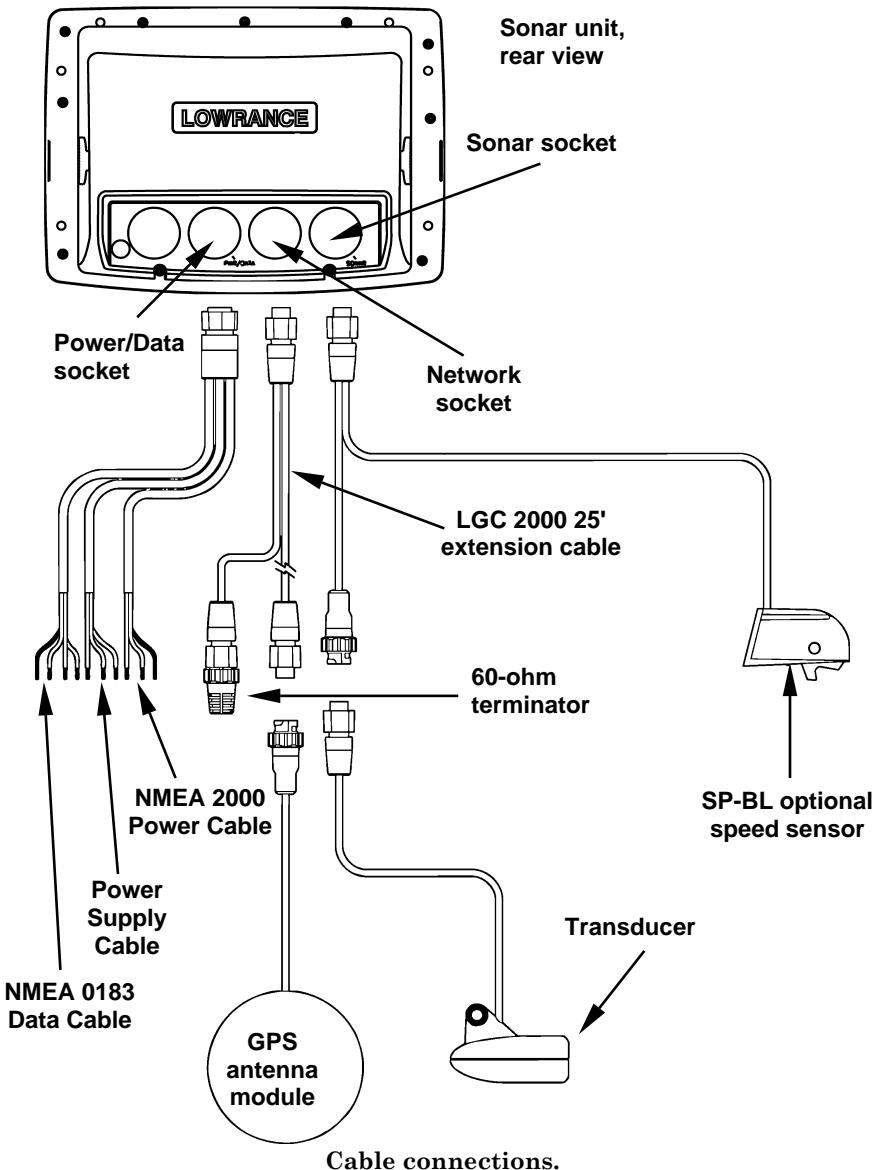
The four wires for the com port are combined with the Power Supply cable and NMEA 2000 Power cable to form the power/data cable (shown earlier). Com-1 uses the yellow wire to transmit, the orange wire to receive and the shield wire for signal ground. Your unit does not use the blue wire.



Com-1 wiring to receive NMEA position information  
from some other GPS receiver.



Com-1 wiring to transmit NMEA position information  
to another NMEA-compatible device.



## Mounting the Unit: Bracket or In-Dash

You can install the unit on top of a dash with the gimbal bracket. It can also be installed in the dash or mounted on a portable power supply.

If you use the supplied bracket, you may be interested in the optional R-A-M® bracket mounting system. This converts the unit's gimbal bracket to a swivel mount, which can be used on the dash or overhead mounting positions.

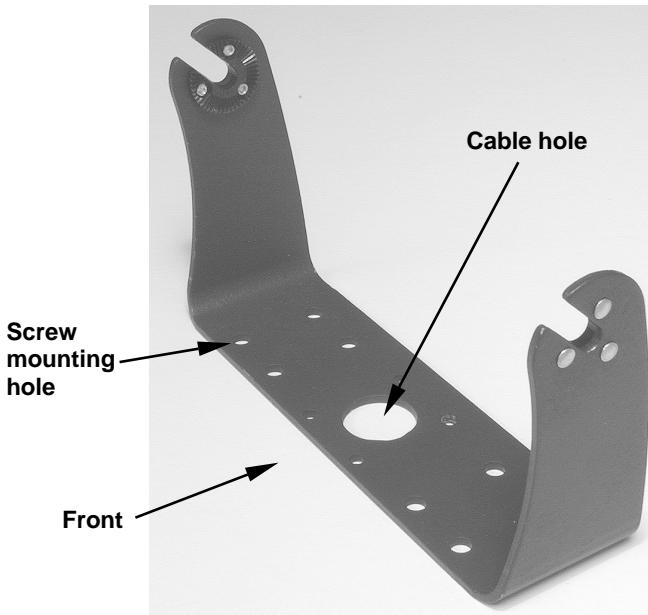


**Optional R-A-M mounting system.**

### **Bracket Installation**

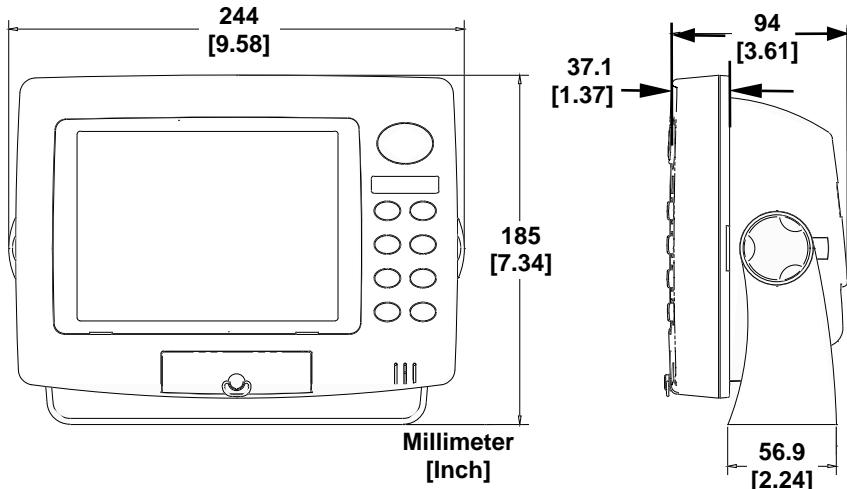
Mount the unit in any convenient location, provided there is clearance behind the unit when it's tilted for the best viewing angle. You should also make sure there is enough room behind the unit to attach the power, transducer and GPS antenna/receiver module cables. (A drawing on the next page shows the dimensions of a gimbal-mounted unit.)

Holes in the bracket's base allow wood screw or through-bolt mounting. You may need to place a piece of plywood on the back side of thin fiberglass panels to reinforce the panel and secure the mounting hardware.



**Install the gimbal bracket. Place the bracket so the arms slope toward the front of your unit.**

Once a location is determined, use the bracket as a template and mark the mounting holes and the hole for the cables. Drill a 1-inch (25.4 mm) hole in the dash for the power, transducer and antenna cables. Screw the bracket to the mounting surface.



**Front view (left) and side view (right) showing dimensions of the sonar/GPS unit when mounted on gimbal bracket.**

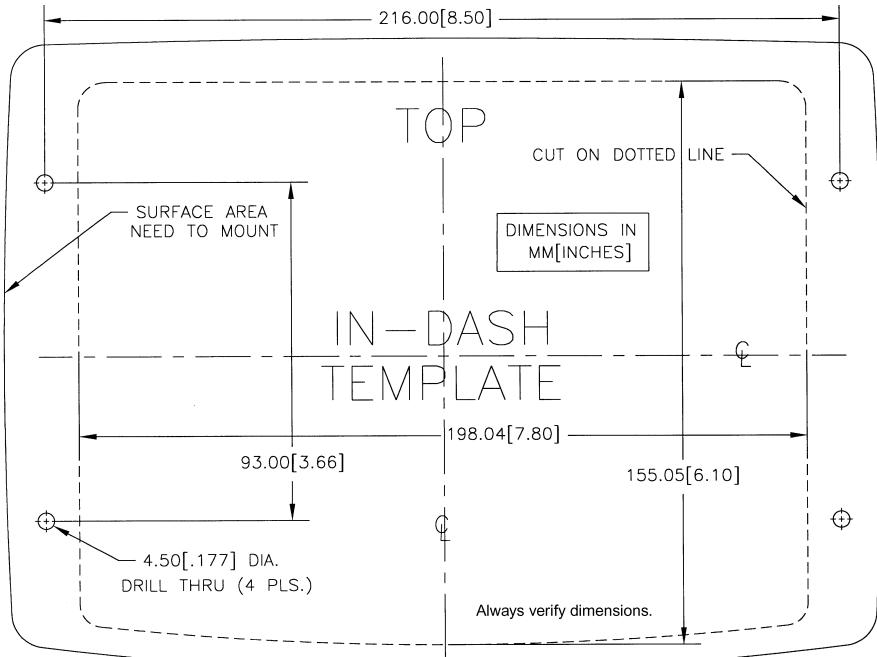
To pass all connectors through the 1" hole, first pass the transducer connector *up* through the hole from under the dash, followed by the antenna connector and any accessory cables. Next, pass the power cable's bare-wire end *down* though the hole from the top.

If you wish, you can fill in the hole around the cables with a good marine caulking compound. No matter what type of installation you prefer, be sure to leave enough slack in the cables to allow tilting or swiveling the unit.

Attach the unit to the gimbal bracket using the supplied gimbal knobs and washers. Attach the cables and the unit is ready to use.

### **In-Dash Installation**

You can mount the unit in the dash with an optional FM-3 In-Dash Adapter Kit. The kit includes mounting hardware and a template for cutting the hole.



**In-dash mounting template for this unit, showing dimensions.  
NOTE: The figure above is *not* printed to scale.**

## **MMC or SDC Memory Card Installation**

Your unit uses MultiMedia Cards to store information, such as sonar logs, custom maps, waypoints, trails and other data. The unit can also use Secure Digital Cards (SD card) to store data. The unit can use up to two cards; a MMC and a SD card can be used at the same time.

### **NOTE:**

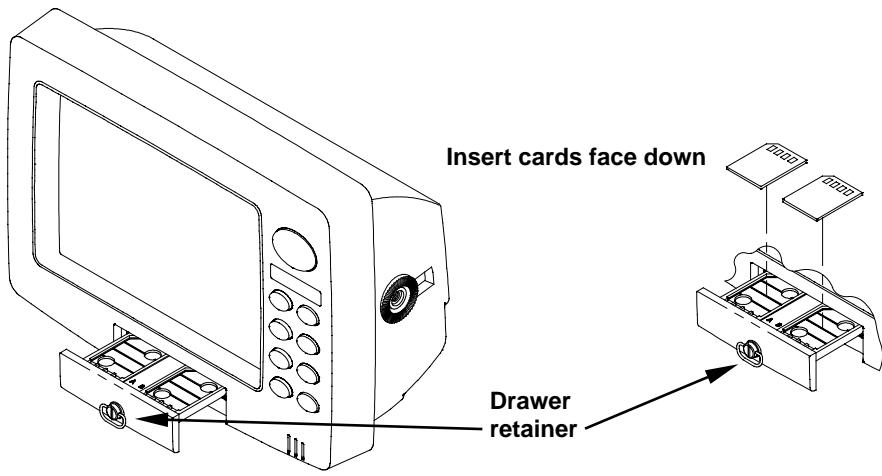
Throughout this manual, we will use the term MMC, but just remember your unit can use an MMC or SD card to store data.

Both of these solid-state flash memory devices are about the size of a postage stamp. A SD card is slightly thicker than a MMC. MMCs are available in storage capacities of 8 MB, 16 MB, 32 MB and 64 MB. SD cards are available in capacities of 8 MB, 16 MB, 32 MB, 64 MB, 128 MB, 256 MB and 1 GB.

Additional MMC cards are available from LEI Extras; see ordering information inside the back cover of this manual. MMCs and SD cards are also available at many camera and consumer electronics stores.

The MMC drawer is located on the front of the case. To install an

MMC, twist the drawer retainer counter-clockwise and pull. The drawer will come out of the unit. Place the MMC in the drawer *face down* (see following figures.)



**Memory card drawer on the LCX-20C.**

Slide the drawer back into the unit and twist the retainer clockwise. The MMC is now ready for use.

## **Other Accessories**

### **MMC and MapCreate**

Other available accessories include MMC cards, MMC card readers and MapCreate™ 6 custom mapping software for your computer. MMC card readers are available in USB versions.



**MapCreate™ 6 CD-ROM, left; MMC card reader for USB ports, right.**

### **Switch Boxes**

Two switch boxes are available for this unit. The SB-7X transducer switch box switches two transducers to one sonar unit. The SB-8X transducer switch box switches two sonar units to one transducer.

If these accessories are not available from your dealer, see the accessory ordering information on the inside back cover of this manual.

Visit our web site for a complete listing of all the available accessories for your unit.

### **Face Cover**

Your unit comes with a white protective cover that snaps on and off the front of the unit. This cover is intended for use when your unit and the vehicle it's mounted in are idle.

### **WARNING:**

**When the unit is mounted in an unprotected area, such as an open boat cockpit, the protective face cover must be removed when the vehicle is moving at high speed. This includes towing a boat on a trailer at highway speeds. Otherwise, wind blast can pop off the cover.**

Now that you have your unit installed, move on to Sec. 3, *Basic Sonar Operations*. In Sec. 3, we'll present a series of step-by-step tutorials to teach you the basics of your sonar operation.

### **NOTE:**

When you first turn the unit on, the Map Page appears. If you'd rather start learning about GPS operation first, turn to Sec. 6, *Basic GPS Operations*. (Remember, you don't need to read this manual from cover-to-cover to get going. We designed it so you can skip around to the section *you* want to read.)

## Section 3: Basic Sonar Operation

This section addresses the unit's *most basic* sonar operations. The instructions presented in Sec. 3 follow a chronological order. Sec. 4, *Sonar Options & Other Features*, will discuss other more advanced functions and utilities. Material in Sec. 4 is arranged in alphabetical order.

Before you turn on the unit, it's a good idea to learn about the different keys, the Main Menu, the four Page screens and how they all work together. BUT, if you just can't wait to get on the water, turn to the one-page **Quick Reference** on page 51.

### Keyboard



**LCX-20C sonar/GPS unit, front view, showing sonar screen, keyboard and access door for the MMC compartment.**

1. **PWR/LIGHT** (Power & Light) – The PWR key turns the unit on and off and activates the backlight.

2. **PAGES** – Pressing this and the  $\leftarrow \rightarrow$  arrow keys switches the unit between the four different page screens. (Satellite Status Page, Navigation Page, Map Page and Sonar Page.) Each page represents one of the unit's major operation modes.

3. **MENU** – Press this key to show the menus and submenus, which allow you to select a command or adjust a feature. This also accesses search functions for streets, intersections, addresses and highway exits.

4. **ARROW KEYS** – These keys are used to navigate through the menus, make menu selections, enter data and move the map and sonar chart cursors.

5. **ENT/ICONS** (Enter & Icons) – This key allows you to save data, accept values or execute menu commands. It is also used to create event marker icons.

6. **EXIT** – The Exit key lets you return to the previous screen, clear data and close menus.

7. **WPT** – (Waypoint) The Waypoint key is used to save and recall waypoints, search for waypoints and access the waypoint list. It also launches the Point-of-Interest (POI) search menus and is involved in some navigation functions.

8. **ZOUT** – (Zoom Out) – This key lets you zoom the screen out. On the Sonar Page, this key returns you to a full sonar chart display, showing the entire water column from surface to bottom. On the Map Page, this lets you see a larger geographic area on the map. Less detail is seen as you zoom out.

9. **ZIN** – (Zoom In) – This key lets you zoom the screen in. On the Sonar Page, this key enlarges fish signals and bottom detail. On the Map Page, zooming in lets you see greater detail in a smaller geographic area on the map.

## **Power/lights on and off**

To turn on the unit, press **PWR**. As the unit powers up, the Map Page is displayed first. To switch to the Sonar Page, press **PAGES** |  $\rightarrow$  | **EXIT**.

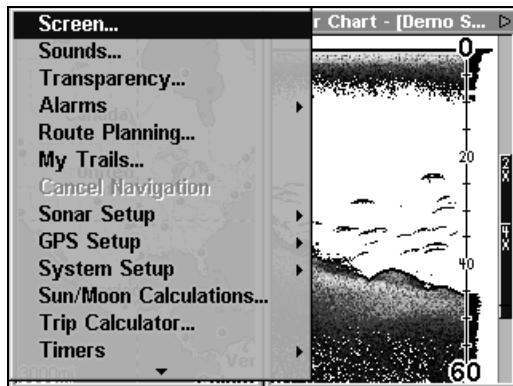
To turn on the backlight, press **PWR** again. The unit has three backlight levels to select from. Repeatedly pressing **PWR** will cycle through the backlight settings and turn off the backlight.

Turn off the unit by pressing and holding the **PWR** key for 3 seconds.

## Main Menu

The unit has a Main Menu, which contains some function commands and some setup option commands. The instructions in this section will deal only with sonar functions, the basic commands that make the unit show sonar signals on your screen. This unit will work fine right out of the box with the factory default settings. But, if you want to learn about the various sonar options, see Sec. 4, *Sonar Options & Other Features*. (For general system setup and GPS options, see Sec. 8, *System Setup and GPS Setup Options*.)

You can access the Main Menu from any of the four Page screens by pressing **MENU | MENU**. To clear the menu screen and return to the page display, press **EXIT**. (Remember, our text style for "**MENU | MENU**" means "press the Menu key twice." See a full explanation of our instruction text formatting on page 10, *Instructions = Menu Sequences*.)



Main Menu.

The Main Menu commands and their functions are:

**Screen** command: changes the contrast or brightness of the display screen.

**Sounds** command: enables or disables the sounds for key strokes and alarms and sets the alarm style.

**Transparency** command: adjusts the level of transparency for menus.

**Alarms** command: turns GPS alarms on or off and changes alarm thresholds.

**Route Planning** command: used to plan, view or navigate a route.

**My Trails** command: shows, creates and deletes plot trails. Also used to navigate or backtrack a trail.

**Cancel Navigation** command: turns off the various navigation

commands. Used to stop navigating after you have reached your destination waypoint, Point of Interest or map cursor location; or after you reach the end of a route or trail.

**Sonar Setup** command: sets various sonar options.

**GPS Setup** command: sets various GPS receiver options.

**System Setup** command: sets general configuration options.

**Sun/Moon Calculations** command: finds the rising and setting time of the sun and the moon.

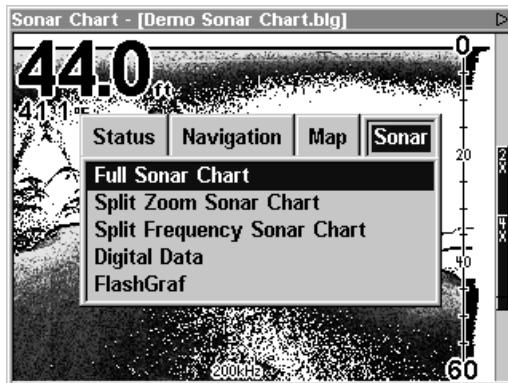
**Trip Calculator** command: shows trip status and statistics.

**Timers** command: controls the up timer, down timer and alarm clock settings.

**Browse MMC Files** command: this allows you to view the installed MMC card and the files it contains.

## Pages

The unit has four Page displays that represent the four major operating modes. They are the Satellite Status Page, the Navigation Page, the Map Page and Sonar Page. They are accessed by pressing the **PAGES** key, then using → or ← to select a Page. (Clear the Pages Menu by pressing **EXIT**.)



Pages Menu, showing sonar display options.

## Satellite Status Page

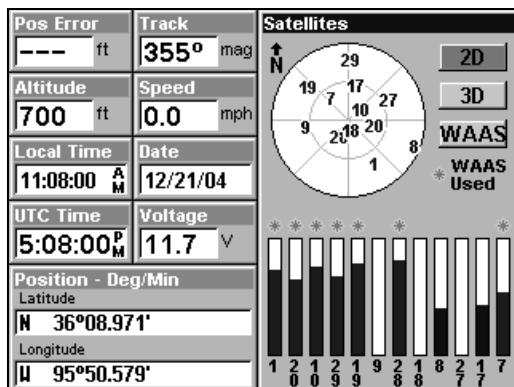
The Satellite Status Page provides detailed information on the status of the unit's satellite lock-on and position acquisition. To get to the Satellite Status Page: Press the **PAGES** key, then use → or ← to select **STATUS**. (Clear the Pages Menu by pressing **EXIT**.)

This page represents a GPS function, so it is discussed in much greater detail in Sec. 6.

No matter what Page you are on, a flashing current position indicator/question mark symbol and flashing GPS data displays indicate that satellite lock has been lost and there is no position confirmed.

### WARNING:

**Do not begin navigating with this unit until the numbers have stopped flashing!**

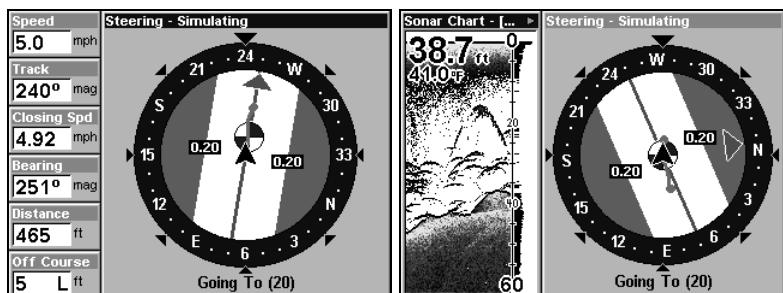


Satellite Status Page.

### Navigation Page

This screen has a compass rose that not only shows your direction of travel, but also the direction to a recalled waypoint. To get to the Navigation Page: Press **PAGES** | → or ← to **NAVIGATION** | **EXIT**.

This page represents a GPS function, so it is discussed in much greater detail in Sec. 6.

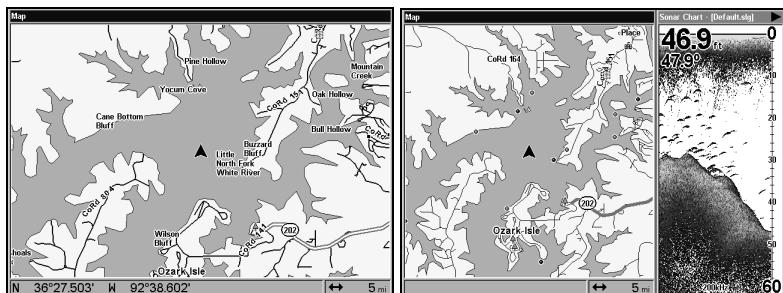


The Navigation Page (left); navigation with sonar (right).

### Map Page

The Map Page screens show your course and track from a "bird's-eye" view, on a moving map. By default, this unit shows the map with north

always at the top of the screen. The arrow in the center of the screen is your present position. It points in the direction you're traveling.



Map Page, showing position on Bull Shoals Lake, Arkansas. The full map option (left). Map with sonar option (right).

Map Page is the default screen that appears when you turn on the unit. To get to the Map Page from another page: Press **PAGES** | → or ← to **MAP** | **EXIT**.

You can display a split screen showing both the Map and Sonar pages at the same time. This feature is discussed in Sec. 4, *Sonar Options & Other Features*.

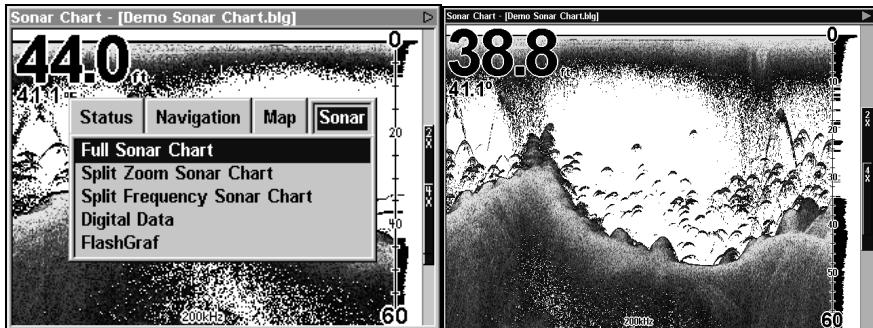
The Map Page represents a GPS function, so it is discussed in much greater detail in Sec. 6.

### Sonar Page

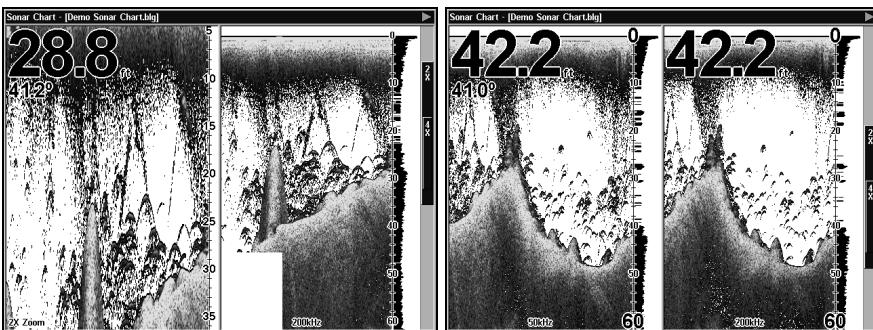
The Sonar Page displays the sonar chart. This is a "cross-section" view of the water column beneath the boat. The chart moves across the screen, displaying sonar signal echoes that represent fish, structure and the bottom.

To get to the Sonar Page: Press the **PAGES** key, then use → or ← to select **SONAR**. (Clear the Pages Menu by pressing **EXIT**.) The Pages Menu offers five chart display options under the Sonar Page category. To access them, press **PAGES** | ← or → to **SONAR** | ↓ to *Option Name* | **EXIT**.

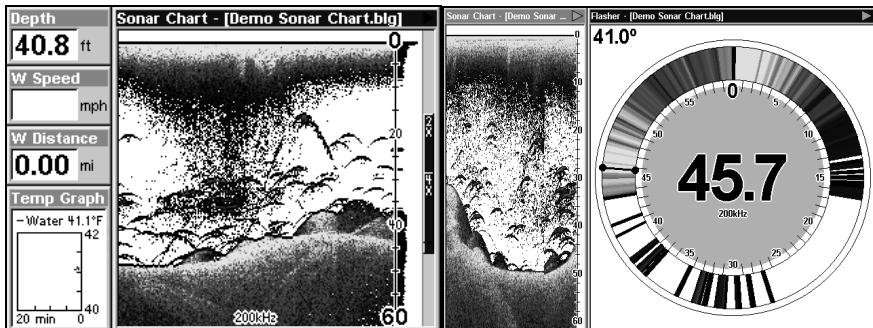
The Sonar Page has its own menu, which is used for advanced functions and for setting various options. (Sonar Options and other features are discussed in Sec. 4.) To Access the Sonar Page menu, from the Sonar Page press **MENU**.



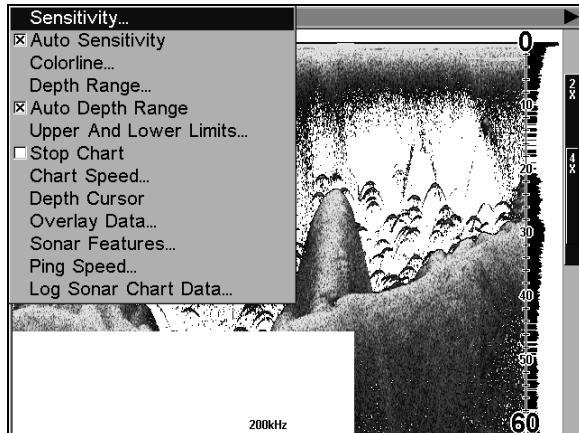
Pages Menu, showing sonar chart display option commands (left).  
Sonar Page in full sonar chart display mode (right).



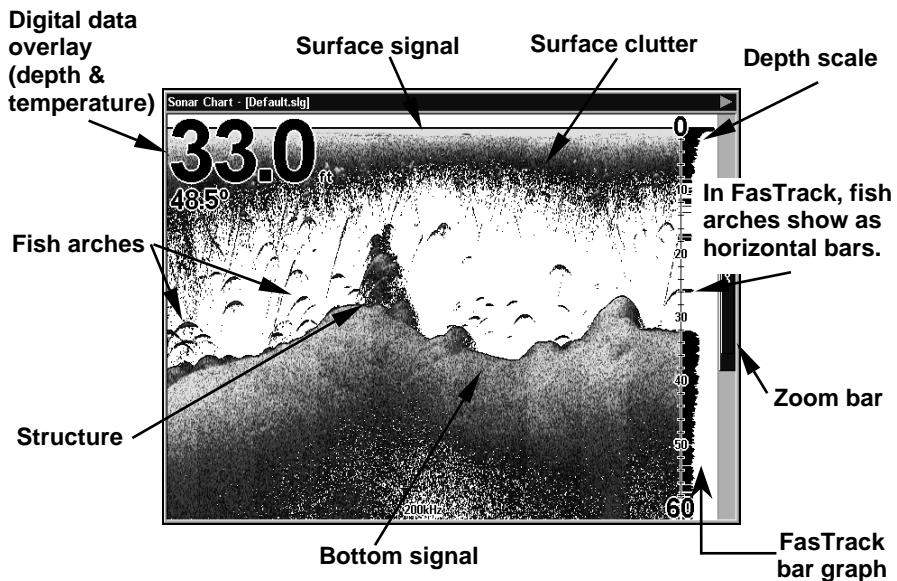
Sonar chart display options (from left) split zoom and split frequency.



Sonar chart display options (from left) digital data and FlashGraf™.



**Sonar Page Menu.** Most of these functions are discussed in Sec. 4.



**Sonar Page, showing full sonar chart mode.**

You can customize how the Sonar Page displays its pictures and other data in many ways. Your unit also includes several special sonar features and options that can help you better interpret the underwater scene.

We'll discuss all of those features and options in Sec. 4, but to show you how easy the unit is to operate, the following page contains a simplified, 10-step quick reference that will cover most fish finding situations. The quick reference describes how your unit will operate with all the sonar features in their automatic modes, which are set at the factory.

## LCX-20C Sonar Quick Reference

1. Mount the transducer, antenna and unit. Connect the unit to electric power and the transducer. (If GPS operation is desired, connect GPS antenna, too.) Make sure the MMC is in. (See complete installation details beginning on page 11.)
2. Launch your boat.
3. To turn on the unit, press and release **PWR** key.
4. Opening screen displays Map Page. Rotate through the four main Page screens (Map Page, Satellite Status Page, Navigation Page, Sonar Page) by pressing **PAGES** |  $\leftarrow$  or  $\rightarrow$  to select *Page Name* | **EXIT**. Switch Pages to display Sonar Page.
5. If GPS data is desired, wait while unit locates satellites and calculates current position. When the unit acquires position, a tone sounds and a position acquired message appears.
6. With position acquired (if desired), head for your fishing grounds. Your unit will automatically display digital depth and surface water temperature in the top left corner of the screen.

The auto settings will track the bottom, displaying it in the lower portion of the screen. The full sonar chart will scroll from right to left, showing you what's under the boat as you cruise across the water. You can change the display by:

**Zoom in** to enlarge the chart for more detail: press **ZIN**.  
**Zoom out** to return to full chart mode: press **ZOUT**.

7. Watch the display for the appearance of fish arches. When you see arches, you've found fish! Stop the boat and get your lure or bait into the water at the depth indicated on the sonar chart.
8. Gauge the fish depth by visually comparing the fish arches with the depth scale on the right side of the screen, or get a more accurate measure with the Depth Cursor. Press **MENU** |  $\downarrow$  to **DEPTH CURSOR** | **ENT**. Press  $\downarrow$  to align the cursor line with the fish arch. The exact depth appears in a box at the right end of the cursor line. To clear the cursor, press **EXIT**.
9. If you are drifting at a very low speed or anchored, you are not moving fast enough for a fish to return the tell-tale fish arch signal. As you drift over a fish, or as a fish swims through the transducer's signal cone, the fish echo will appear as a straight line suspended between the surface and the bottom.
10. To turn off the unit, press and hold **PWR** key for three seconds.

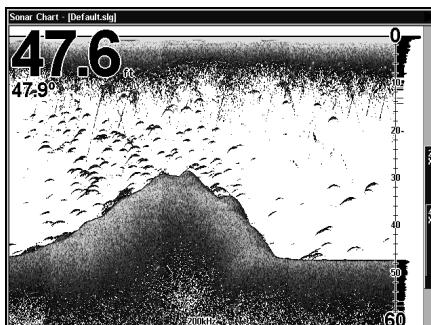
## Sonar Operations

As you can see from the quick reference on the previous page, basic operation is pretty easy, right out of the box. If you are a sonar novice, try operating the unit with the factory defaults until you get a feel for how it's working.

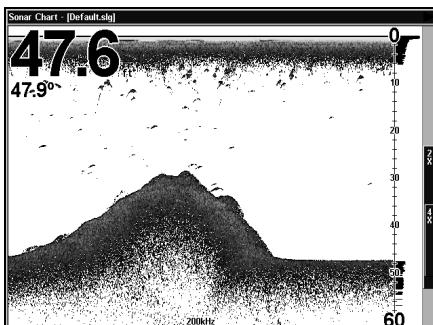
As you're learning the basics, there is one setting you might want to tinker with from time to time — Sensitivity.

Sensitivity controls the unit's ability to pick up echoes. If you want to see more detail, try increasing the sensitivity, a little at a time. There are situations when too much clutter appears on the screen. Decreasing the sensitivity can reduce the clutter and show the strongest fish echoes, if fish are present. As you change the sensitivity setting, you can see the difference on the chart as it scrolls.

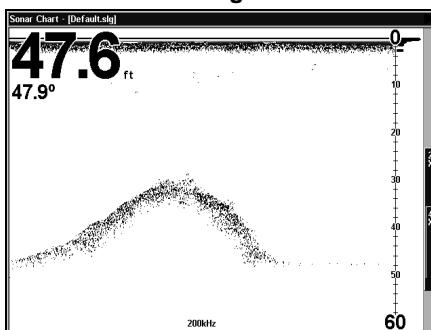
**Fig. 1**



**Fig. 2**



**Fig. 3**



**Fig. 4**



These figures show results of different sensitivity levels on the same location. Fig. 1: Sensitivity at 88 percent. Typical of full auto mode. Fig. 2: Sensitivity set at 75 percent. Fig. 3: Sensitivity set at 50 percent. Fig. 4: Sensitivity set at 100 percent.

You can change the sensitivity level whether you are in Auto Sensitivity mode or Manual Sensitivity mode. The adjustment method works the same in both modes, but gives you slightly different results.

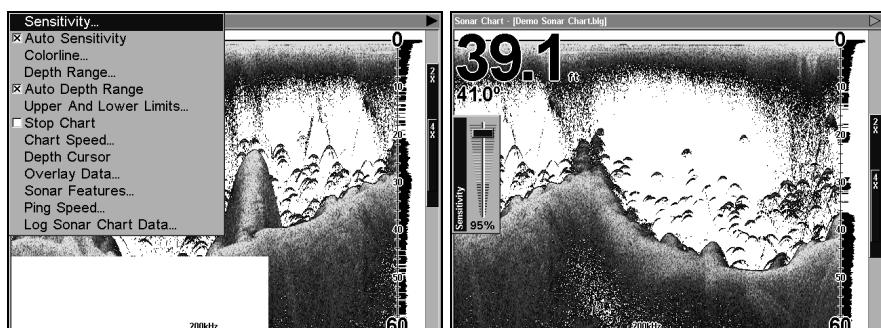
Adjusting sensitivity in Auto Sensitivity Mode is similar to manually adjusting a car's speed with the accelerator pedal while cruise control is on. You can tell the car to run faster, but when you let off the gas the cruise control *automatically* keeps you from running slower than the minimum speed setting. In this unit, auto mode will let you increase sensitivity to 100 percent, but the unit will *limit* your *minimum* setting. This prevents you from turning sensitivity down too low to allow automatic bottom tracking. When you change the setting with auto turned on, the unit will continue to track the bottom and make minor adjustments to the sensitivity level, with a bias toward the setting you selected.

Adjusting sensitivity in Manual Sensitivity Mode is similar to driving a car without cruise control — you have *complete* manual control of the car's speed. In this unit, manual mode allows you to set sensitivity at 100 percent (maximum) or zero percent (minimum.) Depending on water conditions, the bottom signal may completely disappear from the screen when you reduce sensitivity to about 50 percent or less!

Try adjusting sensitivity in both auto and manual modes to see how they work.

### To adjust sensitivity:

1. Press **MENU | ENT**.
2. The Sensitivity Control Bar appears. Press  $\downarrow$  to decrease sensitivity; press  $\uparrow$  to increase sensitivity. When it's set at the desired level, press **EXIT**. (When you reach the maximum or minimum limit, a tone sounds.)



Sonar Menu with Sensitivity command selected (left). The Sensitivity Control Bar (right).

### NOTE:

If you want to change the sensitivity in Manual Mode, first turn off Auto Sensitivity: from the Sonar Page, press **MENU |  $\downarrow$**  to **AUTO SENSITIVITY | ENT |  $\uparrow$**  to **SENSITIVITY | ENT**. Press  $\downarrow$  or  $\uparrow$  to pick a different sensitivity setting. When it's set at the desired level, press **EXIT**.

## **Important Tip:**

While you are experimenting and learning, it's possible to scramble the settings so that the sonar picture disappears from your screen. If that happens, remember that it's easy to switch back to full automatic operation by simply restoring the factory auto settings. Here's how:

### **To Restore Factory Settings**

1. Press **MENU** | **MENU** | **↓** to **SYSTEM SETUP** | **ENT** | **↓** to **RESET**

**OPTIONS** | **ENT**.

2. The unit asks if you want to reset all the options. Press **←** to **YES** | **ENT**. All options are reset, and the unit reverts back to the Map Page at the 4000-mile zoom range. (Any recorded sonar logs or GPS data will be unchanged.)

## **Fish Symbols vs. Full Sonar Chart**

You may have noticed in the quick reference that we used fish arches in full sonar chart mode for our example, and not the popular Fish I.D.<sup>TM</sup> fish symbol feature. Here's why.

Fish I.D. is an easier way for a sonar novice to recognize a fish signal return when he sees it. However, locating a fish via symbol has some limitations.

Your sonar unit's microprocessor is remarkably powerful, but it can be fooled. Some of the echoes *calculated* to be fish could be tree limbs or turtles! *To see what's under your boat in maximum detail, we recommend you turn off Fish I.D. and begin learning to interpret fish arches.*

Fish I.D. is most handy when you're in another part of the boat or performing some task that prevents you from watching the sonar screen. Then, you can turn on Fish I.D. and the audible fish alarm. When that lunker swims under your boat, you'll hear it!

Fish I.D. can also be useful when you want to screen out some of the sonar detail gathered by your unit. For example, in one case, fisherman in San Francisco Bay saw clouds of clutter in the water but no fish arches. When a downrigger was pulled up, it brought up several small jellyfish. The fisherman switched their Lowrance sonar to Fish I.D., which screened out the schools of jellyfish and clearly showed the game fish there as fish symbols.

## **Other Free Training Aids**

The sonar options section discusses Fish I.D., fish alarms and other features in greater detail. If you or a friend has Internet access, you can also learn more about interpreting what you see on your sonar screen.

Visit our web site, **www.lowrance.com**. Be sure to check out the free Sonar Tutorial, which includes animated illustrations and more pictures of actual sonar returns, all described in detail. There's even a "printer friendly" version of the tutorial available on our web site...it makes a great supplement to this operation manual!

You can also download a free copy of our Sonar Viewer software. This PC-based software application plays back any sonar chart log recorded with a Lowrance sonar product. Features include:

- Adjustable range, zoom, sensitivity, color line, noise rejection, surface clarity, etc. of the recorded file.
- Color interpretation of sonar signals can be user defined.
- Operates like a Windows Multimedia Player with forward, reverse, pause, fast forward, fast reverse, and scroll buttons.
- Adjustments update the entire record displayed
- Can print in full color.
- Window can dynamically be sized on your monitor.
- Mouse cursor shows GPS position, depth and sounding number anywhere on the visible record.

For the ultimate training aid, be sure to download the free emulator software for your unit. Aside from being just plain fun, this program can help you learn both basic and advanced operations without burning boat fuel! Lowrance is the first sonar manufacturer to provide this type of training tool for customers.

This PC application simulates the actual sonar/GPS unit on your computer. You can run it from your computer keyboard or use your mouse to press the virtual keys. Easy download and installation instructions are available on our web site.



**A free training emulator is available for your unit on our web site.**

The emulator works exactly like your real sonar/GPS unit. Using the Sonar Simulator and GPS Simulator features, it allows you to play back sonar logs, run GPS routes and trails, even create real waypoints you can use in the field! You can even take snapshots of the Sonar Chart and print them or e-mail them to friends.

# Section 4:

## Sonar Options & Other Features

Material in this section is arranged in alphabetical order.

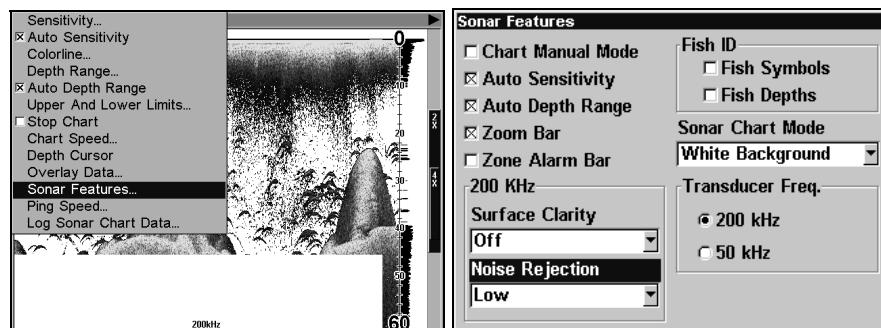
### ASP™ (Advanced Signal Processing)

The ASP™ feature is a noise rejection system built into the sonar unit that constantly evaluates the effects of boat speed, water conditions and interference. This automatic feature gives you the best display possible under most conditions.

The ASP feature is an effective tool in combating noise. In sonar terms, noise is any undesired signal. It is caused by electrical and mechanical sources such as bilge pumps, engine ignition systems and wiring, air bubbles passing over the face of the transducer, even vibration from the engine. In all cases, noise can produce unwanted marks on the display.

The ASP feature has four settings — Off, Low, Medium and High. If you have high noise levels, try using the "High" ASP setting. However, if you are having trouble with noise, we suggest that you take steps to find the interference source and fix it, rather than continually using the unit with the high ASP setting.

There are times when you may want to turn the ASP feature off. This allows you to view all incoming echoes before they are processed by the ASP feature.



**Sonar Menu with Sonar Features selected (left). The Sonar Features menu (right), Noise Rejection selected with ASP at default low setting.**

### To change the ASP level:

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.
2. Press **↓** to **NOISE REJECTION** | **ENT**.
3. Press **↓** or **↑** to select a setting, then press **ENT**.
4. To return to the previous page, press **EXIT** | **EXIT**.

## Alarms

This unit has three different types of sonar alarms. The first is the Fish Alarm. It sounds when the Fish I.D.<sup>TM</sup> feature determines an echo is a fish.

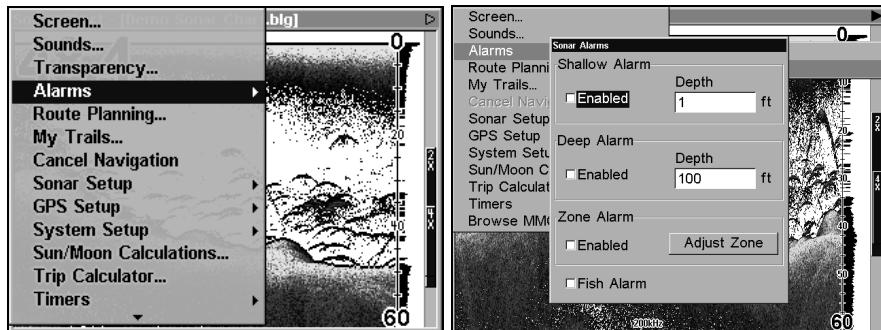
Another alarm is the Zone Alarm, which consists of a bar on the side of the screen. Any echo on the chart that appears inside this bar triggers the alarm.

The last alarm is the Depth Alarm, which has both a Shallow and a Deep setting. Only the bottom signal will trigger this alarm. This is useful as an anchor watch, a shallow water alert, or for navigation.

### Depth Alarms

The depth alarms sound a tone when the bottom signal goes shallower than the shallow alarm's setting or deeper than the deep alarm's setting. For example, if you set the shallow alarm to 10 feet, the alarm will sound a tone if the bottom signal is less than 10 feet. It will continue to sound until the bottom goes deeper than 10 feet.

The deep alarm works just the opposite. It sounds a warning tone if the bottom depth goes deeper than the alarm's setting. Both depth alarms work only off the digital bottom depth signals. No other targets will trip these alarms. These alarms can be used at the same time or individually.



Main Menu and Sonar Alarms command (left);  
The Sonar Alarms menu (right).

#### To adjust and turn on the shallow alarm:

1. Press **MENU | MENU | ↓** to **ALARMS | ENT | ↓** to **SONAR ALARMS | ENT**.
2. Press **→** to **SHALLOW ALARM DEPTH | ENT**.
3. Press **↑** or **↓** to change the first number, then press **→** to move the cursor to the next number and repeat until the depth is correct, then press **ENT**.

4. Press **←** to **SHALLOW ALARM ENABLED | ENT | EXIT | EXIT | EXIT**.
5. To turn off the alarm, press **MENU | MENU | ↓** to **ALARMS | ENT | ↓** to **SONAR ALARMS | ENT | ENT | EXIT | EXIT**.

To switch to a different depth setting, open the Sonar Alarms menu and repeat the instructions in step 3 above.

**To adjust and turn on the deep alarm:**

1. Press **MENU | MENU | ↓** to **ALARMS | ENT | ↓** to **SONAR ALARMS | ENT**.
2. Press **↓** to **DEEP ALARM ENABLED | →** to **DEEP ALARM DEPTH | ENT**.
3. Press **↑** or **↓** to change the first number, then press **→** to move the cursor to the next number and repeat until the depth is correct, then press **ENT**.
4. Press **←** to **DEEP ALARM ENABLED | ENT | EXIT | EXIT | EXIT**.
5. To turn off the alarm, press **MENU | MENU | ↓** to **ALARMS | ENT | ↓** to **SONAR ALARMS | ENT | ↓** to **DEEP ALARM ENABLED | ENT | EXIT | EXIT | EXIT**.

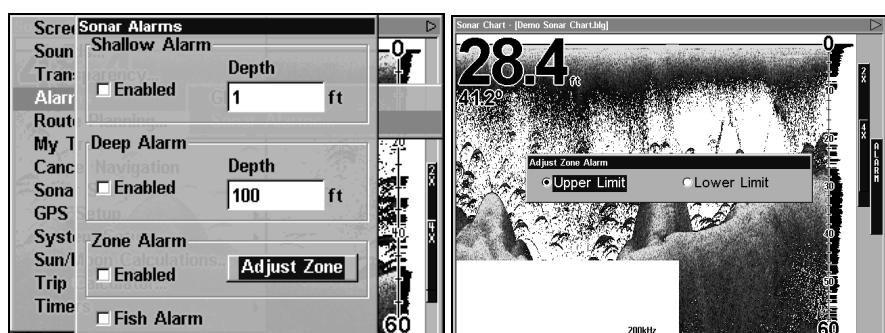
To switch to a different depth setting, open the Sonar Alarms menu and repeat the instructions in step 3 above.

**Zone Alarm**

The zone alarm is triggered when any echo passes inside the zone alarm bar, shown on the right side of the screen.

**To adjust and turn on the zone alarm:**

1. Press **MENU | MENU | ↓** to **ALARMS | ENT | ↓** to **SONAR ALARMS | ENT**.
2. Press **↓** to **ZONE ALARM ENABLED | →** to **ADJUST ZONE | ENT**.



Sonar Alarms menu, with **Adjust Zone** command selected (left); **Adjust Zone Alarm** selection box, with **Upper Limit** selected (right).

3. To set the upper boundary for the Zone Alarm, use **←** or **→** to select **UPPER**, then press **↑** or **↓** to move the top of the bar to the desired depth.

4. To set the lower boundary for the Zone Alarm, use  $\leftarrow$  or  $\rightarrow$  to select **LOWER**, then press  $\uparrow$  or  $\downarrow$  to move the bottom of the bar to the desired depth.

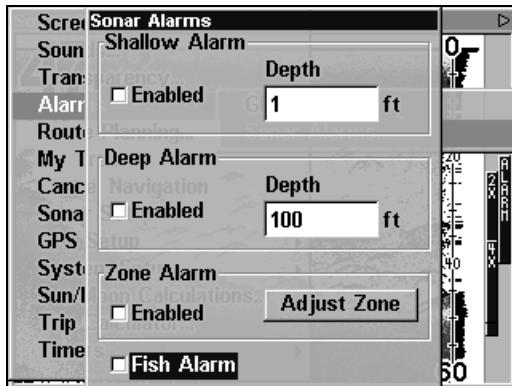
5. Press **EXIT** |  $\leftarrow$  to **ZONE ALARM ENABLED** | **ENT** | **EXIT** | **EXIT**. Now, any echo — fish, bottom, structure — within the zone alarm's depth range will trigger the zone alarm.

6. To turn off the alarm, press **MENU** | **MENU** |  $\downarrow$  to **ALARMS** | **ENT** |  $\downarrow$  to **SONAR ALARMS** | **ENT** |  $\downarrow$  to **ZONE ALARM ENABLED** | **ENT** | **EXIT** | **EXIT** | **EXIT**.

To switch to a different depth setting, open the Sonar Alarms menu and repeat the instructions in steps 3 and 4 above.

### Fish Alarm

Use the fish alarm for a distinctive audible alarm when fish or other suspended objects are detected by the Fish I.D.<sup>TM</sup> feature (Fish I.D. must be turned on for the Fish Alarm to work). A different tone sounds for each fish symbol size shown on the display.



**Sonar Alarms menu with Fish Alarm selected. The checkbox is blank, indicating the alarm is turned off.**

#### To turn the fish alarm on:

1. Press **MENU** | **MENU** |  $\downarrow$  to **ALARMS** | **ENT** |  $\downarrow$  to **SONAR ALARMS** | **ENT**.
2. Press  $\downarrow$  to **FISH ALARM** | **ENT** | **EXIT** | **EXIT** | **EXIT**.
3. To turn off the alarm, press **MENU** | **MENU** |  $\downarrow$  to **ALARMS** | **ENT** |  $\downarrow$  to **SONAR ALARMS** | **ENT** |  $\downarrow$  to **FISH ALARM** | **ENT** | **EXIT** | **EXIT** | **EXIT**.

### Calibrate Speed

The speed sensor can be calibrated to compensate for inaccuracies. Before you change the setting, first calculate the percentage that the speed is off. You will enter this percentage in a moment.

For example, if you figure the sensor is reading 10 percent faster than

actual speed, you will enter  $-10$  in the calibration window. If the sensor is reading 5 percent slower than true speed, you will enter  $+5$  in the window.

A good way to gauge your speed sensor's performance is to compare its reading with the ground speed measured by your unit's GPS functions. When you make a run to compare GPS ground speed to speed sensor speed, perform your test in relatively calm water free of current, if possible. (Unless, of course, you are taking the current speed into consideration when making your calculation.) After you have a correction figure, here's how to enter it:

1. Press **MENU | MENU |  $\downarrow$**  to **SONAR SETUP | ENT |  $\downarrow$**  to **CALIBRATE WATER SPEED | ENT**.

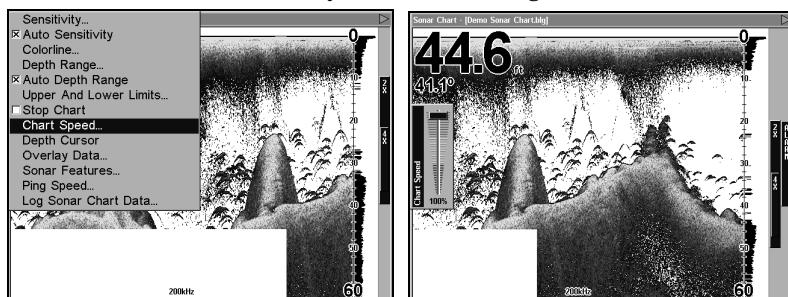
2. Enter the number you calculated earlier: press  $\uparrow$  or  $\downarrow$  to change the first character (+ or -), then press  $\rightarrow$  to move the cursor to the next number and repeat until the percentage is correct, then press **EXIT**.

## Chart Speed

The rate echoes scroll across the screen is called the chart speed. The default is maximum. We recommend you leave the setting there for virtually all fishing conditions.

You, however, might consider experimenting with chart speed when you are stationary or drifting very slowly. You may sometimes achieve better images as you slow the chart speed to match how fast you are moving across the bottom.

If you are at anchor, ice fishing or fishing from a dock, experiment with a chart speed around 50 percent. If you are drifting slowly, try a chart speed around 75 percent. When you are stationary and a fish swims through the sonar signal cone, the image appears on the screen as a long line instead of a fish arch. Reducing the chart speed may result in a shorter line that more closely resembles a regular fish return.



Sonar Page menu with Chart Speed command selected (left);  
The Chart Speed Control Bar (right).

If you do experiment with chart speed, remember to reset it to maximum when you resume trolling or moving across the water at higher speed. To change chart speed:

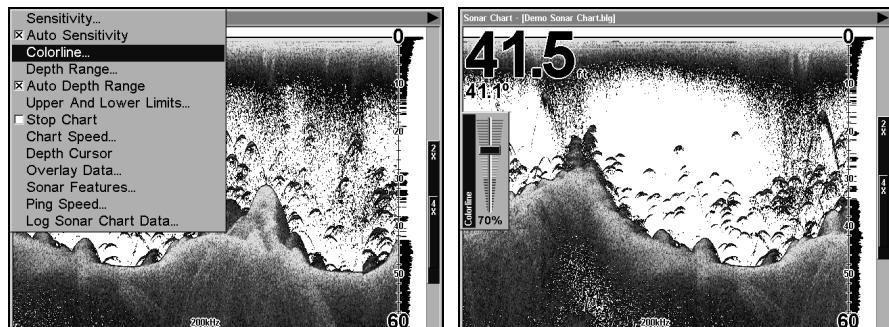
1. From the Sonar Page, press **MENU** | **↓** to **CHART SPEED** | **ENT**.
2. The Chart Speed Control Bar appears. Press **↓** to decrease chart speed; press **↑** to increase chart speed.
3. When it's set at the desired level, press **EXIT**.

## ColorLine™

ColorLine lets you distinguish between strong and weak echoes. It "paints" a brighter color on targets that return a stronger signal. This allows you to tell the difference between a hard and soft bottom. For example, a soft, muddy or weedy bottom returns a weaker signal, which is shown with a narrow, colored line (dark blue tinged with red or a little yellow.) Since fish are among the weakest echoes, they show up mostly as blue arches. A hard bottom or other relatively hard target returns a strong signal displayed as a wide, brightly colored line (reddish yellow to bright yellow.)

If you have two signals of equal size, one with red to yellow color and the other without, then the target with brighter color (yellow) is the stronger signal. This helps distinguish weeds from trees on the bottom, or fish from structure.

ColorLine is adjustable. Experiment with your unit to find the ColorLine setting that's best for you.

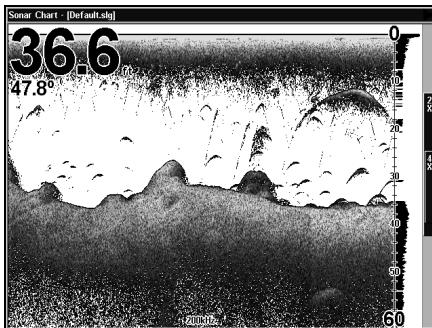


Sonar Page menu with ColorLine command selected (left);  
The ColorLine control bar (right).

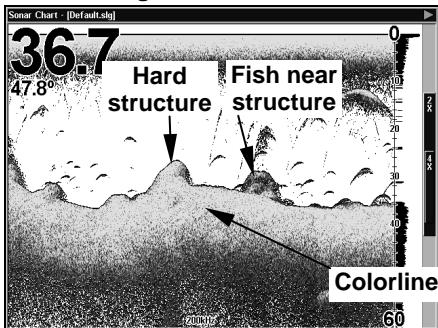
To adjust the ColorLine level:

1. From the Sonar Page, press **MENU** | **↓** to **COLORLINE** | **ENT**.
2. The ColorLine Control Bar appears. Press **↓** to decrease ColorLine; press **↑** to increase Colorline.
3. When it's set at the desired level, press **EXIT**.

**Fig. 1A**



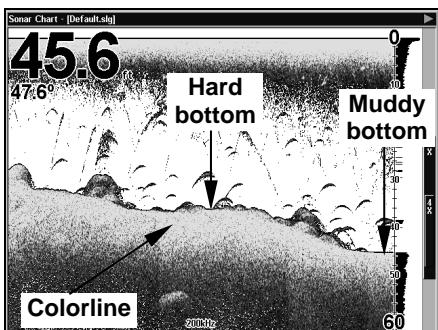
**Fig. 1B**



**Fig. 2A**



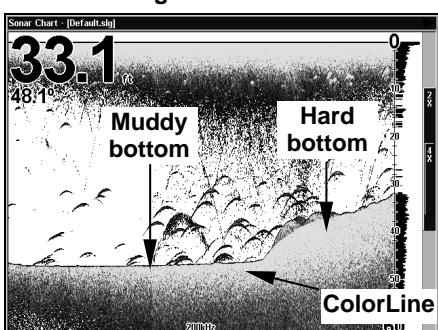
**Fig. 2B**



**Fig. 3A**



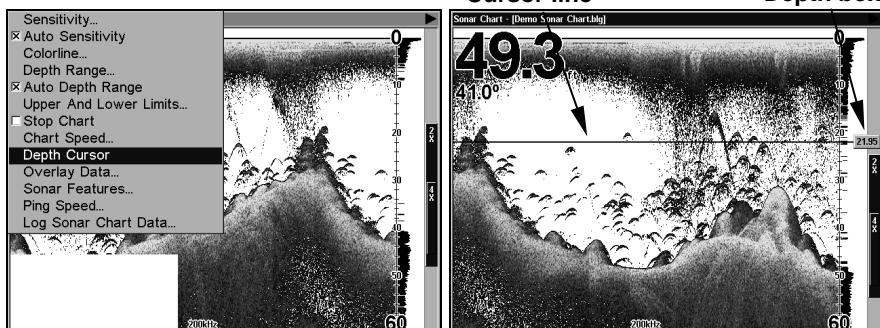
**Fig. 3B**



The "A" figures to the left show locations with ColorLine set at the factory level of 70 percent. The "B" figures on the right show the same locations with ColorLine increased to 84 percent. In Figure 1B, no fish are near the left structure, but the right structure shows fish holding next to the structure.

## Depth Cursor

The depth cursor consists of a horizontal line with a digital depth box on the right side. The numbers inside the box show the depth of the cursor.



**Sonar Page menu with Depth Cursor command selected (left). Sonar chart with the depth cursor active (right). The line indicates the large fish is 21.95 feet deep.**

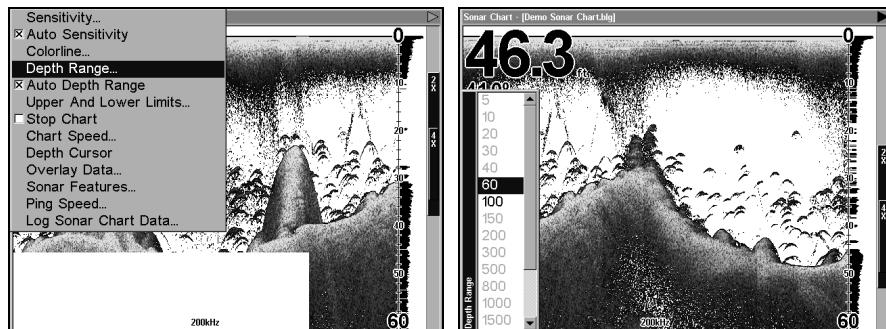
The cursor can be moved to any location on the screen, letting you pinpoint the depth of a target.

1. From the Sonar Page, press **MENU** | **↓** to **DEPTH CURSOR** | **ENT**.
2. The depth cursor appears. Press **↓** to lower the cursor line; press **↑** to raise the cursor line.
3. To clear the depth cursor, press **EXIT**.

## Depth Range - Automatic

When turned on for the first time, the bottom signal is automatically placed in the lower half of the screen. This is called Auto Ranging and is part of the automatic function. You can change the range to a different depth, depending upon the bottom depth and the current range. To do this:

1. From the Sonar Page, press **MENU** | **↓** to **DEPTH RANGE** | **ENT**.



**Sonar Page menu with Depth Range command selected (left); The Depth Range Control Scale (right).**

2. The Depth Range Control Scale appears. Press  $\uparrow$  or  $\downarrow$  to select a different depth range. A blue bar highlights the selected range. The lighter range numbers can not be selected.

3. When the new range is selected, press **EXIT** to clear the menu.

## **Depth Range - Manual**

You have complete control over the range when the unit is in the manual mode. There are 16 depth ranges, from 5 to 4,000 feet.

### **To switch to Manual Depth Range:**

1. First, turn off automatic depth range. From the Sonar Page, press **MENU** $\downarrow$  to **AUTO DEPTH RANGE** | **ENT**.

2. Press  $\uparrow$  to **DEPTH RANGE** | **ENT** and the Depth Range Control Scale appears.

3. Press  $\downarrow$  or  $\uparrow$  to select a different depth range. A horizontal blue bar highlights the selected range.

4. When the new range is selected, press **EXIT** to clear the menu.

### **To turn Auto Depth Range on again:**

From the Sonar Page, press **MENU** $\downarrow$  to **AUTO DEPTH RANGE** | **ENT** | **EXIT**.

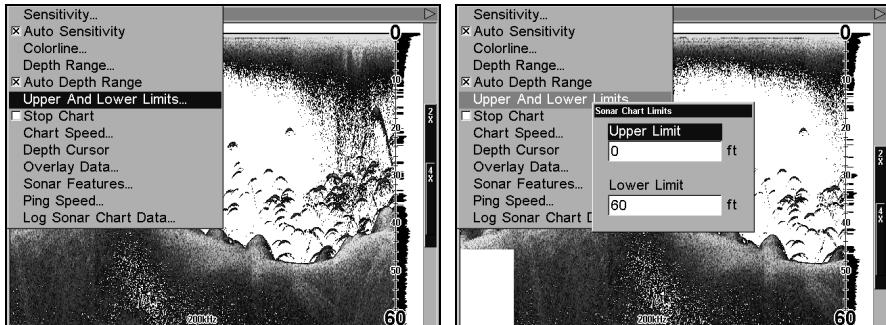
### **NOTE:**

The sonar's depth capability depends on the transducer installation, water and bottom conditions, and other factors.

## **Depth Range - Upper and Lower Limits**

Virtually any segment of the water column can be displayed by using the upper and lower limit feature. This lets you pick the shallow and deep range limits shown on the screen, provided there is at least 10 feet between the upper and lower limit you select. For example, a range from 12 feet to 34 feet could be used.

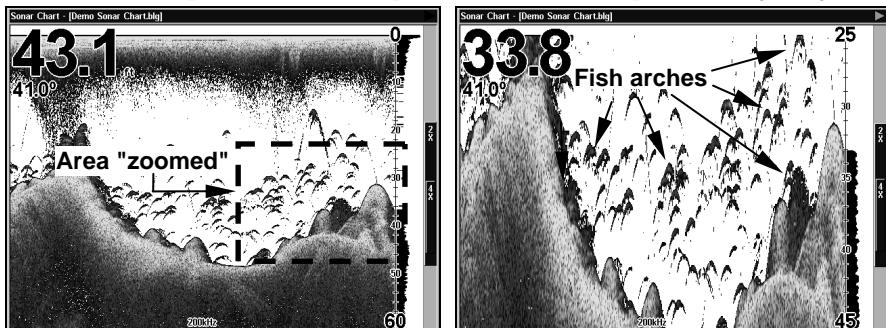
Changing the upper and lower limits gives you far greater control over the depth range. This feature lets you "zoom in" the display in almost unlimited combinations. Nearly any segment of the water column, from the surface to the bottom can be shown. This enlarges the sonar targets to best suit your fishing needs and water conditions.



Sonar Page Menu with Upper and Lower Limits command selected (left); Sonar Chart Limits menu, with Upper Limit selected (right).

### To change the upper and lower limits:

1. From the Sonar Page, press **MENU**|**↓** to **UPPER AND LOWER LIMITS** | **ENT**. The Sonar Chart Limits menu appears, with Upper Limit selected.
2. To set the upper limit, press **ENT**. Press **↑** or **↓** to change the first number, then press **→** to move the cursor to the next number and repeat until the depth is correct, then press **EXIT**.
3. To set the lower limit, press **↓** to **LOWER LIMIT** | **ENT**. Press **↑** or **↓** to change the first number, then press **→** to move the cursor to the next number and repeat until the depth is correct, then press **EXIT**|**EXIT**|**EXIT**.



Normal display, in auto depth range mode, (left); Display "zoomed" with Upper and Lower Limits focusing on the portion of the water column from 25 feet to 45 feet deep (right). In the "zoomed" image on the right, note the target definition, showing two fish holding just off the structure.

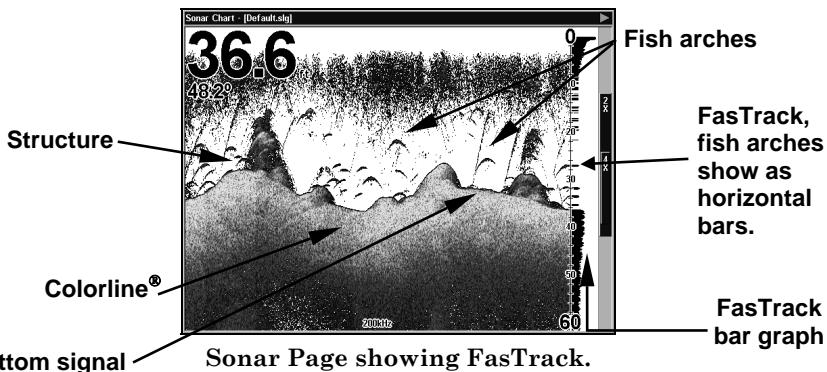
### To turn off upper and lower limits:

From the Sonar Page, press **MENU** | **↓** to **AUTO DEPTH RANGE** | **ENT**|**EXIT**.

### FasTrack™

This feature automatically converts all echoes to short horizontal lines on the display's far right side. The graph on the rest of the screen continues to operate normally. FasTrack gives you a rapid update of

conditions directly under the boat. This makes it useful for ice fishing, or when you're fishing at anchor. When the boat is not moving, fish signals are long, drawn out lines on a normal chart display. FasTrack converts the graph to a vertical bar graph that, with practice, makes a useful addition to fishing at a stationary location.



## Fish I.D.<sup>™</sup> (Fish Symbols & Depths)

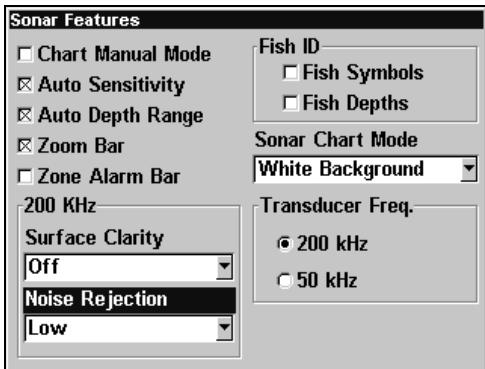
The Fish I.D. feature identifies targets that meet certain conditions as fish. The microcomputer analyzes all echoes and eliminates surface clutter, thermoclines, and other undesirable signals. In most instances, remaining targets are fish. The Fish I.D. feature displays fish symbols on the screen in place of the actual fish echoes.

There are several fish symbol sizes. These are used to designate the relative size between targets. In other words, Fish I.D. displays a small fish symbol when it recognizes a target as a small fish, a medium fish symbol on a larger target and so on.

The sonar's microcomputer is sophisticated, but it can be fooled. It can't distinguish between fish and other suspended objects such as trotlines, turtles, submerged floats, air bubbles, etc. Individual tree limbs extending outwards from a group of limbs is the hardest object for the Fish I.D. feature to distinguish from fish.

You may see fish symbols on the screen when actually, there are no fish. The reverse also is true.

Does that mean Fish I.D. is broken? No. The feature is simply interpreting sonar returns in a specific way to help take some of the work out of reading the screen. Remember: Fish I.D. is one of the many tools we provide so you can analyze your sonar returns for maximum fish finding information. This and other features can help you successfully "see" beneath the boat under varied water and fishing conditions. Practice with Fish I.D. mode on and off to become more familiar with it. The default for Fish I.D. is off.



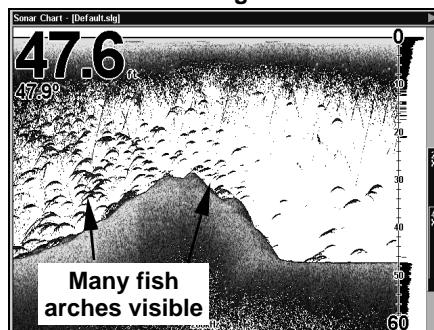
The Sonar Features menu.

**To turn the Fish I.D. feature on:**

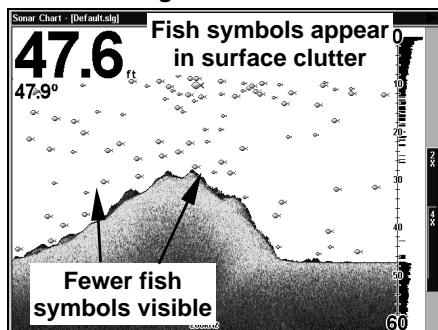
1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.
2. Press **→** to **FISH SYMBOLS** | **ENT** | **EXIT** | **EXIT**.

To turn off Fish I.D., repeat the instructions in step 1.

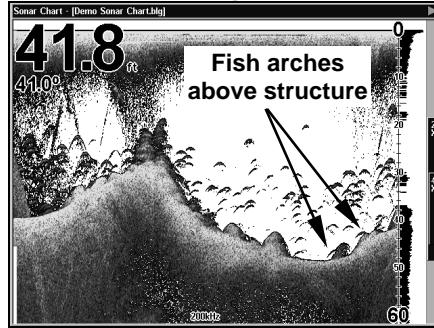
**Fig. 1 A**



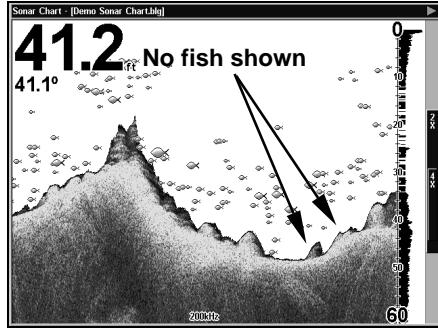
**Fig. 1 B**



**Fig. 2 A**



**Fig. 2 B**



Figures 1A and 2A (left) show Sonar Page in normal chart mode. Figures 1B and 2B (right) show the same underwater scene with Fish I.D. turned on. Note how arches are replaced with symbols.

## FishTrack™

The FishTrack feature shows the depth of a fish symbol when it appears on the display. This lets you accurately gauge the depth of targets. This feature is available only when the Fish I.D. feature is on. The default setting for FishTrack is off.

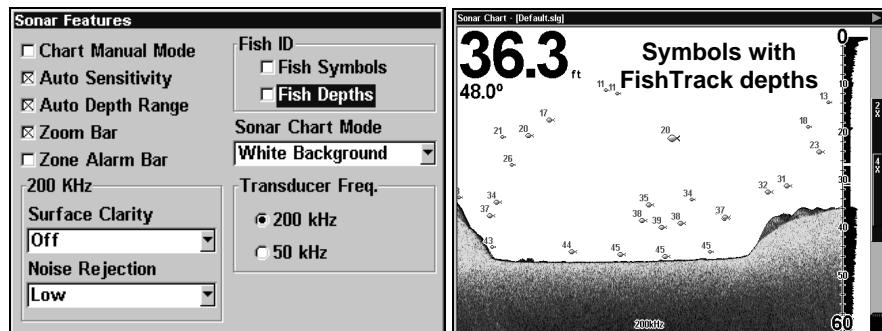
### To turn on FishTrack:

**(Note:** These instructions will turn on FishTrack *and* Fish I.D. at the same time.)

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.

2. Press **→** **↓** to **FISH DEPTHS** | **ENT** | **EXIT** | **EXIT**.

To turn off FishTrack, repeat the instructions in step 1. Turning off FishTrack in this manner will not turn off Fish I.D. symbols.



Sonar Features menu with Fish I.D. Depths selected (left). When the check box to the left is unchecked, the feature is off. Sonar Page showing Fish I.D. symbols and FishTrack depths turned on (right).

## Frequency (Change Transducer Frequency)

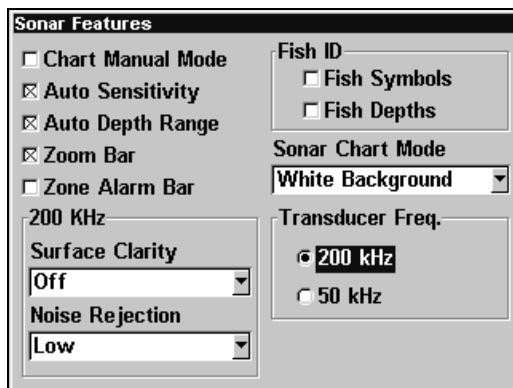
### (Dual-Frequency Transducers only)

A dual-frequency transducer operates with both 200 kHz and 50 kHz. The 200 kHz frequency has a 12° cone angle and the 50 kHz frequency has a 35° cone angle.

The default frequency is 200 kHz, which is best for use in shallow water (about 300 feet or less). This frequency is the best choice for about 80 percent of the fresh and salt water sport fishing applications. When you get into very deep salt water, 300 to 500 feet or deeper, the 50 kHz frequency is the best choice.

The 200 kHz transducer will give you better detail and definition, but less depth penetration. The 50 kHz transducer will give you greater depth penetration, but a little less detail and less definition. (Remember, all sonar units typically read deeper in fresh water than in salt water.)

There is a common exception to these rules of thumb. Some fishermen on freshwater lakes (or the ocean) using downriggers like to see them on the sonar. In many of those cases, you'll see a 50 kHz transducer frequency in use because the wider cone angle lets them watch the bait.



**Sonar Features menu with a frequency of 200 kHz selected.**

**To change the frequency setting to 50 kHz:**

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.
2. Press **→** **↓** to **50 kHz** | **ENT**.
3. Press **EXIT** | **EXIT** to clear the menu.

**To change the frequency setting to 200 kHz:**

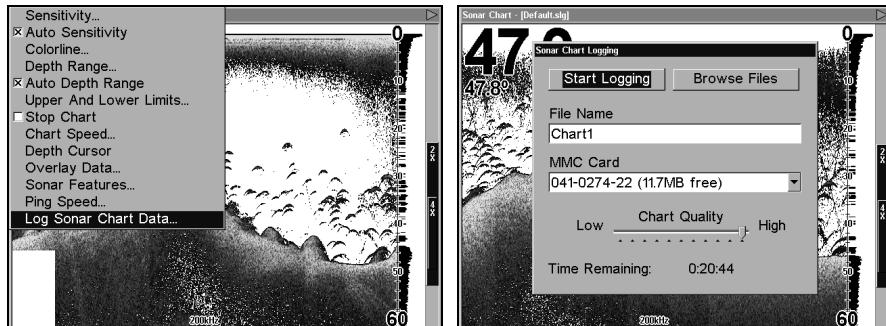
1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.
2. Press **→** **↓** to **200 kHz** | **ENT**.
3. Press **EXIT** | **EXIT** to clear the menu.

## **HyperScroll™**

See the entry on Ping Speed, which controls the HyperScroll feature.

## **Log Sonar Chart Data**

If you have an MMC installed in the unit, the sonar data shown on the screen can be saved to it. This can be played back at any time. (To play a recorded sonar chart log, see the entry in this section for Sonar Simulator.) If you have a personal computer and internet access, download our free Sonar Viewer and your unit's emulator at our web site, [www.lowrance.com](http://www.lowrance.com). That will allow you to replay sonar logs on your personal computer.



The Sonar Page menu with the Log Sonar Chart Data command selected (left). Sonar Chart Logging menu, with the Start Logging command selected (right). The MMC has 11.7 MB of free space, which will record the scrolling chart for 20 minutes and 44 seconds.

### To record or log chart data:

1. Press **MENU** | **↓** to **LOG SONAR CHART DATA** | **ENT**.
2. To record data using the default settings, press **ENT**. The menu clears and the Sonar Page title bar shows the name of the file you are recording. Warning messages will appear as recording time begins to run out.

### NOTE:

You can change any of the settings by using the cursor arrows to highlight different commands. Select **FILE NAME** if you want to change the name. Select **CHART QUALITY** if you want to lower the file quality and record for a longer period of time. After you've changed the settings, select **START LOGGING**.

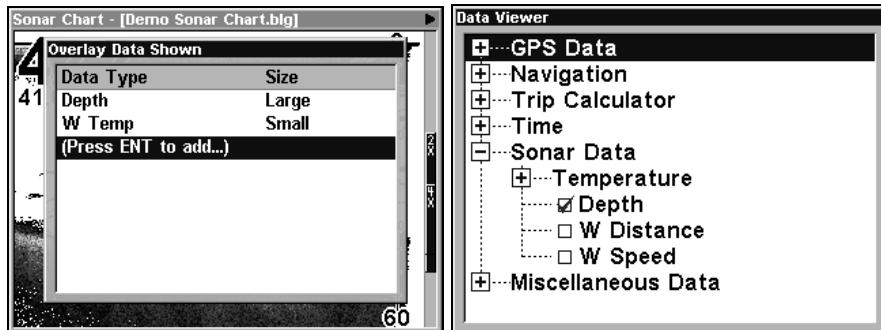
## Noise Rejection

See the entry on Advanced Signal Processing in this section.

## Overlay Data

On any Page display except Satellite Status, you can "float" or overlay additional Sonar or data on the screen with the Overlay Data command. The various data available from your unit are divided into categories in the Overlay Data menu. These categories include GPS Data, Navigation, Trip Calculator, Time, Sonar Data and Miscellaneous Data.

You can select items from any of these categories for display, in any combination. The category divisions are there only to help you sort through the information.



Overlay Data Shown window (left); Data viewer with the Sonar Data category expanded (right).

### To overlay information on your screen:

1. Press **MENU** | **↓** to **OVERLAY DATA** | **ENT**.
2. If you have overlay data on your display, you'll see a list of that data on the overlay data shown menu. To add data select **(ENTER TO ADD)** and press **ENT**. The data viewer shows information categories with "+" or "-" symbols next to each category name. A category with a "+" next to it is *expandable*, meaning its contents are hidden.

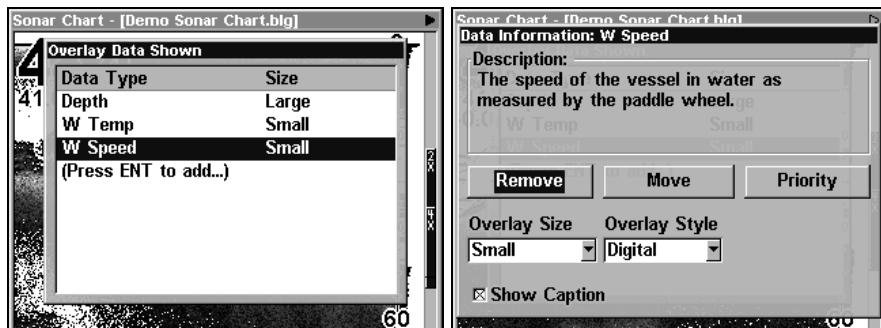
Selecting the category name and pressing **ENT** will show the category's contents, so you can choose items within it. An expanded category (one with a "-" next to its name) can be collapsed to hide its contents. Just select the category and press **ENT**.

3. Expand any categories that might contain data you want to display. Then press **↓** or **↑** to select a data option.
4. With the data option highlighted, press **ENT** to check it (turn it on) or uncheck it (turn it off). As you turn it on, the data will appear on top of the screen. Every Page display has a maximum number of items you can show using the Overlay Data command.
5. After the desired changes are made, press **EXIT|EXIT** to return to the page display.

### To remove overlaid data:

1. While on the Page display that shows the item or items you want to remove, press **MENU|↓** to **OVERLAY DATA** | **ENT**.
2. You'll see a list of the overlay data currently displayed. Select the item you want to remove from your display and press **ENT|ENT** to remove the data. To remove another item, select the item and press **ENT|ENT**.

- When you have finished removing all the items you want from the screen, press **EXIT** to return to the page display.



Overlay Data Shown, with water speed selected (left). Press **ENT** to access **REMOVE** option (right). Press **ENT** again to remove item and return to the Overlay Data Shown screen.

#### To move overlaid data:

You may find it useful to rearrange data floating in your display window.

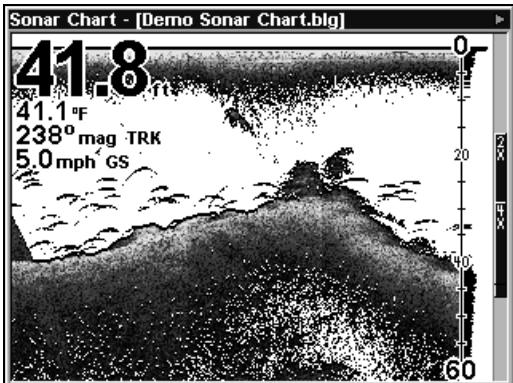
- Press **MENU** | **↓** to **OVERLAY DATA** | **ENT**.
- You'll see a list of the overlay data currently displayed. Select the item you want to move and press **ENT** | **→** to **MOVE** | **ENT**.
- The data begins to flash on your screen. Use any combination of **→**, **←**, **↑** and **↓** to move the data to a new location on the screen.
- When satisfied, press **EXIT** | **EXIT**.

#### NOTE:

The Customize command and the Overlay Data command both use the same information categories. The difference between the two commands is the Customize command is only used to modify pages with digital data boxes, while Overlay Data changes information floating on the screen. See Customize Page Displays, on page 82 for information on customizing data boxes.

#### To change displayed data font size:

- From the Map or Sonar page, press **MENU** | **↓** to **OVERLAY DATA** | **ENT**.
- Press **↓** or **↑** to select *Data Type* | press **→** or **←** to *Data Size* | **EXIT**.
- The selected data type will be displayed in the new size. (To change the font size of another data type repeat these steps, beginning with step two above.)
- To return to the previous page, press **EXIT**.



**The overlay data on this sonar display includes, Depth, Temperature, Ground Speed and the Track the boat is following.**

**NOTE:**

Some data types can be displayed in only one font size. If that is the case, the Data Size box will not be displayed for that data type.

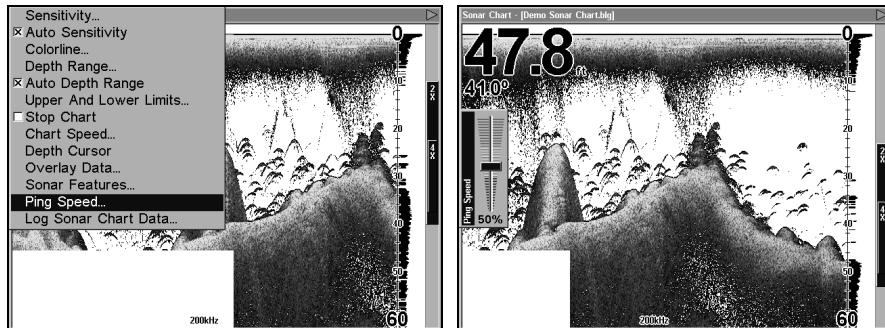
## **Ping Speed & HyperScroll™**

Ping Speed controls the rate at which the transmitter and transducer broadcast sonar sound waves — pings — into the water. The unit has a default ping speed of 50 percent. At normal boating speeds, this automatically provides enough return echoes to refresh the screen and scroll the chart at maximum chart speed.

However, when you are running at high speeds, or just want the fastest possible screen update, you may want to use the HyperScroll™ feature. When you change the Ping Speed to any setting greater than 50 percent, the unit automatically enters HyperScroll mode.

These faster ping rates allow you to maintain a high-detail picture on the screen, and the screen refresh rate and chart scroll speed can keep pace with the boat as it moves quickly over the bottom terrain.

When using HyperScroll, you may also need to manually decrease the sensitivity for optimum performance. Depending on water depth and other conditions, HyperScroll may cause a second bottom echo to return to the transducer during the next ping cycle, or sounding. This can result in a large amount of clutter appearing on the screen. If this occurs, just decrease the sensitivity to a level that eliminates the clutter. When you turn HyperScroll off, you can return to your original sensitivity level.



**Sonar Menu with Ping Speed command selected (left).  
The Ping Speed Control Bar (right) at default setting.**

### To change Ping Speed:

1. From the Sonar Page, press **MENU** | **↓** to **PING SPEED** | **ENT**.
2. The Ping Speed Control Bar appears. Press **↑** to increase ping speed; press **↓** to decrease ping speed. When it's set at the desired level, press **EXIT**.

### To turn off HyperScroll:

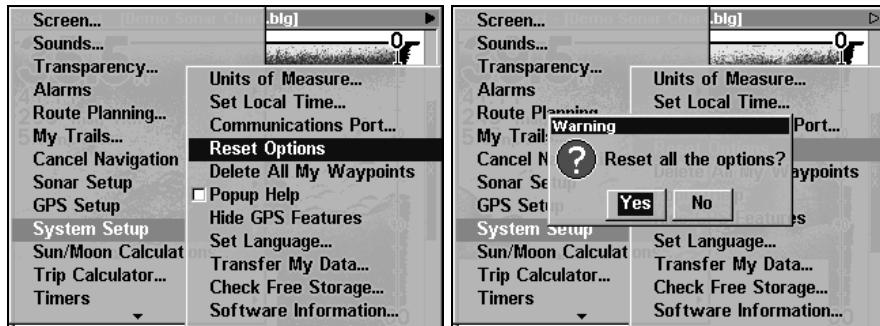
1. From the Sonar Page, press **MENU** | **↓** to **PING SPEED** | **ENT**.
2. The Ping Speed Control Bar appears. Press **↓** to decrease ping speed to 50 percent. When it's set at the desired level, press **EXIT**.

When you boost ping speed and switch into HyperScroll, the width of the FasTrack bar graph display doubles in width at the right side of the screen. This allows you to better see the virtually instantaneous sonar returns, just as you would on a flasher sonar unit. For more information on FasTrack, see it's entry in this section.

## Reset Options

This command is used to reset all features, options and settings to their original factory defaults. This is useful when you have changed several settings and want to return the unit to basic automatic operation.

1. Press **MENU** | **MENU** | **↓** to **SYSTEM SETUP** | **ENT** | **↓** to **RESET OPTIONS** | **ENT**.
2. Press **←** to **YES** | **ENT**.
3. All the menus are cleared and the unit reverts to the Map Page at the 4000-mile zoom range, just as if you had turned it on for the first time. All options have been returned to the factory settings.



System Setup menu with Reset Options command selected (left). The Reset Options dialog box, with "Yes" selected (right).

#### NOTE:

Reset Options does *not* erase any waypoints, routes, plot trails, or sonar logs.

### Reset Water Distance

The sonar chart's Digital Data display option includes a window that shows distance traveled, called Water Distance ("W Distance"). This information is calculated from an optional water speed sensor, not the GPS. The Water Distance window can be reset to zero using the Reset Water Distance command.

Press **MENU | MENU | ↓** to **SONAR SETUP | ENT | ↓** to **RESET WATER DISTANCE | ENT**. The menus are cleared and the water distance is reset to 0.00.

### Set Keel Offset

This unit measures water depth from the face of the transducer. Since the transducer is installed below the water surface, the depth displayed by the digital depth, chart depth scale, chart cursor or fish symbols is *not* exact. If the transducer is 1 foot below the surface, and the screen shows the water depth as 30 feet, then the actual depth is 31 feet.

On sailboats or other large vessels with deep drafts, the distance between the transducer installation and the keel or lower engine unit can be several feet. In those cases, an inexact depth reading could result in grounding or striking underwater structure. The Keel Offset feature eliminates the need for the navigator to mentally calculate how much water is under his keel.

Keel Offset lets you calibrate the digital depth: chart depth scale, chart cursor depth and fish symbol depth displayed on the screen. To calibrate the depth indicators, first measure the distance from the face of the

transducer to the lowest part of the boat. In this example, we will use 3.5 feet. This will entered as a *negative* 3.5 feet, which makes the depth indicators perform as if the transducer's lower in the water than it really is.

1. Press **MENU | MENU | ↓** to **SONAR SETUP | ENT**.
2. Use **↓** to scroll down to **KEEL OFFSET**, then press **ENT**. The Keel Offset dialog box appears. Press **↓** to change the plus (+) sign to a minus (−) sign.
3. Press **→** to the first number, then press **↑** to change the number to 3
4. Press **→** to the second number, then press **↑** to change the number to 5, then press **EXIT**. The depth indicators now accurately show the water depth beneath the keel.

#### **NOTE:**

If knowing the exact depth of water beneath the keel is less important, you can calibrate the depth indicators so that they show the actual water depth from surface to bottom. To do this, first measure the distance from the face of the transducer to the surface (the water line on the boat). In this example, we will use 1.5 feet. This will be entered as a *positive* 1.5 feet, which makes the depth indicators perform as if the transducer's higher in the water than it really is.

1. Press **MENU | MENU | ↓** to **SONAR SETUP | ENT | ENT**.
2. The Keel Offset dialog box appears with a plus (+) sign at the front of the box.
3. Press **→** to the first number, then press **↑** to change the number to 1.
4. Press **→** to the second number, press **↑** to change the number to 5, then press **EXIT**. The depth indicator now accurately shows the water depth from surface to bottom.

## **Sensitivity & Auto Sensitivity**

The sensitivity controls the ability of the unit to pick up echoes. Sensitivity can be adjusted, because water conditions vary greatly. A low sensitivity level (from zero to 50 percent) excludes much of the bottom information, fish signals, and other target information.

High sensitivity levels let you see this detail, but it can also clutter the screen with many undesired signals. Typically, the best sensitivity level shows a good solid bottom signal with some surface clutter.

## Automatic Sensitivity

The default sensitivity mode is automatic. The unit bases the sensitivity level on water depth and conditions. When the unit is in the automatic mode, sensitivity is automatically adjusted to keep a solid bottom signal displayed, plus a little more power. This gives it the capability to show fish and other detail.

However, situations occur when it becomes necessary to increase or decrease the sensitivity. This typically happens when you wish to see more detail, so an increase in sensitivity is indicated. Or, wave action and boat wakes can create enough tiny air bubbles to clutter much of the water column. In that case, a decrease in sensitivity is indicated to reduce some of the clutter.

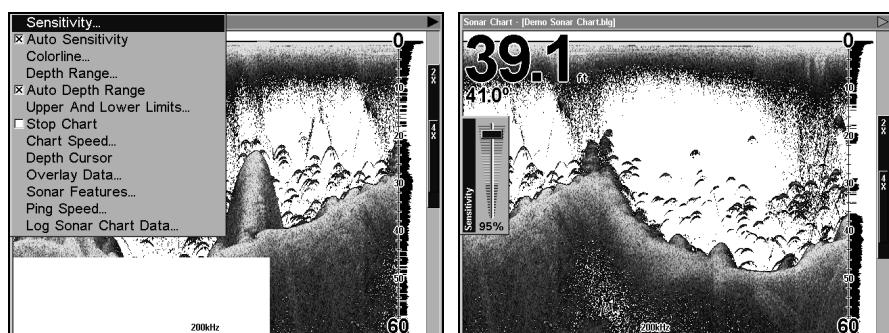
The control bar used to adjust sensitivity up or down is the same whether the unit is in the automatic or manual mode. In automatic you can adjust sensitivity up to 100 percent but the unit will limit your *minimum* setting. In auto, the unit will continue to make small adjustments, allowing for the setting you selected.

In manual mode, you have *complete* control over sensitivity, with the ability to set it anywhere from zero to 100 percent. Once you select a level in manual, the unit will continue to use that exact sensitivity setting until you change it or revert to auto mode.

### To adjust sensitivity in auto mode:

1. Press **MENU | ENT**.

2. The Sensitivity Control Bar appears. Press  $\downarrow$  to decrease sensitivity; press  $\uparrow$  to increase sensitivity. When it's set at the desired level, press **EXIT**. (When you reach the maximum or minimum limit, a tone sounds.)



Sonar Menu with Sensitivity command selected (left).  
The Sensitivity Control Bar (right).

## To adjust sensitivity in manual mode:

1. First, turn off Auto Sensitivity: from the Sonar Page, press **MENU** | **↓** to **AUTO SENSITIVITY** | **ENT**.

2. Press **↑** to **SENSITIVITY** | **ENT** and the Sensitivity Control Bar appears. Press **↓** or **↑** to pick a different sensitivity setting. When it's set at the desired level, press **EXIT**.

## To turn Auto Sensitivity back on:

From the Sonar Page, press **MENU** | **↓** to **AUTO SENSITIVITY** | **ENT** | **EXIT**.

### NOTE:

To return to the original factory setting for Auto Sensitivity, see the entry in this section on Reset Options. If sensitivity is in manual mode, the Reset Options command will switch back to Auto and reset the factory setting at the same time.

### *Tip:*

For quicker sensitivity adjustments, try leaving the Sensitivity Control Bar on the screen as the chart scrolls. You can see the changes on the screen as you press the up or down arrows. This is handy when there's a lot of clutter in the water, and you are matching the sensitivity to rapidly changing water conditions.

## Sonar Chart Mode

The default color scheme for the sonar chart is white background, but we offer other variations to suit your viewing preferences. The chart can be displayed in grayscale, reverse grayscale, blue background, nightview, iceview or bottom color tracking.

### To change the chart mode:

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.

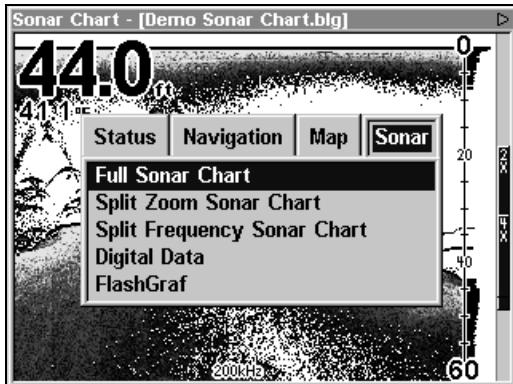
2.. Press **→** | **↓** to **SONAR CHART MODE** | **ENT**.

3. Press **↓** or **↑** to *Mode Name* | **ENT**.

4. Press **EXIT** | **EXIT** to return to the Sonar Page.

## Sonar Page & Sonar Chart Display Options

The Pages Menu offers five chart display options for units with dual-frequency transducers and four options for units with single-frequency transducers. To access them, press **PAGES** | **←** or **→** to **SONAR** | **↓** to *Option Name* | **ENT**.



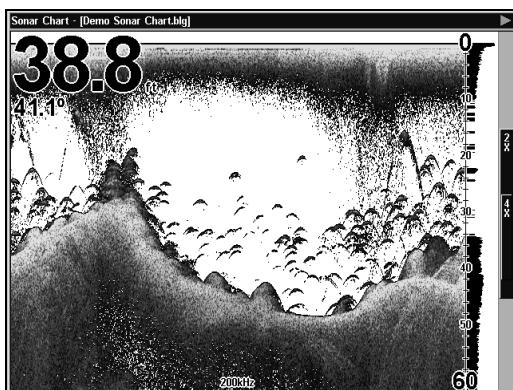
Pages Menu, showing sonar chart display options.

### Full Sonar Chart

This is the default mode used when the unit is turned on for the first time or when it's reset to the factory defaults.

The bottom signal scrolls across the screen from right to left. Depth scales on the right side of the screen aid in determining the depth of targets. The line at the top of the screen represents the surface. The bottom depth and surface temperature (if equipped with a temperature sensor or a transducer with a temp sensor built in) show at the top left corner of the screen.

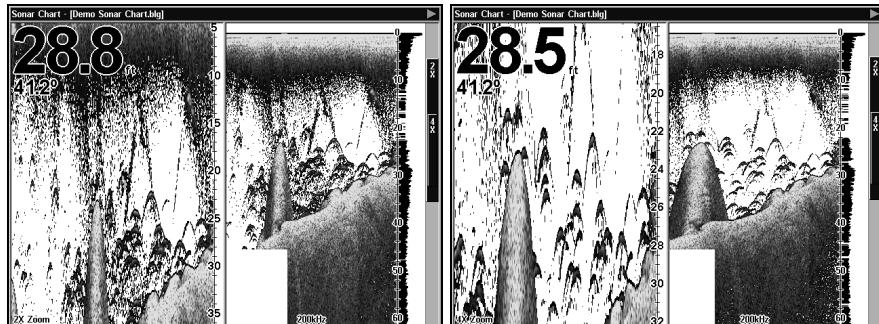
The FasTrack™ display shows just to the right of the scale. This changes all echoes into short horizontal bars, replicating a flasher sonar. The zoom bar on the far right shows the area that's zoomed when the zoom is in use. (See the Zoom section on page 89 for more information.)



Full Sonar Chart. The Overlay Data (depth and water temperature) are each set to a different text size.

## Split Zoom Sonar Chart

A split chart shows the underwater world from the surface to the bottom on the right side of the screen. The left side shows an enlarged version of the right side. The zoom range shows at the bottom left corner of the screen.

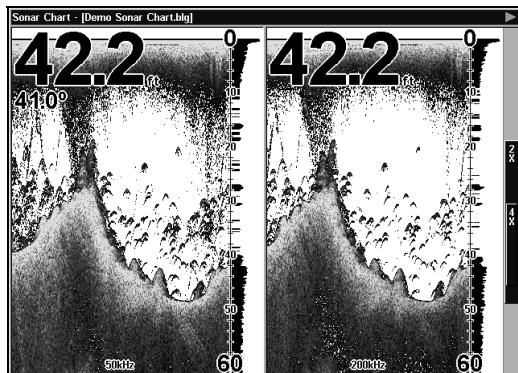


**Split Zoom Sonar Chart.** Image (left) shows the left window zoomed to 2X. The image on the right shows the left window zoomed to 4X.

## Split Frequency Sonar Chart

**(Dual-Frequency Transducers only)**

This page option shows sonar data from the 50 kHz transducer element on the left side of the screen and data from the 200 kHz transducer on the right side. All other functions and features are the same as the Full Chart page.



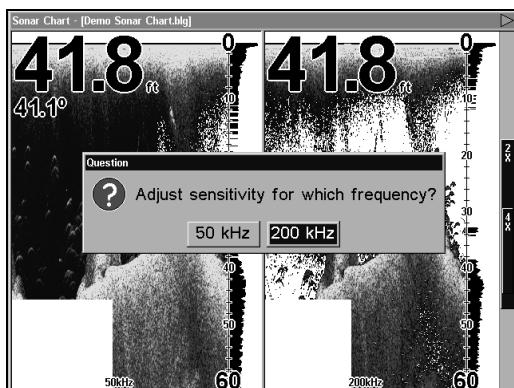
**Split Frequency Sonar Chart page, with  
50 kHz view on the left and 200 kHz view on the right.**

You can adjust the sensitivity in each window.

**To adjust sensitivity in auto mode:**

1. Press **MENU | ENT.**
2. The unit asks which you wish to adjust. Press  $\leftarrow$  or  $\rightarrow$  to select the one you want then press **ENT.**

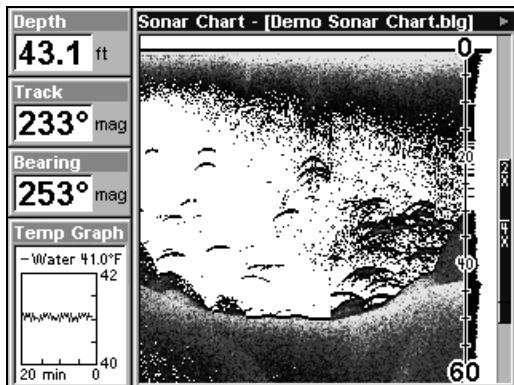
3. The Sensitivity Control Bar appears. Press ↓ to decrease sensitivity; press ↑ to increase sensitivity. When it's set at the desired level, press **EXIT**. (When you reach the maximum or minimum limit, a tone sounds.)



**The Split Frequency Sonar Chart page allows you to adjust sensitivity separately for each window.**

## Digital Data/Chart

This mode shows the chart on the right side of the screen. The left side has four digital boxes containing, Depth, Track, Bearing and a Temperature Graph.



**Digital Data/Chart**

## Customize Page Displays

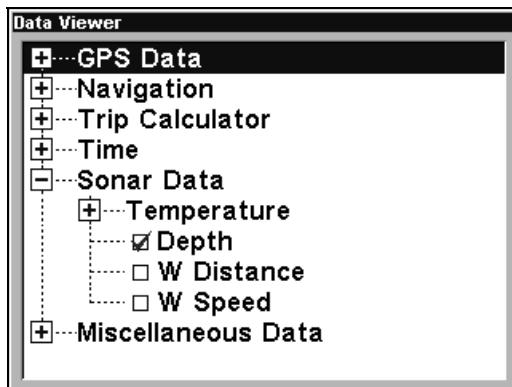
Every Page display option except Full Map (on the Map Page) has customizable Digital Data boxes to provide on-screen information.

The various data available from your unit are divided into categories in the Data Viewer menu. These categories include GPS Data, Navigation,

Trip Calculator, Time, Sonar and Miscellaneous Data You can select items from any of these categories for display in any data box. The category divisions are only there to help you sort through the information.

### To change information displayed in a data box:

On the page with the digital data box you wish to change, press **MENU** | **↓** to **CUSTOMIZE** | **ENT**. A data box name flashes, indicating it is selected. Press **ENT** to modify the box or hit **↑** or **↓** to select another box, then press **ENT**. You'll see a list of categories with "+" or "-" symbols next to each category. A category with a "+" is *expandable*, meaning its contents are hidden.



**Data Viewer with the Sonar Data category expanded.**

Selecting the category name and pressing **ENT** will show the category's contents, so you can choose items within it. An expanded category (one with a "-" next to its name) can be collapsed to hide its contents. Just select the category name and press **ENT**.

Expand any categories that might contain data you want to display. Then press **↓** or **↑** to select a different data option. With the new option highlighted, press **ENT** to switch the contents of the box to the new data type, then press **EXIT**. You can now select another box to change. When you are finished with the settings, press **EXIT** again and the box name stops flashing.

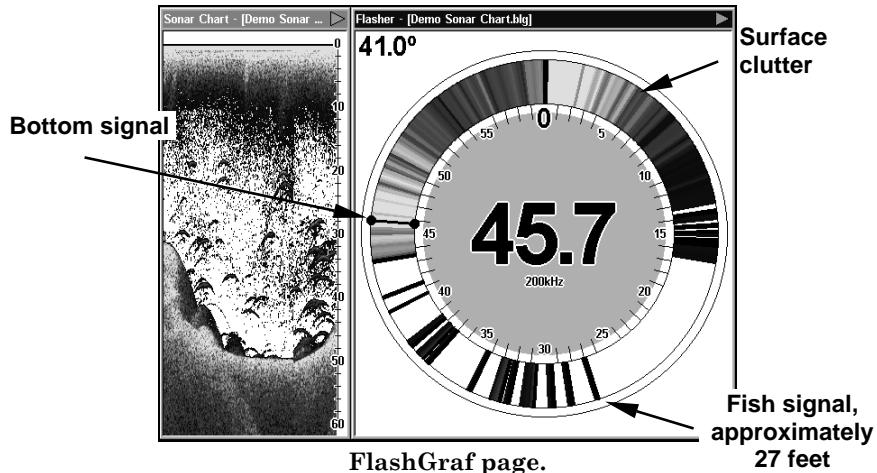
### NOTE

A Page display can only show a limited number of data boxes.

### FlashGraf™

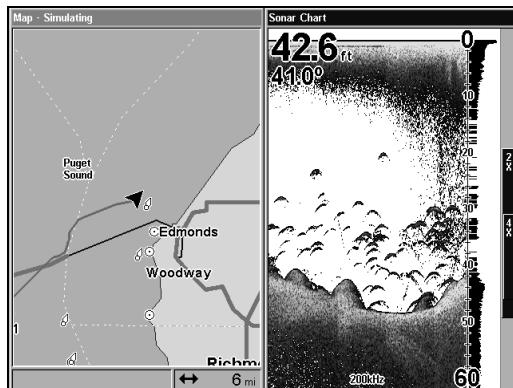
The FlashGraf sonar page option represents a flasher style sonar combined with a scrolling chart. A circular dial shows all returning echoes at a high screen refresh rate. It uses the Colorline feature to

show weaker targets as lighter colors. The bottom depth is shown as a black bar across the outer circle. You can adjust the size of the chart and the flasher windows by using the Resize Window command, which is described on page 105.



### Map With Sonar Split Screen

There is a page mode that splits the screen in half, with the map on the left and the sonar on the right. This screen option can be found on the Pages Menu under the Map Page category.



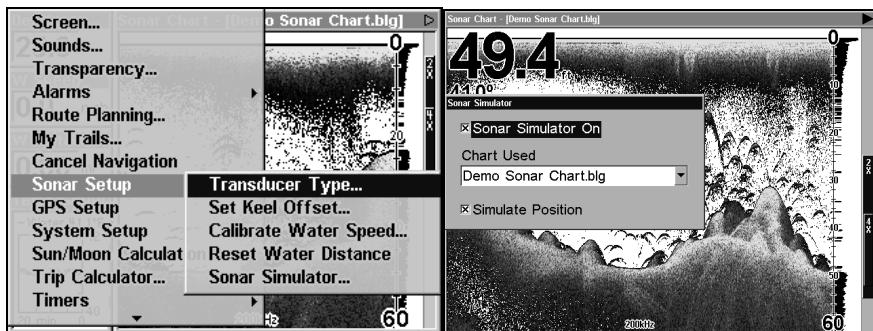
Map with Sonar split screen.

When this screen is activated, you need to specify which side of the Menu, is active. To toggle between the two windows, press **PAGES | PAGES**. The window with the blue title bar at the top of the screen is the active window. To switch back, just press **PAGES | PAGES** again.

## Sonar Simulator

This unit has a built-in simulator that lets you run it as if you were on the water. All sonar features and functions are useable. When in simulator mode, you will see the chart file name in the Sonar Page title bar and a play symbol will flash on and off at the right end of the title bar. To use the simulator:

1. From the Sonar Page, press **MENU | MENU | ↓** to **SONAR SETUP | ENT | ↓** to **SONAR SIMULATOR ENT | ENT**.

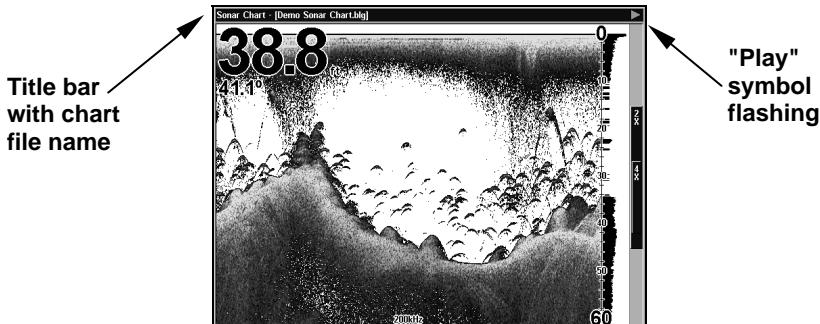


Main Menu with Sonar Setup command selected (left). Sonar Simulator menu, with simulator turned on (right).

### NOTE:

With Simulate Position checked, the simulator will also automatically run the GPS simulator (if GPS data was recorded with the sonar log).

2. To use the default sonar chart log stored in the unit, press **ENT | EXIT**. The recorded chart begins scrolling across the screen, just as if you were on the water.
3. Turn off Sonar Simulator by pressing **MENU | MENU | ↓** to **SONAR SETUP | ENT | ↓** to **SONAR SIMULATOR | ENT | ENT | EXIT**.



Sonar Page, playing a recorded sonar chart in Sonar Simulator mode.

### **Tip:**

The Sonar Simulator can use sonar charts recorded (logged) on a MMC card. (To see how, read the entry in this section on Log Sonar Chart Data.) To play back a sonar chart, make sure the MMC containing the chart is installed, then:

1. Press **MENU | MENU | ↓ to SONAR SETUP | ENT | ↓ to SONAR SIMULATOR | ENT.**
2. Press **↓ to CHART USED | ENT.**
3. Press **↓ or ↑ to select *chart name* | ENT | ↑ to SONAR SIMULATOR ON | ENT | EXIT.**

While you're in the Sonar Simulator menu, don't forget to check Simulate Position if you want to run the sonar and GPS simulators simultaneously. As you review sonar logs, you can create waypoints to mark sites you want to return to.

While the simulator is running, you can switch from one chart log to another by opening the Sonar Simulator menu and using the instructions in step 2 to select a different chart.

### **NOTE:**

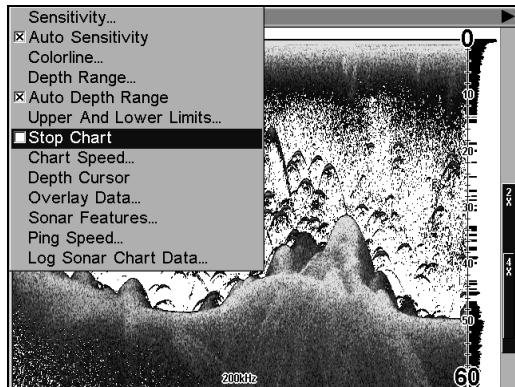
If you turn on your unit before attaching a transducer, it may enter a demo mode. The words "demo mode" flash on the bottom of the screen and a sonar chart plays much like the simulator. Unlike the simulator, the demo mode is for demonstration only, and will automatically stop as soon as you turn on the unit with a transducer attached. The simulator will continue to function normally.

## **Stop Chart**

If you are running multiple units on a boat or using this unit in a car, there are times when you may want to turn off the sonar. This command turns off the sonar and stops the chart from scrolling. Sonar restarts automatically each time you turn on your unit.

Press **MENU | ↓ to STOP CHART | ENT | EXIT.**

To turn on sonar and start the chart scrolling again, repeat the above step.



**Sonar Menu with Stop Chart command selected. The box is unchecked, indicating the chart is scrolling across the screen.**

## Surface Clarity

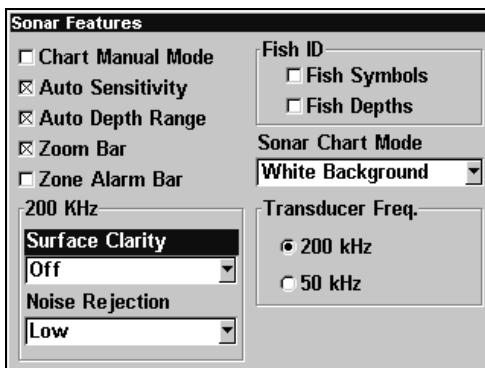
The markings extending downward from the zero line on the chart are called "surface clutter." These markings are caused by wave action, boat wakes, temperature inversion and more.

The surface clarity control reduces or eliminates surface clutter signals from the display. It does this by changing the sensitivity of the receiver, decreasing it near the surface and gradually increasing it as the depth increases.

There are three levels of surface clarity available: low, medium, or high. It can also be turned off. The default level is off.

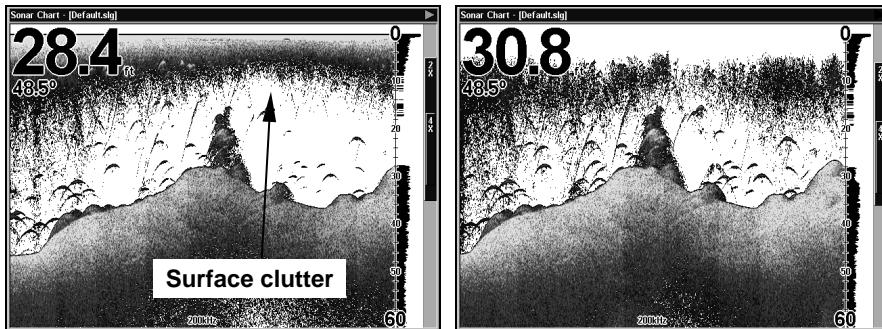
### To adjust the Surface Clarity level:

1. From the Sonar Page, press **MENU** | **↓** to **SONAR FEATURES** | **ENT**.



**Sonar Features menu with Surface Clarity selected.**

2. Press **↓** to **SURFACE CLARITY** | **ENT**.
3. Press **↓** or **↑** to select *clarity level* | **EXIT** | **EXIT** | **EXIT**.

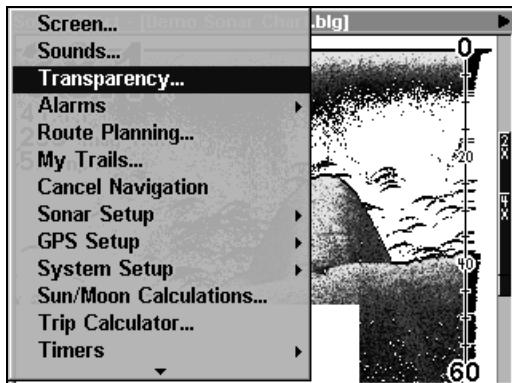


In the illustration on the left, Surface Clarity is turned off.  
The view on the right shows Surface Clarity set on high.

## Transparency

Use the transparency menu to adjust the transparency of menu windows. A high transparency allows you to continue monitoring the screen's display while adjusting feature settings, though the text of the menus may fade until it is unreadable. A low transparency will usually make menu text easier to read, at the cost of watching your display.

Experiment with this feature until you find the right level of transparency for your eyes.



Main Menu with Transparency command selected.

### To adjust Menu Transparency level:

Press **MENU |MENU|↓ to TRANSPARENCY |ENT**. The TRANSPARENCY slider bar appears. Press **↑** or **↓** to move the bar. The lower end of the scale makes the menus opaque; the upper end is maximum transparency.

### Upper and Lower Limits

See the entry in this section for Depth Range - Upper and Lower Limits

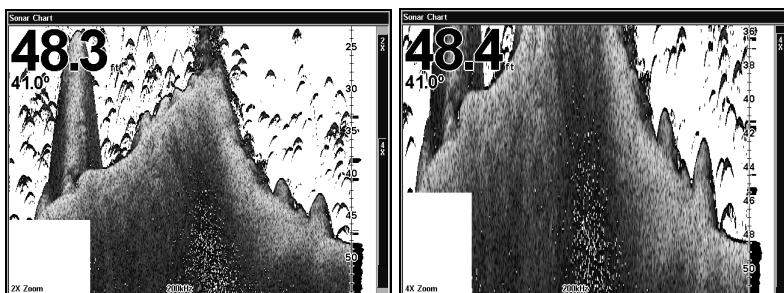
## Zoom & Zoom Bar

"Zooming in" is a common, fast and easy method used to enlarge small detail, fish signals and the bottom with its associated structure. This unit lets you zoom in quickly and easily by pressing the Zoom In key, **ZIN**.

Pressing **ZIN** once doubles the size (2X) of all echoes on the screen. Pressing it again quadruples the size of the echoes (4X). The zoom bar on the far right side of the screen shows which echoes will be displayed on the screen when the **ZIN** key is pressed.

For example, pressing the **ZIN** key once will enable a 2X zoom that will show all echoes that are between the top and bottom of the 2X zoom bar. Pressing the key again will give a 4X zoom and only the echoes between the top and bottom of the 4X bar will show on the screen.

Press the Zoom Out key, **ZOUT**, to return the display to the normal mode.



Sonar page zoomed 2X (left). The same view zoomed 4X (right).

## Zoom Pan

Your unit has the handy ability to quickly zoom in on any portion of the water column with just the touch of an arrow key. The Zoom Pan feature lets you rapidly move the zoomed area up and down to different depths. By "pointing" your zoom at different portions of the chart as it scrolls, you can get a good, close-up look at structure or cover below you.

To use Zoom Pan, switch to a manual depth range setting (see page 65) and turn on 2X or 4X Zoom. Then, simply press **↑** or **↓** to pan up and down the water column.

# Notes

## Section 5: Sonar Troubleshooting

If your unit is not working, or if you need technical help, please use the following troubleshooting section before contacting the factory customer service department. It may save you the trouble of returning your unit for repair. For contact information, refer to the last page, just inside the back cover of this manual.

### **Unit won't turn on:**

1. Check the power cable's connection at the unit. Also check the wiring.
2. Make certain the power cable is wired properly. The red wire connects to the positive battery terminal, black to negative or ground.
3. Check the fuse.
4. Measure the battery voltage at the unit's power connector. It should be at least 11 volts. If it isn't, the wiring to the unit is defective, the battery terminals or wiring on the terminals are corroded, or the battery needs charging.

### **Unit operates only in demo mode:**

The transducer or antenna module have not yet been connected or have been disconnected. To leave demo mode, make sure that either the transducer or the antenna is securely connected before turning the unit on.

### **Unit freezes, locks up, or operates erratically:**

1. Electrical noise from the boat's motor, trolling motor, or an accessory may be interfering with the sonar unit. Rerouting the power and transducer cables away from other electrical wiring on the boat may help. Route the sonar unit's power cable directly to the battery instead of through a fuse block or ignition switch
2. Inspect the transducer cable for breaks, cuts, or pinched wires.
3. Check both the transducer and power connectors. Make certain both are securely plugged in to the unit.

### **Weak bottom echo, digital readings erratic, or no fish signals:**

1. Make certain the transducer is pointing straight down. Clean the face of the transducer. Oil, dirt and fuel can cause a film to form on the transducer, reducing its effectiveness. If the transducer is mounted inside the hull, be sure it is shooting through only one layer of fiberglass and that it is securely bonded to the hull. Do NOT use RTV silicone rubber adhesive or Marine-Tex™ epoxy.
2. Electrical noise from the boat's motor can interfere with the sonar.

This causes the sonar to automatically increase its Discrimination or noise rejection feature. This can cause the unit to eliminate weaker signals such as fish or even structure from the display.

3. The water may be deeper than the sonar's ability to find the bottom. If the sonar can't find the bottom signal while it's in the automatic mode, the digital sonar display will flash continuously. It may change the range to limits far greater than the water you are in. If this happens, place the unit in the manual mode, then change the range to a realistic one, (for example, 0-100 feet) and increase the sensitivity. As you move into shallower water, a bottom signal should appear.

4. Check the battery voltage. If the voltage drops, the unit's transmitter power also drops, reducing its ability to find the bottom or targets.

### **Bottom echo disappears at high speeds or erratic digital reading or weak bottom echo while boat is moving**

1. The transducer may be in turbulent water. It must be mounted in a smooth flow of water in order for the sonar to work at all boat speeds. Air bubbles in the water disrupt the sonar signals, interfering with its ability to find the bottom or other targets. The technical term for this is cavitation.

2. Electrical noise from the boat's motor can interfere with the sonar. This causes the sonar to automatically increase its Discrimination or noise rejection feature. This can cause the unit to eliminate weaker signals such as fish or even structure from the display. Try using resistor spark plugs or routing the sonar unit's power and transducer cables away from other electrical wiring on the boat.

### **No fish arches when the Fish I.D. feature is off:**

1. Make certain the transducer is pointing straight down. This is the most common problem if a partial arch is displayed.

2. The sensitivity may not be high enough. In order for the unit to display a fish arch, it has to be able to receive the fish's echo from the time it enters the cone until it leaves. If the sensitivity is not high enough, the unit shows the fish only when it is in the center of the cone.

3. Use the Zoom feature. It is much easier to display fish arches when zoomed in on a small range of water than a large one. For example, you will have much better luck seeing fish arches with a 30 to 60 foot range than a 0 to 60 foot range. This enlarges the targets, allowing the display to show much more detail.

4. The boat must be moving at a slow trolling speed to see fish arches. If the boat is motionless, fish stay in the cone, showing on the screen as straight horizontal lines.

## NOISE

A major cause of sonar problems is electrical noise. This usually appears on the sonar's display as random patterns of dots or lines. In severe cases, it can completely cover the screen with black dots, or cause the unit to operate erratically, or not at all.

To eliminate or minimize the effects of electrical noise, first try to determine the cause. With the boat at rest in the water, the first thing you should do is turn all electrical equipment on the boat off. Make sure the engine is also off. Turn your sonar on, then turn off Noise Reject [also known as the ASP feature (Advanced Signal Processing)]. Sensitivity should be set at 90-95 percent. There should be a steady bottom signal on the display. Now turn on each piece of electrical equipment on the boat and view the effect on the sonar's display. For example, turn on the bilge pump and view the sonar display for noise. If no noise is present, turn the pump off, then turn on the VHF radio and transmit. Keep doing this until all electrical equipment has been turned on, their effect on the sonar display noted, then turned off.

If you find noise interference from an electrical instrument, trolling motor, pump, or radio, try to isolate the problem. You can usually reroute the sonar unit's power cable and transducer cable away from the wiring that is causing the interference. VHF radio antenna cables radiate noise when transmitting, so be certain to keep the sonar's wires away from it. You may need to route the sonar unit's power cable directly to the battery to isolate it from other wiring on the boat.

If no noise displays on the sonar unit from electrical equipment, then make certain everything except the sonar unit is turned off, then start the engine. Increase the RPM with the gearshift in neutral. If noise appears on the display, the problem could be one of three things; spark plugs, alternator, or tachometer wiring. Try using resistor spark plugs, alternator filters, or routing the sonar unit's power cable away from engine wiring. Again, routing the power cable directly to the battery helps eliminate noise problems. Make certain to use the in-line fuse supplied with the unit when wiring the power cable to the battery.

When no noise appears on the sonar unit after all of the above tests, then the noise source is probably cavitation. Many novices or persons with limited experience make hasty sonar installations which function perfectly in shallow water, or when the boat is at rest. In nearly all cases, the cause of the malfunction will be the location and/or angle of the transducer. The face of the transducer must be placed in a location that has a smooth flow of water at all boat speeds. Read your transducer owner's manual for the best mounting position.

# Notes

## Section 6: Basic GPS Operations

This section addresses the unit's *most basic* GPS operations. The tutorials presented in Sec. 6 follow a chronological order. Sec. 7, *Advanced GPS Operations*, will discuss other more advanced functions and utilities. Material in Sec. 7 is arranged in alphabetical order.

Before you turn on the unit and find where you are, it's a good idea to learn about the different keys, the four Page screens and how they all work together. BUT, if you just can't wait to get outside, turn to the one-page **Quick Reference** on page 107.

### Keyboard



LCX-20C sonar/GPS unit, front view, showing sonar screen, keyboard and access door for the MMC compartment.

1. **PWR/LIGHT** (Power & Light) – The PWR key turns the unit on and off and activates the backlight.
2. **PAGES** – Pressing this and the  $\leftarrow \rightarrow$  arrow keys (4) switches the unit between the four different page screens. (Satellite Status Page,

Navigation Page, Map Page and Sonar Page.) Each page represents one of the unit's major operation modes.

**3. MENU** – Press this key to show the menus and submenus, which allow you to select a command or adjust a feature. This also accesses search functions for streets, intersections, addresses and highway exits.

**4. ARROW KEYS** – These keys are used to navigate through the menus, make menu selections, move the map cursor and sonar chart cursor and enter data.

**5. ENT/ICONS** (Enter & Icons) – This key allows you to save data, accept values or execute menu commands. It is also used to create event marker icons.

**6. EXIT** – The Exit key lets you return to the previous screen, clear data or close a menu.

**7. WPT** – (Waypoint) The Waypoint key is used to save and recall waypoints, search for waypoints and access the waypoint list. It also launches the Point-of-Interest (POI) search menus and is involved in some navigation functions.

**8. ZOUT** – (Zoom Out) – This key lets you zoom the screen out. On the Sonar Page, this key returns you to a full sonar chart display, showing the entire water column from surface to bottom. On the Map Page, this lets you see a larger geographic area on the map. Less detail is seen as you zoom out.

**9. ZIN** – (Zoom In) – This key lets you zoom the screen in. On the Sonar Page, this key enlarges fish signals and bottom detail. On the Map Page, zooming in lets you see greater detail in a smaller geographic area on the map.

## **Power/lights on and off**

To turn on the unit, press **PWR**. As the unit powers up, the Map Page is displayed first. (To switch to another page, press **PAGES** | **←** or **→** to *Page Name* | **EXIT**.)

To turn on the backlight, press **PWR** again. The unit has three backlight levels to select from. Repeatedly pressing **PWR** will cycle through the backlight settings and turn off the backlight.

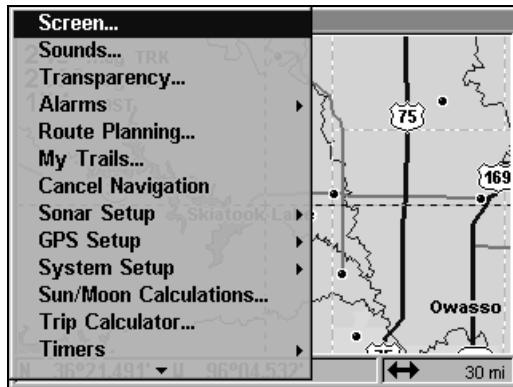
Turn off the unit by pressing and holding the **PWR** key for 3 seconds.

## **Main Menu**

The Unit has a Main Menu, which contains some function commands and some setup option commands. The tutorial lessons in this section

will deal only with functions and basic commands that make the Unit do something. The unit will work fine for these lessons right out of the box with the factory default settings. But, if you want to learn about the various options, see Sec. 8, *System Setup and GPS Setup Options*.

You can access the Main Menu from any of the four Page screens by pressing **MENU | MENU**. To clear the menu screen and return to the page display, press **EXIT**.



Main Menu.

The Main Menu commands and their functions are:

**Screen** command: changes the contrast or brightness of the display screen.

**Sounds** command: enables or disables the sounds for key strokes and alarms and sets the alarm style.

**Transparency** command: adjusts the level of transparency for menus.

**Alarms** command: turns GPS or sonar alarms on or off and changes alarm thresholds.

**Route Planning** command: used to plan, view or navigate a route.

**My Trails** command: shows, hides, creates and deletes plot trails. Also used to navigate or backtrack a trail.

**Cancel Navigation** command: turns off the various navigation commands. Used to stop navigating after you have reached your destination waypoint, Point of Interest or map cursor location; or after you reach the end of a route or trail.

**Sonar Setup** command: sets various sonar options.

**GPS Setup** command: sets various GPS receiver options.

**System Setup** command: sets general configuration options.

**Sun/Moon Calculations** command: finds the rising and setting time of the sun and the moon.

**Trip Calculator** command: shows trip status and statistics.

**Timers** command: controls the up timer, down timer and alarm clock settings.

**Browse MMC Files** command: this allows you to view the installed MMC card and the files it contains.

## Pages

The unit has four Page displays that represent the four major operating modes. They are the Satellite Status Page, the Navigation Page, Map Page and the Sonar Page. They are accessed by pressing the **PAGES** key, then using → or ← to select a Page. (Clear the menu by pressing **EXIT**.)



Pages Menu, showing some Map display options.

## Sonar Page

The Sonar Page displays the sonar chart, a view of the water column from the surface to the bottom. The chart scrolls across the screen from right to left, displaying signal echoes that represent fish, structure and the bottom. The Sonar Page is discussed in detail in Sec. 3. To get to the Sonar Page: Press the **PAGES** key, then use → or ← to select **SONAR**. (Clear the Pages Menu by pressing **EXIT**.)

## Satellite Status Page

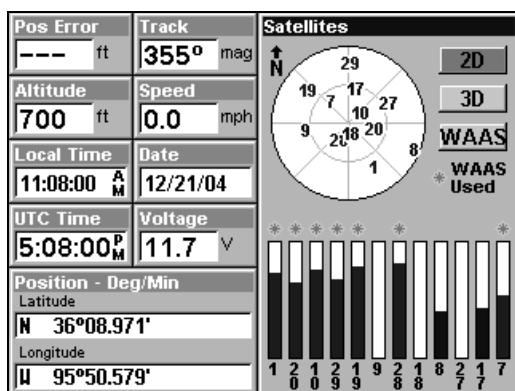
The Satellite Status Page, shown, provides detailed information on the status of the unit's satellite lock-on and position acquisition. To get to the Satellite Status Page: Press the **PAGES** key, then use → or ← to select **STATUS**. (Clear the Pages Menu by pressing **EXIT**.)

No matter what Page you are on, a flashing current position indicator/question mark symbol and flashing GPS data displays

indicate that satellite lock has been lost and there is no position confirmed. The Satellite Status Page shows you the quality and accuracy of the current satellite lock-on and position calculation.

## WARNING:

**Do not begin navigating with this unit until the numbers have stopped flashing!**



The Satellite Status Page.

This screen shows a graphical illustration of the satellites that are in view. Each satellite is shown on the circular chart relative to your position. The point in the center of the chart is directly overhead. The small inner ring represents 45° above the horizon and the large ring represents the horizon. North is at the top of the screen. You can use this to see which satellites are obstructed by obstacles in your immediate area if the unit is facing north.

The GPS receiver is tracking satellites that are in light blue. The receiver hasn't locked onto a satellite if the number is dark blue, therefore it isn't being used to solve the position.

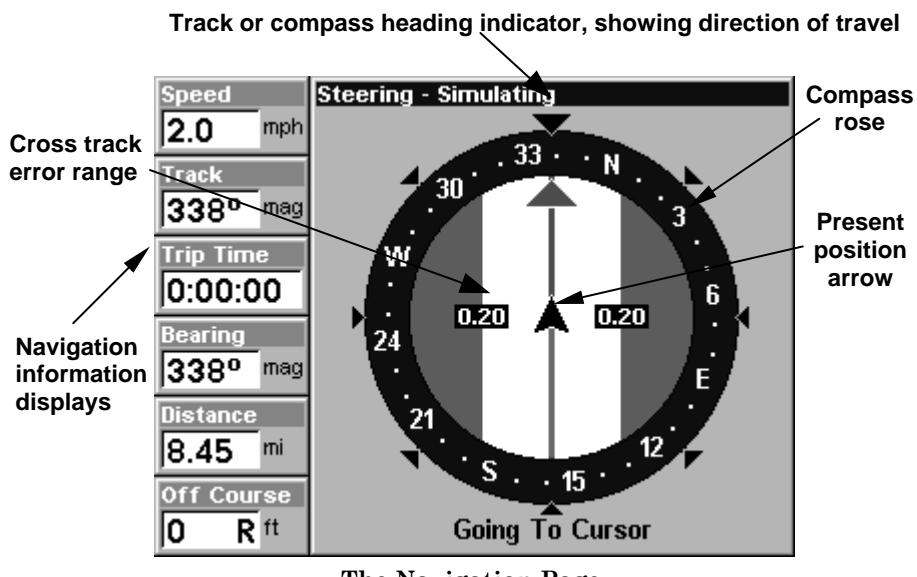
Beneath the circular graph are the bar graphs, one for each satellite in view. Since the unit has twelve channels, it can dedicate one channel per visible satellite. The taller the bar on the graph, the better the unit is receiving the signals from the satellite.

The "Estimated Position Error" (horizontal position error) shown in the upper left corner of the screen is the expected error from a benchmark location. In other words, if the EPE shows 50 feet, then the position shown by the unit is estimated to be within 50 feet of the actual location. This also gives you an indicator of the fix quality the unit currently has. The smaller the position error number, the better (and more accurate) the fix is. If the position error flashes dashes, then the unit hasn't locked onto the satellites, and the number shown isn't valid.

The Satellite Status Page has its own menu, which is used for setting various options. (Options and setup are discussed in Sec. 8.) To access the Satellite Status Page Menu, from the Status Page, press **MENU**

## Navigation Page

This screen has a compass rose that not only shows your direction of travel, but also the direction to a recalled waypoint. It also has a Navigation with Sonar option that will display two windows, one with a sonar chart, the other with the compass rose. To get to the Navigation Page: Press **PAGES** | → or ← to **NAVIGATION** | **EXIT**.



The Navigation Page.

### NOTE:

Remember, when information displays are flashing, satellite lock has not been achieved and no position fix has been determined. A question mark will also flash on the present position arrow in the center of the compass rose.

Speed (ground speed) is the velocity you are making over the ground. (If you wish, you can customize the Speed window to display Closing Speed instead. Closing Speed is also known as velocity made good. It's the speed that you're making toward the waypoint. For instructions, see the Customize Page Displays entry in Sec. 8.)

Track is the heading, or the current direction you are actually traveling. Bearing is the direction of a line-of-sight from your present

position to the destination. No matter what direction you are steering, the Bearing window shows the compass direction straight to the destination from your location at the moment. Distance shows how far it is to the waypoint you're navigating toward.

The Off Course window shows the current cross track error. This shows the distance you are off-course to the side of the desired course line. The course line is an imaginary line drawn from your position when you started navigating to the destination waypoint. The course line is shown on the Navigation Page screen (and the Map Page screen) as a red line.

The cross track error range is shown on the compass rose as a wide, white, corridor enclosing the course line. The outer edges of this white corridor represent lines that show the current cross track error range. The default for the cross track error range is 0.20 miles.

For example, if the present position symbol touches the right cross track error line, then you are 0.20 miles to the right of the desired course. You need to steer left to return to the desired course. You can use the **ZIN** or **ZOUT** keys to change the cross track error range.

A circular symbol depicting your destination (waypoint) appears on the screen as you approach the waypoint, as shown on the screen in the following figure.

Trip Time is the time that it will take to reach your destination at your present closing speed. (You can also customize the time window to show Arrival Time instead. Arrival Time is the local time it will be when you arrive at the destination, based upon your present closing speed and track.)

The Navigation Page has its own menu, which is used for some advanced functions and for setting various options. (Options and setup are discussed in Sec. 8.) To access the Navigation Page Menu, from the Navigation Page, press **MENU**.

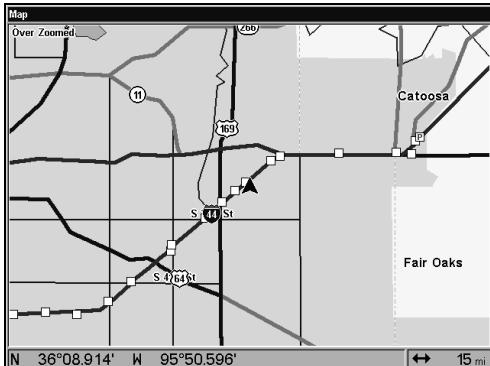
## Map Page

The Map Page screens show your course and track from a "bird's-eye" view. By default, this unit shows the map with north always at the top of the screen. (This can be changed. See the topic *Map Orientation*, in Sec. 8.) If you're navigating to a waypoint, the map also shows your starting location, present position, course line and destination. You, however, don't have to navigate to a waypoint to use the map.

Map Page is the default screen that appears when you turn on the unit. To get to the Map Page from another page: Press **PAGES** | → or ← to **MAP** | **EXIT**. When the Map Page is displayed, a screen similar to the following figure appears.

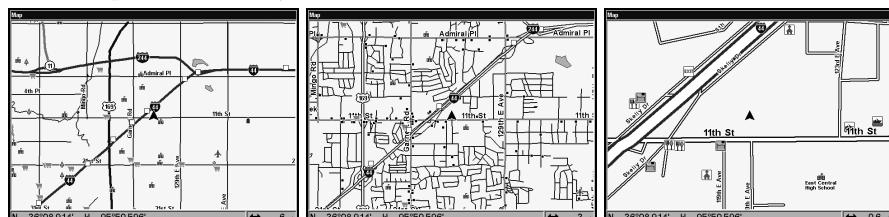
The arrow in the center of the screen is your present position. It points in the direction you're traveling. The map zoom range is the distance across the screen. This number shows in the lower right corner. In the example below, the range is 15 miles from the left edge of the map to the right edge of the map.

The Zoom In and Zoom Out keys zoom the map to enlarge or reduce its coverage area and the amount of mapping detail shown. There are 37 available map zoom ranges, from 0.05 miles to 4,000 miles.



**The map is zoomed to 15 miles. The Over Zoomed notice in the top left corner means you have reached the map's detail limits for the area. Zooming in any closer will reveal no more map details because a custom map has not been loaded on the MMC.**

If you're using only the factory-loaded background map, the maximum zoom range is 20 miles. You can continue to zoom in closer, but the map will simply be enlarged without revealing more map content (except for a few major city streets.) Load your own high-detail custom map made with MapCreate, and you can zoom in to 0.05 miles.



**Map Pages with high-detail MapCreate map. Arterial streets appear at the 6 mile zoom range, with a few Point of Interest icons visible (left). Numerous Points of Interest dots become visible at the 3 mile range, along with minor streets (center). At the 0.6 mile zoom, you can see an interstate highway with an exit, major and minor streets as well as Point of Interest icons (right).**

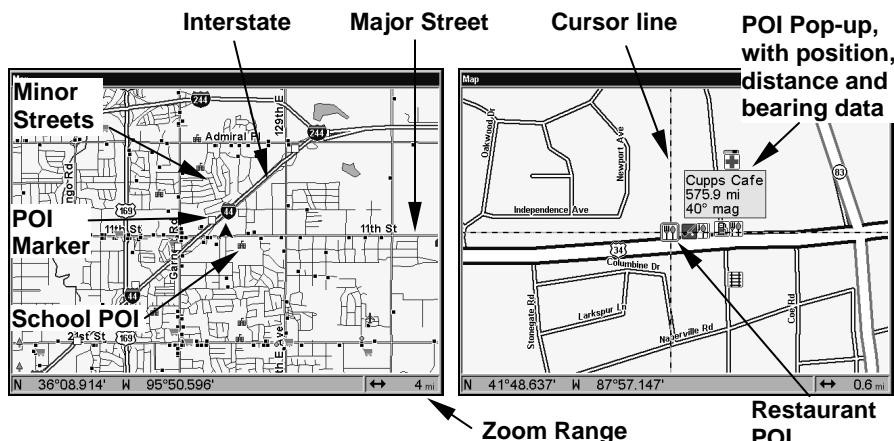
## Background map vs. MapCreate map content

The background map includes: low-detail maps of the whole world (containing cities, major lakes, major rivers, political boundaries); and medium-detail maps of the United States.

The medium-detail U.S. maps contain: all incorporated cities; shaded metropolitan areas; county boundaries; shaded public lands (such as national forests and parks); some major city streets; Interstate, U.S. and state highways; Interstate highway exits and exit services information; large- and medium-sized lakes and streams; and more than 60,000 navigation aids with 10,000 wrecks and obstructions in U.S. coastal and Great Lakes waters

MapCreate custom maps include massive amounts of information not found in the background map. MapCreate contains: Points of Interest database, all the minor roads and streets, all the landmark features (such as summits, schools, radio towers, etc.); more rivers, streams, smaller lakes and ponds and their names.

What's more important is the large scale map detail that allows your GPS unit to show a higher level of position accuracy. For example, the background map would show you the general outline and approximate shape of a coastline or water body, but the higher detail in MapCreate shows the shoreline completely and accurately. Many smaller islands would not be included in the background map, but are in MapCreate.



When the map is zoomed out far enough, most POIs appear as square dots. As you zoom in closer, the symbols become readable icons. In the 0.6 mile zoom example (right), the cursor has selected the Cupps Café POI, which triggers a pop-up box with the POI name. This pop-up box works on POIs at any zoom range.

## Tip:

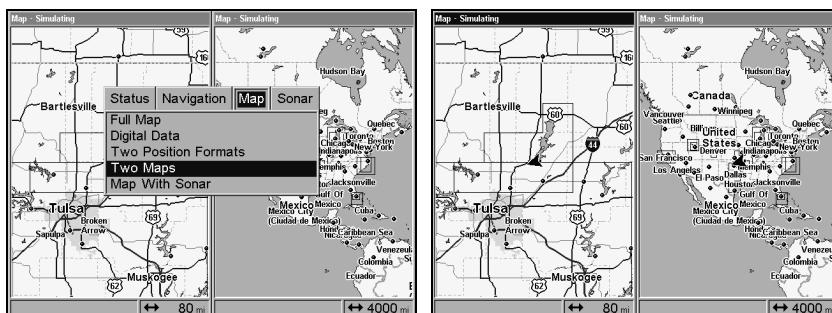
In some urban areas, businesses are so close to one another that their POI icons crowd each other on the screen. In the preceding figure, you can see a jumbled pile of POIs along Highway 34. You can reduce screen clutter and make streets and other map features easier to see by turning off the *display* of POIs you're not watching for. (To see how, check the text on Map Detail Category Selection, page 148.)

The Map Page has its own menu, which is used for several functions and for setting various options. To access the Map Page Menu, from the Map Page, press **MENU**.

The Pages Menu also offers several map display options under the Map Page category. To access them, press **PAGES** |  $\leftarrow$  or  $\rightarrow$  to **MAP** |  $\downarrow$  to **Option** | **EXIT**.



Digital Data map page (left); Two Position Formats page (right).



Pages Menu with Two Maps option selected (left).

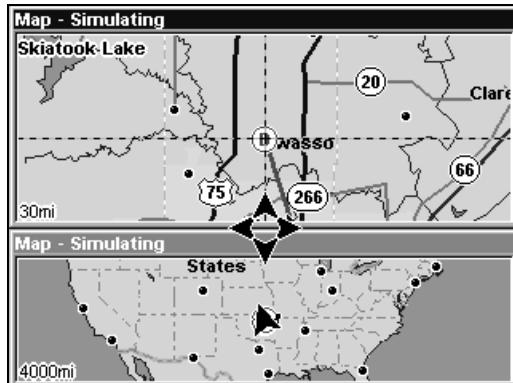
Map Page with two map windows (right). The left map is active.

In pages that have two major windows (such as two maps) you can toggle back and forth between the two windows by pressing **PAGES** | **PAGES**. This allows you to change which map the cursor, keyboard and menus

operate on. A dark blue title bar denotes the active window.

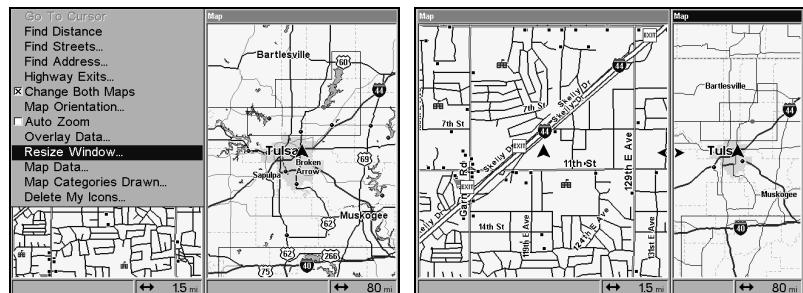
Resize Window is another handy feature for pages that have two major windows. You can change the horizontal size of the windows to suit your viewing preference. Here's how:

1. From any two-window display, press **MENU**↓ to **RESIZE WINDOW | ENT**.
2. Two flashing arrows appear along the centerline dividing the two windows. Press ← or → to adjust the window widths. Press **EXIT** to clear the menu. When you are using the Two Maps page, four flashing arrows appear, which allow you to not only resize the window from side to side, but also gives you the option of stacking the windows, one on top of the other.



**The Two Maps page with one window stacked on top of the other.**

3. To change the window size again or revert back to the original display, just follow the steps above. (Most dual-window displays use half the screen for each window by default.) You can also use the Reset Options command to revert to the factory default.



**Map Menu with Resize Window command selected (left). Pressing → moves the centerline and enlarges the left window (right).**

The following page contains a 12-step quick reference for the most basic

GPS operations. If you don't want to carry the manual with you as you practice with the Unit, you might consider photocopying this quick reference page and tucking it into your pocket.

## GPS Quick Reference

Start outdoors, with a clear view of the open sky. As you practice, try navigating to a location at least a few blocks away. While you're learning, navigation in too small an area will constantly trigger arrival alarms.

1. Connect the unit to electric power and the antenna module. Make sure the MMC is in. (See complete installation details beginning on page 13.)
2. To turn on the unit, press and release **PWR** key.
3. Opening screen displays map of North America at the 4,000-mile zoom range. Rotate through the four main Page screens (Map Page, Satellite Status Page, Navigation Page and Sonar Page) by pressing **PAGES** | ← or → to select *Page Name* | **EXIT**. Switch Pages to display Satellite Status Page.
4. Wait while unit locates satellites and calculates current position. Process is visible on Satellite Page. This takes an average of 1 minute or less under sky conditions unobstructed by terrain or structures. When the unit acquires position, a tone sounds and a position acquired message appears.
5. With position acquired, press the **PAGES** key to display the Map Page, which shows a bird's eye view of the earth. You can move around the map by:

**Zoom in** closer to see greater detail: press **ZIN** (zoom in key.)

**Zoom out** to see more area, less detail: press **ZOUT** (zoom out key.)

**Scroll** map north, south, east or west using arrow keys ↑ ↓ → ← .

To stop scrolling and return to current position on map, press **EXIT** key.

6. Set a waypoint (*Wpt 001*) at your current position so you can navigate back here: press **WPT** | **WPT**. Waypoint symbol and "001" appears.

7. Zoom/scroll map to find a nearby object or location to go to. Use arrow keys to center cursor cross-hair over the map object or location.

8. Navigate to the selected destination: press **MENU** | **ENT**. Follow the red course line on Map Page or compass bearing arrow on Navigation Page.

9. At destination, Arrival Alarm goes off; to clear it, press **EXIT**. Cancel navigation: press **MENU** | **MENU** | ↓ to **CANCEL NAVIGATION** | **ENT** | ← to **YES** | **ENT**.

10. Return to Wpt 1 by Navigate To Waypoint or Backtrack Trail. **To Waypoint**: press **WPT** | → to **SAVED** | **ENT** | **ENT** | **ENT**. Use ↑ or ↓ to select *Wpt 001*, press **ENT** | **ENT**; follow navigation displays. **Trail**: press **MENU** | **MENU** | ↓ to **MY TRAILS** | **ENT**. Press ↓ to **Trail 1** | **ENT** | → | ↓ to **NAVIGATE** | **ENT** | ↓ to **NAVIGATE** | → to **REVERSE** | **ENT** | ← to **NAVIGATE** | **ENT**. (If arrival alarm sounds, press **EXIT**.) Follow navigation displays.

11. Back home, Arrival Alarm goes off; press **EXIT**. Cancel navigation: press **MENU** | **MENU** | ↓ to **CANCEL NAVIGATION** | **ENT** | ← to **YES** | **ENT**.

12. To turn off the unit, press and hold **PWR** key for three seconds.

## Find Your Current Position

Finding your current position is as simple as turning the unit on. Under an unobstructed sky, the unit automatically searches for satellites and calculates its position in approximately one minute or less.

If for some reason satellite acquisition takes longer, you may be inside a structure or vehicle or in terrain that is blocking signal reception. To correct this, be sure you are positioned so the unit's antenna module has as clear a view of the sky as possible, then turn the unit off and back on again.

## Moving Around the Map: Zoom & Cursor Arrow Keys

The map is presented from a bird's eye view. The current zoom range shows in the lower right corner of the screen.

1. Press the **ZIN** key (zoom in) to move in closer and see greater detail in a smaller geographic area.
2. Press the **ZOUT** key (zoom out) to move farther away and see less map detail, but a larger geographic area.

When you are traveling, the map will automatically move as you move. This keeps your current location roughly centered on the screen.

You can manually pan or scroll the map northward, southward, eastward or westward by using the arrow keys, which launch the cross-hair map cursor. This allows you to look at map places other than your current position. To clear the cursor, press **EXIT**, which switches the map back to the current position or the last known position.

### **Tip:**

Use the cursor to determine the distance from your current position to any map object. Simply use the arrow keys to position the cursor over the object or landmark. The distance, measured in a straight line, appears in the pop-up box. Press **EXIT** to clear the cursor.



## Selecting Any Map Item With the Cursor

1. Use the zoom keys and the arrow keys to move around the map and find the item you wish to select.
2. Use the arrow keys and center the cursor cross-hair on the desired object. On most items, a pop-up box will give the name of the selected item.

## Searching

Now that you've seen how the unit can find where *you* are, let's search for something somewhere else. Searching is one of the most powerful features in the Lowrance GPS product line.

In this example, we'll look for the *nearest* fast-food restaurant. For more information on different types of searches, refer to *Sec. 9, Searching*.

### NOTE:

This example requires the Point of Interest (POI) database included with a high detail MapCreate 6 custom map.

After the unit has acquired a position:

1. Press **WPT** | **↓** to **POI-RESTAURANTS**.
2. You could search the entire restaurant category, but in this example we will narrow our search. Press **→** to **SUBCATEGORY** column | **↓** to **FAST FOOD CHAINS** | **ENT** | **↓** to **NEAREST** | **ENT**.
3. The unit says it is calculating, then a list of restaurants appears, with the closest at the top of the list, and the farthest at the bottom of the list. The nearest is highlighted.

Find Waypoint		
Category	Subcategory	
My Waypoints	Asian	
Airports	Banquet Rooms	
Cities	Barbecue	
Countries	Coffee Shops	
Landmarks	Delicacies	
POI-Attractions	Fast Food Chains	
POI-Emergency/Gov't	Ice Cream	
POI-Entertainment	Italian	
POI-Fishing	Mexican	
POI-Hunting	Miscellaneous	
POI-Lodging	Pizza	
POI-Marine	Sandwiches	
POI-Restaurants	Seafood	
POI-Services	Steak Houses	
POI-Shopping		
POI-Sports		

Find By Nearest		
Name	Distance	Bearing
Taco Bueno	0.18	245°
Sonic Drive-In	0.47	265°
Captain D's Seafood Restaurant	0.92	202°
McDonald's	0.93	202°
Long John Silver's	1.04	201°
Burger King	1.15	197°
KFC	1.18	200°
Arby's	1.22	148°
Church's Chicken	2.03	188°
Sonic Drive-In	2.09	159°
Arby's	2.15	190°
Whataburger	2.18	197°
Wendy's	2.34	203°
Arby's	2.44	254°
Taco Bueno	2.48	209°
McDonald's	2.51	283°

### Category Selection menu (left) and list of the nearest restaurants (right).

4. You could scroll ↑ or ↓ to select another restaurant, but for now we will just accept the nearest one. Press **ENT**.
5. The POI information screen appears. This is how you can use the unit as a business phone directory! If you wanted to navigate there, you could press **ENT**, since the **Go To WAYPOINT** command is highlighted. But we just want to see it on the map, so press ↓ to **FIND ON MAP|ENT**.

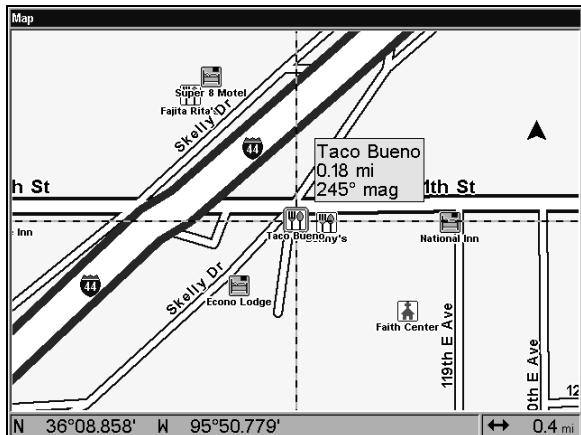
Waypoint Information	
Taco Bueno (Fast Food Chain)	<b>Go To Waypoint</b>
11710 E 11th St	
Tulsa, OK 74128	
918-438-4370	
N 36°08.859' W 95°50.779'	GPS
Distance: 0.18 mi	
Bearing: 245° mag	
POI-Restaurants	
Fast Food Chains	

Waypoint Information	
Taco Bueno (Fast Food Chain)	<b>Go To Waypoint</b>
11710 E 11th St	
Tulsa, OK 74128	
918-438-4370	
N 36°08.859' W 95°50.779'	GPS
Distance: 0.18 mi	
Bearing: 245° mag	
POI-Restaurants	
Fast Food Chains	

POI information screen on the nearest fast food restaurant, showing name, street address, phone number, latitude/longitude distance and compass bearing. The Go To command is selected (left). The figure on the right has the Find On Map command highlighted.

6. The unit's map appears, with the cross-hair cursor highlighting the restaurant's POI symbol. A pop-up name box identifies the POI, as well as its distance and bearing. A data box at the bottom of the screen continues to display the location's latitude and longitude.



### Map screen showing the result of a restaurant search.

7. To clear the search and return to the last page displayed, press **EXIT | EXIT**. (Before you completely exited out of the Search menus, you could have gone looking for another place.)

#### NOTE:

Search works from mapping and POI data loaded in the unit. If you have not loaded a MMC for the area you are searching you may not find anything.

## Set a Waypoint

A waypoint is simply an electronic "address," based on the latitude and longitude of a position on the earth. A waypoint represents a location, spot or destination that can be stored in memory, then recalled and used later for navigation purposes.

You can create a waypoint at the cursor position on the map or at your current position, while you are navigating. You can create a waypoint at any location by manually entering the position's latitude and longitude. It is also possible to copy waypoints from your unit to your personal computer with MapCreate software. When you want to repeat a trip, these archived waypoints can be reloaded into your GPS unit.

### To create and save a Waypoint

These first two techniques use the Quick Save method, the fastest and easiest way to create a waypoint.

#### Create Waypoint at Current Position

While you are traveling, press **WPT | WPT**. The waypoint is saved and automatically given a name with a sequential number, such as "waypoint 003." The waypoint symbol and number appear on the map.

Fig 1.

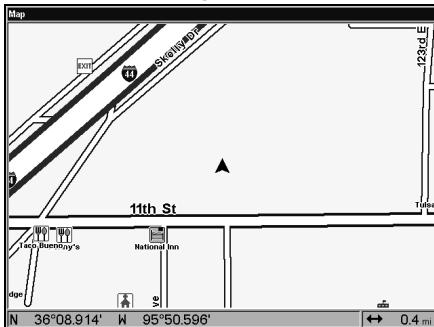


Fig 2.

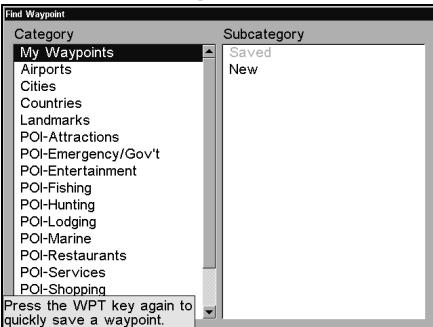


Fig 3.

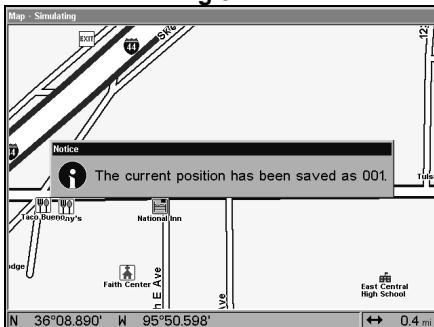
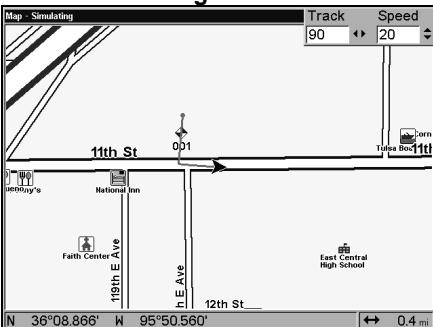


Fig 4.



Sequence for setting a waypoint. Fig. 1: while traveling, press **WPT** twice to call up the Find Waypoint screen (Fig. 2) and set a point. Fig. 3: a message says the waypoint has been saved. Fig. 4: vehicle continues on its way; the waypoint number is visible on map.

#### NOTE:

The Quick Save method uses the default waypoint symbol until you edit an existing waypoint and change its symbol. (Edit Waypoint Symbol is described in Sec. 7.) After you have changed a waypoint symbol, the unit will remember the one you chose and use it the next time you "quick save" a waypoint. To revert back to the *default* symbol, edit a waypoint and choose it, or use the Reset Options command (described in Sec. 8).

#### Create Waypoint on Map

1. Use the arrow keys to move the cursor to the place where you want to make a waypoint.
2. Press **WPT | WPT**. The waypoint is saved and automatically given a name with a sequential number, such as "waypoint 001." The waypoint symbol and number appear on the map.

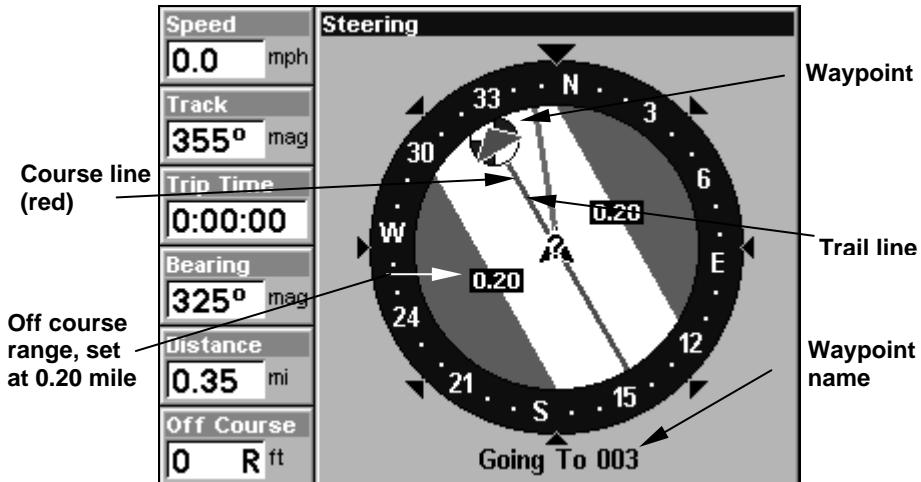
### Create Waypoint by Entering a Position

1. Press **WPT** |  $\rightarrow$  to **SUBCATEGORY** column |  $\downarrow$  to **NEW** | **ENT**.
2. Press  $\downarrow$  to **ENTERED POSITION** | **ENT** |  $\rightarrow$  to **CREATE** | **ENT**.
3. Press  $\rightarrow$  to **LATITUDE** | **ENT**. Enter the latitude by pressing  $\uparrow$  or  $\downarrow$  to change the first character, then press  $\rightarrow$  to the next character and repeat until the latitude is correct. Press **ENT**.
4. Press  $\downarrow$  to **LONGITUDE** | **ENT**. Enter the longitude by pressing  $\uparrow$  or  $\downarrow$  to change the first character, then press  $\rightarrow$  to the next character and repeat until the longitude is correct. Press **ENT**, then **EXIT** | **EXIT** to return to the previous page display. The waypoint is saved and automatically given a name with a sequential number, such as "waypoint 001." The waypoint symbol and number appear on the map and in the waypoint list.

### Navigate To a Waypoint

You can select any waypoint visible on the Map Page with the cursor, then use the Navigate to Cursor command, which will be covered later in this section. You can avoid scrolling the map to pick your waypoint if you use the Find Waypoint commands:

1. Press **WPT** |  $\rightarrow$  to **SAVED** | **ENT**. To look up the nearest waypoint, press  $\downarrow$  to **NEAREST** | **ENT**; or, to look by name and scroll through the entire waypoint list, just press **ENT**. For this example, we'll look by name.
2. If your waypoint list is a long one, you can spell out the waypoint name in the **FIND BY NAME** box. Press  $\uparrow$  or  $\downarrow$  to change the first character, then press  $\rightarrow$  to move the cursor to the next character and repeat until the name is correct, then press **ENT** to jump to the list below.
3. If the list is short, you can jump directly to the **FIND IN LIST** box by pressing **ENT**. Use  $\uparrow$  or  $\downarrow$  to select the waypoint name, press **ENT** and the waypoint information screen appears with the **Go To** command selected.
4. To begin navigating to the waypoint, press **ENT**.



Navigation Page, navigating toward waypoint 003.

## Set Man Overboard (MOB) Waypoint

One of boating's most terrifying events is having a friend or family member fall overboard. It's particularly dangerous at night or if you're out of sight of land. Of course, the first thing to do is remain calm and then use all standard safety procedures to rescue the person.

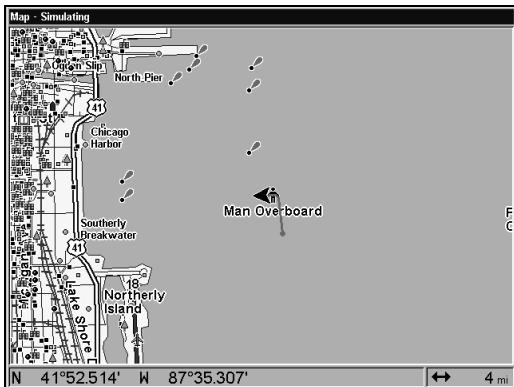
This unit has a man overboard feature that shows navigation data to the location where the feature was activated. To activate it, press the **ZOUT** and **ZIN** keys at the same time. Your position at the time these keys are pressed is used as the man overboard position.

### ***Caution:***

*Saving a new "Man Overboard" waypoint will erase the previous "Man Overboard" waypoint.*

## Navigate Back to MOB Waypoint

Find your way back to the accident position with the Navigation Page or Map Page. When MOB is activated, the Navigation Page automatically shows the compass rose with its bearing arrow pointing toward the man overboard position, and the destination name says "Going To Man Overboard." The Map Page displays a Man Overboard waypoint, represented by a human figure, and the steering arrow points where to steer to reach that position.



The cursor is redirected toward the Man Overboard position on the Map Page. The victim is astern of the vessel. The GPS shows which direction to steer to for the rescue.

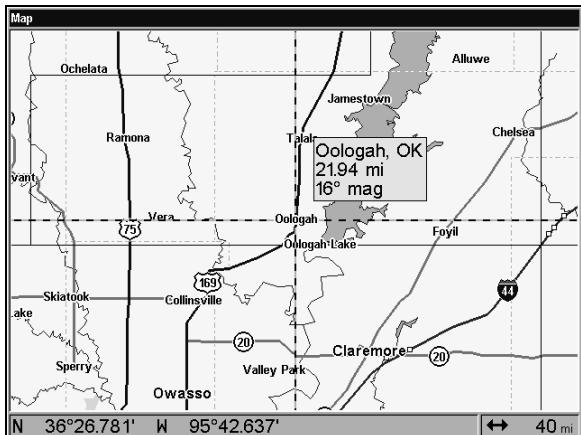
The man overboard position is also stored in the waypoint list for future reference. It can be edited the same as any other waypoint.

To cancel navigation to MOB, press **MENU | MENU | ↓** to **CANCEL NAVIGATION | ENT | ←** to **YES | ENT**. The unit stops showing navigation information.

## Navigate to Cursor Position on Map

The **Go To Cursor** command navigates to the current cursor position on the map. It's a quick and handy way to navigate to anything you can see on the map display.

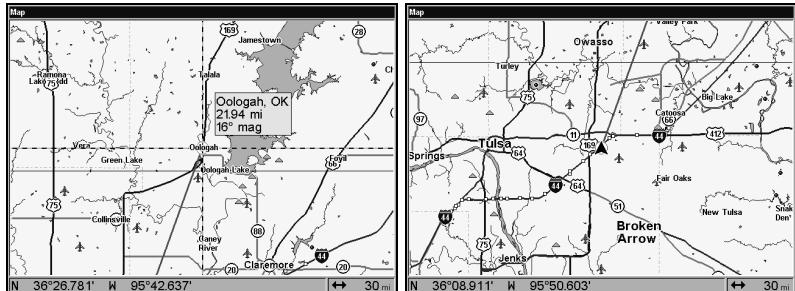
1. Use the cursor (controlled by the arrow keys) with the zoom in and zoom out keys to maneuver around the map until you find a location you want to go to.
2. Center the cursor over the location to select it. See the example in the following figure. Many map items such as waypoints, Points of Interest, towns, etc. can be "selected," and appear "highlighted" with a pop-up box. Other features, such as a river or a street intersection will not appear "highlighted," but the cursor will take you to those locations just the same.



**Navigate to cursor. In this example, the town of Oologah, Oklahoma has been selected.**

3. Press **MENU | ENT** and the unit will begin navigating to the cursor location.

The Map Page will display a red line from your current position to the cursor position. The Navigation Page displays a compass rose showing navigation information to your destination. See the following examples.



**The 30-mile zoom figure (left) clearly shows the red course line connecting your current position to your destination. The 30-mile zoom (right) shows current position and direction to destination on screen.**

To stop navigating to the cursor, use the Cancel Navigation command: press **MENU | MENU | ↓ to CANCEL NAVIGATION | ENT | ← to YES | ENT**. The unit stops showing navigation information.

## **Navigate to a Point of Interest**

POIs in view on the map can be located easily by using the Navigate to Cursor command above. Just use the cursor to select the POI.

The other method involves searching for POIs with the Find Waypoint command, launched with the **WPT** key. (See the searching example earlier in this section or turn to Sec. 9, *Searching*, for detailed instructions on POI searches.)

After you have looked up an item with the Find Waypoint command, use the → to make sure the **Go To** command is highlighted at the top of the screen, then press **ENT**. The unit begins navigating to the item.

To cancel navigation, press **MENU | MENU | ↓** to **CANCEL NAVIGATION | ENT | ←** to **YES | ENT**. The unit stops showing navigation information.

## **Creating and Saving a Trail**

A trail, or plot trail, is a string of position points plotted by the unit as you travel. It's a travel history, a record of the path you have taken. Trails are useful for repeating a journey along the same track. They are particularly handy when you are trying to retrace your trip and go back the way you came. On the screen, trails are represented by a magenta line extending from the back of the current position arrow.

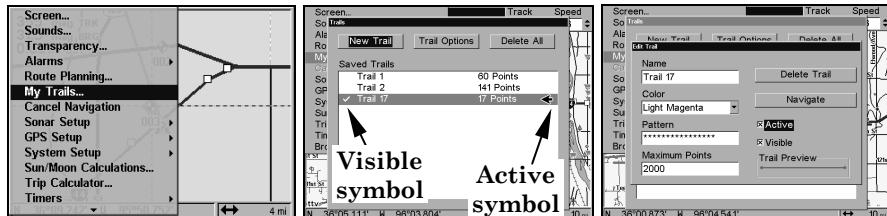
The unit is set at the factory to automatically create and record a trail while it is turned on. The unit will continue recording the trail until the length reaches the maximum trail point setting. Default is 2,000, but it can record trails up to 9,999 points long. When the point limit is reached, the unit begins recording the trail over itself.

By default, the trail flashes once a second, making it easier to see against the background map. With the default auto setting, the unit creates a trail by placing a dot (trail point) on the screen every time you change directions. The methods used for creating a trail and the trail update rate can be adjusted or even turned off. See Sec. 8 for *Trail Options*.

To preserve a trail from point A to point B, you must "turn off" the trail by making it *inactive* before heading to point C or even back to point A. When the current trail is set inactive, the unit *automatically* creates and begins recording a new trail.

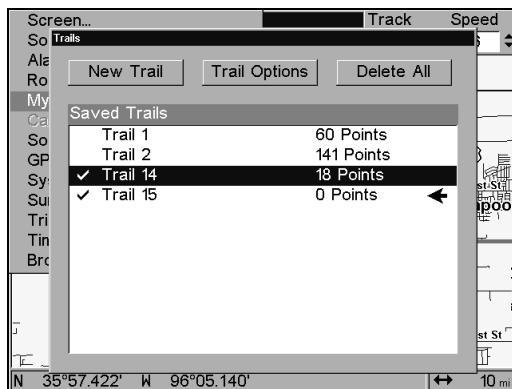
### **To Save a Trail**

1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT**.



Sequence for saving a trail and beginning a new one. My Trails... command (left). The Trails Menu (center). The arrow to the right of Trail 17 indicates the trail is "active," and the check to the left indicates the trail is visible on the map display. The third figure (right) shows the Edit Trail menu, with the Active command selected.

2. Press  $\downarrow$  to the active Trail Name | ENT.
3. Press  $\rightarrow$ , then  $\downarrow$  to ACTIVE | ENT. This unchecks the Active option.
4. To return to the previous page, press EXIT | EXIT | EXIT | EXIT. As you left the Edit Trail menu, you will notice a new trail was started with a new sequential number. In the example below, the new trail is number 15, showing zero points. Note Trail 14 is inactive, but is still visible on the map.



A new trail, "Trail 15," is created when Trail 14 is made inactive. Any new travel will be recorded in this trail, which is active and visible.

Trails do not need to be visible in order to be active.

You can save and recall up to 10 different plot trails, which can be copied to your MMC for archiving or for transfer to your MapCreate software.

### **Tip:**

Another quick way to stop recording one trail and begin a new one is to use the New Trail command: Press **MENU | MENU | ↓** to **MY TRAILS | ENT | ENT**.

### **Caution:**

*You also have the option of completely turning off trail recording, under the trail Options command. However, if the Update Active Trail option is left off, it will cancel the automatic trail creation feature.*

## **Displaying a Saved Trail**

The active trail is automatically displayed on the map (the "Visible" option) with the factory default settings. You can selectively turn the trail display off and on for any saved or active trail. In the Saved Trails List, visible trails have a check mark in front of the trail name.

### **To turn off trail display:**

1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT**.
2. Press **↓ | ↓** to enter the Saved Trail list, then use **↑** or **↓** to select the desired **Trail Name | ENT**.
3. Press **↓ →** to **VISIBLE | ENT**. To return to the previous page, press **EXIT | EXIT | EXIT | EXIT**.

### **To turn on trail display:**

1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT**.
2. Press **↓ | ↓** to enter the Saved Trail list, then use **↑** or **↓** to select the desired **Trail Name | ENT**.
3. Press **↓ →** to **VISIBLE | ENT**. To return to the previous page, press **EXIT | EXIT | EXIT | EXIT**.

## **Navigating Trails**

There are three methods for following a trail: visual trailing, navigating a trail (forward) and backtracking a trail (backward). Try each method to see which you prefer.

Visual trailing is the simplest method. It uses only the Map Page and requires no menu commands at all. The technique works the same if you are running a trail forward (from start to end) or backward (from end to start.) Visual trailing, however, provides no navigation information during the trip, such as the time to your destination.

The other two methods provide a full range of navigation data and work with both the Map Page and Navigation Page. The only difference between them is "navigating a trail" follows a trail forward (from start to end) while "backtracking" follows a trail in reverse (from end to start.)

When hiking at walking speed with a hand-held GPS, we often use visual back trailing because it is a bit better at following each little turn on a footpath. At faster speeds, such as the highway or on the water, the Navigate Trail and Backtrack Trail commands are handy.

### **Visual Trailing**

1. On the Map Page, zoom (**ZIN** or **ZOUT**) so your flashing trail is visible.
2. Begin moving and watch the Map Page. Simply walk or steer so your current position arrow traces along the trail you have just made.

#### ***Tip:***

Generally, when using this method, the smaller the zoom range, the more accurately you will be able to steer along the trail.

### **Navigate a Trail (forward)**

The following figures illustrate the menu sequence for navigating a trail.

1. Press **MENU** | **MENU** | **↓** to **MY TRAILS** | **ENT**.
2. Press **↓** | **↓** to enter the Saved Trail list, then use **↑** or **↓** to select the desired *Trail Name* | **ENT**.
3. Press **→** to **DELETE TRAIL** | **↓** to **NAVIGATE** | **ENT**.
4. Press **↓** to **NAVIGATE** | **ENT**. The unit begins showing navigation information along the trail.

#### **NOTE:**

If you are already located at or near the beginning of your trail, the arrival alarm will go off as soon as you hit Enter. Just press **EXIT** to clear the alarm and proceed.

5. Now, begin moving and follow your unit.
6. When you reach your destination, be sure to cancel your navigation: press **MENU** | **MENU** | **↓** to **CANCEL NAVIGATION** | **ENT**. The unit asks if you're sure, press **←** | **ENT**.

Figure 1.

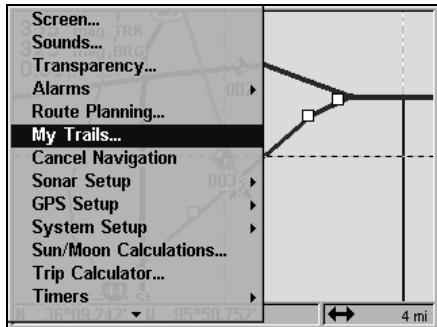


Figure 2.

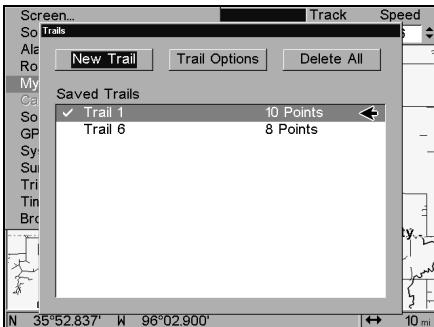


Figure 3.

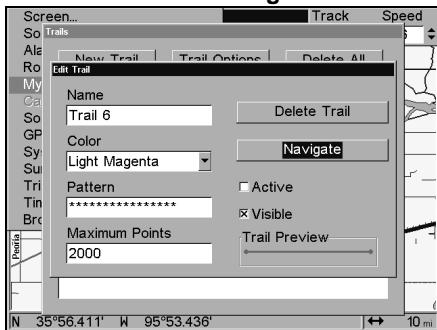
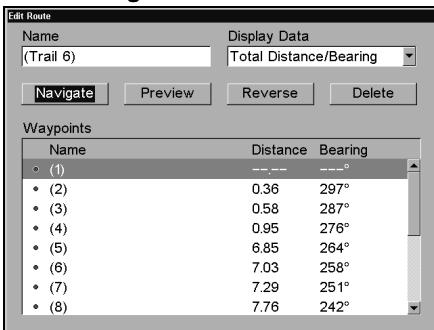


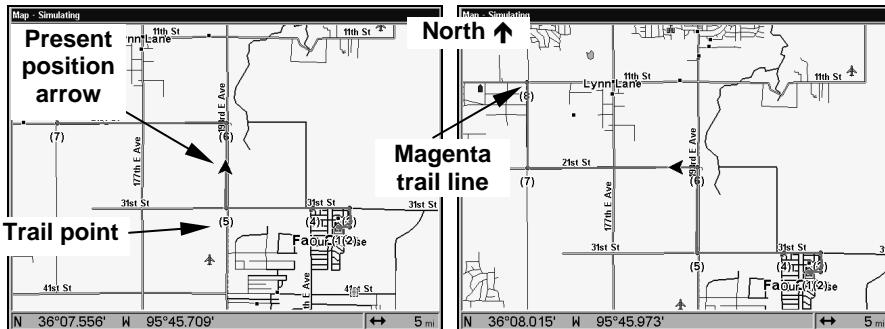
Figure 4.



**Navigate a trail menu sequence:** Fig. 1, My Trails command. Fig. 2, Trails Menu. Fig. 3, Edit Trail Menu. Fig. 4, Edit Route Menu with **Navigate** command highlighted for Trail 6. A trail is always converted to a "route" when you navigate the trail.

On the Map Page, the trail you are navigating is represented by a magenta line. The bearing arrow on the compass rose points to the next waypoint on the trail.

As you travel, the arrival alarm will go off when you near a trail waypoint, and the bearing arrow on the compass rose will swing around and point to the next trail waypoint. Press **EXIT** to clear the alarm.



**Navigate trail, map views:** the driver (left) is northbound heading straight toward trail point 6. The northbound driver (right) has reached point 6 and has turned west to follow trail.

1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT.**
2. Press **↓ | ↓** to enter the Saved Trail list, then use **↑** or **↓** to select the desired **Trail Name | ENT.**
3. Press **→** to **DELETE TRAIL | ↓** to **NAVIGATE | ENT.**
4. Press **↓** to **NAVIGATE | →** to **REVERSE | ENT | ←** to **NAVIGATE | ENT.** The unit begins showing reverse navigation information along the trail.

#### **NOTE:**

If you are already located at or near the end of your trail, the arrival alarm will go off as soon as you hit Enter. Just press **EXIT** to clear the alarm and proceed.

5. Now, begin moving and follow your unit.
6. When you reach your destination, be sure to cancel your navigation. Press **MENU | MENU | ↓** to **CANCEL NAVIGATION | ENT.** The unit asks if you're sure, press **← | ENT.**

## **Transfer Custom Maps and GPS Data Files**

### **Custom Maps:**

Custom maps work only from the MMC card or SDC card. When a card containing a Custom Map File is loaded into the unit, it automatically loads the map into memory when the unit is turned on.

Instructions for copying Custom Map Files to an MMC are contained in the instruction manual for your MMC card reader and MapCreate 6 software. For instructions on inserting a MMC into the Unit, see Sec. 2, *Installation/Accessories*.

## NOTE:

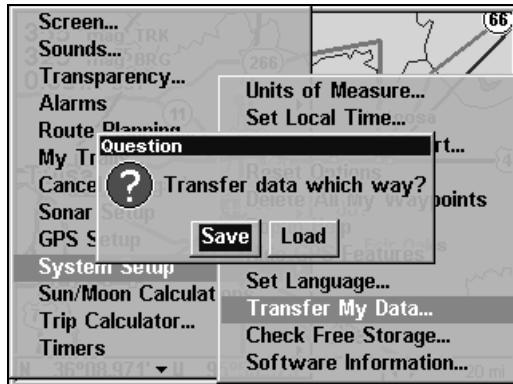
To load a Navionics® chart, see Sec. 8 for the entry *Navionics Charts*.

### GPS Data files:

GPS Data Files contain waypoints, routes, trails and event marker icons. Instructions for copying GPS Data Files between your computer and a MMC are contained in the instruction manual for your MMC card reader and MapCreate 6 software.

GPS data automatically recorded in the unit's internal memory must be saved to the MMC as a GPS Data File in order to store it on your personal computer. GPS Data Files stored on an MMC must be copied from the card to the unit's internal memory before the unit can read them. Here's how:

1. Insert the MMC into your unit. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ↓** to **TRANSFER MY DATA | ENT** and the screen below appears.



The Transfer My Data submenu asks if you want to save data to the MMC or load data from the MMC into the unit's memory.

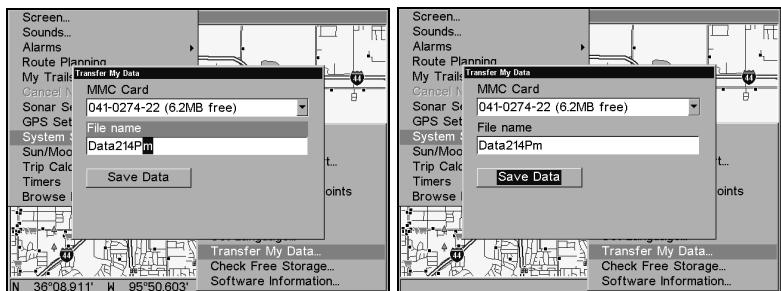
2. The Transfer My Data menu includes a message which tells you if an MMC is present or not. If no MMC is present, you must first insert a card into the unit to activate the Load or Save commands.

To transfer data **from the unit to the MMC**: press **ENT** (for **SAVE**.)

To transfer data **from the MMC to the unit**: press **→** to **LOAD | ENT**.

3. **Saving to MMC:** To accept the default name "Data" for the GPS Data File, press **↓** to **SAVE DATA | ENT**. If you wish to rename the file (as shown in the following figures), press **ENT** to activate the selection box. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the name is correct. Then, press **ENT | ↓** to **SAVE DATA | ENT**.

The unit will display a completion message when the data transfer is finished. To return to the Page view, repeatedly press **EXIT**.



From left to right, these figures show the sequence for naming and saving a GPS Data File from the unit's memory to an MMC.

**4. Loading to unit memory:** There may be more than one GPS Data File (\*.USR) on the card. To select a file, press **ENT** to activate the selection box, use **↓** or **↑** to highlight the file, then press **ENT** to accept the selection. Next, press **↓** to **LOAD|ENT**. The unit will display a completion message when the data transfer is finished. To return to the Page view, press **EXIT|EXIT|EXIT|EXIT**.

Figure 1.

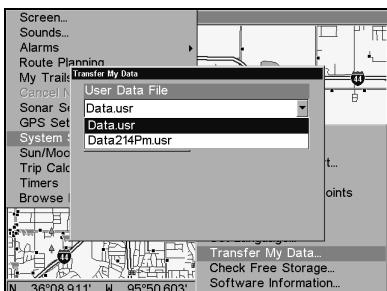
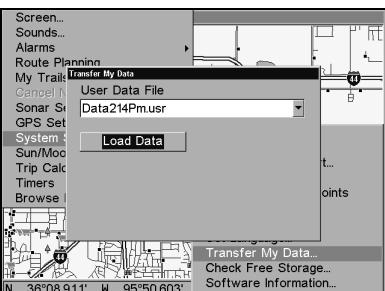


Figure 2.



These figures show the menu sequence for loading a GPS Data File from an MMC into the unit's memory.

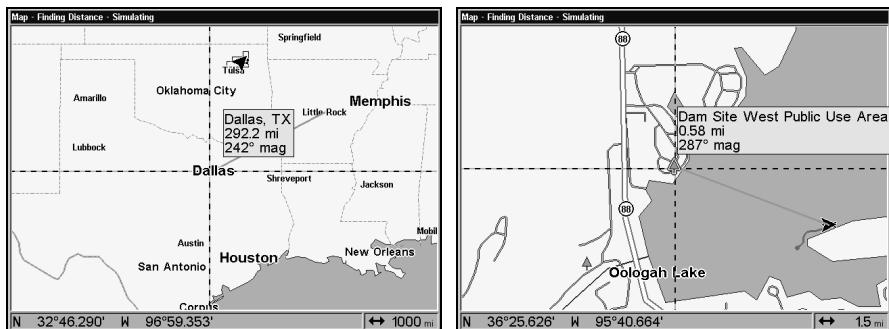
## Cancel Navigation

You can turn off any of the navigation commands after you reach your destination or at any other time by using the Cancel Navigation command. Press **MENU|MENU|↓** to **CANCEL NAVIGATION|ENT|←** to **YES|ENT**.

## Section 7: Advanced GPS Operations

### Find Distance From Current Position

1. While on the Map Page press: **MENU** | **↓** to **FIND DISTANCE** | **ENT**.
2. Center your cursor over the position you want to find the distance to. A rubber band line appears, connecting your current position to the cursor's location. The distance along that line will appear in a pop-up box. The box also shows the bearing to the point you're measuring to.
3. Press **EXIT** to return to regular operation.



The distance from Dallas to Little Rock is 292.2 miles (left). The distance from the boat's current position to the boat ramp is 0.58 miles (right).

### Find Distance From Point to Point

You can also measure distance between two other points on the map.

1. While on the Map Page press: **MENU** | **↓** to **FIND DISTANCE** | **ENT**.
2. Center your cursor over the first position. (A rubber band line appears, connecting your *current* position to the cursor's location.) Press **ENT** to set the first point, and the rubber band line disappears.
3. Move the cursor to the second position. The rubber band line reappears, connecting the first point you set to the cursor. The distance along that line will appear in a pop-up box.
4. Press **EXIT** to clear the command and return to the page screen.

### Icons

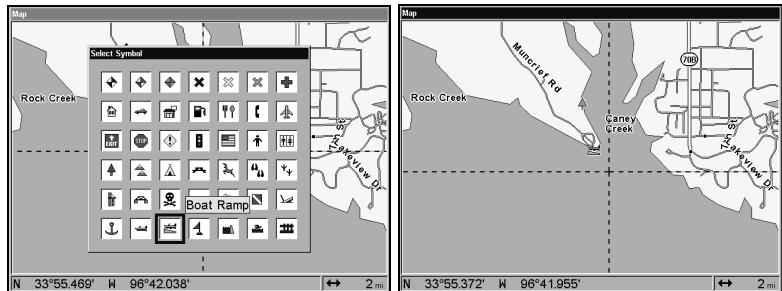
Icons are graphic symbols used to mark some location, personal point of interest or event. They can be placed on the map screen, saved and recalled later for navigation purposes. These are sometimes referred to as event marker icons. The unit has 42 different symbols you can pick from when creating an icon.

Icons are similar to waypoints, but they do not store as much information as waypoints do. You can't use a menu to navigate to icons like you can with waypoints. But, you *can* use the map cursor and navigate to any icon on the map.

You can create an icon at the cursor position on the map, or at your current position while you are navigating.

### Create Icon on Map

1. Use the arrow keys to move the cursor to the place you want to make an icon.
2. Press **ENT** and the screen shows a "Select Icon Symbol" menu.
3. Press  $\leftarrow$  or  $\uparrow$  or  $\rightarrow$  or  $\downarrow$  to select your icon symbol, then press **ENT**. The icon appears on the map.



Select Icon Symbol menu (left); Boat Ramp icon on map (right).  
(Cursor has been moved for clarity).

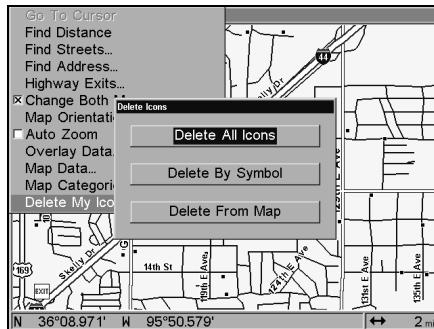
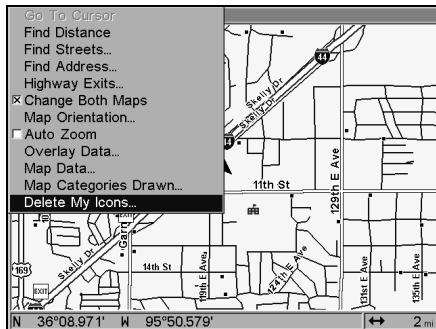
### Create Icon at Current Position

1. While you are traveling, press **ENT** and the screen shows the "Select Icon Symbol" menu.
2. Press  $\leftarrow$  or  $\uparrow$  or  $\rightarrow$  or  $\downarrow$  to select your icon symbol, then press **ENT**. The icon appears on the map.

### Delete an Icon

You can delete all the icons at one time, delete all icons represented by a particular symbol, or delete a selected icon from the map.

1. Press **MENU** |  $\downarrow$  to **DELETE MY ICONS** | **ENT**.
2. Press  $\downarrow$  to **DELETE ALL ICONS**, **DELETE BY SYMBOL**, or **DELETE FROM MAP** and press **ENT**.



### Delete icons menu.

The Delete All Icons command will ask if you are sure. Press **←** to **YES|ENT**. All icons will be deleted from the map.

The Delete by Symbol command will launch the Select Symbol menu. Press **←** or **↑** or **→** or **↓** to select the icon symbol to delete, then press **ENT**. A message appears saying all icons with the selected symbol have been deleted.

The Delete From Map command will prompt you to move the cursor over an icon to select it. After selecting the icon, press **ENT** and it disappears from the map.

### Navigate to an Icon

Use the Navigate to Cursor command, and use the cursor to select the desired icon on the map.

1. Use arrow keys to center cursor cross-hair over the icon.
2. To navigate to the selected icon location: press **MENU|ENT**. Follow course line on the Map Page or the compass bearing arrow on the Navigation Page.

## Routes

A route is a series of waypoints, linked together in an ordered sequence to mark a course of travel. You can visualize a route as a string of beads. The beads represent waypoints and the string represents the course of travel connecting waypoint to waypoint.

The course from one waypoint to the next is a leg. Routes are composed of one or more legs. The legs of all GPS routes are based on straight lines between waypoints.

A route provides the automatic capability to navigate through several waypoints without having to reprogram the unit after arriving at each waypoint. Once programmed into the GPS unit, a route provides the option of navigating forward through the route waypoints or in reverse order. You can even begin navigating in the middle of a route!

## Create and Save a Route

You have the option of creating and editing a route in the unit, or you can make a route on your computer with our MapCreate 6 software.

### PC-created Routes

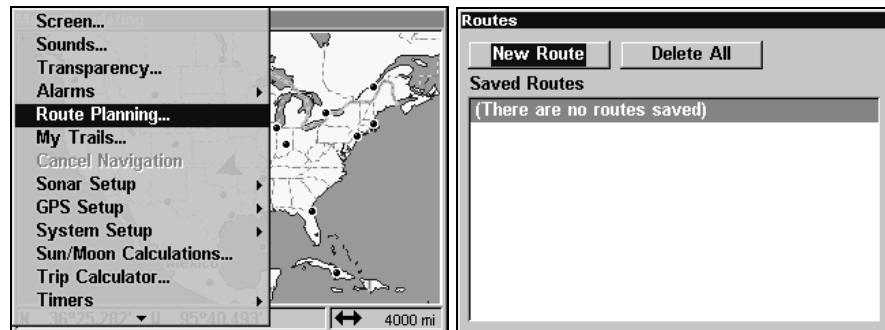
MapCreate is the easiest method for preparing a route, simply because your PC's larger screen, keyboard and mouse are easier to manipulate than the gimbal-mounted unit.

To load a MapCreate route into the unit, follow the instructions in MapCreate's manual for creating and saving a route as part of a GPS Data File (file format \*.usr). Copy the GPS Data File to an MMC and insert the MMC in the unit. (See Sec. 2 for instructions on installing MMCs. To load the GPS Data File into the Unit memory, see the entry on *Transfer Custom Maps & GPS Data Files* in Sec. 6, *Basic GPS Operations*.

### Routes Created in the Unit

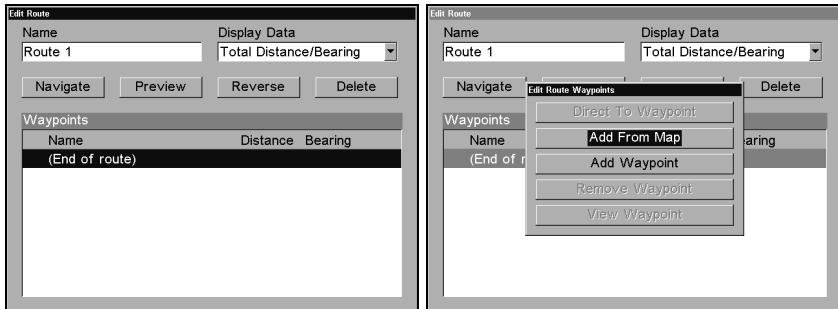
You can create a route by selecting saved waypoints from the waypoint list or you can set a series of route waypoints on the map with cursor arrows and the Enter key. In this example, we'll create a route from the map.

1. From the **NAVIGATION PAGE (WITH DIGITAL DATA)**, press **MENU | ENT** or from the **MAP PAGE**, press **MENU | MENU | ↓** to **ROUTE PLANNING | ENT**.



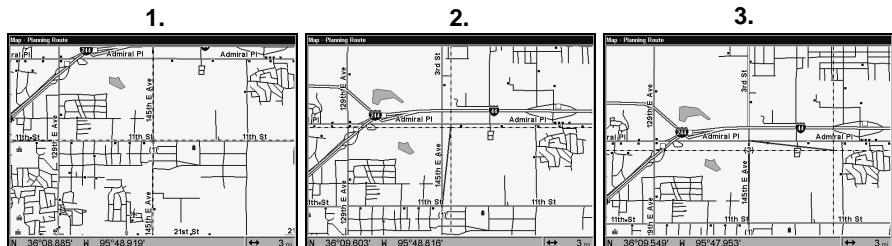
Route Planning command on Main Menu (left) will open the Route List screen (right).

2. Press **↓ | ↓ | ↑ or ↓** to **route name | ENT | ↓** to **(END OF ROUTE) | ENT | ↓** to **ADD FROM MAP | ENT**. The Map Page appears with the cursor showing.

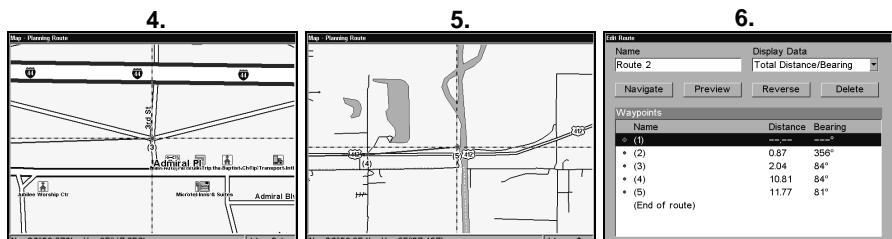


**Edit Route menu (left). Edit Route Waypoints menu (right) with Add From Map command selected.**

3. Use the Zoom keys and arrow keys to move the map and cursor until the cursor is centered on the spot where you want your route to begin.
4. To set the first route waypoint press **ENT**. In this example, we moved to the intersection of 11th Street and 145th E. Ave. to start our route, which ends at a public hunting area next to a river.



**Route creation sequence, from left:** (Fig. 1) Set route waypoint (1) at 11th St. & 145th Ave. (Fig. 2) Move cursor north to set point (2) at 145th & Admiral. (Fig. 3) With point (2) set, move cursor east to mark interstate on-ramp with waypoint (3). In figures 2 and 3, notice the rubber band line extending from the previously set waypoint to the cursor. This line will become the course for the route.



**Route creation sequence, continued:** (Fig. 4) Point (3) set at on-ramp. (Fig. 5) Waypoint (4) set at highway exit to frontage road leading to river. Waypoint (5) ends the route at a tree stand in the hunting area. (Fig. 6) Press **EXIT** to save the route and you return to this screen.

5. Move the cursor to the next point in the route, a spot where you need to turn or change direction, and press **ENT** to set the next waypoint.
6. Repeat step five until the route reaches your destination.
7. To save your route, press **EXIT**. The unit reverts to the Edit Route screen, with the route automatically named "Route 1" and stored in the unit's internal memory. In our example, Route 1 already existed, so the unit automatically made "Route 2."

You can edit the route and run other commands, but if you are finished with the route for now, return to the last page displayed by pressing **EXIT** repeatedly.

### Delete a Route

1. From the **NAVIGATION PAGE (WITH DIGITAL DATA)**, press **MENU | ENT** or from the **MAP PAGE** press **MENU | MENU | ↓** to **ROUTE PLANNING | ENT**.
2. Press **↓** to *Saved Routes*, use **↓** to select route, then press **| ENT**.
3. Press **↓** or **↑** to **NAVIGATE**, then **→** to **DELETE | ENT | ←** to **YES | ENT**.

### **Tip:**

You can also delete all routes at once:

1. From the **NAVIGATION PAGE (WITH DIGITAL DATA)**, press **MENU | ENT** or from the **MAP PAGE** press **MENU | MENU | ↓** to **ROUTE PLANNING | ENT**.
2. Press **→** to **DELETE ALL | ENT | ←** to **YES | ENT**.

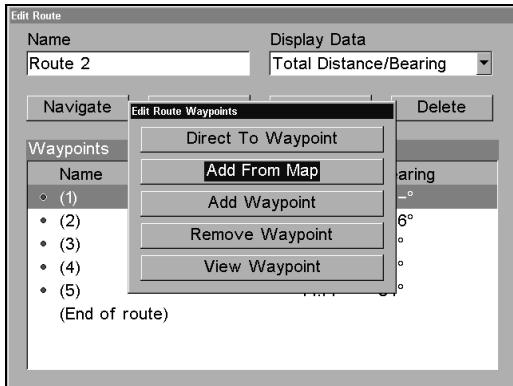
### Edit a Route

You can edit the route name if you wish.

1. From the **NAVIGATION PAGE (WITH DIGITAL DATA)**, press **MENU | ENT** or from the **MAP PAGE** press **MENU | MENU | ↓** to **ROUTE PLANNING | ENT**.
2. Press **↓** to *Saved Routes*, select a route, then press **| ENT | ENT**.
3. Press **↑** or **↓** to change the first character, then press **→** to move the cursor to the next character and repeat until the name is correct, then press **ENT**. Return to the previous page by pressing **EXIT | EXIT | EXIT | EXIT**.

You can edit the route by adding and removing waypoints.

1. From the **NAVIGATION PAGE (WITH DIGITAL DATA)**, press **MENU | ENT** or from the **MAP PAGE** press **MENU | MENU | ↓** to **ROUTE PLANNING | ENT**.
2. Press **↓** to *Saved Routes*, pick a route and press **| ENT | ↓** to the **WAYPOINTS** list. Use **↓** and **↑** to select a waypoint, then press **ENT**.

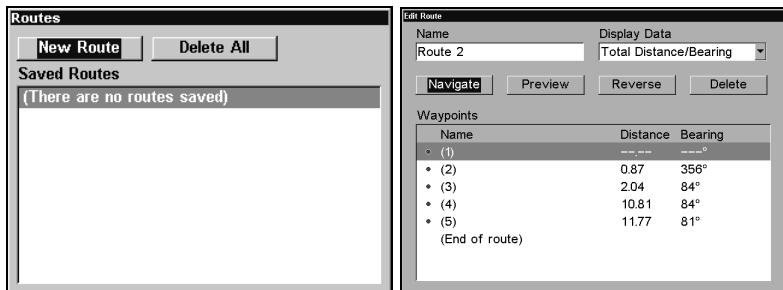


**Edit Route Waypoints menu.**

3. Use ↓ and ↑ to select a command from the Edit Route Waypoints menu and press ENT. Add From Map lets you insert a waypoint in the route by clicking on a map location with the cursor. Add Waypoint calls up the Waypoint list so you can insert a waypoint. The Remove Waypoint command will delete the waypoint from the route. View Waypoint will show you where the selected waypoint is on the map.

## Navigate a Route

1. From the **NAVIGATION PAGE (WITH DIGITAL DATA)**, press **MENU | ENT** or from the **MAP PAGE**, press **MENU | MENU | ↓ to ROUTE PLANNING | ENT**.



**Routes menu (left) and the Edit Route menu (right) with the Navigate command selected.**

2. Press ↓ to select *Saved Route*, pick a route and press |ENT|↓ to **NAVIGATE | ENT**.
3. Upon arrival at your destination, cancel navigation: press **MENU | MENU | ↓ to CANCEL NAVIGATION | ENT | ← to YES | ENT**.

## Navigate a Route in Reverse

Here's how you run a route backward, from the end waypoint to the beginning waypoint:

1. From the **NAVIGATION PAGE**, press **MENU | ENT** or from the **MAP PAGE**, press **MENU | MENU | ↓** to **ROUTE PLANNING | ENT**.
2. Press **↓** to select **route name | ENT | ↓** to **NAVIGATE | →** to **REVERSE | ENT | ←** to **NAVIGATE | ENT**.
3. Upon arrival at your destination, cancel navigation: press **MENU | MENU | ↓** to **CANCEL NAVIGATION | ENT | ←** to **YES | ENT**.

Figure 1.

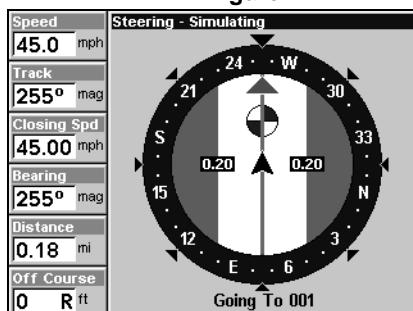
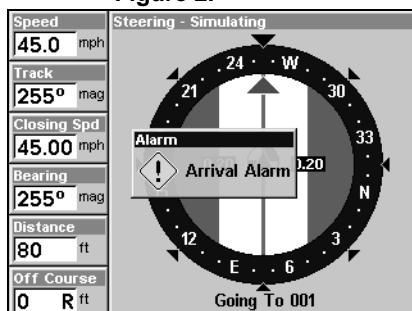


Figure 2.



Navigating along a route: Fig. 1 shows the Navigation Page at the start of a route, heading straight for the waypoint 001. In Fig. 2, the traveler has arrived at Wpt 001 and the arrival alarm has been triggered.

## Trails

### Delete a Trail

This is the command used to delete a trail: Press **MENU | MENU | ↓** to **MY TRAILS | ENT | ↓** to **trail name | ENT | →** to **DELETE TRAIL | ENT | ←** to **YES | ENT**.

### Tip:

You can also delete all trails at once:

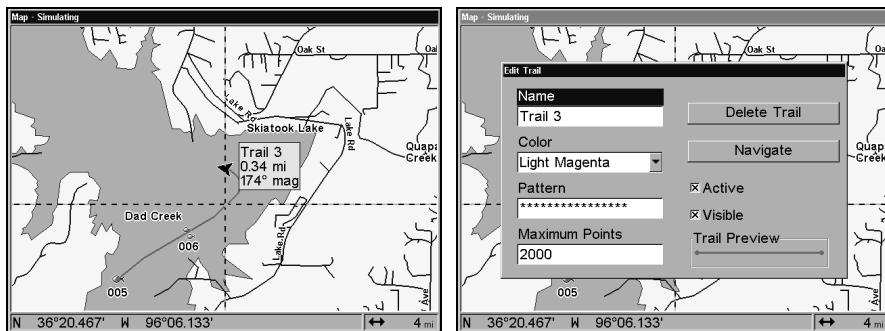
1. Press **MENU | MENU | ↓** to **MY TRAILS | ENT**.
2. Press **→** to **DELETE ALL | ENT | ←** to **YES | ENT**.

### Edit a Trail Name

To edit a trail name: press **MENU | MENU | ↓** to **MY TRAILS | ENT | ↓** to **trail name | ENT | ENT**. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the name is correct. Press **ENT** then **EXIT | EXIT | EXIT | EXIT** to return to the previous page display.

## Tip:

You can quickly call up the Edit Trail menu by selecting a trail on the map with the cursor. Simply move the cursor over a trail and a pop-up box appears. Press **WPT** and the Edit Trail menu opens.



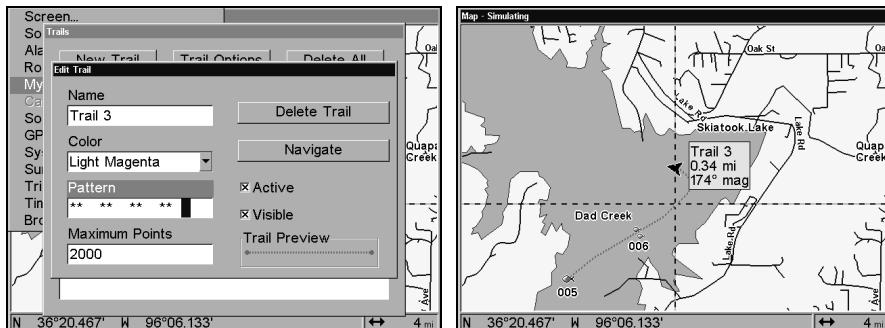
Trail selected with map cursor (left). The pop-up box shows distance and bearing from current position to the selected point on the trail. The Edit Trail menu (right).

### Edit a Trail Color

To edit a trail color: press **MENU | MENU | ↓** to **MY TRAILS | ENT | ↓** to *trail name* | **ENT | ↓** to **COLOR | ENT**. Press **↑** or **↓** to select a color style, then press **ENT**. Press **EXIT | EXIT | EXIT | EXIT** to return to the previous page display.

### Edit a Trail Pattern

To edit a trail pattern: press **MENU | MENU | ↓** to **MY TRAILS | ENT | ↓** to *trail name* | **ENT | ↓** to **PATTERN | ENT**. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the pattern is correct. Press **ENT**, then **EXIT | EXIT | EXIT | EXIT** to return to the previous page display.



Edit Trail Menu with Pattern option selected (left). Edited trail with dotted line pattern (right).

## Utilities

Utilities are useful tools for traveling or for outdoor activities.

### Alarm Clock

To get to the alarm clock menu: press **MENU | MENU | ↓** to **TIMERS | ENT | ↓** to **ALARM CLOCK | ENT**.

### Sun/Moon Rise & Set Calculator

To get to the Sun/Moon menu: press **MENU | MENU | ↓** to **SUN/MOON CALCULATIONS | ENT**.

### Trip Calculator

To get to the Calculator menu: press **MENU | MENU | ↓** to **TRIP CALCULATOR | ENT**.

### Trip Down Timer

To get to the Down Timer menu: press **MENU | MENU | ↓** to **TIMERS | ENT | ↓** to **DOWN TIMER | ENT**.

### Trip Up Timer

To get to the Up Timer menu: press **MENU | MENU | ↓** to **TIMERS | ENT | ENT**.

## Waypoints

### Delete a Waypoint

To delete a waypoint from the waypoint list: press **WPT | ENT | ENT | ENT | ↓** to *waypoint name* | **ENT | ↓** to **DELETE WAYPOINT | ENT | ←** to **YES | ENT**.

To delete a waypoint from the map:

1. Use the arrow keys to select the waypoint with the cursor.

2. Press **WPT | →** to **DELETE WAYPOINT | ENT | ←** to **YES | ENT**. To return to the previous page and clear the cursor, press **EXIT**.

To delete all waypoints at one time: press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ↓** to **DELETE ALL MY WAYPOINTS | ENT | ←** to **YES | ENT**. To return to the previous page, press **EXIT | EXIT**.

### Edit a Waypoint

#### Waypoint Name

To edit waypoint name: 1. Press **WPT | ENT | ENT | ENT | ↓** to *waypoint name* | **ENT | ↓** to **EDIT WAYPOINT | ENT | ENT**.

2. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the name is correct. Press **ENT** then **EXIT | EXIT | EXIT | EXIT** to return to the previous page display.

## Waypoint Symbol

To edit waypoint symbol: 1. Press **WPT|ENT|ENT|ENT|↓** to *waypoint name|ENT|↓* to **EDIT WAYPOINT|ENT|↓** to **CHOOSE SYMBOL|ENT**.

2. Use arrow keys to select desired symbol and press **ENT**. To return to the previous page, press **EXIT|EXIT|EXIT|EXIT**.

## Waypoint Position

To edit waypoint position: 1. Press **WPT|ENT|ENT|ENT|↓** to *waypoint name|ENT|↓* to **EDIT WAYPOINT|ENT**.

2. Latitude: press → to **LATITUDE|ENT**. Press ↑ or ↓ to change the first character, then press → to the next character and repeat until the latitude is correct. Press **EXIT**.

3. Longitude: press ↓ to **LONGITUDE|ENT**. Press ↑ or ↓ to change the first character, then press → to the next character and repeat until the longitude is correct. Press **EXIT**.

4. When latitude and longitude are correct, return to the previous page: press **EXIT|EXIT|EXIT|EXIT**.

## Selecting a Waypoint

To select a waypoint on the map (for navigating, editing, etc.,) use the arrow keys and center the cursor over the waypoint. A highlighted halo will appear around the waypoint.

## Set a Waypoint by Average Position

This feature sets a waypoint at the current position after taking several position readings and averaging them. This boosts waypoint position accuracy by helping to eliminate errors caused by atmospheric conditions and other factors.

1. Press **WPT|→** to **SUBCATEGORY** column |↓ to **NEW|ENT**.

2. Press ↓ or ↑ to **AVERAGE POSITION|ENT** | press → to **CREATE|ENT**.

3. Wait while the unit takes points to average for the position. (The greater the number of points, the greater the accuracy.) When the desired number of points accumulates, press **ENT** to create and save the waypoint.

4. The Edit Waypoint menu appears. You can simply save the waypoint by pressing **EXIT|EXIT** or you can edit the waypoint.

## Set a Waypoint by Projecting a Position

This feature sets a waypoint at a point located a specific distance and bearing from a reference position. The reference position can be selected from your waypoint list, a map feature or from the Points of Interest list.

1. Press **WPT** | **→** to **SUBCATEGORY** column | **↓** to **NEW** | **ENT**.
2. Press **↓** to **PROJECTED POSITION** | **ENT** | **→** to **CREATE** | **ENT**.
3. Press **→** to **CHOOSE REFERENCE** | **ENT**. Use **↑** and **↓** to select a waypoint, map feature or Point of Interest. When the point has been selected, press **ENT** and the point's position appears as the reference position.
4. Press **↓** to **DISTANCE** | **ENT**. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the distance is correct. Press **ENT**.
5. Press **↓** to **BEARING** | **ENT**. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the bearing is correct. Press **ENT**.
6. Press **↑** to **PROJECT** | **ENT**. The Edit Waypoint menu appears. You can simply save the new projected waypoint by pressing **EXIT** | **EXIT** or you can edit the waypoint. (Press **EXIT** | **ENT** if you want to immediately begin navigating to the new waypoint.)

## Section 8: System & GPS Setup Options

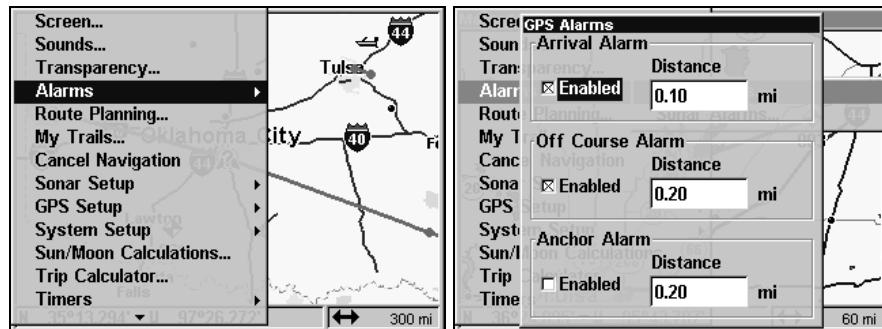
### Alarms

This unit has several GPS alarms. The factory default setting has all the alarms turned on. You can turn the alarms off and on and change their distance settings.

You can set an arrival alarm to flash a warning message and sound a tone when you cross a preset distance from a waypoint. For example, if you have the arrival alarm set to 0.1 mile, then the alarm will flash a message when you come within 0.1 mile of the recalled waypoint.

The off course alarm warns you when your track drifts too far to the right or left of the course line to the waypoint. For example, if the alarm is set to 0.1 mile, then the alarm flashes a message if you drift 0.1 of a mile or more to the right or left of the line to the waypoint.

The anchor alarm is triggered when you drift outside of a preset radius. Again, using the 0.1 mile as an example, if you're anchored and your boat moves more than 0.1 mile, the alarm will flash a message and sound a tone.



Alarms command (left); Alarm menu (right).

To change alarm settings:

1. Press **MENU** | **MENU** | **↓** to **ALARMS** | **ENT**. Choose **GPS ALARMS** | **ENT**.
2. Scroll **↓** or **↑** to select the desired category, then press **ENT** to check or clear the Enabled box. This turns the alarm on (checked) or off (unchecked.)
3. To change distance settings, scroll **↓** or **↑** to select the desired category, then press **→** | **ENT** to activate the distance dialog box. Press **↑** or **↓** to change the first character, then press **→** to the next character and repeat until the name is correct.

4. When your adjustments are finished, return to the last page displayed by repeatedly pressing **EXIT**.

### **IMPORTANT ALARM NOTES:**

Anchor Alarm - The anchor alarm may be triggered even when you're sitting still. This typically happens when using small (less than 0.05 mile) anchor alarm ranges.

Arrival Alarm - If you set the arrival alarm's distance to a small number and you run a route (see the Navigate Routes segment), this unit may not show navigation data to the next waypoint, once you arrive at the first one, since you may not be able to come close enough to the first waypoint to trip the arrival alarm.

### **Auto Satellite Search**

To lock onto the satellites, the GPS receiver needs to know its current position, UTC time and date. (Elevation (altitude) is also used in the equation, but it's rarely required to determine a position.) It needs this data so that it can calculate which satellites should be in view. It then searches for only those satellites.

When your GPS receiver is turned on for the first time, it doesn't know what your position or elevation (altitude) is. It does know the current UTC time and date since these were programmed into it at the factory and an internal clock keeps the time while the unit is turned off. (If the time and/or date are incorrect, you can set it using the "Set Local Time" menu.)

The unit begins searching for the satellites using the above data that it acquired the last time it was turned on. This probably was at the factory. Since it's almost certain that you're not at our factory, it's probably looking for the wrong satellites.

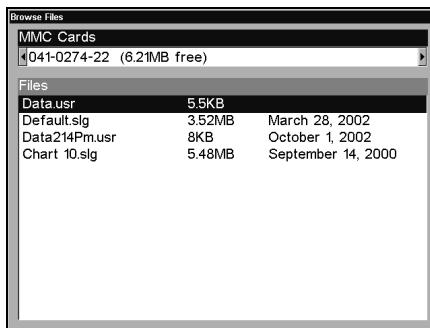
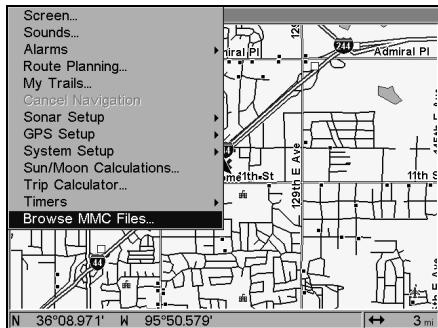
If it doesn't find the satellites it's looking for after approximately one minute, it switches to Auto Search. The receiver looks for any satellite in the sky. Due to advanced technology, the auto search time has shrunk significantly from the early days of GPS.

Once the unit locks onto the satellites, it should take less than a minute to find your position the next time it's turned on, provided you haven't moved more than approximately 100 miles from the last location it was used.

### **Check MMC Files and Storage Space**

To check MMC Files:

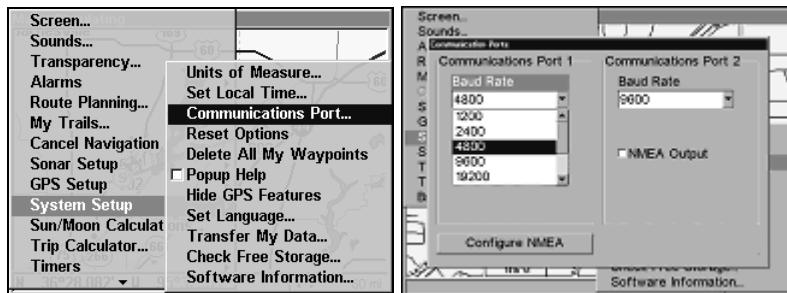
Press **MENU** | **MENU** | **↓** to **BROWSE MMC FILES** | **ENT**.



Main Menu (left); MMC File Browser (right).

## Communications Port Configuration

The unit has two NMEA 0183 version 2.0 compatible communication ports, or com ports for short. The Com Port Menu, which is accessed from the System Setup Menu, allows you to configure the communications ports to send or receive data to another electronic device, such as an autopilot. Com port 1 and Com port 2 can be used for NMEA.



Menus for changing Com Port settings.

For assistance in configuring the unit to communicate with another device, consult the factory. Customer service phone numbers are in the back of this manual. Also see the entries below for *Configure NMEA*. To set Com Port Configuration:

1. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT.**
2. Press **↓** to **COMMUNICATIONS PORT | ENT.**

## Configure NMEA

You can configure the unit to use specific NMEA sentences.

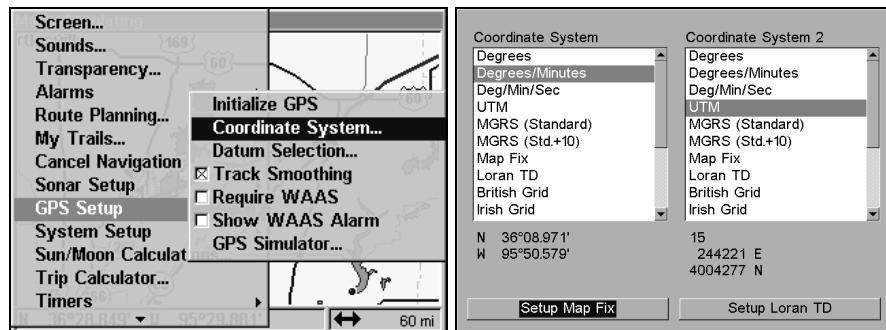
1. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT.**
2. Press **↓** to **COMMUNICATIONS PORT | ENT | ↓** to **CONFIGURE NMEA | ENT.**

3. A menu appears showing the prefixes of the available NMEA sentences. A check mark next to a prefix means the prefix is in use. Use  $\uparrow$ ,  $\downarrow$ ,  $\rightarrow$ ,  $\leftarrow$  to select a prefix, then press **ENT** to turn off the prefix. (Press **ENT** again to check the box and turn a prefix on.)

4. When the desired prefixes are checked or unchecked, press **EXIT** | **EXIT** | **EXIT** | **EXIT** to return to the previous page.

## Coordinate System Selection

The Coordinate System Menu lets you select the coordinate system to use when displaying and entering position coordinates.



Menus for changing coordinate system.

To get to Coordinate System Selection:

1. Press **MENU** | **MENU** |  $\downarrow$  to **GPS SETUP** | **ENT**.

2. Press  $\downarrow$  to **COORDINATE SYSTEM** | **ENT**.

This unit can show a position in degrees ( $36.14952^\circ$ ); degrees, minutes and thousandths of a minute ( $36^\circ 28.700'$ ); or degrees, minutes, seconds and tenths of a second ( $36^\circ 28' 40.9''$ ). It can also show position in: UTM (Universal Transverse Mercator) projection; MGRS (Standard); MGRS (Standard + 10); Map Fix; Loran TD; British, Irish, Finnish, German, New Zealand, Swedish, Swiss, Taiwan, Greek and Military grids.

UTM's are marked on USGS topographic charts. This system divides the Earth into 60 zones, each 6 degrees wide in longitude.

British, Irish, Finnish, German, New Zealand, Swedish, Swiss, Taiwan, and Greek grid systems are each the national coordinate system used only in their respective countries. In order to use these grid systems, you must be in the respective country. This unit will pick the matching datum for you when you select the grid. See the entry on Map Datum Selection for more information.

The military grid reference system (MGRS) uses two grid lettering schemes, which are referred to as standard and standard + 10 MGRS

on this unit. Your position and datum in use determines which one to use. If you use standard, and your position is off significantly, then try the alternate.

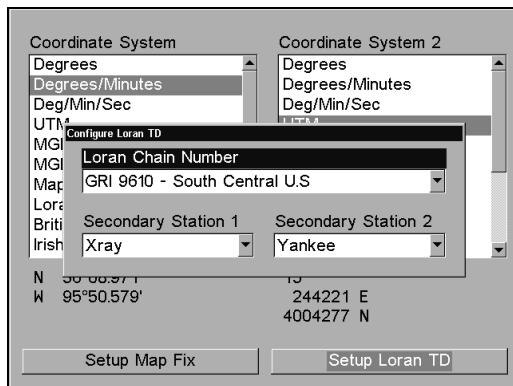
**NOTE:** When the position format is changed, it affects the way all positions are shown on all screens. This includes waypoints.

To change the coordinate system, press **ENT** while **COORDINATE SYSTEM** is highlighted. Press the **↑** or **↓** keys to highlight the desired format. Press **ENT** to select it. Press **EXIT** to close the menu.

### To setup Loran TD:

**NOTE:**

If the Loran TD conversion is chosen, you must enter the local Loran chain identification for the master and slaves. Do this by selecting "Setup Loran TD" at the bottom of the "Coordinate System" menu and select the ID. Press **EXIT** to close this menu.



Configure Loran TD menu.

### Map Fix

Map Fix is used with charts or maps. This system asks for a reference position in latitude/longitude, which you take from a marked location on the map. It then shows the present position as distance on the map from that reference point.

For example, if it shows a distance of UP 4.00" and LEFT 0.50", you then measure up four inches and to the left a half-inch from the reference point on the map to find your location.

### To configure a map fix:

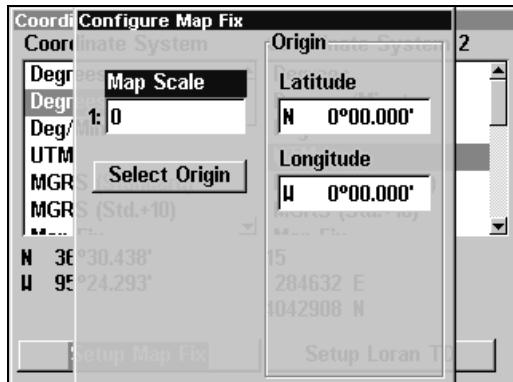
To use this format, you need to follow these steps in order. First, take your map of the area and determine a reference latitude/longitude. (Please note that in order for this system to work, the

latitude/longitude lines must be parallel with the edge of the map. USGS maps are parallel, others may not be. Also, this works better with smaller scale maps.) The reference position can be anywhere on the map, but the closer it is to your location, the smaller the numbers will be that you'll have to deal with.

Once you've decided on a reference position, you can save it as a waypoint. See the waypoint section for information on saving a waypoint. Save the reference position as a waypoint. Exit from the waypoint screens.

1. Press **MENU | MENU | ↓ to GPS SETUP | ENT.**
2. Press **↓ to COORDINATE SYSTEM | ENT.**
3. Press **↓ to SETUP MAP FIX | ENT.**

The following screen appears, and **MAP SCALE** is highlighted. Press **ENT** and enter the map's scale. This is generally at the bottom of the paper map. It's shown as a ratio, for example 1:24000. Press **EXIT** and the unit returns to the Configure Map Fix screen.



**Configure a map fix so the unit can find your position on a printed chart or topographical map.**

Press **↓ to SELECT ORIGIN | ENT|ENT|ENT** to bring up the waypoint list. Select the waypoint that you saved the reference point under and press **ENT**. The unit displays a waypoint information screen with the command **SET AS ORIGIN** selected; press **ENT** and the unit returns to the Configure Map Fix menu. Finally, press **EXIT** to close this menu. Now press **↑ to COORD SYSTEM | ENT**, select **MAP FIX** from the list and press **ENT | EXIT | EXIT | EXIT**. All position information now shows as a distance from the reference point you chose.

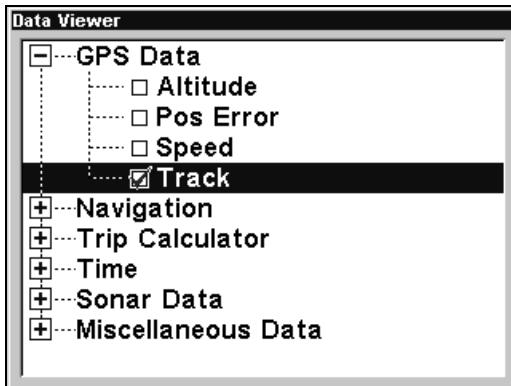
## Customize Page Displays

Several page display options have customizable data boxes to provide constant on-screen information.

The various data available from your unit are divided into categories in the Data Viewer menu. These categories include GPS Data, Navigation, Trip Calculator, Time, Sonar Data and Miscellaneous Data. You can select items from any of these categories for display in any data box. The category divisions are there to help you sort through the information.

### To change the information displayed in a data box:

On the Page display you wish to change, press **MENU** | **↓** to **CUSTOMIZE** | **ENT**. A data box name flashes, indicating it is selected. Press **ENT** to change the box or hit **↑**, **↓**, **→** or **←** to select another box, then press **ENT**. You'll see a list of categories with "+" or "-" symbols next to each category. A category with a "+" is *expandable*, meaning its contents are hidden.



Customize Menu with the GPS Data category expanded.

Selecting the category name and pressing **ENT** will show the category's contents, so you can choose items within it. An expanded category (one with a "-" next to its name) can be collapsed to hide its contents. Just select the category name and press **ENT**.

Expand any categories that might contain data you want to display. Then press **↓** or **↑** to select a different data option. With the new option highlighted, press **ENT** to switch the contents of the box to the new data type, then press **EXIT**. You can now select another box to change. When you are finished with the settings, press **EXIT** again to end the Customize command, and the box name stops flashing.

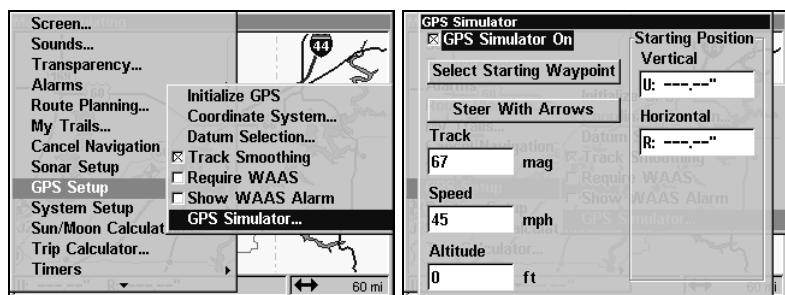
A Page display can show a limited number of data boxes. You can not turn them off or add more data boxes.

## GPS Simulator

The GPS simulator lets you use the unit as if you were outdoors navigating somewhere. It's a great way to practice using your unit. You can set the starting location by entering latitude/longitude (Starting Position) or from a stored waypoint, map place or POI location (**CHOOSE START** command). You can steer your position and change speed on the map by using the arrow keys (**STEER WITH ARROWS** command) or by setting the track and speed in the dialog boxes provided on the simulator menu screen.

### To get to the GPS Simulator:

1. Press **MENU | MENU | ↓ to GPS SETUP | ENT.**
2. Press **↓ to GPS SIMULATOR | ENT.** The GPS Simulator Menu appears.



GPS Setup Menu (left); GPS Simulator menu (right).

Choose the desired settings, then turn the simulator on by highlighting the **GPS SIMULATOR ON** box and pressing **ENT** key. Press **EXIT | EXIT | EXIT** to close this menu. A message and tone appear periodically, warning you that the simulator is on. To turn the simulator off, repeat the above steps or turn the unit off.

While in simulator mode, you can press **EXIT** to clear the steering and speed boxes from the screen while continuing the simulation. This will allow you to use the map cursor during a simulation. To turn steering and speed boxes back on again, return to the GPS Simulator menu, select the **STEER WITH ARROWS** command, press **ENT**. Press **EXIT** to return to the previous page.

### Simulating Trail or Route Navigation

In Simulator mode, your unit can automatically follow a trail or route without manual steering if you use these steps:

1. From the Map Page, go to the simulator menu. Pick a **STARTING POSITION** at or near the beginning of your trail/route. Enter an approximate **TRACK** (shown in compass degrees) that will point you toward the start of the trail/route.
2. Set **SPEED** to zero. Select **STEER WITH ARROWS** command and press **ENT**, which turns on the simulator and returns you to the Map Page.
3. Begin navigating along the trail/route. (If you are close enough to the first waypoint, the arrival alarm will usually go off as soon as navigation begins. Press **EXIT** to clear the alarm.) When navigation starts, press ↑ to increase speed to the desired setting.
4. Press **EXIT** to turn off the steering and speed boxes. The unit will now automatically "steer" along the trail or route. When you arrive at your "destination," cancel navigation as you normally do.

***Tip:***

You can pick any spot on the map to begin your simulation session by using the Initialize GPS command. This makes your unit think it's located at the position you select.

## **Hide GPS Features**

If there is no GPS antenna/receiver module attached to this unit, the GPS menus and features can be hidden from view with this command. The default setting is off, allowing you to rotate between the Sonar Page and the GPS pages and features. To hide GPS features:

Press **MENU|MENU|↓** to **SYSTEM SETUP|ENT|↓** to **HIDE GPS FEATURES | ENT**. The GPS menus and pages are now hidden.

To restore **GPS FEATURES**, press **MENU|MENU|↓** to **SHOW GPS FEATURES | ENT**. The GPS menus and pages are available once again.

## **Initialize GPS**

This command makes the unit operate as if it is sitting someplace other than its actual location. So, you and your unit could be located in Kansas City, but practice navigating in the ocean off Islamorada, Florida.

1. With the GPS simulator off, press **MENU|MENU|↓ TO GPS SETUP|ENT|ENT**.
2. A message appears, telling you to move the cursor near the desired location and press **ENT**. When the message automatically clears, follow the message instructions. Turn on the GPS Simulator.
3. In a moment, your present position marker arrow appears on the map in the location you selected with the cursor. The unit will consider

that spot as its last known position until changed by either a live satellite lock-on or a new simulator location.

## Map Auto Zoom

This receiver has an auto zoom feature that eliminates much of the button pushing that other brands of GPS receivers force you to make. It works in conjunction with the navigation features.

First, start navigation to a waypoint. (See the waypoint section for more information on navigating to a waypoint.) Then, with the auto zoom mode on, the unit zooms out until the entire course shows, from the present position to the destination waypoint. As you travel toward the destination, the unit automatically begins zooming in — one zoom range at a time — always keeping the destination on the screen.

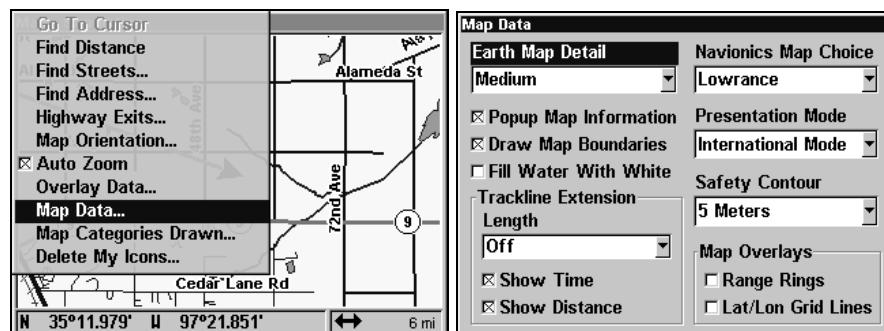
To turn this feature on, from the **MAP PAGE**, press **MENU** | **↓** to **AUTO ZOOM** | **ENT** | **EXIT**. Repeat these steps to turn it off.

## Map Data

This menu lets you turn the map off, if desired (which turns the map screen into a GPS plotter); turn off or on the pop-up map info boxes; draw the map boundaries or boxes around the areas of high detail; or fill water areas with white. You can also turn on or off Map Overlays, which display latitude and longitude grid lines or range rings on the map. This menu lets you select Navionics Maps. For instructions, see the *Navionics Charts* entry in this section.

To get to Map Data:

From the Map Page, press **MENU** | **↓** to **MAP DATA** | **ENT**.



Map Menu (left); Map Data Menu (right).

## Pop-up Map Info

From the Map Page, press **MENU** | **↓** to **MAP DATA** | **ENT**. Press **↓** to **POPUP MAP INFO**. With the option highlighted, press **ENT** to check it (turn on)

and uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

## **Map Boundaries**

From the Map Page, press **MENU|↓** to **MAP DATA|ENT**. Press **↓** to **DRAW MAP BOUNDARIES**. With the option highlighted, press **ENT** to check it (turn on) or uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

## **Fill Water With White**

From the Map Page, press **MENU|↓** to **MAP DATA|ENT**. Press **↓** to **FILL WATER WITH WHITE**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

## **Map Overlays (Range Rings; Lat/Long Grid)**

The map screen can be customized with four range rings and/or grids that divide the plotter into equal segments of latitude and longitude.

Range rings are handy for visually estimating distances on the map. The ring diameters are based on the current zoom range. For example: at the 100-mile zoom, the screen will show two rings with your current position in the center. The large ring touching the left and right sides of the screen is 100 miles in diameter (same as the zoom range). The second smaller ring is 50 miles in diameter (always 1/2 the zoom range).

The distance from your current position to the smaller ring (the ring's radius) is 25 miles (always 1/4 the zoom range). With the arrow keys and map cursor, you can scroll the map to see the third and fourth rings. In this example, the distance to the third ring is 75 miles and distance to the fourth ring is 100 miles from your current position.

**To set range rings:** From the Map Page, press **MENU|↓** to **MAP DATA|ENT**. Press **↓** and **→** to **RANGE RINGS**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

**To set Lat/Long Grid:** From the Map Page, press **MENU|↓** to **MAP DATA|ENT**. Press **↓** and **→** to **LAT/LON GRID LINES**. With the option highlighted, press **ENT** to check it (turn on) and uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.

## **Map Datum Selection**

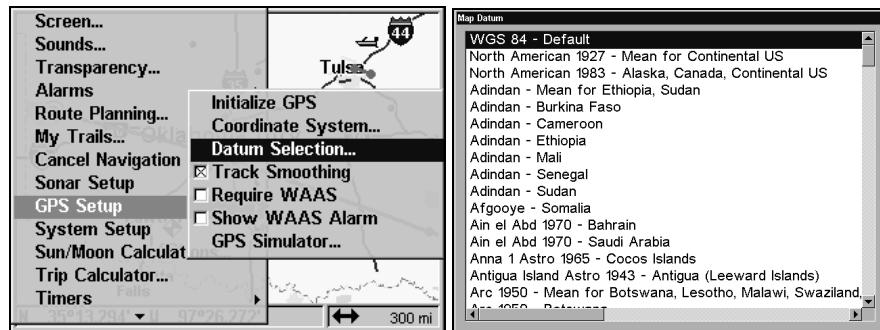
Maps and charts are based on a survey of the area that's covered by the map or chart. These surveys are called "Datums." Maps that are

created using different datums will show the same latitude/longitude in slightly different locations.

All datums are named. The GPS system is based on the WGS-84 datum, which covers the entire world. Other datums may also cover the entire world, or just a small portion of it. By default, your unit uses the WGS-84 datum. It, however, can show your position using one of 191 different datums. To change the datum:

1. Press **MENU|MENU|↓** to **GPS SETUP | ENT|↓** to **DATUM SELECTION | ENT**.
2. Scroll **↓** or **↑** to select the desired datum, then press **ENT**.
3. To return to the last page displayed, press **EXIT|EXIT**.

A list of the datums used by this unit is in the back of this manual.



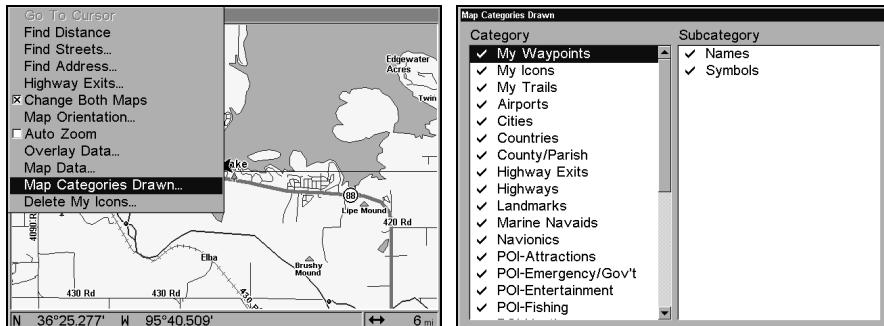
GPS Setup Menu (left); Map Datum Menu (right).

## Map Detail Category Selection

This menu determines which of the mapping features are shown on the screen. This includes, waypoints, trails, icons, cities, highways, etc. You can select any of these items, customizing the map to your needs.

To get to Map Categories:

1. From the Map Page, press **MENU|↓** to **MAP CATEGORIES DRAWN|ENT**.
2. Press **↑** or **↓** to select a category or press **→** then press **↑** or **↓** to select a subcategory. Press **ENT** to turn it off (no check) or on (checked.)
3. To return to the last page displayed, press **EXIT|EXIT**.

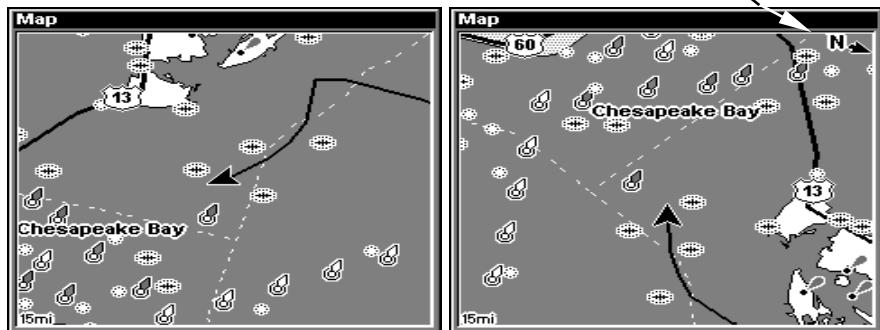


Map Menu (left); Map Categories Drawn Menu (right).

## Map Orientation

By default, this receiver shows the map with north always at the top of the screen. This is the way most maps and charts are printed on paper.

In Track Up mode, map shows "N" and arrow to indicate north.



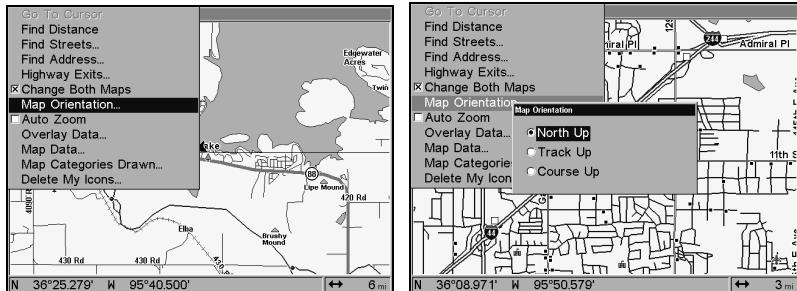
Map orientation is shown in north up (left) and track up (right).

This is fine if you're always traveling due north. What you see to your left corresponds to the left side of the map, to your right is shown on the right side of the map, and so on. If, however, you travel any other direction, the map doesn't line up with your view of the world.

To correct this problem, a track-up mode rotates the map as you turn. Thus, what you see on the left side of the screen should always be to your left, and so on.

Another option is course-up mode, which keeps the map at the same orientation as the initial bearing to the waypoint. When either the track-up or course-up mode is on, an "N" shows on the map screen to help you see which direction is north.

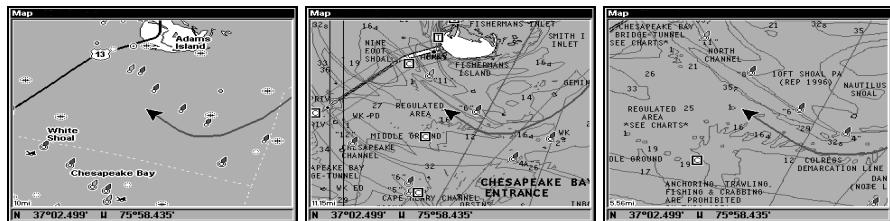
To change map orientation: from the Map Page, press **MENU** | **↓** to **MAP ORIENTATION** | **ENT**. Use **↑** or **↓** to select the desired mode, then press **ENT**. Press **EXIT** | **EXIT** to return to the page display.



**Map Menu (left) Map Orientation menu with the North Up map orientation option selected (right).**

## Navionics® Charts

Your Unit can display Navionics® electronic charts on MMCs. They work just like a MapCreate custom map on a MMC.



**Entrance to Chesapeake Bay in a MapCreate 6 custom map with a 10-mile zoom (left). The same position on Navionics chart at 11.15-mile zoom (center) and with a 5.56-mile zoom (right).**

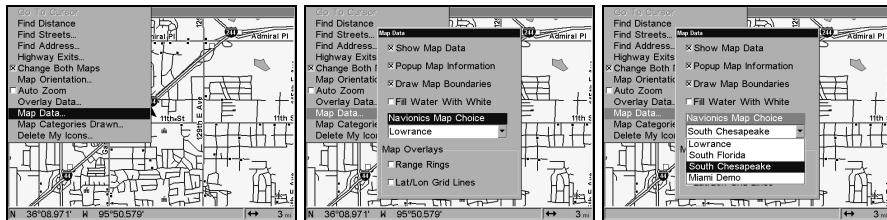
### To display a Navionics chart:

1. Install the Navionics MMC in the memory card compartment and turn on the unit. (For full card install instructions, see Sec. 2.)

#### WARNING:

**You should never format the MMC containing your Navionics chart. Formatting the MMC will permanently erase the chart from the card.**

2. From the Map Page, press **MENU**↓ to **MAP DATA** | **ENT**→ to **NAVIONICS MAP CHOICE** | **ENT**. Use ↑ or ↓ to select the *Map Name*, then press **ENT** | **EXIT** | **EXIT**.



These figures show menu sequence (from left to right) for selecting a Navionics chart for the South Chesapeake Bay area.

3. To turn off a Navionics chart, From the Map Page, press **MENU**|**↓** to **MAP DATA** | **ENT** | **→** to **NAVIONICS MAP CHOICE** | **ENT**. Use **↑** or **↓** to select **LOWRANCE**, then press **ENT** | **EXIT** | **EXIT**.

## Port Information

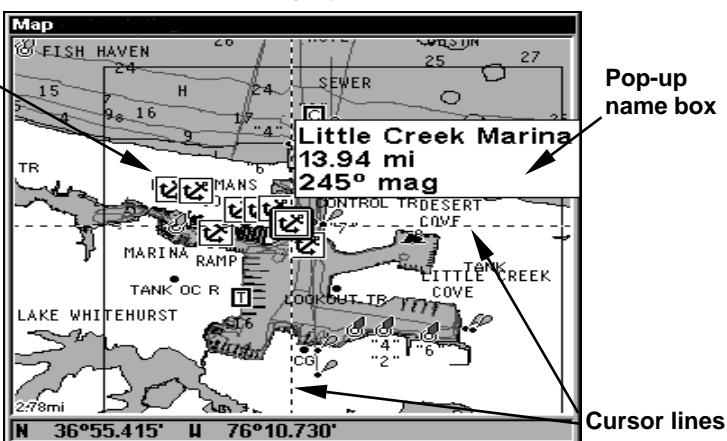
Navionics charts contain Port Services information, represented by anchor icons on the map display. An example is displayed in the following figure.

### To view Port Services information:

1. Use the arrow keys to move the cursor over a Port Services icon. When selected, a pop-up name box appears.
2. Press **WPT** to display the Port Services Information screen.

The Port Services information screen has two windows. The top window lists the various service categories. The lower window lists the detailed services available in each basic category.

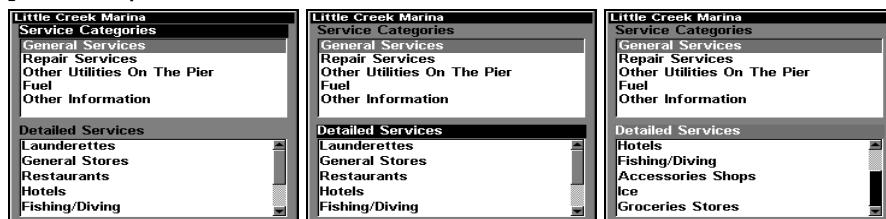
### Port Services icons



Navionics chart showing Port Services icon selected by cursor.

3. To scroll through the Service Categories window: press **ENT** then use **↑** or **↓** to see the types of services available. As you highlight a different category, the list in the lower window changes. To return to the Map Page, press **EXIT** | **EXIT**.

4. The General Services category includes a long list of items in the Detailed Services window. To scroll through the Detailed Services window: from **SERVICE CATEGORIES**, press ↓ to **DETAILED SERVICES | ENT**, then use ↑ or ↓ to read the list of available services. To return to the Map Page, press **EXIT|EXIT**. To return to the top service category window, press **ENT|↑**.



Port Services information screens.

## Tidal Current Information

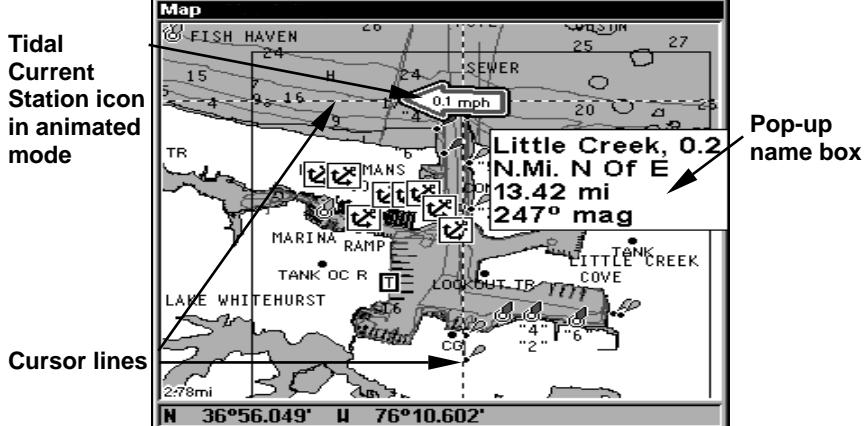
Navionics charts contain Tidal Current information, represented at large zoom ranges by a box icon with the letter "C." The icon stands for a Tidal Current Station location.



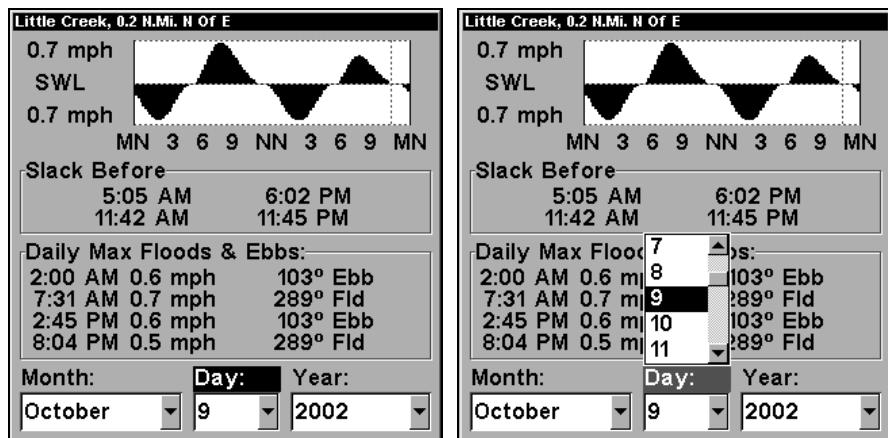
When you zoom in to a sufficiently small zoom range, the icon itself becomes an animated arrow showing tidal current velocity and direction *for the selected tidal station*. At larger zoom ranges, you can select the boxed "C" icon and it becomes an animated arrow with a pop-up name box. An example is displayed in the following figure.

### To view Tidal Current information:

1. Use the arrow keys to move the cursor over a Tidal Current Station icon. When selected, a pop-up name box appears.
2. Press **WPT** to display the Tidal Current Information screen.



Navionics chart showing Tidal Current Station icon selected by cursor. In this example, the tidal current is in flood but it's about to enter the slack water stage. The current is flowing to the west at 0.1 mph.



Current Information screen.

The Tidal Current Information screen displays daily tidal current data for the station at the present time. The graph at the top of the example above is an approximate view of the flood and ebb pattern from midnight (MN), to noon (NN) to midnight (MN). The velocity scale at the top left side of the graph changes dynamically based upon the maximum velocity of the current for that day.

Slack water, the period of little or no current, is represented by the Slack Water Line (SWL). The flood appears above the SWL and the ebb appears below the SWL.

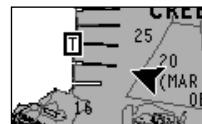
You can look up tidal current data for other dates by changing the month, day and year selection boxes. To select another date:

1. Use → and ← to highlight month, day or year, then press **ENT**.
2. Use ↑ and ↓ to select the desired month, day or year, then press **ENT**.

To clear the information screen, press **EXIT**.

## Tide Information

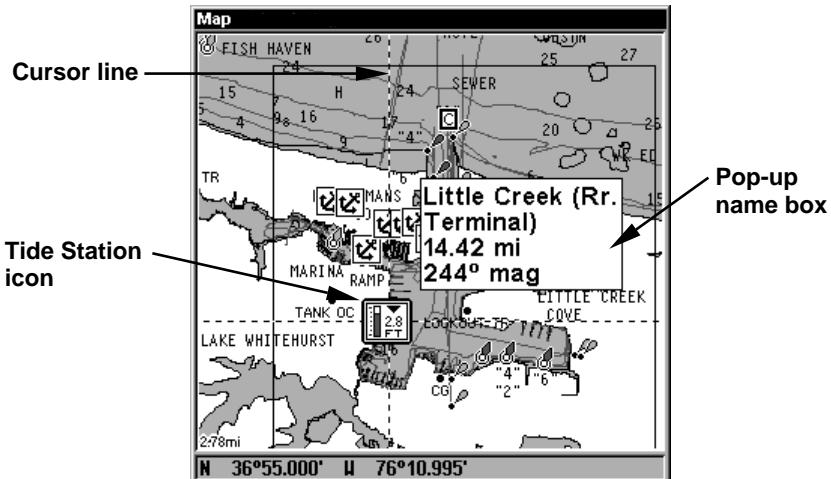
Navionics charts contain Tidal Information, represented at large zoom ranges by a box icon with the letter "T." The icon stands for a Tidal Station location. An example is displayed in the figure on the right.



When you zoom in to a sufficiently small zoom range, the icon itself becomes an animated gauge showing a rising or falling tidal height *for the selected station*. At larger zoom ranges, you can select the boxed "T" icon and it becomes an animated gauge with a pop-up name box. An example is displayed in the following figure.

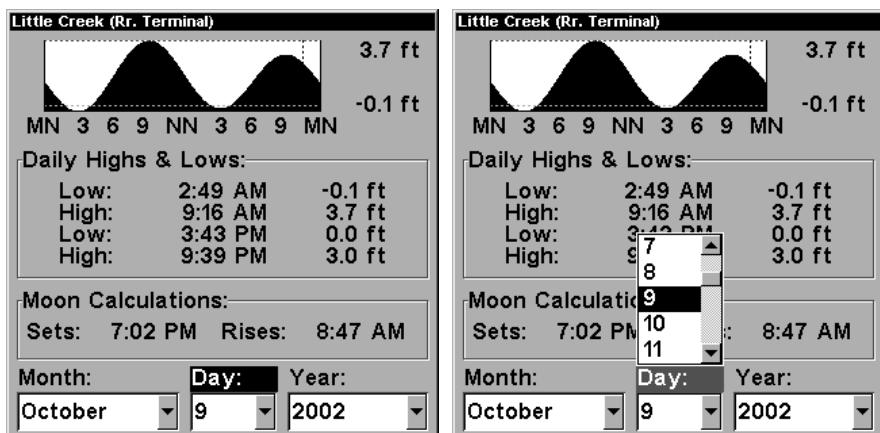
### To view tide information:

1. Select a Tide Station icon: use the arrow keys to move the cursor over an icon. When it is selected, a pop-up name box appears.
2. After selecting the Tide Station icon, press **WPT** to display the Tide Information screen.



Navionics chart showing Tide Station icon selected by cursor.

In the example above, the tide is at 2.8 feet and falling, as shown by the down arrow at the top of the icon.



#### Tide Information screen.

The Tide Information screen displays daily tidal data for the station at the present time. The graph at the top of the screen is an approximate view of the tidal range pattern for the day, from midnight (MN), to noon (NN) to midnight (MN). The dotted line across the graph is the Mean Lower Low Water line (MLLW).

The height scale on the top right side of the graph changes, based upon the maximum *range* of the tide for that day. The MLLW line also adjusts its position as the height scale changes.

You can look up tidal data for other dates by changing the month, day and year selection boxes. To select another date:

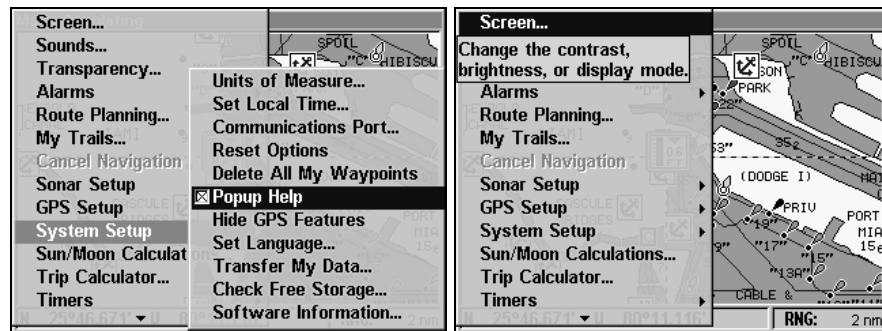
1. Use → and ← to highlight month, day or year, then press **ENT**.
2. Use ↑ and ↓ to select the desired month, day or year, then press **ENT**.

To clear the information screen, press **EXIT**.

## Pop-up Help

Help is available for virtually all of the menu labels on this unit. By highlighting a menu item and leaving it highlighted for a few seconds, a "pop-up" message appears that describes the function of the menu item. This feature is on by default.

**To set up Popup Help:** Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ↓** to **POPUP HELP**. With the option highlighted, press **ENT** to check it (turn on) or uncheck it (turn off.) After the option is set, press **EXIT|EXIT** to return to the page display.



System Setup menu (left) with Pop-up Help command highlighted. The example on the right shows the Pop-up Help message for the Screen command, located on the Map Menu.

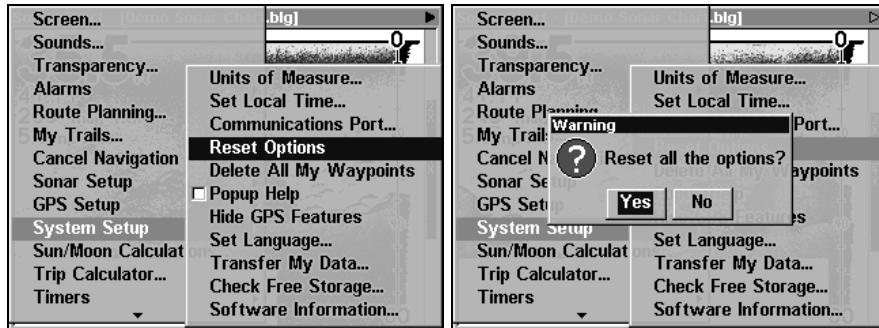
## Reset Options

To reset all features to their factory defaults:

Press **MENU** | **MENU** | **↓** to **SYSTEM SETUP** | **ENT** | **↓** to **RESET OPTIONS** | **ENT** | **←** to **YES** | **ENT**.

## NOTE:

Reset Options does *not* erase any waypoints, routes, icons, plot trails or sonar logs.



Reset Options command (left)  
and the Reset Options Menu (right).

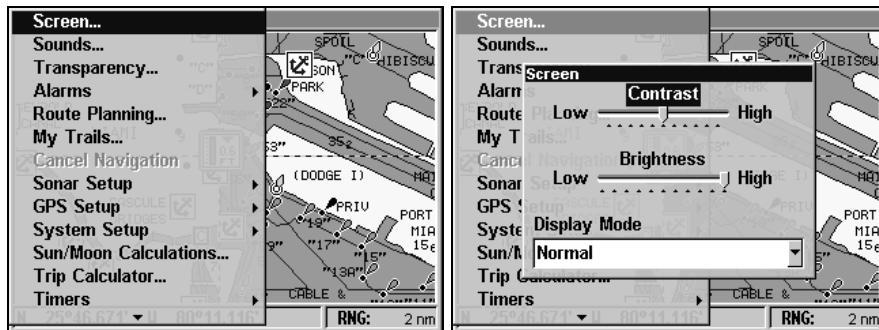
## Screen Contrast and Brightness

To access the Screen menu, press **MENU | MENU | ENT.**

### Once in the Screen menu:

To adjust the display's contrast:

The **CONTRAST** slider bar is already selected. Press  $\rightarrow$  or  $\leftarrow$  to move the bar. The left end of the scale is minimum contrast; the right end is maximum contrast.



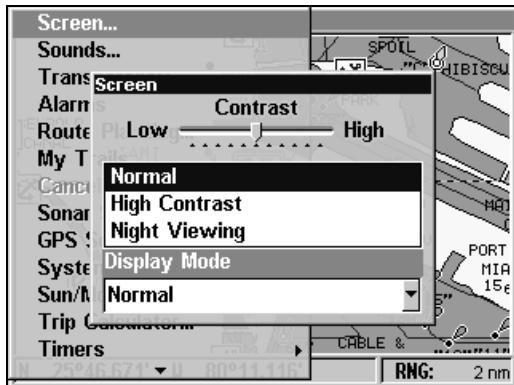
Screen Command (left) and Screen Menu with Contrast selected, (right).

To adjust the display's brightness:

Press  $\downarrow$  to **BRIGHTNESS**. Press  $\rightarrow$  or  $\leftarrow$  to move the bar. The left end of the scale is minimum contrast; the right end is maximum contrast.

To adjust the screen's display mode:

Press  $\downarrow$  to **DISPLAY MODE | ENT|** press  $\uparrow$  or  $\downarrow$  to select *mode* | **EXIT**.



Display Mode menu.

## Set Language

This unit's menus are available in 10 languages: English, French, German, Spanish, Italian, Danish, Swedish, Russian, Dutch and Finnish. To select a different language:

1. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT**.
2. Press **↓** to **SET LANGUAGE | ENT**.
3. Use **↓** or **↑** to select a different language and press **ENT**. All menus now appear in the language you selected.

## Set Local Time

Using the correct local time setting is handy when estimating local arrival time while navigating. Also, the time and date are saved when a waypoint is created.

To access the Set Local Time menu, you must first acquire your position. Once that is done: press **MENU|MENU|↓** to **SYSTEM SETUP | ENT|↓** to **SET LOCAL TIME | ENT**.

### Once in the Time Settings menu:

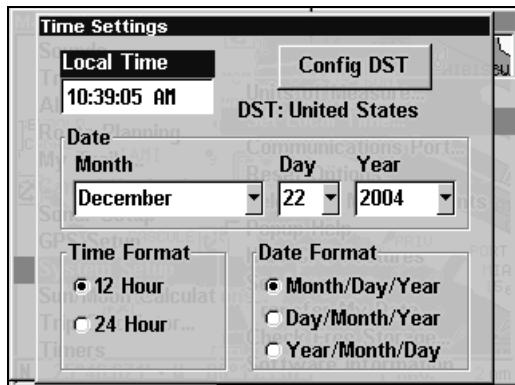
**To set Local Time:** Press **ENT**. Press **↑** or **↓** to change the first character, then press **→** to move the cursor to the next character. Repeat until the time is correct, then press **ENT**.

**To set the Month:** Press **↓** to **MONTH|ENT**. Press **↑** or **↓** to select the month, then press **ENT**.

**To set the Day:** Press **→** to **DAY|ENT**. Press **↑** or **↓** to select the day, then press **ENT**.

**To set the Year:** Press **→** to **YEAR|ENT**. Press **↑** or **↓** to select the year, then press **ENT**.

You also may switch the Time Format between 12 and 24 hour options. The Date Format also may be modified between three options: Month/Day/Year, Day/Month/Year and Year/Month/Day.



**Time Settings Menu.**

At the top right of the menu is the **CONFIG DST** button. This feature allows your unit to automatically adjust with the time change caused by Daylight Saving Time (you should only have to set it once). You may select which set of rules matches DST in your region, or simply accept the default.

Once you have each field set the way you want, press **EXIT** repeatedly until you return to the previous page.

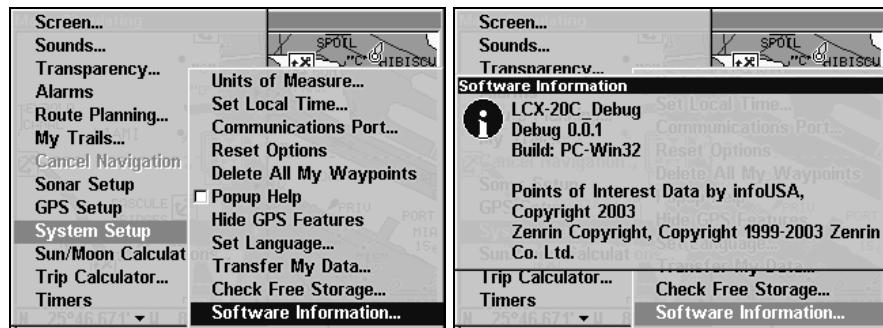
## Show WAAS Alarm

When the signal is available, your unit will automatically use WAAS to boost the accuracy of the position fix. When the WAAS signal is lost or acquired, an alarm message appears. Since the U.S. government is still developing the WAAS system, it's not unusual for a GPS/WAAS receiver to frequently lose and reacquire its lock on a WAAS satellite. That can result in the alarm repeatedly going on and off. You have the option of turning off the WAAS Acquired/Lost alarm without affecting how the unit uses WAAS. Here's how:

1. Press **MENU|MENU|↓** to **GPS SETUP | ENT|↓** to **Show WAAS ALARM**.
2. With the option highlighted, press **ENT** to uncheck it (turn off) or check it (turn on). After the option is set, press **EXIT|EXIT** to return to the page display.
3. You can return to this command and press **ENT** again to turn the feature on.

## Software Version Information

From time to time, Lowrance updates the operating system software in some of its products. These software upgrades are usually offered to customers as free downloads from our web site, [www.lowrance.com](http://www.lowrance.com). These upgrades make the unit perform better or introduce a new feature or function. You can find out what software version is running in your Unit by using the Software Information command.



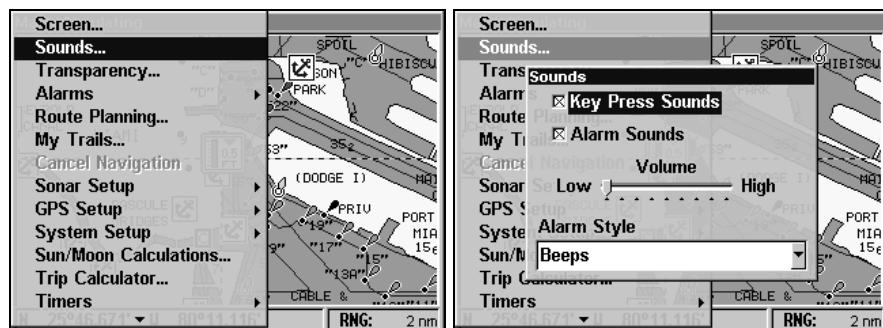
Software Information command (left); Software Information (right).

1. Press **MENU | MENU | ↓** to **SYSTEM SETUP | ENT | ↓** to **SOFTWARE INFO | ENT**.
2. Read the information displayed on the screen.
3. To return to the last page displayed, press **EXIT | EXIT | EXIT**.

## Sounds and Alarm Sound Styles

Sounds triggered by key strokes and alarms can be adjusted:

You first press **MENU | MENU | ↓** to **SOUNDS | ENT**.



Sounds command (left); The Sounds menu (right).

### Once in the Sounds menu

**To set Key Press Sounds:** With the option highlighted, press **ENT** to check it (turn on) or uncheck it (turn off). After the option is set, press **EXIT | EXIT** to return to the page display.

**To set Alarm Sounds:** Press ↓ to **ALARM SOUNDS**. With the option highlighted, press **ENT** to check it (turn on) or uncheck it (turn off). After the option is set, press **EXIT|EXIT** to return to the page display.

**To set Alarm Volume:** Press ↓ to **VOLUME**. Press → or ← to move the bar. The left end of the scale is low volume; the right end is high volume. After the option is set, press **EXIT|EXIT** to return to the page display.

**To set Alarm Style:** Press ↓ to **ALARM STYLE | ENT**. Press ↑ or ↓ to change the style, then press **ENT**. After the option is set, press **EXIT|EXIT** to return to the page display.

## Track Smoothing

This is a factory setting on the GPS Setup menu that *should always be left on*. When stopped or traveling at slow speeds (such as walking or trolling), Track Smoothing prevents wandering of trails, the steering arrow, compass rose and a map in track-up mode.



Track Smoothing option, turned on.

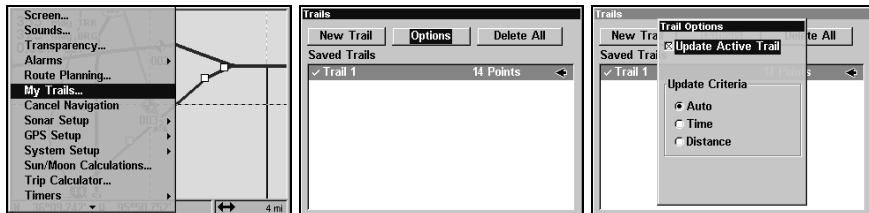
## Trail Options

There are several options you can use with trails. Some affect all trails, other options can be applied to a particular trail. You can change the way trails are updated and the way they're displayed. Trails also may be hidden, created or deleted in the trail menu.

### General Trail Options

To access the Trails Menu:

Press **MENU|MENU|↓ to **MY TRAILS|ENT****.



**My Trails** command (left); **Trails** Menu (left); **Trail Options** (right).

## Delete All Trails

To remove all of the trails from memory: from the Trails Menu, press → to **DELETE ALL** | **ENT** | ← to **Yes** | **ENT**.

## Update Trail Option

This menu lets you change the way the trail updates occur.

### WARNING:

If you *uncheck* the **Update Trail** option, automatic trail creation and recording will be turned *off*. You must turn it back on to record trails. The default setting is *on*.

From the Trails Menu, press → to **OPTIONS** | **ENT**. With **UPDATE ACTIVE TRAIL** highlighted, press **ENT** to check it (turn on) or uncheck it (turn off).

### Update Trail Criteria (Auto, Time, Distance)

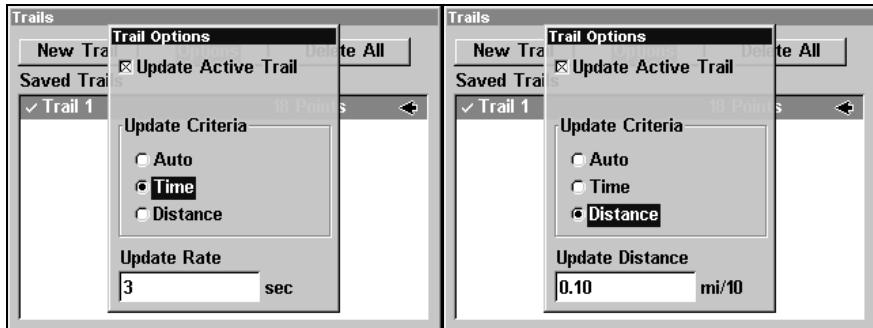
The options are automatic, time, or distance. When it's in the default automatic mode, the unit doesn't update the plot trail while you're traveling in a straight line. Once you deviate from a straight line, the unit "drops" a plot point (trail waypoint) onto the trail. This conserves plot trail points. If a plot trail uses all of the available points allotted to it, the beginning points are taken away and placed at the end of the trail.

From the Trails Menu, press → to **TRAIL OPTIONS** | **ENT** | ↓ to **UPDATE CRITERIA**. Press ↑ or ↓ to select *criteria type* | **ENT**. If you selected Time, the Update Rate data entry box appears on the menu. If you selected Distance, the Update Distance data entry box appears on the menu.

### Trail Update Rate (Time, Distance)

You can update a trail by time, with a range from 1 second to 9999 seconds; the default is 3 seconds. You can update by distance, with a range from 0.01 mile/nm/km to 9.99 mile/nm/km; the default is 0.10 miles.

With one of the Update Criteria selected, use the cursor arrows to highlight either the **UPDATE TIME** or **UPDATE DISTANCE** data entry boxes and press **ENT**. Press ↑ or ↓ to change the first character, then press → to the next character and repeat until the entry is correct. Press **EXIT** to return to the Trail Options Menu.

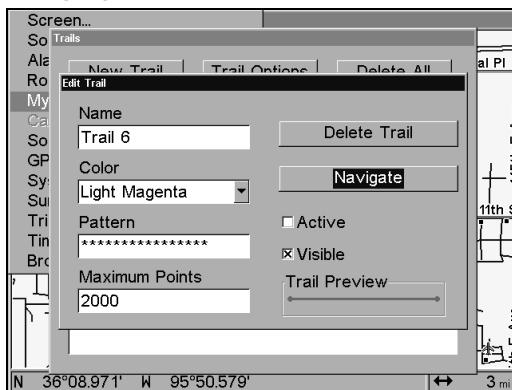


Update Time Rate setting (left) and Update Distance setting (right).

### Specific Trail Options

#### Delete Trail

To delete a specific trail: From the Trails Menu, press **↓** to **Saved Trails|ENT**. Select a trail and press **ENT**. The Edit Trail menu appears as seen in the following figure. Press **→** to **DELETE TRAIL|ENT|←|YES|ENT**.



Edit Trail menu.

#### New Trail

To manually start a new trail in the Trails Menu make sure **NEW TRAIL** is highlighted and press **ENT|EXIT**.

#### Trail Visible/Invisible and Other Trail Options

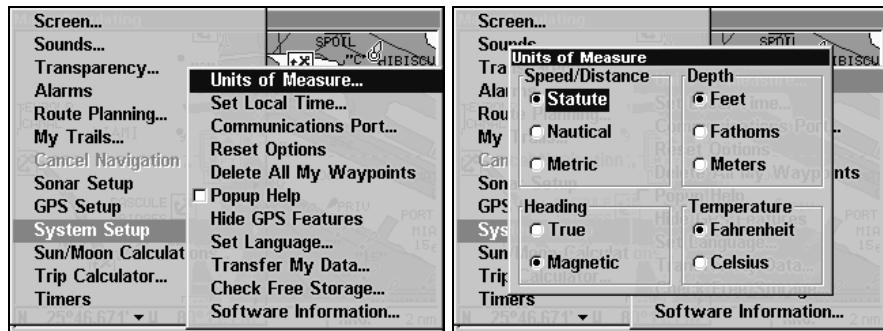
The name, maximum number of points in the trail, activity, and visibility are all changed on the Edit Trail menu screen. The Active setting determines whether or not the unit is recording new points for a particular trail.

On the Edit Trail menu, press **↓** or **↑** to highlight the section you wish to change, then press **ENT**. Make your changes, then press **EXIT** to close this menu.

## Units of Measure

This menu sets the speed and distance (statute or nautical miles, meters), depth (feet, fathoms, or meters), temperature (degrees Fahrenheit or Celsius) and heading (true or magnetic) units. To change the units:

Press **MENU|MENU|↓** to **SYSTEM SETUP | ENT|ENT**.



System Setup Menu (left); Units of Measure Menu (right).

**To set Speed/Distance Unit of Measure:** Press **↑** or **↓** to change the Speed/Distance, then press **ENT**. After the option is set, press **EXIT|EXIT|EXIT** to return to the page display.

**To set Heading:** Press **↑** or **↓** to change the heading type, then press **ENT**. After the option is set, press **EXIT|EXIT|EXIT** to return to the page display.

**To set Depth:** Press **→** to **DEPTH**. Press **↑** or **↓** to change the heading type, then press **ENT**. After the option is set, press **EXIT|EXIT|EXIT** to return to the page display.

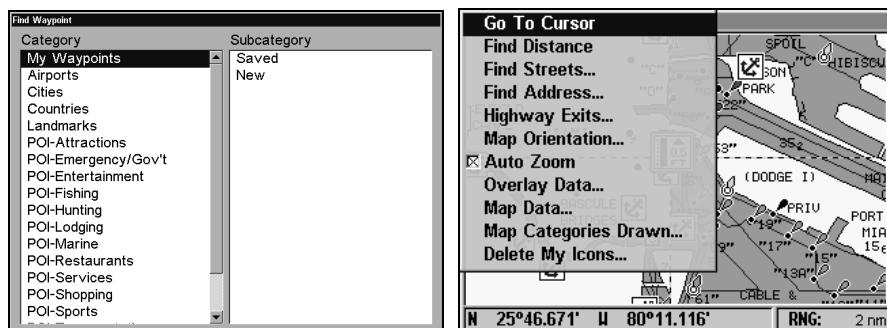
**To set Temperature:** Press **→** to **TEMPERATURE**. Press **↑** or **↓** to change the heading type, then press **ENT**. After the option is set, press **EXIT|EXIT|EXIT** to return to the page display.

## Section 9: Searching

### NOTE:

The background map loaded in your unit lets you search for U.S. Interstate Highway exits and exit services, as well as some land features, including cities and lakes. For a full set of searchable land features, including landmarks, streets, addresses and Points of Interest, you must load your own high-detail custom map produced with our MapCreate 6 software.

The unit's varied search functions all begin with either the Find Waypoint menu or the Map Page menu. Press **WPT** and the Find Waypoint menu appears for waypoints and Points of Interest (POI). From the Map Page, press **MENU** and the Map Page menu appears for streets, addresses and highway exits.



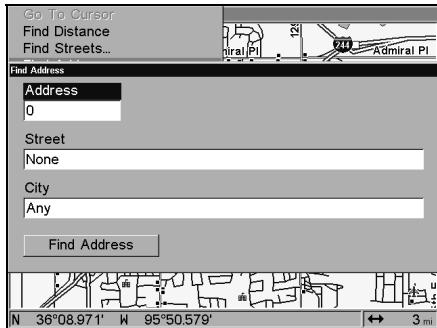
Find Waypoint menu (left) and Map Page menu (right).

### NOTE:

You can search for items after the unit has acquired a position, or while using it in the simulator mode. Distance and bearing to the selected item will be calculated from the unit's current position, or the last known position. You can look up items by name, or search for the item nearest to you.

### Find Addresses

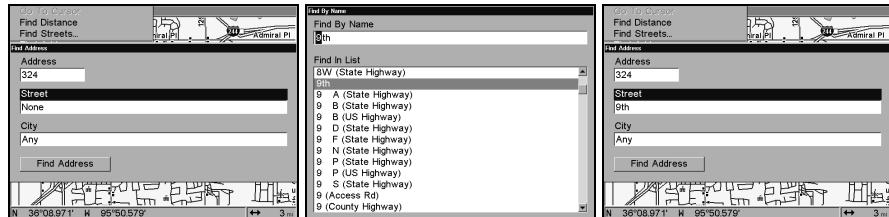
1. From the Map Page, press **MENU**↓ to **FIND ADDRESS** | **ENT**.
2. Press **ENT** to search in the Address field.



### Find Address Menu.

3. **To enter an address**, press  $\uparrow$  or  $\downarrow$  to change the first number, then press  $\rightarrow$  to move the cursor to the next number and repeat until the number is correct, then press **ENT**.

4. **To enter a street name**, press  $\downarrow$  to **STREET|ENT**. There are two options: **A**. You can spell out the name in the top selection box. Press  $\uparrow$  or  $\downarrow$  to change the first letter, then press  $\rightarrow$  to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B**. Or jump down to the lower selection list by pressing **ENT**, then press  $\downarrow$  or  $\uparrow$  to select a street name from the list and press **ENT**. The street name you selected is now in the street field.



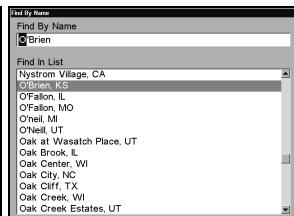
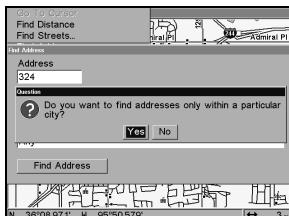
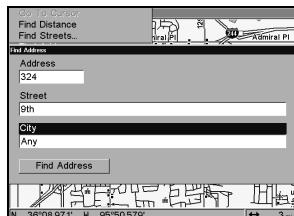
Find Address menu (left); Find Street menu (center) with Find By Name field active; street name entry complete (right).

5. **To enter a city name**, press  $\downarrow$  to **City|ENT**. You will be asked if you want to find addresses only within a particular city. This option is designed to limit an address search to a single city if necessary.

If you select yes, there are two options: **A**. You can spell out the city name in the top selection box. Press  $\uparrow$  or  $\downarrow$  to change the first letter, then press  $\rightarrow$  to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B**. Or jump down to the lower selection list by pressing **ENT**, then press  $\downarrow$  or  $\uparrow$  to select a city name from the list, then press **ENT**. The city name you selected is now in the city field.

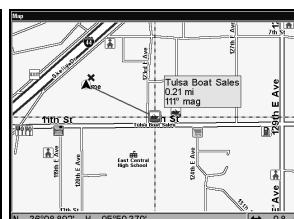
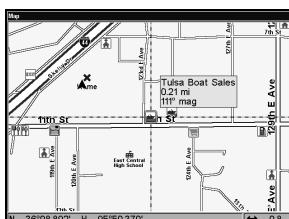
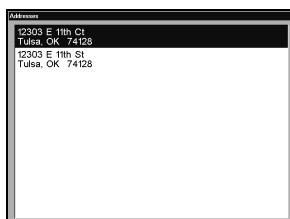
## NOTE:

We recommend you do *not* enter a city name unless the list is too long to search through. The unit can actually search quicker when you don't enter a city name.



**Find city field (left); search in particular city only option (center); Find City by name (right).**

6. When the necessary search fields are filled in, press **↓** to **FIND ADDRESS|ENT**. Your unit asks you to wait while it searches for the address. (If an address is not in the database, a message appears saying the address could not be found.)
7. The unit will display a list of addresses. If the address you are looking for is highlighted at the top of the list, press **ENT**. If not, use **↓** and **↑** to select the correct address from the list, then press **ENT**. The Map Page will then appear with the location selected by the cursor. (In the example below, we are looking for 12303 East 11th Street in Tulsa, not 11th Court, so we had to scroll down the list to select the right one.)



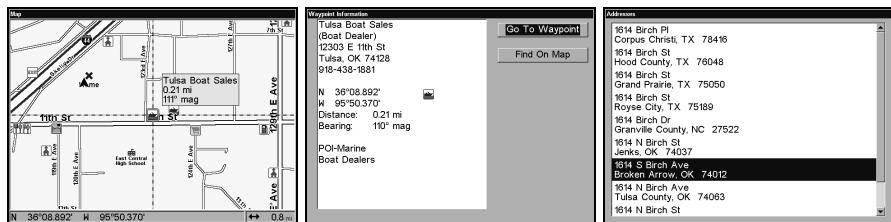
**Address search result list (left); Map Page showing location of the address on the map, highlighted by cursor (center). After the address is located, you can navigate to it (right).**

8. To navigate to the address, press **MENU|ENT|EXIT** and your unit will begin showing navigation information to the address pointed out by the cursor. If you are only looking up an address (not navigating), just press **EXIT** to return to the previous page.

### **Tip:**

If the address also happens to be an item in the Point of Interest database, you can look up the item's phone number in the Waypoint Information list. With the address location selected by the cursor on

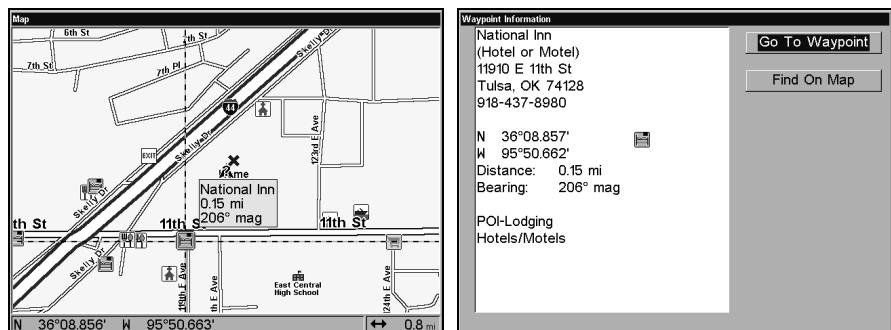
the map, press **WPT**. The POI's Waypoint Information window appears, with the Go To Waypoint command highlighted. If you want to go ahead and navigate to the POI address, just press **ENT|EXIT**.



Map Page showing location of the address on the map, highlighted by cursor (left). This address is a business in the POI database, so you can display the POI information window, then navigate to it (center). This address is not in the POI database, so the Waypoint key will not display any information for this address (right).

## Find Any Item Selected by Map Cursor

On the Map Page: with a POI or map feature selected by the cursor press **WPT**. To return to the previous page, press **EXIT**.



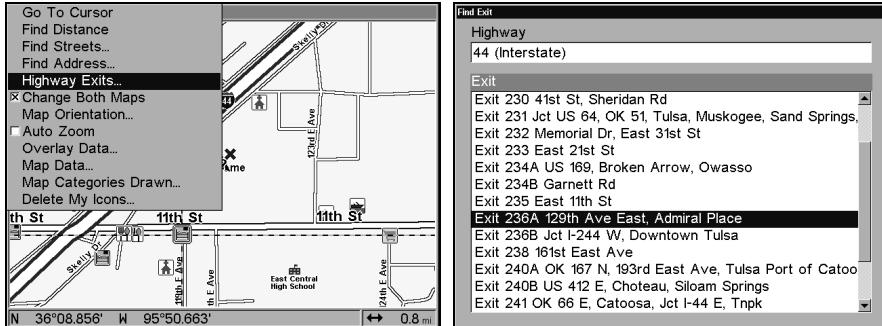
A POI selected by the cursor (left); POI information screen (right).

### NOTE:

Since the Go To Waypoint command is highlighted, you can navigate to the selected POI by pressing **ENT|EXIT** while in the POI Waypoint Information screen.

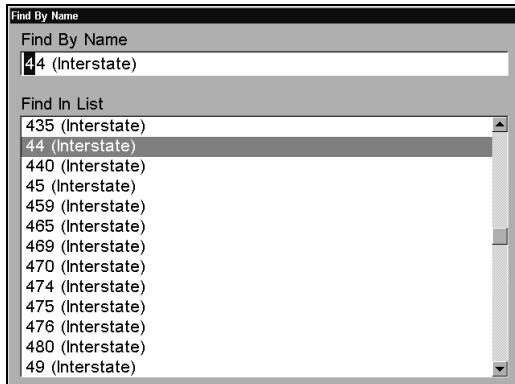
## Find Interstate Highway Exits

1. From the Map Page, press **MENU|↓** to **HIGHWAY EXITS | ENT**, which calls up the **FIND EXIT** menu.



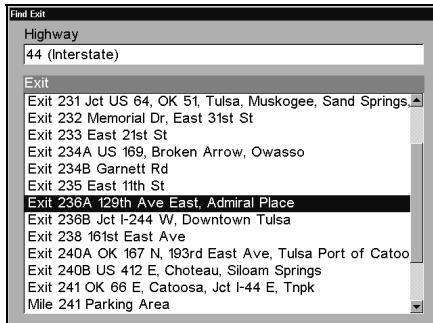
Find Highway Exits command (left) and Find Exit menu (right).

2. First, select a highway name by pressing **ENT**, which calls up the **FIND BY NAME** menu. There are two highway search options: **A.** You can spell out the highway name in the top selection box. Press **↑** or **↓** to change the first letter, then press **→** to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B.** Or jump down to the lower selection list by pressing **ENT**, then press **↓** or **↑** to select a highway from the list, then press **ENT**.



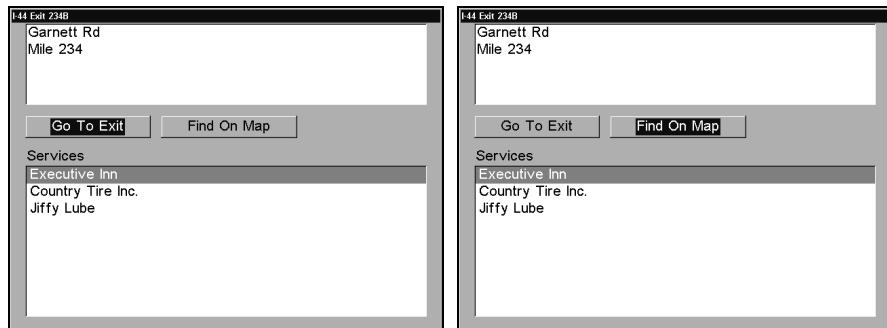
Find By Name menu.

3. Once you have selected a highway name you can then select an exit. Press **↓** to switch to the Exit List, then press **↓** or **↑** until you highlight the exit, then press **ENT**.



### Find Exit menu, with an exit selected in the Exit List.

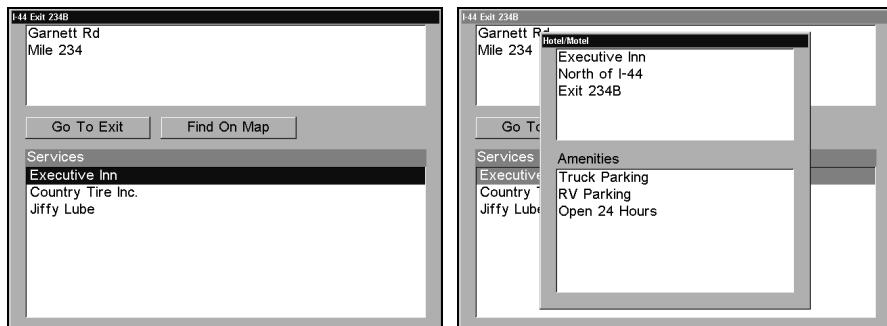
4. In the Exit Information screen you have two choices. **A.** Press **ENT** to navigate or "go to" the exit. **B.** Press **→|ENT** to find the exit on the map.



Go To Exit option (left); Find On Map option (right).

#### Tip:

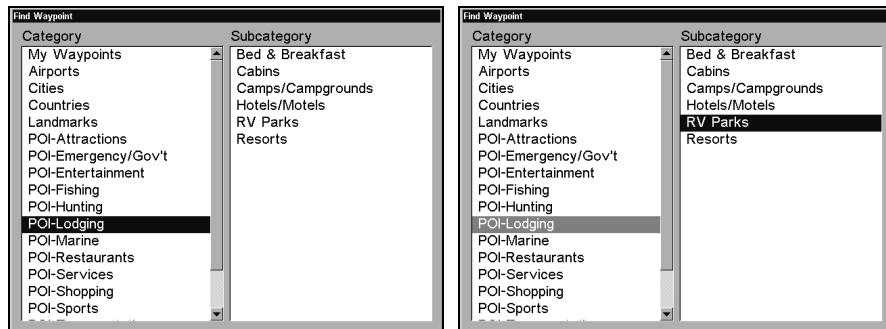
You can also look up some additional information on the Exit Services located near this exit. Press **↓** to **SERVICES** then **↓** or **↑** to select **Service Name | ENT**.



Exit Information screen (left); general location and amenities information (right).

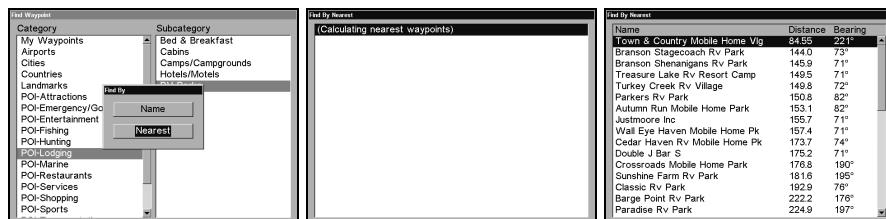
## Find Map Places or Points of Interest (POI)

1. Press **WPT**, press  $\downarrow$  or  $\uparrow$  to select a map place or POI category, then press **ENT**. (To narrow your search, press  $\rightarrow$  then press  $\downarrow$  or  $\uparrow$  to select a subcategory before pressing **ENT**.) You will be given two options; **SEARCH BY NAME** or **BY NEAREST**.



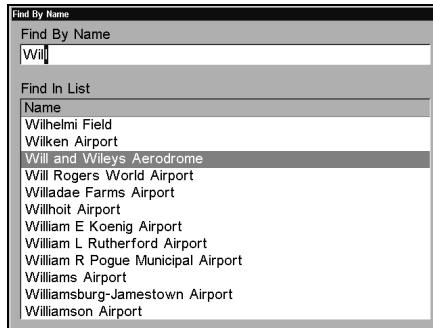
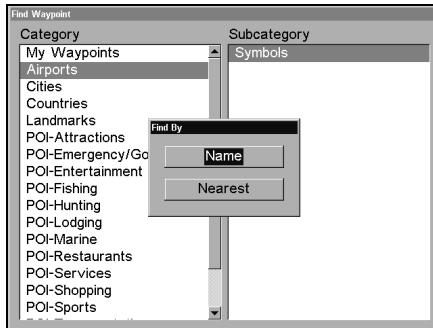
Find Waypoint menu with Lodging POI category selected (left) and with the RV Parks subcategory selected (right).

2. **Search by nearest POI.** Press  $\downarrow$ |**ENT**. The **FIND BY NEAREST** menu will show a calculating screen, then a list of the nearest POI's will appear. Press  $\downarrow$  or  $\uparrow$  to the selected POI and press **ENT** to call up the POI's Waypoint Information screen.



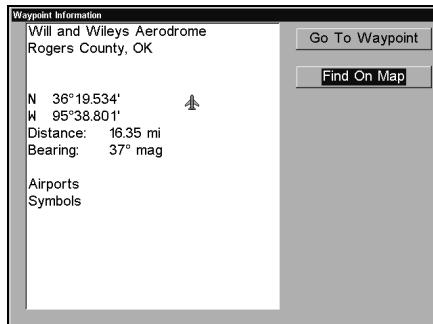
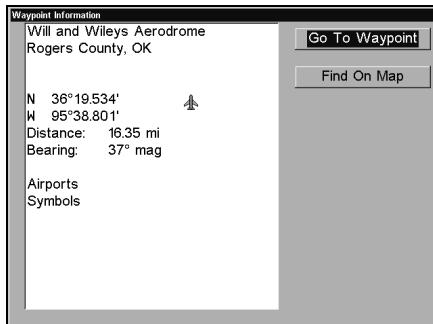
Find by Nearest (left); Calculating screen (center); POI list, (right).

3. **Search by name of POI.** Press **ENT**. There are two options: **A.** You can spell out the POI in the top selection box. Press  $\uparrow$  or  $\downarrow$  to change the first letter, then press  $\rightarrow$  to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B.** Or jump down to the lower selection list by pressing **ENT**, then  $\downarrow$  or  $\uparrow$  to select a POI from the list, then press **ENT** to call up the POI's Waypoint Information screen.



Find by Name option (left); Find by Name menu (right).

4. When the POI's Waypoint Information screen is displayed, you can choose to **Go To** the POI waypoint by pressing **ENT** or find it on the map by pressing→|**ENT**.

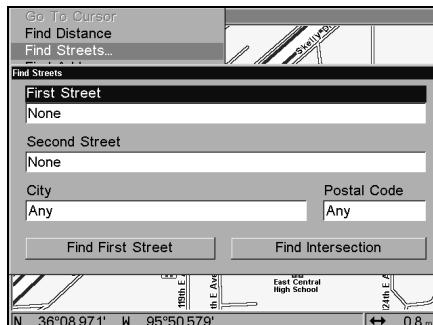
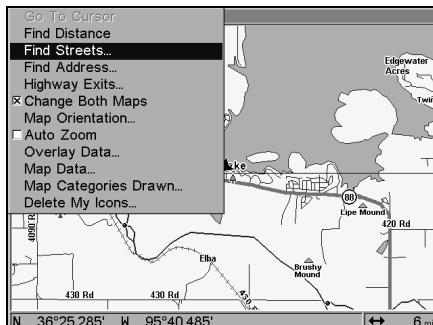


Go To Waypoint POI option (left); Find on Map POI option (right).

## Find Streets or Intersections

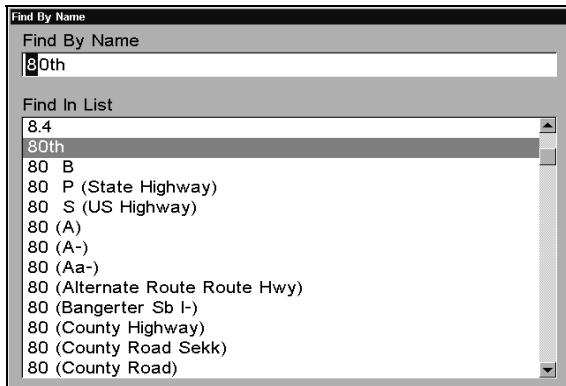
### Find a Street

1. From the Map Page, press **MENU**|↓ to **FIND STREETS** | **ENT** and the Find Streets Menu appears.



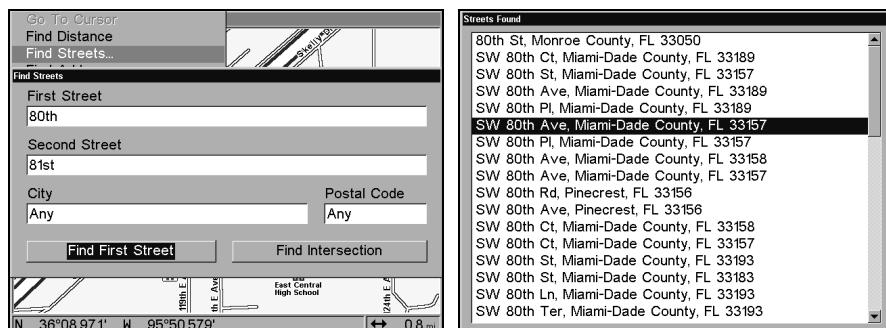
Find Streets command (left); Find Streets menu (right).

2. You must first fill in a street name in the First Street dialog box. Press **ENT** to display the **FIND BY NAME** menu. There are two options: **A.** You can spell out the street in the top selection box. Press  $\uparrow$  or  $\downarrow$  to change the first letter, then press  $\rightarrow$  to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B.** Or you can jump down to the lower box and pick a street from the selection list. Press **ENT**, then press  $\downarrow$  or  $\uparrow$  to select a street from the list and press **ENT**.



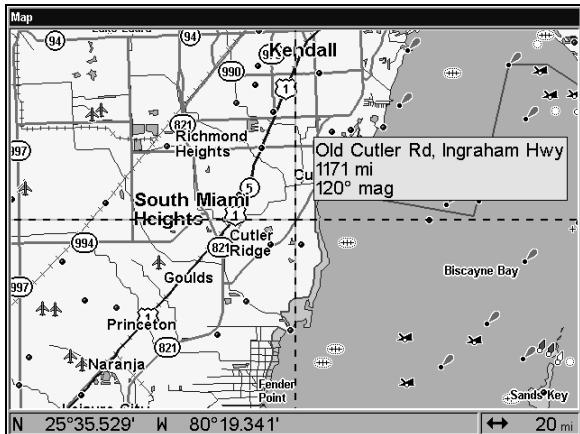
**Find Street By Name menu. Spell out name in the top box, or select from the list in the lower box.**

3. The Find Streets menu reappears with the street you're searching for in the First Street box. (In this example, it's 80th Street.) To search for that street, press  $\downarrow$  to find **FIRST STREET |ENT**. A message appears asking you to wait while the unit finds the street. When the Streets Found list appears, press  $\uparrow$  or  $\downarrow$  to select the street you are searching for and press **ENT**.



**The Find Streets menu (left) with the Find First Street command highlighted. Streets Found list (right).**

4. The Map Page appears, with the cursor pointing to the found street.



**Map Page showing results of a street search.  
The cursor points to the located street.**

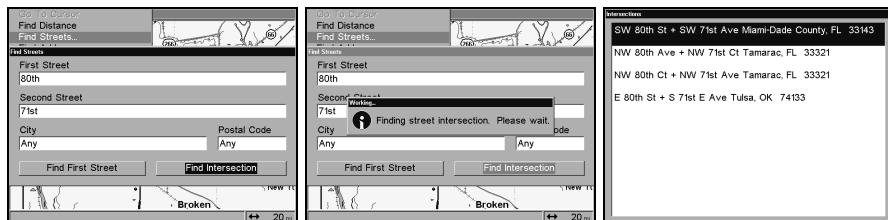
If you want to navigate to the found street at the cursor location, just press **MENU|ENT|EXIT**.

### Find an Intersection

You must enter one street in the First Street dialog box and enter the next street in the Second Street dialog box.

1. From the Map Page, press **MENU|↓** to **FIND STREETS|ENT** and the **FIND STREETS** menu appears.
2. You must fill in a street name in the First Street dialog box. Press **ENT** to display the **FIND BY NAME** menu. There are two options: **A**. You can spell out the street in the top selection box. Press **↑** or **↓** to change the first letter, then press **→** to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B**. Or you can jump down to the lower box and pick a street from the selection list. Press **ENT**, then press **↓** or **↑** to select a street from the list and press **ENT**.
3. The Find Streets menu reappears with the street you're searching for in the First Street box. (In this example, it's 80th Street.)
4. Now fill in the second street. Press **↓** to **SECOND STREET|ENT** and the **FIND BY NAME** menu appears again. Just like before, there are two options: **A**. You can spell out the second street in the top selection box. Press **↑** or **↓** to change the first letter, then press **→** to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B**. Or you can jump down to the lower box and pick the second street from the selection list. Press **ENT**, then press **↓** or **↑** to select a street from the list and press **ENT**.

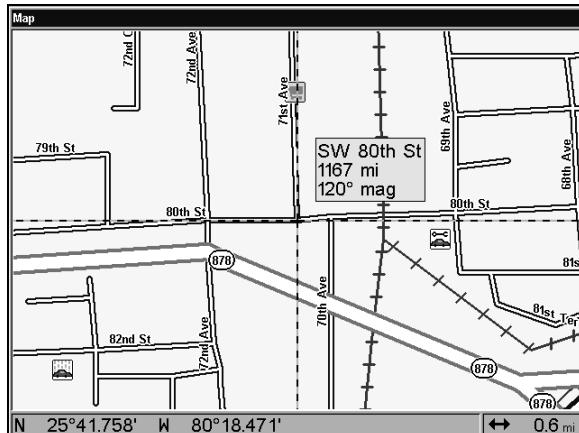
5. The Find Streets menu reappears with the first and second street dialog boxes filled in. In this example, we selected 71st Street as our second street. You could now use similar techniques to select a city or Zip code, but your search will probably be faster if you leave those boxes blank. (You can specify a city and/or Zip code later on to narrow the search, if the resulting list is too long.)



**Find Intersection command highlighted (left) and Working message (center). The Intersections Found list (right).**

6. To search for the intersection of the two streets, press ↓ to **FIND INTERSECTION|ENT**. A message appears asking you to wait while the unit finds the intersection. When the **INTERSECTIONS FOUND** list appears, press ↑ or ↓ to select the intersection you are searching for and press **ENT**. (In the example on the previous page, we selected the intersection of SW 80th Street and SW 71st Avenue in Miami, Fla.)

7. The Map Page appears, with the cursor pointing to the found intersection. The intersection in our example is shown below.



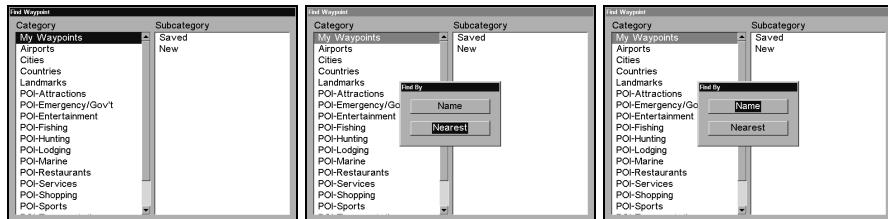
**Map Page showing results of an intersection search.  
The cursor points to the located intersection.**

If you want to navigate to the found intersection, just press **MENU|ENT|EXIT**.

## Find Waypoints

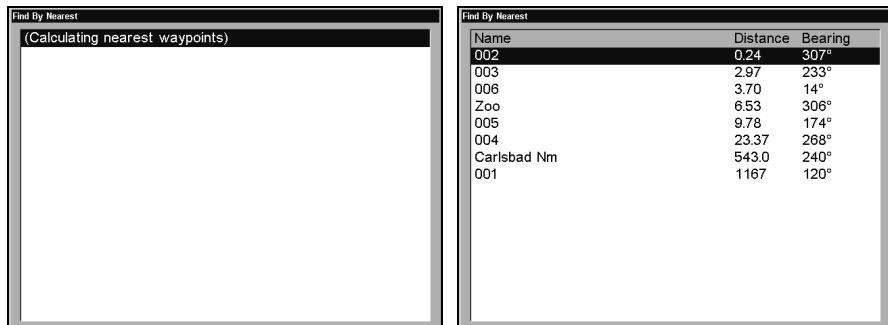
1. Press **WPT|ENT**.

2. If searching for the waypoint **By Name**, press **ENT**. If searching for the **Nearest** waypoint, press **↓** to **NEAREST|ENT**. (To search by name, jump to step 5 below.)



Find Waypoint menu (left); Find By Nearest command (center); Find by Name command (right).

3. If you're looking for **nearest**, the unit says it is calculating, then a list of waypoints appears. The location closest to you is highlighted at the top of the list and the one farthest from you is at the bottom of the list.

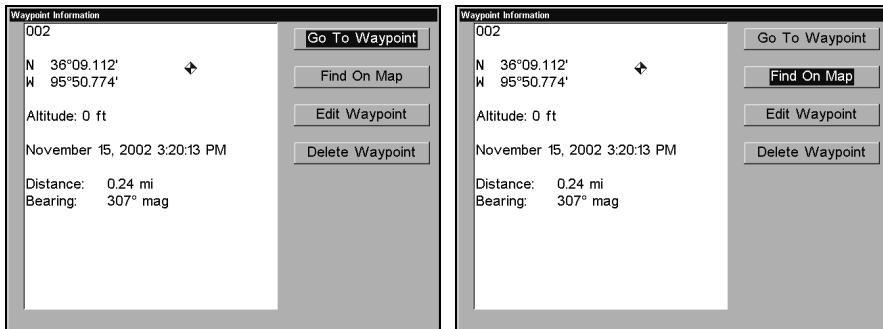


Calculating message (left) and list of the nearest waypoints (right).

4. To see location information on the closest waypoint, press **ENT** and the Waypoint Information screen appears. (If you wanted, you could select another waypoint from the list with the **↑** or **↓** keys.)

A. **To navigate** to the waypoint, press **ENT**. (The Go To Waypoint command is already highlighted.) The unit will show navigation information to the waypoint.

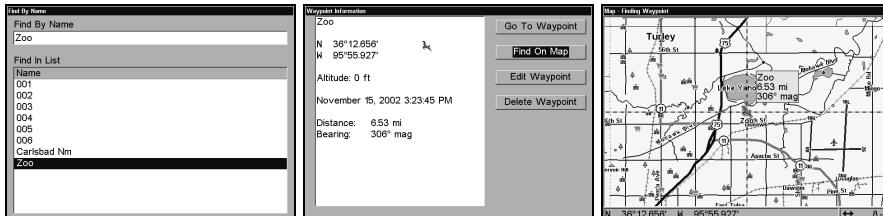
B. **To find** the waypoint, press **↓** to **FIND ON MAP|ENT**. The Map Page appears with the cursor highlighting the found waypoint.



**Waypoint Information screens with the Go To Waypoint command selected (left) and the Find on Map command selected (right).**

To clear these menus and return to the previous page, press **EXIT** repeatedly.

5. **If you're looking by name**, there are two options: **A**. You can spell out the name in the top selection box. Press  $\uparrow$  or  $\downarrow$  to change the first letter, then press  $\rightarrow$  to move the cursor to the next letter and repeat until the name is correct, then press **ENT|ENT**. **B**. Or you can jump down to the lower selection list by pressing **ENT**, then press  $\downarrow$  or  $\uparrow$  to select a waypoint from the list, then press **ENT**. The waypoint information screen appears.



**Find By Name menu (left); Waypoint Information screen (center); The found waypoint is highlighted by the cursor on the Map Page (right).**

**A. To navigate** to the waypoint, press **ENT**. (Go To Waypoint command is already highlighted.) The unit will show navigation information to the waypoint.

**B. To find** the waypoint, press  $\downarrow$  to **FIND|ENT**. The Map Page appears with the cursor highlighting the found waypoint.

To clear these menus and return to the previous page, press **EXIT** repeatedly.

# Notes

# Section 10: Supplemental Material

## Datums Used by This Unit

WGS 1984 Default	Arc 1950 - Botswana	Bermuda 1957 - Bermuda
Adindan Mean for Ethiopia, Sudan	Arc 1950 - Burundi	Bissau - Guinea-Bissau
Adindan Burkina Faso	Arc 1950 - Lesotho	Bogota Observatory - Colombia
Adindan Cameroon	Arc 1950 - Malawi	Bukit Rimpah - Indonesia (Bangka & Belitung Islands)
Adindan Ethiopia	Arc 1950 - Swaziland	Camp Area Astro - Antarctica (McMurdo Camp Area)
Adindan Mali	Arc 1950 - Zaire	Campo Inchauspe - Argentina
Adindan Senegal	Arc 1950 - Zambia	Canton Astro 1966 - Phoenix Islands
Adindan Sudan	Arc 1950 - Zimbabwe	Cape - South Africa
Afgooye Somalia	Arc 1960 - Mean for Kenya, Tanzania	Cape Canaveral - Bahamas, Florida
Ain el Abd 1970 Bahrain	Ascension Island 1958 - Ascension Island	Carthage - Tunisia
Ain el Abd 1970 Saudi Arabia	Astro Beacon E 1945 - Iwo Jima	Switzerland
Anna 1 Astro 1965 Cocos Islands	Astro DOS 71/4 - St. Helena Island	Chatham Island Astro 1971; New Zealand (Chatham Island)
Antigua Island Astro 1943; Antigua (Leeward Islands)	Astro Tern Island (FRIG) 1961 - Tern Island	Chua Astro Paraguay
Arc 1950; Mean for Botswana, Lesotho, Malawi, Swaziland, Zaire, Zambia and Zimbabwe	Astronomical Station 1952 - Marcus Island	Corrego Alegre Brazil
	Australian Geodetic 1966 - Australia & Tasmania	Dabola Guinea
	Australian Geodetic 1984 - Australia & Tasmania	Djakarta (Batavia) Indonesia (Sumatra)
	Ayabelle Lighthouse - Djibouti	
	Bellevue (IGN) - Efate & Erromango Islands	

DOS 1968	European 1950	Mahe Island	
New Georgia Islands (Gizo Island)	Italy (Sardinia)	Massawa Ethiopia (Eritrea)	
Easter Island 1967 Easter Island	European 1950 (Sicily)	Merchich Morocco	
European 1950 Mean for Austria, Belgium, Denmark, Finland, France, West Germany, Gibraltar, Greece, Italy, Luxembourg, Netherlands, Norway, Portugal, Spain, Sweden, Switzerland	European 1950 Malta	Midway Astro 1961 Midway Islands	
European 1950 Mean for Austria, Denmark, France, West Germany, Netherlands, Switzerland	Ireland 1965 Ireland	Minna Cameroon	
European 1950 Mean for Iraq, Israel, Jordan, Lebanon, Kuwait, Saudi Arabia, Syria	ISTS 061 Astro 1968 South Georgia Islands	Minna Nigeria	
European 1950 Mean for Iraq, Israel, Jordan, Lebanon, Kuwait, Saudi Arabia, Syria	ISTS 073 Astro 1969 Diego Garcia	Johnston Island 1961 Johnston Island	Montserrat Island Astro 1958; Montserrat (Leeward Islands)
European 1950 Mean for Iraq, Israel, Jordan, Lebanon, Kuwait, Saudi Arabia, Syria	Kandawala Sri Lanka	Kerguelen Island 1949 Kerguelen Island	M'Poraloko Gabon, Nahrwan, Oman (Masirah Island)
European 1950 Mean for Iraq, Israel, Jordan, Lebanon, Kuwait, Saudi Arabia, Syria	Kertau 1948 West Malaysia & Singapore	Nahrwan Saudi Arabia	
European 1950 Cyprus	Kusaie Astro 1951 Caroline Islands	Nahrwan United Arab Emirates	
European 1950 Egypt	L.C. 5 Astro 1961 Cayman Brac Island	Naparima BWI Trinidad & Tobago	
European 1950 England, Channel Islands, Ireland, Scotland, Shetland Islands	Leigon Ghana	North American 1927 Mean for Antigua, Barbados, Barbuda, Caicos Islands, Cuba, Dominican Republic, Grand Cayman, Jamaica, Turks Islands	
European 1950 Finland, Norway	Liberia 1964 Liberia		
European 1950 Greece	Luzon Philippines (Excluding Mindanao)		
European 1950 Iran	Luzon Philippines (Mindanao)		
	Mahe 1971	North American 1927 Mean for Canada	

North American 1927 Mean for CONUS (Continental United States)	North American 1927 Cuba	Great Britain 1936 - England
North American 1927 Mean for CONUS (East of Mississippi River) including Louisiana, Missouri, Minnesota	North American 1927 Greenland (Hayes Peninsula)	Ordinance Survey Great Britain 1936 - England, Isle of Man, Wales
North American 1927 Mean for CONUS (West of Mississippi River)	North American 1927 Mexico	Ordinance Survey Great Britain 1936 - Scotland, Shetland Islands
North American 1927 Alaska	North American 1983 Alaska, Canada, CONUS	Ordinance Survey Great Britain 1936 - Wales
North American 1927 Bahamas (Except San Salvador Island)	North American 1983 Central America, Mexico	Ordinance Survey Great Britain 1936 - Wales
North American 1927 Bahamas (San Salvador Island)	Observatorio Metereo 1939; Azores (Corvo & Flores Islands)	Pico de las Nieves Canary Islands
North American 1927 Canada (Alberta, British Columbia)	Old Egyptian 1907 Egypt	Pitcairn Astro 1967 Pitcairn Island
North American 1927 Canada (Manitoba, Ontario)	Old Hawaiian Mean for Hawaii, Kauai, Maui, Oahu	Point 58 Sweden
North American 1927 Canada (New Brunswick, Newfoundland, Nova Scotia, Quebec)	Old Hawaiian Hawaii	Santo (DOS) 1965 Espirito Santo Island
North American 1927 Canada (Northwest Territories, Saskatchewan)	Old Hawaiian Kauai	Sao Braz Azores (Sao Miguel, Santa Maria Islands)
North American 1927 Canada (Yukon)	Old Hawaiian Maui	Sapper Hill 1943 East Falkland Island
North American 1927 Canal Zone	Old Hawaiian Oahu	Schwarzzeck Nambia
	Oman	Selvagem Grande Salvage Islands
	Oman	SGS 85
	Ordinance Survey Great Britain 1936 - Mean for England, Isle of Man, Scotland, Shetland Islands, Wales	Soviet Geodetic System 1985
	Ordinance Survey	South American 1969 Mean for Argentina,

Bolivia, Brazil, Chile, Colombia, Ecuador, Guyana, Paraguay, Peru, Trinidad & Tobago, and Venezuela	South American 1969 Paraguay South American 1969 Peru	Tokyo Korea
South American 1969 Argentina	South American 1969 Trinidad & Tobago	Okinawa
South American 1969 Bolivia	South American 1969 Venezuela	Tristan Astro 1968 Tristan da Cunha
South American 1969 Brazil	South Asia Singapore	Viti Levu 1916 Fiji (Viti Levu Island)
South American 1969 Chile	Tananarive Observatory 1925; Madagascar	Wake
South American 1969 Colombia	Timbalai 1948 Brunei, East Malaysia (Sabah, Sarawak)	Eniwetok 1960 Marshall Islands
South American 1969 Ecuador	Tokyo	Wake Island Astro 1952 Wake Atoll
South American 1969 Ecuador (Baltra, Galapagos)	Mean for Japan, Korea, Okinawa	WGS 1972 Global Definition
South American 1969 Guyana	Tokyo Japan	Yacare Uruguay
		Zanderij Suriname

## FCC Compliance

This device complies with Part 15 of the U.S. Federal Communications Commission (FCC) Rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the manufacturer could void the user's authority to operate the equipment.

### Note:

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the factory customer service department for help.

# Notes

# Notes

# Notes

## LOWRANCE DATABASES LICENSE AGREEMENT

THIS IS A LEGAL AGREEMENT BETWEEN THE END-USER WHO FIRST PURCHASES THIS PRODUCT AS A CONSUMER ITEM FOR PERSONAL, FAMILY, OR HOUSEHOLD USE ("YOU") AND LOWRANCE ELECTRONICS, INC., THE MANUFACTURER OF THIS PRODUCT ("WE", "OUR", OR "US"). USING THE PRODUCT ACCCOMPANIED BY THIS LICENSE AGREEMENT CONSTITUTES ACCEPTANCE OF THESE TERMS AND CONDITIONS. IF YOU DO NOT ACCEPT ALL TERMS AND CONDITIONS, PROMPTLY RETURN THE PRODUCT WITHIN 30 DAYS OF PURCHASE. PLEASE RETURN USING THE ENCLOSED UPS SHIPPING LABEL AND INCLUDE: PROOF OF PURCHASE, NAME, ADDRESS, AND PHONE NUMBER. YOUR PURCHASE PRICE AND ANY APPLICABLE TAXES WILL BE REFUNDED. PLEASE ALLOW 4-6 WEEKS TO PROCESS YOUR REFUND.

1. This License Agreement applies to the one or more databases that your product may contain. We refer to these singly as a "Database" and together as the "Databases." Your product may thus include the "WBS Database" which contains worldwide background surface mapping data, the "SmartMap Database" which contains inland mapping data, or other Databases.
2. The Databases that your product may contain are licensed, not sold. We grant to you the nonexclusive, nonassignable right to use these Databases for supplemental navigation reference purposes, but only as long as you comply with the terms and conditions of this License Agreement. We reserve the right to terminate this license if you violate any aspect of this License Agreement. You are responsible for using official government charts and prudent navigation for safe travel.
3. The Databases housed in your product are protected by the copyright notices appearing on the product or its screen(s). You may NOT modify, adapt, translate, reverse engineer, decompile, disassemble, rent, lease, or resell any Database, and you may NOT create derivative works based upon any Database or its contents. Any unauthorized reproduction, use, or transfer of a Database may be a crime and may subject you to damages and attorney fees.
4. This License Agreement will terminate immediately without prior notice from us if you fail to comply with or violate any of the provisions of this Agreement. Upon termination, you will promptly return all products containing one or more Databases to us.
5. Prices and programs are subject to change without notice.
6. This License Agreement shall be governed by the laws of the State of Oklahoma and comprises the complete and exclusive understanding between you and us concerning the above subject matter.

## **DATABASES LIMITED WARRANTY**

"We", "our", or "us" refers to Lowrance Electronics, Inc., the manufacturer of this product. "You" or "your" refers to the first person who purchases the product as a consumer item for personal, family, or household use. The Databases Limited Warranty applies to the one or more databases that your product may contain. We refer to each of these as a "Database" or together as the "Databases." Your product may thus include the "WBS Database" which contains worldwide background surface mapping data, the "SmartMap Database" which contains inland mapping data, or other Databases.

We warrant to you that we have accurately compiled, processed, and reproduced the portions of the source material on which the Databases are based. However, we are under no obligation to provide updates to the Databases, and the data contained in the Databases may be incomplete when compared to the source material. **WE MAKE NO EXPRESS OR IMPLIED WARRANTY OF ANY KIND ABOUT THE ACCURACY OF THE SOURCE MATERIAL ITSELF, INCLUDING BUT NOT LIMITED TO IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE.**

If there is a defect in any Database, your exclusive remedy shall be, at our option, either a refund of the price you paid for the product containing the defective Database or a replacement of such product. **WE WILL NOT UNDER ANY CIRCUMSTANCES BE LIABLE TO ANYONE FOR ANY SPECIAL, CONSEQUENTIAL, INCIDENTAL, OR OTHER INDIRECT DAMAGE OF ANY KIND.**

Some states do not allow the exclusion or limitation of incidental or consequential damages, so the above limitations or exclusions may not apply to you.

This warranty does NOT apply in the following circumstances: (1) when the product has been serviced or repaired by anyone other than us; (2) when the product has been connected, installed, combined, altered, adjusted, or handled in a manner other than according to the instructions furnished with the product; (3) when any serial number has been effaced, altered, or removed; or (4) when any defect, problem, loss, or damage has resulted from any accident, misuse, negligence, or carelessness, or from any failure to provide reasonable and necessary maintenance in accordance with the instructions of the owner's manual for the product.

We reserve the right to make changes or improvements in our products from time to time without incurring the obligation to install such improvements or changes on equipment or items previously manufactured.

This warranty gives you specific legal rights and you may also have other rights which may vary from state to state.

Your remedies under this warranty will be available so long as you can show in a reasonable manner that the defect occurred within one (1) year from the date of your original purchase, and we must receive your warranty claim no later than 30 days after such 1-year period expires. Your claim must be substantiated by a dated sales receipt or sales slip.

## **LOWRANCE ELECTRONICS FULL ONE-YEAR WARRANTY**

"We," "our," or "us" refers to LOWRANCE ELECTRONICS, INC., the manufacturer of this product. "You" or "your" refers to the first person who purchases this product as a consumer item for personal, family or household use.

We warrant this product against defects or malfunctions in materials and workmanship, and against failure to conform to this product's written specifications, all for one (1) year from the date of original purchase by you. **WE MAKE NO OTHER EXPRESS WARRANTY OR REPRESENTATION OF ANY KIND WHATSOEVER CONCERNING THIS PRODUCT.** Your remedies under this warranty will be available so long as you can show in a reasonable manner that any defect or malfunction in materials or workmanship, or any non-conformity with the product's written specifications, occurred within one year from the date of your original purchase, which must be substantiated by a dated sales receipt or sales slip. Any such defect, malfunction, or non-conformity which occurs within one year from your original purchase date will either be repaired without charge or be replaced with a new product identical or reasonably equivalent to this product, at our option, within a reasonable time after our receipt of the product. If such defect, malfunction, or non-conformity remains after a reasonable number of attempts to repair by us, you may elect to obtain without charge a replacement of the product or a refund for the product. **THIS REPAIR, OR REPLACEMENT OR REFUND (AS JUST DESCRIBED) IS THE EXCLUSIVE REMEDY AVAILABLE TO YOU AGAINST US FOR ANY DEFECT, MALFUNCTION, OR NON-CONFORMITY CONCERNING THE PRODUCT OR FOR ANY LOSS OR DAMAGE RESULTING FROM ANY OTHER CAUSE WHATSOEVER. WE WILL NOT UNDER ANY CIRCUMSTANCES BE LIABLE TO ANYONE FOR ANY SPECIAL, CONSEQUENTIAL, INCIDENTAL, OR OTHER INDIRECT DAMAGE OF ANY KIND.**

Some states do not allow the exclusion or limitation of incidental or consequential damages, so the above limitations or exclusions may not apply to you.

This warranty does NOT apply in the following circumstances: (1) when the product has been serviced or repaired by anyone other than us; (2) when the product has been connected, installed, combined, altered, adjusted, or handled in a manner other than according to the instructions furnished with the product; (3) when any serial number has been effaced, altered, or removed; or (4) when any defect, problem, loss, or damage has resulted from any accident, misuse, negligence, or carelessness, or from any failure to provide reasonable and necessary maintenance in accordance with the instructions of the owner's manual for the product.

We reserve the right to make changes or improvements in our products from time to time without incurring the obligation to install such improvements or changes on equipment or items previously manufactured.

This warranty gives you specific legal rights and you may also have other rights which may vary from state to state.

**REMINDER:** You must retain the sales slip or sales receipt proving the date of your original purchase in case warranty service is ever required.

**LOWRANCE ELECTRONICS  
12000 E. SKELLY DRIVE, TULSA, OK 74128  
(800) 324-1356**

## **How to Obtain Service... ...in the USA:**

We back your investment in quality products with quick, expert service and genuine Lowrance parts. If you're in the United States and you have technical, return or repair questions, please contact the Factory Customer Service Department. Before any product can be returned, you must call customer service to determine if a return is necessary. Many times, customer service can resolve your problem over the phone without sending your product to the factory. To call us, use the following toll-free number:

**800-324-1356**

8 a.m. to 5 p.m. Central Standard Time, M-F

*Lowrance Electronics may find it necessary to change or end our shipping policies, regulations, and special offers at any time. We reserve the right to do so without notice.*

## **...in Canada:**

If you're in Canada and you have technical, return or repair questions, please contact the Factory Customer Service Department. Before any product can be returned, you must call customer service to determine if a return is necessary. Many times, customer service can resolve your problem over the phone without sending your product to the factory. To call us, use the following toll-free number:

**800-661-3983**

**905-629-1614 (not toll-free)**

8 a.m. to 5 p.m. Eastern Standard Time, M-F

## **...outside Canada and the USA:**

If you have technical, return or repair questions, contact the dealer in the country where you purchased your unit. To locate a dealer near you, visit our web site, [www.lowrance.com](http://www.lowrance.com) and look for the Dealer Locator.

# **Accessory Ordering Information for all countries**

To order Lowrance accessories such as power cables or transducers, please contact:

**1)** Your local marine dealer or consumer electronics store. Most quality dealers that handle marine electronic equipment or other consumer electronics should be able to assist you with these items.

To locate a Lowrance dealer near you, visit our web site, [www.lowrance.com](http://www.lowrance.com) and look for the Dealer Locator. Or, you can consult your telephone directory for listings.

**2)** U.S. customers: LEI Extras Inc., PO Box 129, Catoosa, OK 74015-0129  
Call 1-800-324-0045 or visit our web site [www.lei-extras.com](http://www.lei-extras.com).

**3)** Canadian customers can write:

Lowrance/Eagle Canada, 919 Matheson Blvd. E. Mississauga, Ontario L4W2R7 or fax 905-629-3118.

## **Shipping Information**

If it becomes necessary to send a product for repair or replacement, you must first receive a return authorization number from Customer Service. Products shipped without a return authorization will not be accepted. When shipping, we recommend you do the following:

1. Please do not ship the knobs or mounting bracket with your unit.
2. If you are sending a check for repair, please place your check in an envelope and tape it to the unit.
3. For proper testing, include a brief note with the product describing the problem. Be sure to include your name, return shipping address and a daytime telephone number. An e-mail address is optional but useful.
4. Pack the unit in a suitable size box with packing material to prevent any damage during shipping.
5. Write the Return Authorization (RA) number on the outside of the box underneath your return address.
6. For your security, you may want to insure the package through your shipping courier. Lowrance does not assume responsibility for goods lost or damaged in transit.

Visit our web site:

[lowrance.com](http://lowrance.com)

**LOWRANCE**  
*We Lead, We Find, You Win.™*

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